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LE25S20MB

Serial Flash Memory 2 Mb (256K x 8)

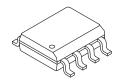


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Overview

The LE25S20MB is a SPI bus flash memory device with a 2M bit ($256K \times 8$ -bit) configuration. It uses a single 1.8 V power supply. While making the most of the features inherent to a serial flash memory device, the LE25S20MB is housed in an 8-pin ultra-miniature package. All these features make this device ideally suited to storing program in applications such as portable information devices, which are required to have increasingly more compact dimensions. The LE25S20MB also has a small sector erase capability which makes the device ideal for storing parameters or data that have fewer rewrite cycles and conventional EEPROMs cannot handle due to insufficient capacity.



SOIC-8 / SOP8K (200 mil)

Features

• Read/write operations enabled by single 1.8 V power supply : 1.65 to 1.95 V supply voltage range

Operating frequency
 Temperature range
 40 MHz
 -40 to +85°C

• Serial interface : SPI mode 0, mode 3 supported

• Sector size : 4K bytes/small sector, 64K bytes/sector

• Small sector erase, sector erase, chip erase functions

• Page program function (256 bytes/page)

• Block protect function

• Highly reliable read/write

Number of rewrite times: 100,000 times

Small sector erase time : 40 ms (typ), 150 ms (max) Sector erase time : 80 ms (typ), 250 ms (max) Chip erase time : 300 ms (typ), 3.0 s (max)

Page program time : 3.0 ms / 256 bytes (typ), 3.5 ms / 256 bytes (max)

• Status functions : Ready / busy information, protect information

• Data retention period : 20 years

• Package : SOP8K (200 mil)

ORDERING INFORMATION

See detailed ordering and shipping information on page 22 of this data sheet.

^{*} This product is licensed from Silicon Storage Technology, Inc. (USA).

Package Dimensions

unit: mm

SOIC-8 / SOP8K (200 mil) CASE 751CV ISSUE O

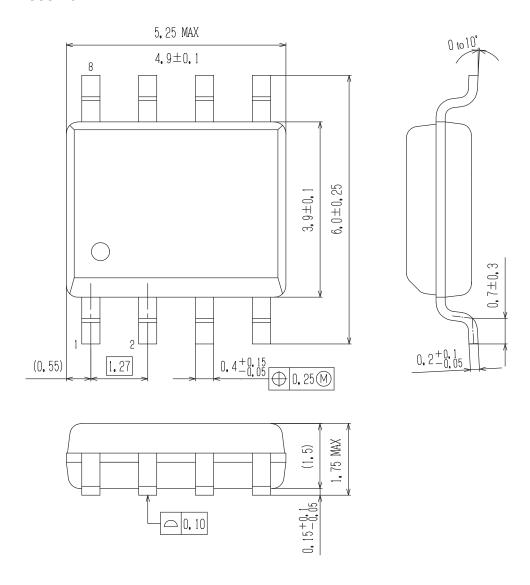


Figure 1 Pin Assignments

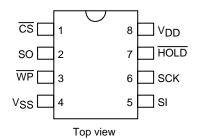


Figure 2 Block Diagram

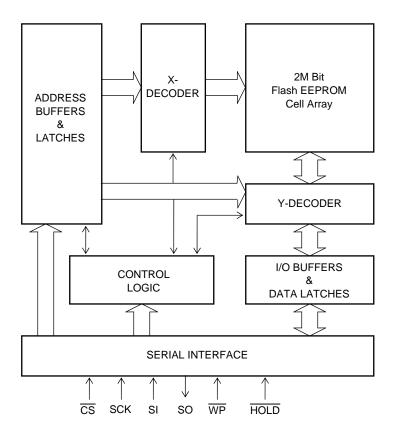


Table 1 Pin Description

Symbol	Pin Name	Description
SCK	Serial clock	This pin controls the data input/output timing.
		The input data and addresses are latched synchronized to the rising edge of the serial clock, and the data
		is output synchronized to the falling edge of the serial clock.
SI	Serial data input	The data and addresses are input from this pin, and latched internally synchronized to the rising edge of
		the serial clock.
so	Serial data output	The data stored inside the device is output from this pin synchronized to the falling edge of the serial clock.
CS	Chip select	The device becomes active when the logic level of this pin is low; it is deselected and placed in standby
		status when the logic level of the pin is high.
WP	Write protect	The status register write protect (SRWP) takes effect when the logic level of this pin is low.
HOLD	Hold	Serial communication is suspended when the logic level of this pin is low.
V_{DD}	Power supply	This pin supplies the 1.65 to 1.95 V supply voltage.
V _{SS}	Ground	This pin supplies the 0 V supply voltage.

Device Operation

The read, erase, program and other required functions of the device are executed through the command registers. The serial I/O corrugate is shown in Figure 3 and the command list is shown in Table 2. At the falling \overline{CS} edge the device is selected, and serial input is enabled for the commands, addresses, etc. These inputs are normalized in 8 bit units and taken into the device interior in synchronization with the rising edge of SCK, which causes the device to execute operation according to the command that is input.

