



**Freescale Semiconductor, Inc.**  
Board Errata

Document Number: FRDMK64F\_ERRATA  
Rev. 2.0, 06/2014

# FRDM-K64F Board Errata

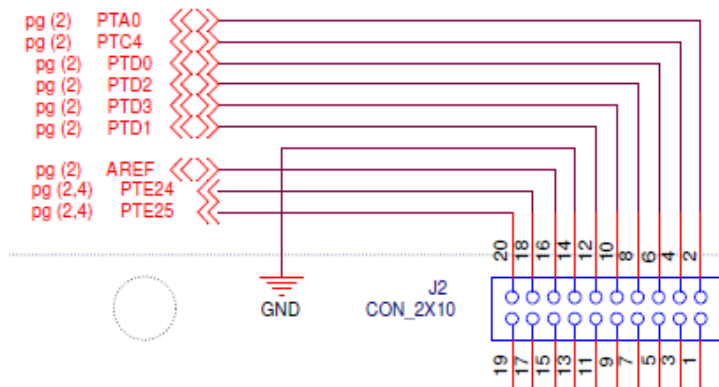
by: Freescale Semiconductor, Inc.

# 1 Errata Title: I<sup>2</sup>C signals are swapped on I/O headers

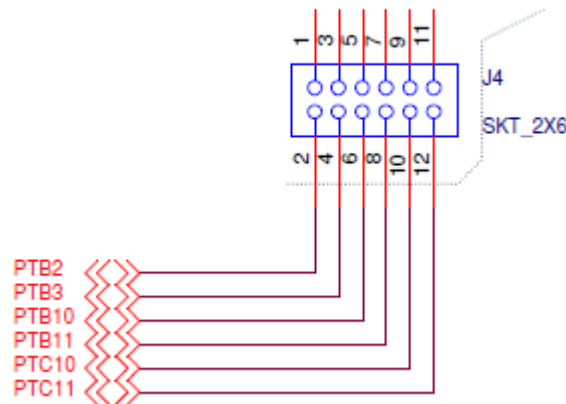
**Description:** Pin 18 (I2C0\_SCL) and pin 20 (I2C0\_SDA) of J2 I/O Header, and pin 10 (I2C\_SCL) and pin 12 (I2C0\_SDA) of J4 I/O Header are swapped. [Figure 1](#) and [Figure 2](#) show the incorrect signals.

**Table 1. Incorrect signals**

FRDM-K64F	Signal	Arduino Uno R3	Signal
J2-18	I <sup>2</sup> C0_SCL	D14	I <sup>2</sup> C_SDA
J2-20	I <sup>2</sup> C0_SDA	D15	I <sup>2</sup> C_SCL
J4-10	I <sup>2</sup> C0_SCL	A4	I <sup>2</sup> C_SDA
J4-12	I <sup>2</sup> C0_SDA	A5	I <sup>2</sup> C_SCL



