

**TSOT26 LIGHT LOAD IMPROVED 1.5A SYNCH DC/DC BUCK CONVERTER**

**Description**

The AP65111A is a 500kHz switching frequency internal compensated synchronous DC/DC buck converter. It has integrated low  $R_{DS(ON)}$  high and low side MOSFETs.

The AP65111A enables continuous load current of up to 1.5A with efficiency as high as 97%.

The AP65111A implements an automatic custom light load efficiency improvement algorithm.

The AP65111A features current mode control operation, which enables fast transient response time and easy loop stabilization.

The AP65111A simplifies board layout and reduces space requirements with its high level of integration and minimal need for external components, making it ideal for distributed power architectures.

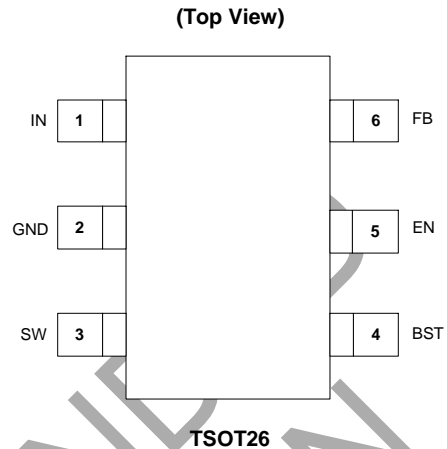
The AP65111A is available in a standard Green TSOT26 package and is RoHS compliant.

**Features**

- $V_{IN}$  4.5V to 18V
- 1.5A Continuous Output Current
- Efficiency Up to 97%
- Automated Light Load Improvement
- $V_{OUT}$  Adjustable from 0.8V
- 500kHz Switching Frequency
- Internal Soft-Start
- Enable Pin
- Overvoltage Protection & Undervoltage Protection
- Overcurrent Protection (OCP) with Hiccup
- Thermal Protection
- **Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)**
- **Halogen and Antimony Free. "Green" Device (Note 3)**

- Notes:
1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS) & 2011/65/EU (RoHS 2) compliant.
  2. See [http://www.diodes.com/quality/lead\\_free.html](http://www.diodes.com/quality/lead_free.html) for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
  3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.

**Pin Assignments**



**Applications**

- Gaming Consoles
- Flat Screen TV Sets and Monitors
- Set-Top Boxes
- Distributed Power Systems
- Home Audio
- Consumer Electronics
- Network Systems
- FPGA, DSP and ASIC Supplies
- Green Electronics

**Typical Applications Circuit**

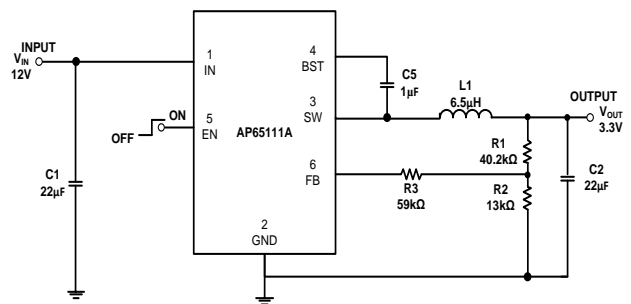
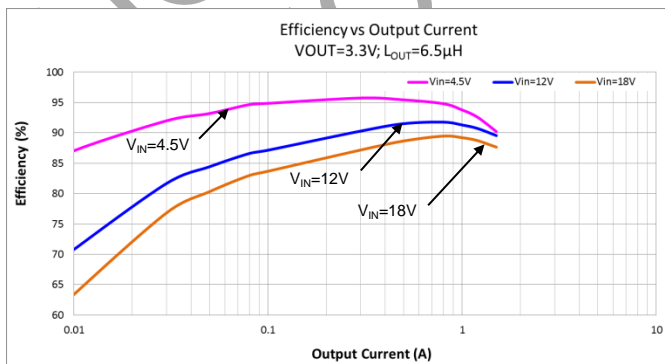