The LE25S20MB supports both serial interface SPI mode 0 and SPI mode 3. At the falling \overline{CS} edge, SPI mode 0 is automatically selected if the logic level of SCK is low, and SPI mode 3 is automatically selected if the logic level of SCK is high.

Figure 3 I/O waveforms

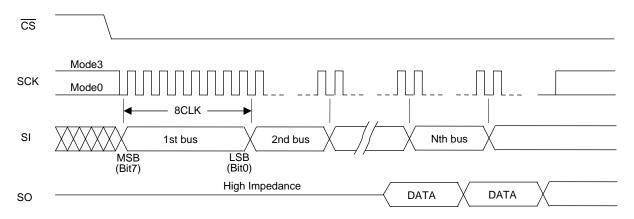


Table 2 Command Settings

Command	1st bus cycle	2nd bus cycle	3rd bus cycle	4th bus cycle	5th bus cycle	6th bus cycle	Nth bus cycle
Read	03h	A23-A16	A15-A8	A7-A0	RD *1	RD *1	RD *1
	0Bh	A23-A16	A15-A8	A7-A0	Х	RD *1	RD *1
Small sector erase	20h / D7h	A23-A16	A15-A8	A7-A0			
Sector erase	D8h	A23-A16	A15-A8	A7-A0			
Chip erase	60h / C7h						
Page program	02h	A23-A16	A15-A8	A7-A0	PD *2	PD *2	PD *2
Write enable	06h						
Write disable	04h						
Power down	B9h						
Status register read	05h						
Status register write	01h	DATA					
JEDEC ID read	9Fh						
ID read	ABh	Х	Х	Х			
power down	B9h						
Exit power down mode	ABh						

Explanatory notes for Table 2

The "h" following each code indicates that the number given is in hexadecimal notation.

Addresses A23 to A17 for all commands are "Don't care".

[&]quot;X" signifies "don't care" (that is to say, any value may be input).

^{*1: &}quot;RD" stands for read data. *2: "PD" stands for page program data.

Table 3 Command Settings

2M bit

sector(64KB)	small sector	address space	e(A23 to A0)
	63	03F000h	03FFFFh
3	to		
	48	030000h	030FFFh
	47	02F000h	02FFFFh
2	to		
	32	020000h	020FFFh
	31	01F000h	01FFFFh
1	to		
	16	010000h	010FFFh
	15	00F000h	00FFFFh
	to		
0	2	002000h	002FFFh
	1	001000h	001FFFh
	0	000000h	000FFFh

Description of Commands and Their Operations

A detailed description of the functions and operations corresponding to each command is presented below.

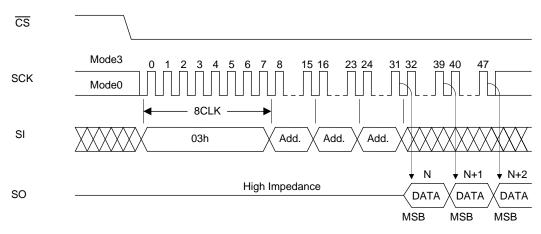
1. Standard SPI read

There are two read commands, the standard SPI read command and High-speed read command.

1-1. Read command

Consisting of the first through fourth bus cycles, the 4 bus cycle read command inputs the 24-bit addresses following (03h). The data is output from SO on the falling clock edge of fourth bus cycle bit 0 as a reference. "Figure 4-a Read" shows the timing waveforms.

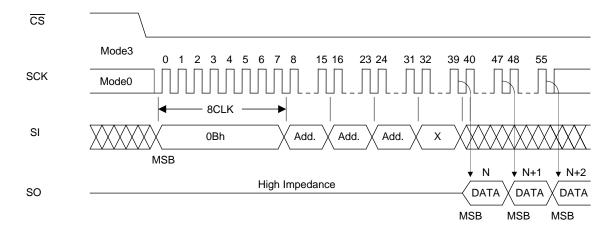
Figure 4-a Read



1-2. High-speed Read command

Consisting of the first through fifth bus cycles, the High-speed read command inputs the 24-bit addresses and 8 dummy bits following (0Bh). The data is output from SO using the falling clock edge of fifth bus cycle bit 0 as a reference. "Figure 4-b High-speed Read" shows the timing waveforms.

Figure 4-b High-speed Read



When SCK is input continuously after the read command has been input and the data in the designated addresses has been output, the address is automatically incremented inside the device while SCK is being input, and the corresponding data is output in sequence. If the SCK input is continued after the internal address arrives at the highest address (3FFFFh), the internal address returns to the lowest address (00000h), and data output is continued. By setting the logic level of $\overline{\text{CS}}$ to high, the device is deselected, and the read cycle ends. While the device is deselected, the output pin SO is in a high-impedance state.

Z. Status Registers

The status registers hold the operating and setting statuses inside the device, and this information can be read (status register read) and the protect information can be rewritten (status register write). There are 8 bits in total, and "Table 4 Status registers" gives the significance of each bit.

