

SiGe:C LNA MMIC for GPS, GLONASS, Galileo and COMPASS

Rev. 1 — 25 January 2016

Preliminary data sheet

## 1. General description

The BGU8103UK is an ultra low current and Low-Noise Amplifier (LNA) for GNSS receiver applications. It comes as an extremely small and thin Wafer Level Chip Scale Package (WLCSP). This product is only used in an overmolded module. The BGU8103UK requires only one external matching inductor.

The BGU8103UK adapts itself to the changing environment resulting from co-habitation of different radio systems in modern cellular handsets. It has been designed for ultra low power consumption and optimal performance when jamming signals from co-existing cellular transmitters are present. At low jamming power levels, it delivers 18.5 dB gain at a noise figure of 0.80 dB and a supply current of 1.2 mA. During high jamming power levels, resulting for example from a cellular transmit burst, it temporarily increases its bias current to improve sensitivity.

## 2. Features and benefits

- Optimized performance at a low supply current of 1.2 mA
- Covers full GNSS L1 band, from 1559 MHz to 1610 MHz
- Noise figure = 0.80 dB
- Gain 18.5 dB
- Input 1 dB compression point of –17 dBm
- Out of band IP3<sub>i</sub> of -11 dBm
- Supply voltage 1.5 V to 3.1 V
- Integrated supply decoupling capacitor
- Power-down mode current consumption < 1 μA</p>
- Integrated temperature stabilized bias for easy design
- Requires only one input matching inductor
- Integrated DC blocking at both RF input and output
- ESD protection on all pins (HBM > 2 kV)
- Integrated matching for the output
- Available in a WLCSP 0.69 mm × 0.44 mm × 0.29 mm: SOT1445-1
- 180 GHz transit frequency SiGe:C technology
- Moisture sensitivity level 1



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#### **Applications** 3.

- LNA for GPS
- GLONASS
- Galileo and COMPASS (BeiDou) in smart phones
- Feature phones
- Tablet PCs
- Digital still cameras
- Digital video cameras
- RF front-end modules
- Complete GNSS modules and wearable applications

#### Quick reference data 4.

#### Table 1. Quick reference data

 $f = 1575 \text{ MHz}; V_{CC} = 1.8 \text{ V}; V_{I(ENABLE)} \ge 0.8 \text{ V}; P_i < -40 \text{ dBm}; T_{amb} = 25 \text{ °C}; input matched to 50 \Omega using a 12 nH inductor; and the equation of the second second$ see Figure 4; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>CC</sub>	supply voltage		1.5	-	3.1	V
I <sub>CC</sub>	supply current		-	1.2	-	mA
G <sub>p</sub>	power gain	no jammer	-	18.5	-	dB
NF	noise figure	$P_i = -40 \text{ dBm}; \text{ no jammer}$ [1]	-	0.8	-	dB
P <sub>i(1dB)</sub>	input power at 1 dB gain compression		-	-17	-	dBm
IP3 <sub>i</sub>	input third-order intercept point	[2]	-	-11	-	dBm

[1] PCB losses are subtracted.

[2]  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz;  $P_i = -20$  dBm at  $f_1$ ;  $P_i = -65$  dBm at  $f_2$ .

#### **Ordering information** 5.

#### Table 2. **Ordering information**

Type number	Package						
	Name	Description	Version				
BGU8103UK	WLCSP6	wafer level chip-scale package; 6 bumps; $0.69 \times 0.44 \times 0.29$ mm	SOT1445-1				

#### Marking 6.

Table 3. Marking codes							
Type number	Marking code						
BGU8103UK	single character, indicating assembly month <sup>[1]</sup>						

[1] Month codes see Table 4.

BGU8103UK

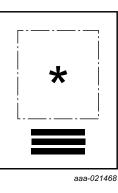
### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and COMPASS

### Table 4. Calender marking month code

Replace asterisk (*)	by character in table	, see <u>Figure 1</u> .
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Year <sup>[1]</sup>	Month	Nonth										
	J	F	м	Α	м	J	J	Α	S	0	Ν	D
2015	A	В	С	D	E	F	G	Н	I	J	К	L
2016	М	N	0	Р	Q	R	S	Т	U	V	W	Х
2017	Y	Z	b	d	f	h	3	4	5	6	7	9

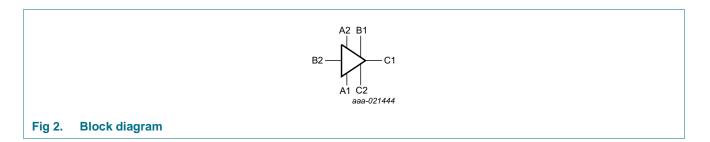
[1] Rotates every 3 years.