Figure 1. Typical Application Circuit

**Pin Descriptions**

Pin Number	Pin Name	Function
1	IN	Power Input. IN supplies the power to the IC, as well as the step-down converter switches. Drive IN with a 4.5V to 18V power source. Bypass IN to GND with a suitably large capacitor to eliminate noise on the input to the IC. See Input Capacitor.
2	GND	Ground
3	SW	Power Switching Output. SW is the switching node that supplies power to the output. Connect the output LC filter from SW to the output load. Note that a capacitor is required from SW to BST to power the high-side switch.
4	BST	High-Side Gate Drive Boost Input. BST supplies the drive for the high-side N-Channel MOSFET a 0.01μF or greater capacitor from SW to BST to power the high side switch.
5	EN	Enable Input. EN is a digital input that turns the regulator on or off. Drive EN high to turn on the regulator; low to turn it off. Attach to IN with a 100kΩ pull up resistor for automatic startup.
6	FB	Feedback Input. FB senses the output voltage and regulates it. Drive FB with a resistive voltage divider connected to it from the output voltage. The feedback threshold is 0.8V. See Setting the Output Voltage.

**Functional Block Diagram**

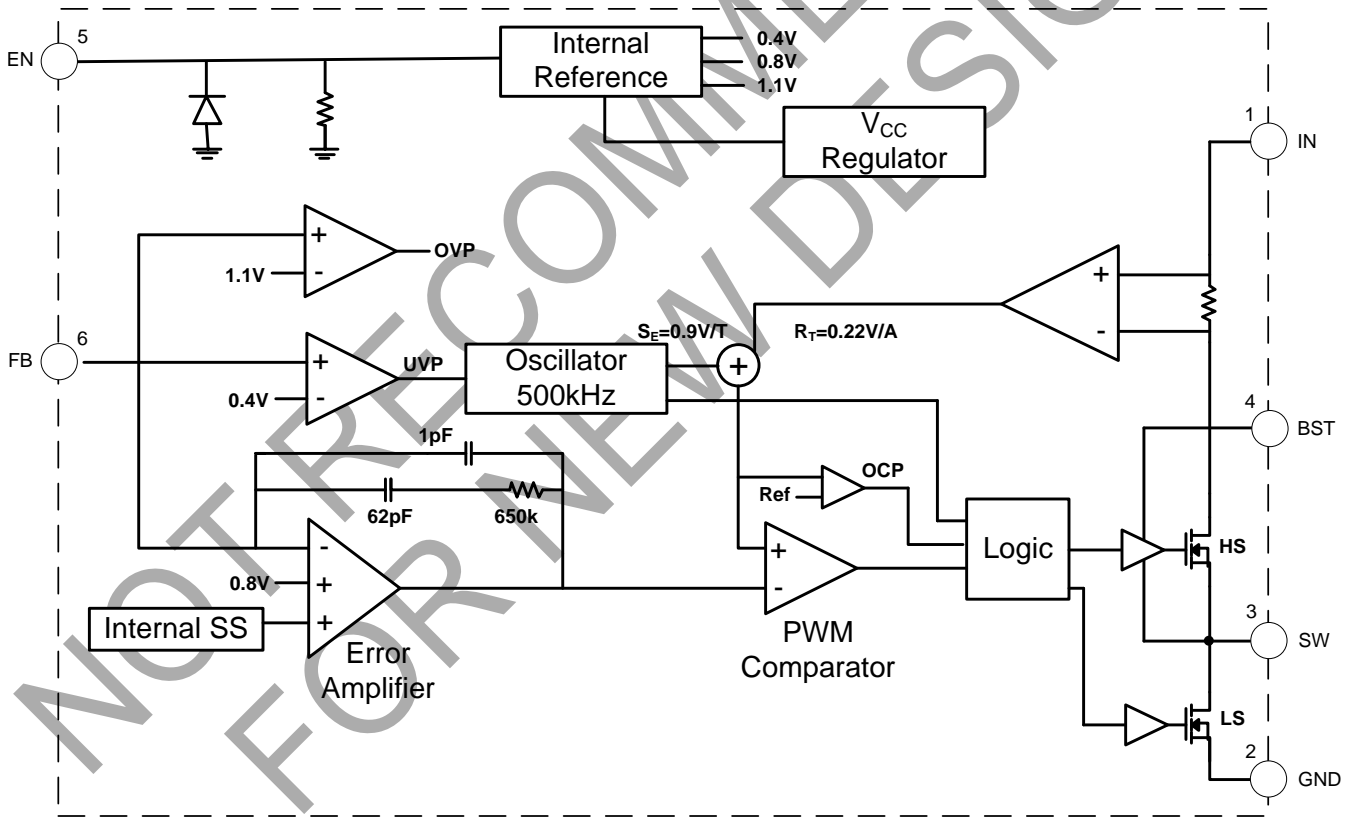


Figure 2. Functional Block Diagram

### Absolute Maximum Ratings (@T<sub>A</sub> = +25°C, unless otherwise specified.) (Note 4)

Symbol	Parameter	Rating	Unit
V <sub>IN</sub>	Supply Voltage	-0.3 to 20	V
V <sub>SW</sub>	Switch Node Voltage	-1.0 to V <sub>IN</sub> +0.3	V
V <sub>BST</sub>	Bootstrap Voltage	V <sub>SW</sub> -0.3 to V <sub>SW</sub> +6.0	V