Table 4 Status Registers

Bit	Name	Logic	Function	Power-on Time Information
D:40	Bit0 RDY		Ready	
BitU	ND1	1	Erase/Program	0
Dist	10/51	0	Write disabled	
Bit1	WEN	1	Write enabled	0
D:10	D.D.o	0		No. 1 Chair Count
Bit2	Bit2 BP0	1		Nonvolatile information
Bit3	DH2 DD4	0	Block protect information	Nonvolatile information
ыз	BP1	1	Protecting area switch	Nonvolatile information
Bit4	BP2	0		Nonvolatile information
Bit4	BP2	1		Nonvolatile Information
Die	TD	0	Block protect	Non-relatile information
Bit5	ТВ	1	Upper side/Lower side switch	Nonvolatile information
Bit6			Reserved bits	0
D:47	CDWD	0	Status register write enabled	Negociatile informetics
Bit7	SRWP	1	Status register write disabled	Nonvolatile information

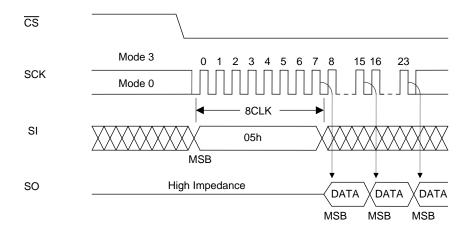
2-1. Status register read

The contents of the status registers can be read using the status register read command. This command can be executed even during the following operations.

- Small sector erase, sector erase, chip erase
- Page program
- Status register write

"Figure 5 Status Register Read" shows the timing waveforms of status register read. Consisting only of the first bus cycle, the status register command outputs the contents of the status registers synchronized to the falling edge of the clock (SCK) with which the eighth bit of (05h) has been input. In terms of the output sequence, SRWP (bit 7) is the first to be output, and each time one clock is input, all the other bits up to RDY (bit 0) are output in sequence, synchronized to the falling clock edge. If the clock input is continued after RDY (bit 0) has been output, the data is output by returning to the bit (SRWP) that was first output, after which the output is repeated for as long as the clock input is continued. The data can be read by the status register read command at any time (even during a program or erase cycle).

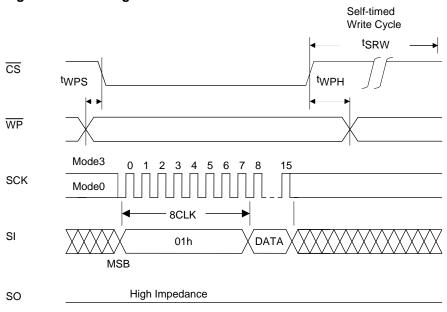
Figure 5 Status Register Read



2-2. Status register write

The information in status registers BP0, BP1, BP2, TB and SRWP can be rewritten using the status register write command. RDY, WEN and bit 6 are read-only bits and cannot be rewritten. The information in bits BP0, BP1, BP2, TB and SRWP is stored in the non-volatile memory, and when it is written in these bits, the contents are retained even at power-down. "Figure 6 Status Register Write" shows the timing waveforms of status register write, and Figure 19 shows a status register write flowchart. Consisting of the first and second bus cycles, the status register write command initiates the internal write operation at the rising \overline{CS} edge after the data has been input following (01h). Erase and program are performed automatically inside the device by status register write so that erasing or other processing is unnecessary before executing the command. By the operation of this command, the information in bits BP0, BP1, BP2, TB and SRWP can be rewritten. Since bits RDY (bit 0), WEN (bit 1) and bit 6 of the status register cannot be written, no problem will arise if an attempt is made to set them to any value when rewriting the status register. Status register write ends can be detected by RDY of status register read. To initiate status register write, the logic level of the \overline{WP} pin must be set high and status register WEN must be set to "1".

Figure 6 Status Register Write



2-3. Contents of each status register

RDY (Bit 0)

The RDY register is for detecting the write (program, erase and status register write) end. When it is "1", the device is in a busy state, and when it is "0", it means that write is completed.

WEN (bit 1)

The WEN register is for detecting whether the device can perform write operations. If it is set to "0", the device will not perform the write operation even if the write command is input. If it is set to "1", the device can perform write operations in any area that is not block-protected.

WEN can be controlled using the write enable and write disable commands. By inputting the write enable command (06h), WEN can be set to "1"; by inputting the write disable command (04h), it can be set to "0." In the following states, WEN is automatically set to "0" in order to protect against unintentional writing.

- At power-on
- Upon completion of small sector erase, sector erase or chip erase
- Upon completion of page program
- Upon completion of status register write
- * If a write operation has not been performed inside the LE25S20MB because, for instance, the command input for any of the write operations (small sector erase, sector erase, chip erase, page program, or status register write) has failed or a write operation has been performed for a protected address, WEN will retain the status established prior to the issue of the command concerned. Furthermore, its state will not be changed by a read operation.