Pin A1 location: the marking stripes below character indicate the side where pin A1 is located.

Fig 1. Marking code description example

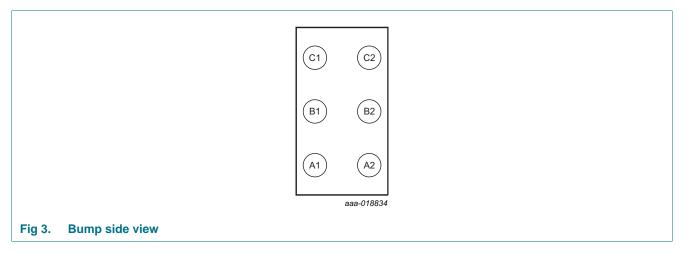
## 7. Block diagram



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## 8. Pinning information

### 8.1 Pinning



## 8.2 Pin description

### Table 5. Bump description

Symbol	Bump	Description
GND	A1	ground
V <sub>cc</sub>	B1	supply voltage
RF_OUT	C1	RF output
ENABLE	A2	enable
RF_IN	B2	RF input
GND_RF	C2	ground RF

## 9. Limiting values

### Table 6. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC</sub>	supply voltage	RF input AC coupled	[1]	-0.5	+5.0	V
V <sub>I(ENABLE)</sub>	input voltage on pin ENABLE	$V_{I(ENABLE)} < V_{CC} + 0.6 V$	[1][2]	-0.5	+5.0	V
V <sub>I(RF_IN)</sub>	input voltage on pin RF_IN	DC; $V_{I(RF_{IN})} < V_{CC} + 0.6 V$	<u>[1][2][3]</u>	-0.5	+5.0	V
V <sub>I(RF_OUT)</sub>	input voltage on pin RF_OUT	DC; $V_{I(RF_OUT)} < V_{CC} + 0.6 V$	<u>[1][2][3]</u>	-0.5	+5.0	V
Pi	input power		[1]	-	10	dBm
P <sub>tot</sub>	total power dissipation	$T_{sp} \le 130 \ ^{\circ}C$		-	55	mW
T <sub>stg</sub>	storage temperature			-65	+150	°C
Tj	junction temperature			-	150	°C

Max

3.1

+85

0.3

Тур

+25

-

0.8

Unit

V

°C

V

V

### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and COMPASS

#### Table 6. Limiting values ...continued

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>ESD</sub>	electrostatic discharge voltage	Human Body Model (HBM) according to JEDEC standard JS-001-2010	-	±2	kV
		Charged Device Model (CDM) according to JEDEC standard JESD22-C101C	-	±2	kV

[1] Stressed with pulses of 200 ms in duration, with application circuit as in Figure 4.

- [2] Warning: due to internal ESD diode protection, the applied DC voltage shall not exceed V<sub>CC</sub> + 0.6 V and shall not exceed 5.0 V in order to avoid excess current.
- [3] The RF input and RF output are AC coupled through internal DC blocking capacitors.

## 10. Recommended operating conditions

Table 7.	Operating conditions		
Symbol	Parameter	Conditions	Min
V <sub>CC</sub>	supply voltage		1.5
T <sub>amb</sub>	ambient temperature		-40
V <sub>I(ENABLE)</sub>	input voltage on pin ENABLE	OFF state	-

## **11. Thermal characteristics**

Table 8.	Thermal characteristics			
Symbol	Parameter	Conditions	Тур	Unit
R <sub>th(j-sp)</sub>	thermal resistance from junction to solder point		225	K/W

ON state

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## 12. Characteristics

### Table 9. Characteristics at V<sub>CC</sub> = 1.8 V

 $f = 1575 \text{ MHz}; V_{CC} = 1.8 \text{ V}; V_{I(ENABLE)} \ge 0.8 \text{ V}; P_i < -40 \text{ dBm}; T_{amb} = 25 \text{ °C}; input matched to 50 \Omega using a 12 nH inductor; see <u>Figure 4</u>; unless otherwise specified.$ 