**Figure 1. Swapped I<sup>2</sup>C signals Pin18 and on J2**

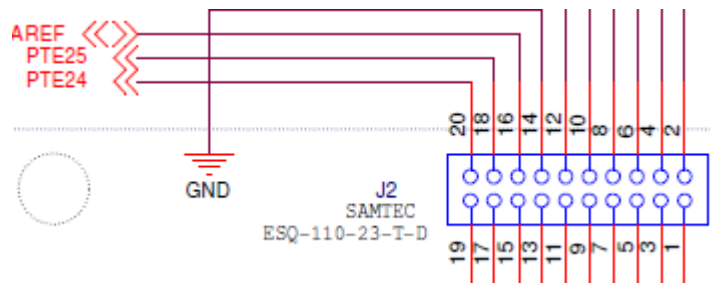


**Figure 2. Swapped I<sup>2</sup>C signals Pin10 and Pin12 on J4**

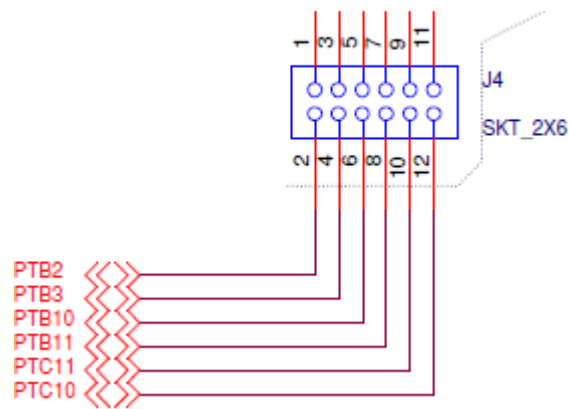
The correct position should be:

**Table 2. Correct signals**

FRDM-K64F	Signal	Arduino Uno R3	Signal
J2-18	I <sup>2</sup> C0_SDA	D14	I <sup>2</sup> C_SDA
J2-20	I <sup>2</sup> C0_SCL	D15	I <sup>2</sup> C_SCL
J4-10	I <sup>2</sup> C0_SDA	A4	I <sup>2</sup> C_SDA
J4-12	I <sup>2</sup> C0_SCL	A5	I <sup>2</sup> C_SCL



**Figure 3. Correct order of I<sup>2</sup>C signals on J2**



**Figure 4. Correct order of I<sup>2</sup>C signals on J4**

**Workaround:**

1. Use jumper wires to connect between Arduino compatible shield signals to the FRDM board I/O header signals. Swap the jumper wires only on the I<sup>2</sup>C signals.
2. When pin 10 of J4 (PTC10) and pin 12 of J4 (PTC11) are not used on the shield, route pin 10 of J4 to pin 20 of J2 and pin 12 of J4 to pin 18 of J2. Configure PTE24 and PTE26 (pin 18 and pin 20 of J2) as GPIO, and use PTC10 and PTC11 (pin 10 and pin 12 of J4) as I<sup>2</sup>C signals.

**Fix Plan:** Fixed in FRDM-K64F board (700 Assembly Rev B, Schematic Rev D1).

## 2 Errata Title: PTA0 is routed to Pin2 of J2

**Description:** Some Arduino shields are using Pin2 of J2 (connected to PTA0) as general purpose signal. The feature associated with Pin2 of J2 cannot be used while debugging.

**Workaround:** Use Jumper wires to connect between Arduino compatible shield and the FRDM board. The Pin2 of J2 on Arduino shield is connected to J9 of J4 I/O Header.

**Fix Plan:** A fix has been planned for future FRDM-K64F boards.

## 3 Errata Title: Unable to establish link status when two FRDM-K64F boards are connected.

**Description:** When two FRDM-K64F boards are connected together with an Ethernet cable, the Ethernet PHY can't establish the link status, and will drop to a default state of 10Mbit and half duplex mode. This is caused by incorrect termination on the TD+ and RD+ signals, which reduces the link signal detection. This issue does not affect other connections such as PC host to FRDM-K64F, TWR-SER1/2 to FRDM-K64F, or network switch to FRDM-K64F when the cable length is less than 25 feet. This issue affects both Rev C and Rev D1 boards.