 $\mathsf{DPU}, \mathsf{DPI}, \mathsf{DPZ}, \mathsf{ID}(\mathsf{DIIS}\,\mathsf{Z}, \mathsf{S}, \mathsf{4}, \mathsf{S})$

Block protect BP0, BP1, BP2 and TB are status register bits that can be rewritten, and the memory space to be protected can be set depending on these bits. For the setting conditions, refer to "Table 5 Protect level setting conditions".

BP0, BP1, and BP2 are used to select the protected area and TB to allocate the protected area to the higher-order address area or lower-order address area.

Table 5 Protect Level Setting Conditions

Potential	;	Status Register Bi	D. d. d. IA.	
Protect Level	ТВ	BP1	BP0	Protected Area
0 (Whole area unprotected)	X	0	0	None
T1 (Upper side 1/4 protected)	0	0	1	03FFFFh to 030000h
T2 (Upper side 1/2 protected)	0	1	0	03FFFFh to 020000h
B1 (Lower side 1/4 protected)	1	0	1	00FFFFh to 000000h
B2 (Lower side 1/2 protected)	1	1	0	01FFFFh to 000000h
3 (Whole area protected)	X	1	1	03FFFFh to 000000h

^{*} Chip erase is enabled only when the protect level is 0.

SRWP (bit 7)

Status register write protect SRWP is the bit for protecting the status registers, and its information can be rewritten. When SRWP is "1" and the logic level of the WP pin is low, the status register write command is ignored, and status registers BP0, BP1, BP2, TB and SRWP are protected. When the logic level of the WP pin is high, the status registers are not protected regardless of the SRWP state. The SRWP setting conditions are shown in "Table 6 SRWP setting conditions".

Table 6 SRWP Setting Conditions

WP Pin	SRWP	Status Register Protect State
0		Unprotected
0	1	Protected
4	0	Unprotected
1	1	Unprotected

Bit 6 are reserved bits, and have no significance.

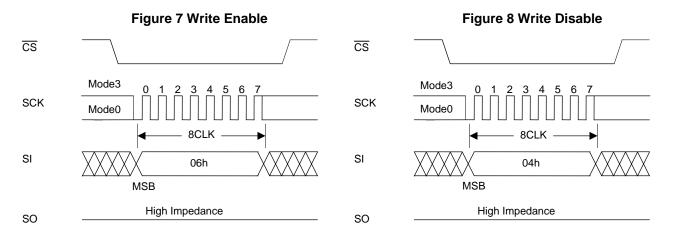
3. Write Enable

Before performing any of the operations listed below, the device must be placed in the write enable state. Operation is the same as for setting status register WEN to "1", and the state is enabled by inputting the write enable command. "Figure 7 Write Enable" shows the timing waveforms when the write enable operation is performed. The write enable command consists only of the first bus cycle, and it is initiated by inputting (06h).

- Small sector erase, sector erase, chip erase
- Page program
- Status register write

4. WITHE DISABLE

The write disable command sets status register WEN to "0" to prohibit unintentional writing. "Figure 8 Write Disable" shows the timing waveforms. The write disable command consists only of the first bus cycle, and it is initiated by inputting (04h). The write disable state (WEN "0") is exited by setting WEN to "1" using the write enable command (06h).

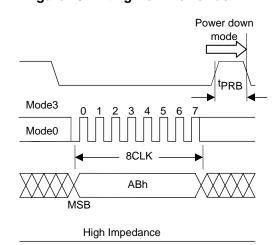


5. Power-down

The power-down command sets all the commands, with the exception of the silicon ID read command and the command to exit from power-down, to the acceptance prohibited state (power-down). "Figure 9 Power-down" shows the timing waveforms. The power-down command consists only of the first bus cycle, and it is initiated by inputting (B9h). However, a power-down command issued during an internal write operation will be ignored. The power-down state is exited using the power-down exit command (power-down is exited also when one bus cycle or more of the silicon ID read command (ABh) has been input). "Figure 10 Exiting from Power-down" shows the timing waveforms of the power-down exit command.

Figure 9 Power-down

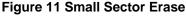
Figure 10 Exiting from Power-down

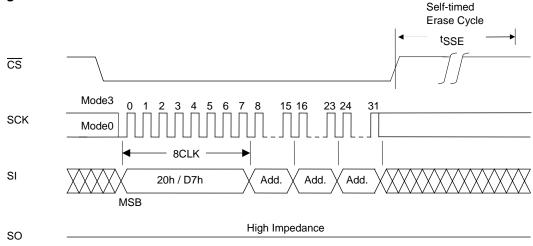


o. Siliali Sector Erasi

Small sector erase is an operation that sets the memory cell data in any small sector to "1". A small sector consists of

4Kbytes. "Figure 11 Small Sector Erase" shows the timing waveforms, and Figure 20 shows a small sector erase flowchart. The small sector erase command consists of the first through fourth bus cycles, and it is initiated by inputting the 24-bit addresses following (20h) or (D7h). Addresses A17 to A12 are valid, and Addresses A23 to A18 are "don't care". After the command has been input, the internal erase operation starts from the rising $\overline{\text{CS}}$ edge, and it ends automatically by the control exercised by the internal timer. Erase end can also be detected using status register $\overline{\text{RDY}}$.