Symbol	Parameter	Conditions	I	Min	Тур	Max	Unit
I <sub>CC</sub>	supply current	$V_{I(ENABLE)} \ge 0.8 V$					
		P <sub>i</sub> < -40 dBm		-	1.2	-	mA
		$P_i = -20 \text{ dBm}$		-	2.5	-	mA
		$V_{I(ENABLE)} \le 0.3 \text{ V}$		-	-	1	μA
G <sub>p</sub>	power gain	no jammer		-	18.5	-	dB
		P <sub>jam =</sub> -20 dBm;		-	20.0	-	dB
		f <sub>jam</sub> = 850 MHz					
		P <sub>jam =</sub> -20 dBm;		-	20.0	-	dB
		f <sub>jam</sub> = 1850 MHz					
RL <sub>in</sub>	input return loss	P <sub>i</sub> < -40 dBm		-	8	-	dB
		$P_i = -20 \text{ dBm}$		-	9	-	dB
RL <sub>out</sub>	output return loss	P <sub>i</sub> < -40 dBm		-	11	-	dB
		$P_i = -20 \text{ dBm}$		-	11	-	dB
ISL	isolation			-	35	-	dB
NF	noise figure	$P_i = -40 \text{ dBm}$ ; no jammer	[1]	-	0.8	-	dB
		$P_i = -40 \text{ dBm}$ ; no jammer	[2]	-	0.9	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	[2]	-	1.1	-	dB
		$P_{jam} = -20 \text{ dBm};$ f <sub>jam</sub> = 1850 MHz	[2] .	-	1.4	-	dB
P <sub>i(1dB)</sub>	input power at 1 dB gain compression			-	-17	-	dBm
IP3 <sub>i</sub>	input third-order intercept point		<u>[3]</u> .	-	-11	-	dBm
IMD3	third-order intermodulation distortion	output referred	[3]	-	-64	-	dBm
t <sub>on</sub>	turn-on time	time from V <sub>I(ENABLE)</sub> ON to 90 % of the gain		-	-	2	μS
t <sub>off</sub>	turn-off time	time from $V_{I(ENABLE)}$ OFF to 10 % of the gain	•	-	-	1	μS

[1] PCB losses are subtracted.

[2] Including PCB losses.

[3]  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz;  $P_i = -20$  dBm at  $f_1$ ;  $P_i = -65$  dBm at  $f_2$ .

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### Table 10. Characteristics at V<sub>CC</sub> = 2.85 V

 $f = 1575 \text{ MHz}; V_{CC} = 2.85 \text{ V}; V_{I(ENABLE)} \ge 0.8 \text{ V}; P_i < -40 \text{ dBm}; T_{amb} = 25 \text{ °C}; input matched to 50 \Omega using a 12 nH inductor; see Figure 4; unless otherwise specified.$ 

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I <sub>CC</sub>	supply current	$V_{I(ENABLE)} \ge 0.8 \text{ V}$				
		P <sub>i</sub> < -40 dBm	-	1.2	-	mA
		$P_i = -20 \text{ dBm}$	-	2.5	-	mA
		$V_{I(ENABLE)} \leq 0.3 \text{ V}$	-	-	1	μA
G <sub>p</sub>	power gain	no jammer	-	18.5	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	-	20.0	-	dB
		$P_{jam} = -20 \text{ dBm};$ f <sub>jam</sub> = 1850 MHz	-	20.0	-	dB
RL <sub>in</sub>	input return loss	P <sub>i</sub> < -40 dBm	-	8	-	dB
		$P_i = -20 \text{ dBm}$	-	9	-	dB
RL <sub>out</sub>	output return loss	P <sub>i</sub> < -40 dBm	-	11	-	dB
		$P_i = -20 \text{ dBm}$	-	11	-	dB
ISL	isolation		-	35	-	dB
NF	noise figure	$P_i = -40 \text{ dBm}; \text{ no jammer}$	1 -	0.8	-	dB
		$P_i = -40 \text{ dBm}; \text{ no jammer}$	1 -	0.9	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	1 -	1.1	-	dB
		P <sub>jam</sub> = -20 dBm; f <sub>jam</sub> = 1850 MHz	-	1.4	-	dB
P <sub>i(1dB)</sub>	input power at 1 dB gain compression		-	-14	-	dBm
IP3 <sub>i</sub>	input third-order intercept point	<u>]</u>	<u>-</u>	-9	-	dBm
IMD3	third-order intermodulation distortion	output referred	<u>-</u>	-68	-	dBm
t <sub>on</sub>	turn-on time	time from V <sub>I(ENABLE)</sub> ON to 90 % of the gain	-	-	2	μS
t <sub>off</sub>	turn-off time	time from V <sub>I(ENABLE)</sub> OFF to 10 % of the gain	-	-	1	μS

[1] PCB losses are subtracted.