**Workaround:** Remove the four resistors R44, R48, R51, and R59 that connect to TD+, TD-, RD+ and RD- signals.

**Fix Plan:** A fix has been planned for future version of FRDM-K64F board (after 700 Assembly Rev B, Schematic Rev D1).

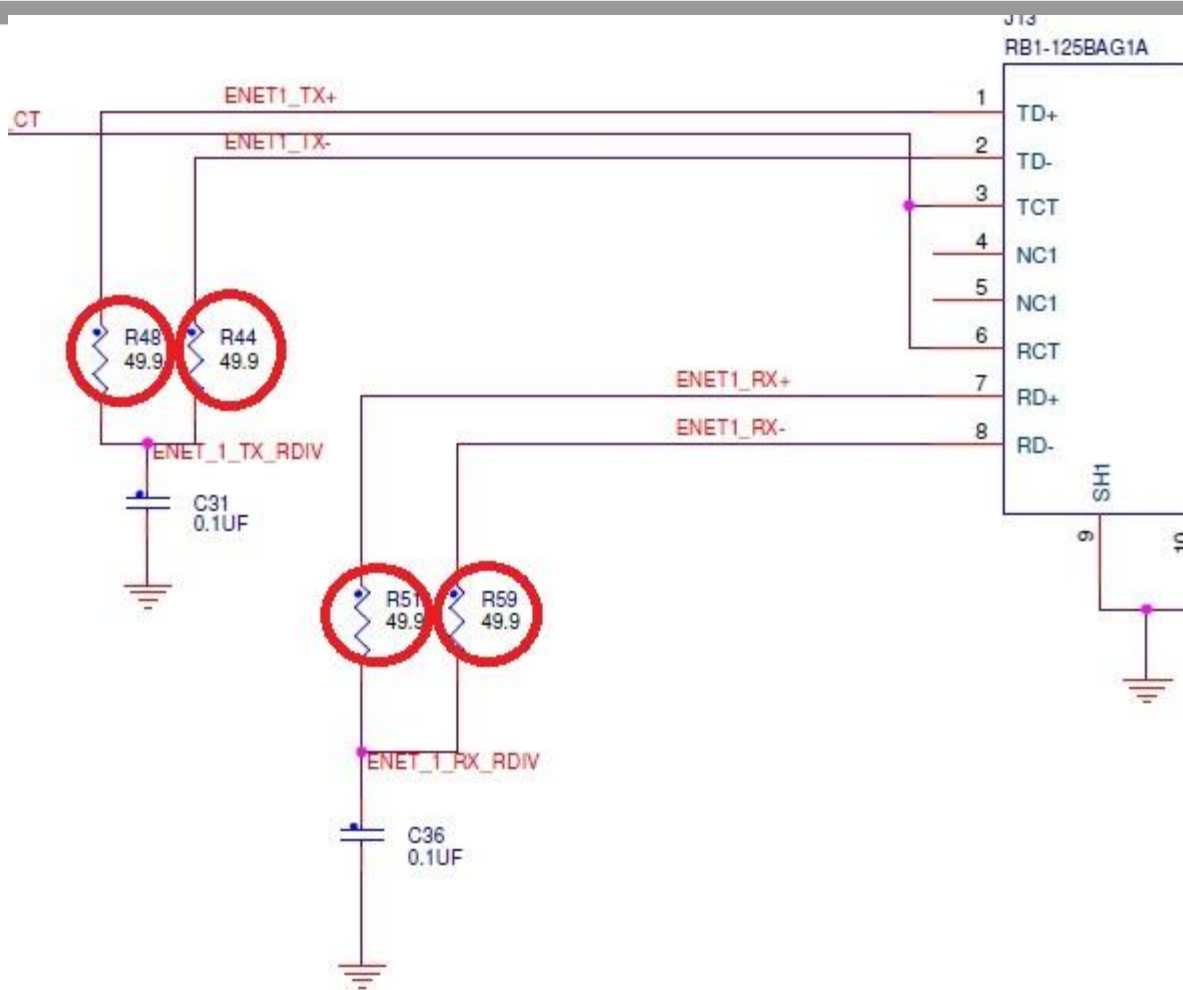


Figure 5. Correct order of I<sup>2</sup>C signals on J2

## Revision history

Table 3 describes the boards to which the errata in this document apply.

Table 3. Revision of the Boards

Board Assembly Rev.	Board Schematic Rev.	Board PN
A	Rev C	FRDM-K64F
B	Rev D1	FRDM-K64F

Table 4. Document Revision History

Revision number	Date	Substantial changes
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1.0	03/2014	Initial release
1.1	04/2014	Additional workaround to Errata 1
2.0	06/2014	Added errata "Unable to establish link status when two FRDM-K64F boards are connected" type

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