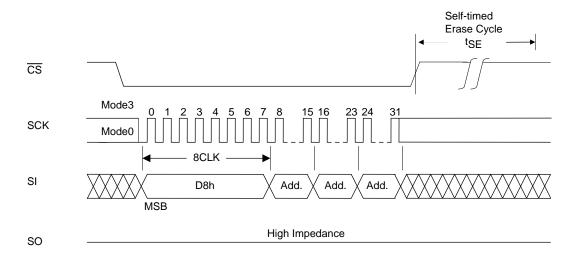




7. Sector Erase

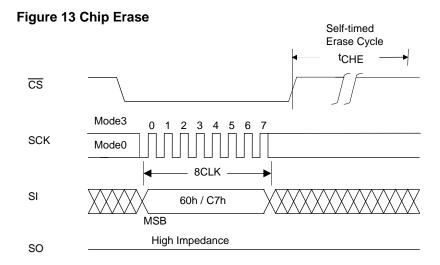
Sector erase is an operation that sets the memory cell data in any sector to "1". A sector consists of 64Kbytes. "Figure 12 Sector Erase" shows the timing waveforms, and Figure 20 shows a sector erase flowchart. The sector erase command consists of the first through fourth bus cycles, and it is initiated by inputting the 24-bit addresses following (D8h). Addresses A17 to A16 are valid, and Addresses A23 to A18 are "don't care". After the command has been input, the internal erase operation starts from the rising \overline{CS} edge, and it ends automatically by the control exercised by the internal timer. Erase end can also be detected using status register \overline{RDY} .

Figure 12 Sector Erase



o. Chip Erasi

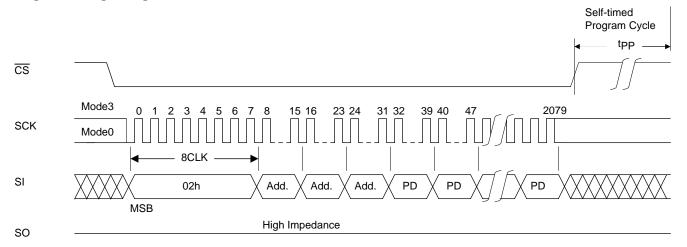
Chip erase is an operation that sets the memory cell data in all the sectors to "1". "Figure 13 Chip Erase" shows the timing waveforms, and Figure 20 shows a chip erase flowchart. The chip erase command consists only of the first bus cycle, and it is initiated by inputting (60h) or (C7h). After the command has been input, the internal erase operation starts from the rising \overline{CS} edge, and it ends automatically by the control exercised by the internal timer. Erase end can also be detected using status register \overline{RDY} .



9. Page Program

Page program is an operation that programs any number of bytes from 1 to 256 bytes within the same sector page (page addresses: A17 to A8). Before initiating page program, the data on the page concerned must be erased using small sector erase, sector erase, or chip erase. "Figure 14 Page Program" shows the page program timing waveforms, and Figure 21 shows a page program flowchart. After the falling \overline{CS} , edge, the command (02H) is input followed by the 24-bit addresses. Addresses A17 to A0 are valid. The program data is then loaded at each rising clock edge until the rising \overline{CS} edge, and data loading is continued until the rising \overline{CS} edge. If the data loaded has exceeded 256 bytes, the 256 bytes loaded last are programmed. The program data must be loaded in 1-byte increments, and the program operation is not performed at the rising \overline{CS} edge occurring at any other timing.

Figure 14 Page Program



10. Silicon id Read

ID read is an operation that reads the manufacturer code and device ID information. The silicon ID read command is not accepted during writing. There are two methods of reading the silicon ID, each of which is assigned a device ID. In the first method, the read command sequence consists only of the first bus cycle in which (9Fh) is input. In the subsequent bus cycles, the manufacturer code 62h which is assigned by JEDEC, 2-byte device ID code (memory type, memory capacity), and reserved code are output sequentially. The 4-byte code is output repeatedly as long as clock inputs are present, "Table 7-1 JEDEC ID code " lists the silicon ID codes and "Figure 15-a JEDEC ID read" shows the JEDEC ID read timing waveforms.

The second method involves inputting the ID read command. This command consists of the first through fourth bus cycles, and the one bite silicon ID can be read when 24 dummy bits are input after (ABh). "Table 7-2 ID code " lists the silicon ID codes and "Figure 15-b ID read" shows the ID read timing waveforms.

If the SCK input persists after a device code is read, that device code continues to be output. The data output is transmitted starting at the falling edge of the clock for bit 0 in the fourth bus cycle and the silicon ID read sequence is finished by setting \overline{CS} high.