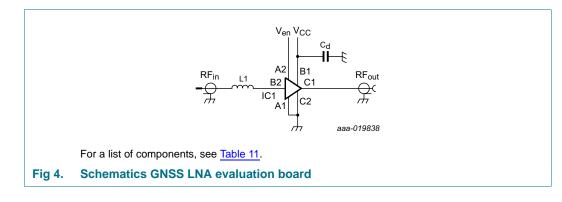
[2] Including PCB losses.

[3]  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz;  $P_i = -20$  dBm at  $f_1$ ;  $P_i = -65$  dBm at  $f_2$ .

SiGe:C LNA MMIC for GPS, GLONASS, Galileo and COMPASS

## **13. Application information**

### 13.1 GNSS LNA



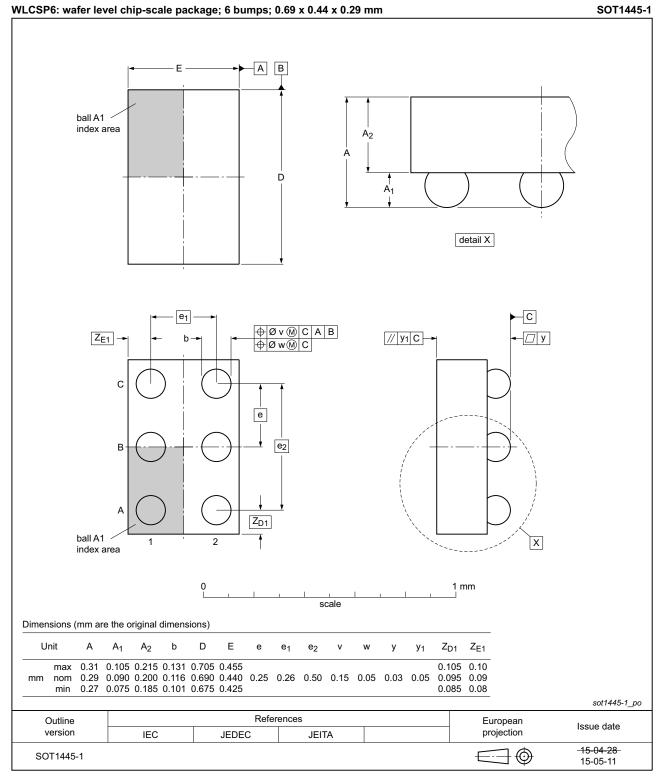
### Table 11. List of components

For schematics, see Figure 4.

Component	Description	Value	Remarks
C <sub>d</sub>	decoupling capacitor	1 nF	to suppress power supply noise
IC1	BGU8103UK	-	NXP Semiconductors
L1	high-quality matching inductor	12 nH	Murata LQW15A

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## 14. Package outline



### Fig 5. Package outline SOT1445-1 (WLCSP6)

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## **15. Handling information**

### 15.1 ElectroStatic Discharge (ESD)

### CAUTION



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the ANSI/ESD S20.20, IEC/ST 61340-5, JESD625-A or equivalent standards.

### 16. Mounting

This WLCSP is only used in an overmolded module (using MUF).

### 17. Abbreviations

#### Table 12. Abbreviations

Acronym	Description
ESD	ElectroStatic Discharge
GLONASS	Global Navigation Satellite System
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
LNA	Low-Noise Amplifier
НВМ	Human Body Model
MMIC	Monolithic Microwave Integrated Circuit
MUF	Molded UnderFill
PCB	Printed-Circuit Board
SiGe:C	Silicon Germanium Carbon
WLCSP	Wafer Level Chip Scale Package

## 18. Revision history

Table 13. Revision history				
Document ID	Release date	Data sheet status	Change notice	Supersedes
BGU8103UK v.1	20160225	Preliminary data sheet	-	-

## **19. Legal information**

### **19.1 Data sheet status**

Document status[1][2]	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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SiGe:C LNA MMIC for GPS, GLONASS, Galileo and COMPASS

### 21. Contents

1	General description 1
2	Features and benefits 1
3	Applications 2
4	Quick reference data 2
5	Ordering information 2
6	Marking 2
7	Block diagram 3
8	Pinning information 4
8.1	Pinning 4
8.2	Pin description 4
9	Limiting values 4
10	Recommended operating conditions 5
11	Thermal characteristics 5
12	Characteristics 6
13	Application information 8
13.1	GNSS LNA
14	Package outline 9
15	Handling information 10
15.1	ElectroStatic Discharge (ESD) 10
16	Mounting 10
17	Abbreviations 10
18	Revision history 10
19	Legal information 11
19.1	Data sheet status 11
19.2	Definitions
19.3	Disclaimers
19.4	Trademarks 12
20	Contact information 12
21	Contents 13

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