Table 7-1 JEDEC ID code

	Output code	
Manufacturer code		62h
	Memory type	16h
2 byte device ID	Memory capacity code	12h(2M Bit)
Device code	1	00h

Table 7-2 ID code

	Output Code
1 byte device ID	34
1 byte device ib	(LE25S20MB)

Figure 15-a JEDEC ID Read

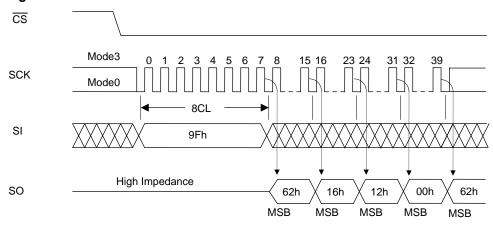
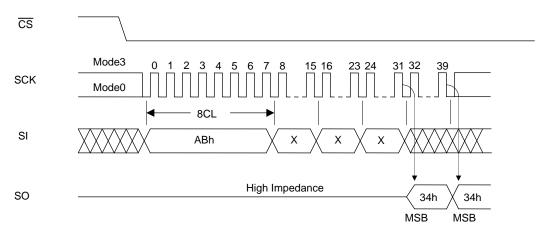


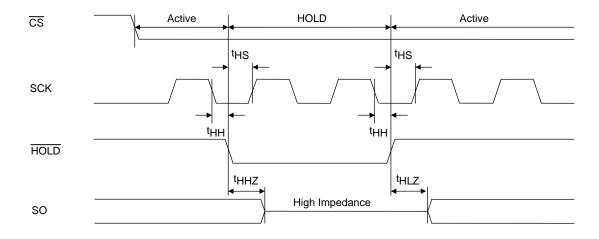
Figure 15-b ID Read



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Using the HOLD pin, the hold function suspends serial communication (it places it in the hold status). "Figure16 HOLD" shows the timing waveforms. The device is placed in the hold status at the falling HOLD edge while the logic level of SCK is low, and it exits from the hold status at the rising HOLD edge. When the logic level of SCK is high, HOLD must not rise or fall. The hold function takes effect when the logic level of CS is low, the hold status is exited and serial communication is reset at the rising CS edge. In the hold status, the SO output is in the high-impedance state, and SI and SCK are "don't care".

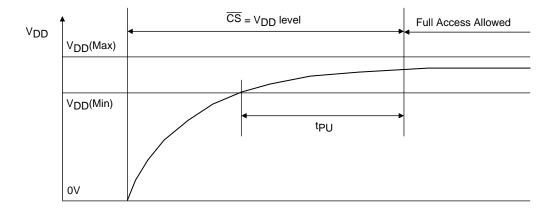
Figure 16 HOLD



12. Power-on

In order to protect against unintentional writing, $\overline{\text{CS}}$ must be within at V_{DD} -0.3 to V_{DD} +0.3 on power-on. After power-on, the supply voltage has stabilized at VDD min. or higher, waits for tpU before inputting the command to start a device operation. The device is in the standby state and not in the power-down state after power is turned on. To put the device into the power-down state, it is necessary to enter a power-down command.

Figure 17 Power-on Timing

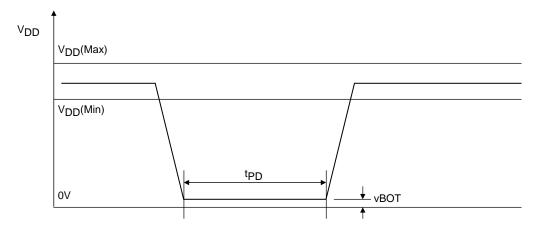


13. Haruware Data Protection

LE25S20MB incorporates a power-on reset function. The following conditions must be met in order to ensure that the power reset circuit will operate stably.

No guarantees are given for data in the event of an instantaneous power failure occurring during the writing period.

Figure 18 Power-down Timing



Power-on timing

Down water	O. made ad	spe			
Parameter	Symbol	min	max	unit	
power-on to operation time	t _{PU}	100		μs	
power-down time	t _{PD}	10		ms	
power-down voltage	^t BOT		0.2	V	

14. Software Data Protection

The LE25S20MB eliminates the possibility of unintentional operations by not recognizing commands under the following conditions.

- When a write command is input and the rising $\overline{\text{CS}}$ edge timing is not in a bus cycle (8 CLK units of SCK)
- When the page program data is not in 1-byte increments
- When the status register write command is input for 2 bus cycles or more

15. Decoupling Capacitor

A $0.1~\mu F$ ceramic capacitor must be provided to each device and connected between V_{DD} and V_{SS} in order to ensure that the device will operate stably.

Specifications

Absolute Maximum Ratings

Parameter	Symbol	Conditions	Ratings	unit
Maximum supply voltage	V _{DD} max	With respect to V _{SS}	-0.5 to +2.4	V
DC voltage (all pins)	VIN/VOUT	With respect to V _{SS}	−0.5 to V _{DD} +0.5	V
Storage temperature	Tstg		−55 to +150	°C

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

Operating Conditions

Parameter	Symbol	Conditions	Ratings	unit
Operating supply voltage	V_{DD}		1.65 to 1.95	V
Operating ambient temperature	Topr		-40 to +85	°C

Allowable DC Operating Conditions

B	0 1 1	0 - 171				
Parameter	Symbol	Conditions	min	typ	max	unit
Read mode operating current	ICCR	$SCK = 0.1V_{DD} / 0.9V_{DD},$ $\overline{HOLD} = \overline{WP} = 0.9V_{DD},$ $SO = open, 25 \text{ MHz}$			6	mA
		$SCK = 0.1V_{DD} / 0.9V_{DD},$ $\overline{HOLD} = \overline{WP} = 0.9V_{DD},$ $SO = open, 40 \text{ MHz}$			8	mA
Write mode operating current (erase+page program)	Iccw	$t_{SSE} = t_{SE} = t_{CHE} = t_{YP.}, t_{PP} = max$			15	mA
CMOS standby current	I _{SB}	$\overline{\text{CS}} = \text{V}_{\text{DD}}, \overline{\text{HOLD}} = \overline{\text{WP}} = \text{V}_{\text{DD}},$ $\text{SI} = \text{V}_{\text{SS}} / \text{V}_{\text{DD}}, \text{SO} = \text{open}$			50	μА
Power-down standby current	I _{DSB}	$\overline{\text{CS}} = \text{V}_{\text{DD}}, \overline{\text{HOLD}} = \overline{\text{WP}} = \text{V}_{\text{DD}},$ $\text{SI} = \text{V}_{\text{SS}} / \text{V}_{\text{DD}}, \text{SO} = \text{open}$			10	μА
Input leakage current	ILI				2	μА
Output leakage current	I _{LO}				2	μА
Input low voltage	V _{IL}		-0.3		0.3V _{DD}	V
Input high voltage	VIH		0.7V _{DD}		V _{DD} +0.3	V
Output low voltage	V _{OL}	I_{OL} = 100 μ A, V_{DD} = V_{DD} min			0.2	.,
		$I_{OL} = 1.6 \text{ mA}, V_{DD} = V_{DD} \text{ min}$			0.4	V
Output high voltage	VOH	$I_{OH} = -100 \mu A$, $V_{DD} = V_{DD} min$	V _{CC} -0.2			V

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

Data hold, Rewriting frequency

Parameter	condition	min	max	unit
Rewriting frequency	Program / Erase	100,000		times/
	Status resister write	1,000		Sector
Data hold		20		year

Pin Capacitance at Ta=25°C, f=1MHz

Parameter	Coursely al	Conditions	Ratings		
	Symbol		max	unit	
Output pin capacitance	c _{so}	V _{SO} = 0 V	12	pF	
Input pin Capacitance	C _{IN}	V _{IN} = 0 V	6	pF	

Note: These parameter values do not represent the results of measurements undertaken for all devices but rather values for some of the sampled devices.

AC Characteristics

Parameter		Symbol	Ratings				
			min	typ	max	unit	
Clock frequency	Read instruc	Read instruction (03h) All instructions except for read (03h)				25	MHz
	All instruction					40	MHz
Input signal rising/falling time		t _{RF}	0.1			V/ns	
SCK logic high level pulse width 25 MHz		25 MHz	^t CLHI	14			ne
		40 MHz		11.5			ns
SCK logic low level pulse width		25 MHz	tcllo	14			ns
		40 MHz		11.5			
CS setup time		tcss	10			ns	
CS hold time		tCSH	10			ns	
Data setup time		t _{DS}	5			ns	
Data hold time		^t DH	5			ns	
CS wait pulse width		tCPH	25			ns	
Output high impedance time from $\overline{\text{CS}}$		^t CHZ			15	ns	
Output data time from SCK		t _V		8	11	ns	
Output data hold time		tHO	1			ns	
Output low impedance time from SCK		^t CLZ	0			ns	
WP setup time		t _{WPS}	20			ns	
WP hold time		tWPH	20			ns	
HOLD setup time		tHS	5			ns	
HOLD hold time		tHH	5			ns	
Output low impedance time from HOLD		^t HLZ			12	ns	
Output high impedance time from HOLD		tHHZ			9	ns	
Power-down time		t _{DP}			5	μS	
Power-down recovery time		t _{PRB}			5	μS	
Write status register time		^t SRW		8	10	ms	
Page programming cycle time		256 Byte			3	3.5	ms
	ycle time	n Byte	tpp		0.15+ n*2.85/256	0.20+ n*3.30/256	ms
Small sector erase cycle time		tSSE		0.04	0.15	s	
Sector erase cycle time		tSE		0.08	0.25	s	
Chip erase cycle time		tCHE		0.3	3.0	S	

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

AC Test Conditions

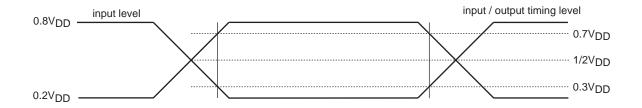
Input pulse level······ $0.2V_{DD}$ to $0.8V_{DD}$

Input rising/falling time · · · · 5 ns

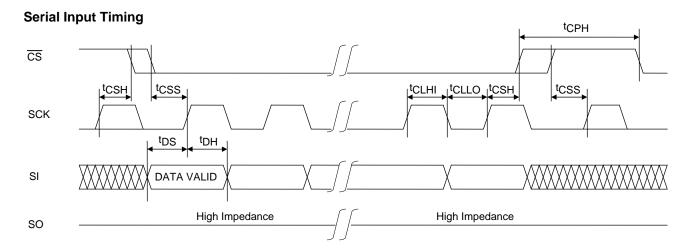
Input timing level · · · · · · · 0.3V_{DD}, 0.7V_{DD}

Output timing level $\cdots 1/2 \times V_{DD}$ Output load ······ 15 pF

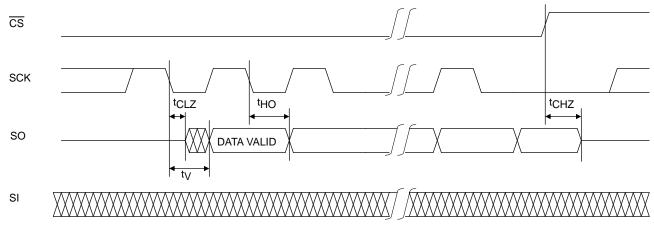
Note : As the test conditions for "typ", the measurements are conducted using 1.8 V for V_{DD} at room temperature.



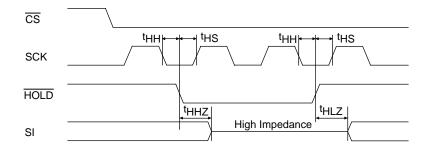
Timing waveforms



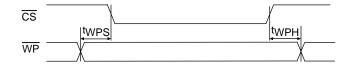
Serial Output Timing



Hold Timing

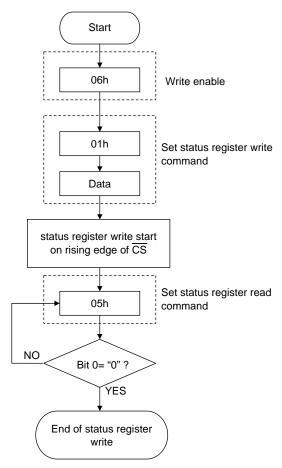


Status resistor write Timing



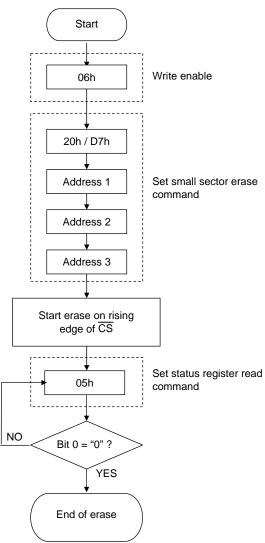
rigure 19 Status Register Write Flowchart

Status register write



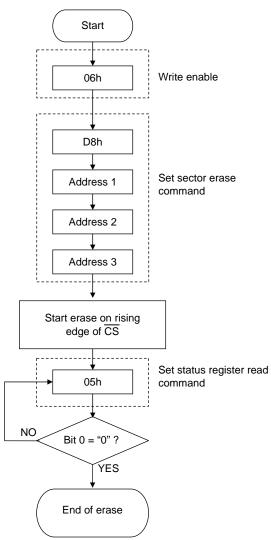
* Automatically placed in write disabled state at the end of the status register write

Small sector erase



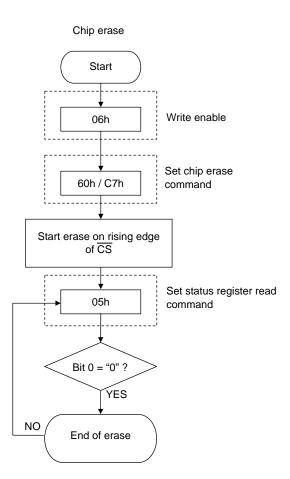
* Automatically placed in write disabled state at the end of the erase

Sector erase

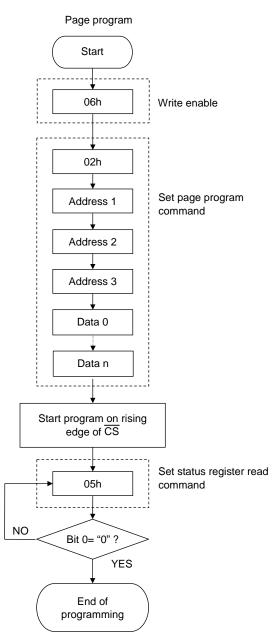


* Automatically placed in write disabled state at the end of the erase

rigure 21 rage riogram riowchart



* Automatically placed in write disabled state at the end of the erase



* Automatically placed in write disabled state at the end of the programming operation.

ONDERING IN ONMATION

Device	Package	Shipping (Qty / Packing)
LE25S20MB-AH	SOIC-8 / SOP8K (200 mil) (Pb-Free / Halogen Free)	2000 / Tape & Reel

[†] For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D. http://www.onsemi.com/pub_link/Collateral/BRD8011-D.PDF

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