V <sub>FB</sub>	Feedback Voltage	-0.3V to +6.0	V
V <sub>EN</sub>	Enable/UVLO Voltage	-0.3V to +6.0	V
T <sub>ST</sub>	Storage Temperature	-65 to +150	°C
T <sub>J</sub>	Junction Temperature	+160	°C
T <sub>L</sub>	Lead Temperature	+260	°C
<b>ESD Susceptibility (Note 5)</b>			
HBM	Human Body Model	2	kV
CDM	Charged Device Model	1	kV

- Notes:
- Stresses greater than the 'Absolute Maximum Ratings' specified above may cause permanent damage to the device. These are stress ratings only; functional operation of the device at these or any other conditions exceeding those indicated in this specification is not implied. Device reliability may be affected by exposure to absolute maximum rating conditions for extended periods of time.
  - Semiconductor devices are ESD sensitive and may be damaged by exposure to ESD events. Suitable ESD precautions should be taken when handling and transporting these devices.

### Thermal Resistance (Note 6)

Symbol	Parameter	Rating		Unit
θ <sub>JA</sub>	Junction to Ambient	TSOT26	120	°C/W
θ <sub>JC</sub>	Junction to Case	TSOT26	30	°C/W

- Note: 6. Test condition for TSOT26: Device mounted on FR-4 substrate, single-layer PC board, 2oz copper, with minimum recommended pad layout.

### Recommended Operating Conditions (@T<sub>A</sub> = +25°C, unless otherwise specified.) (Note 7)

Symbol	Parameter	Min	Max	Unit
V <sub>IN</sub>	Supply Voltage	4.5	18	V
T <sub>A</sub>	Operating Ambient Temperature Range	-40	+85	°C

- Note: 7. The device function is not guaranteed outside of the recommended operating conditions.

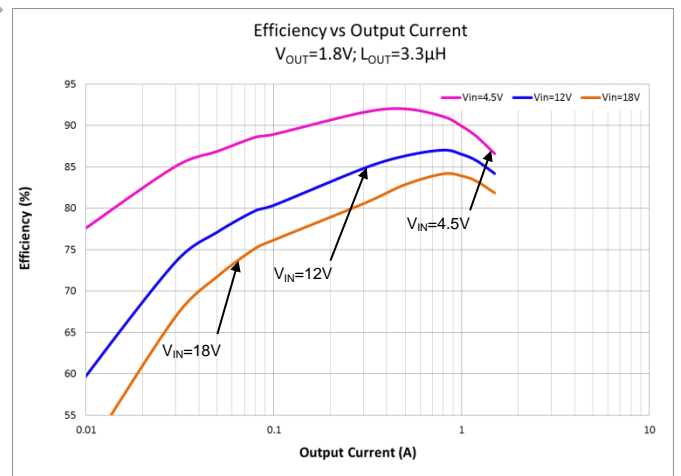
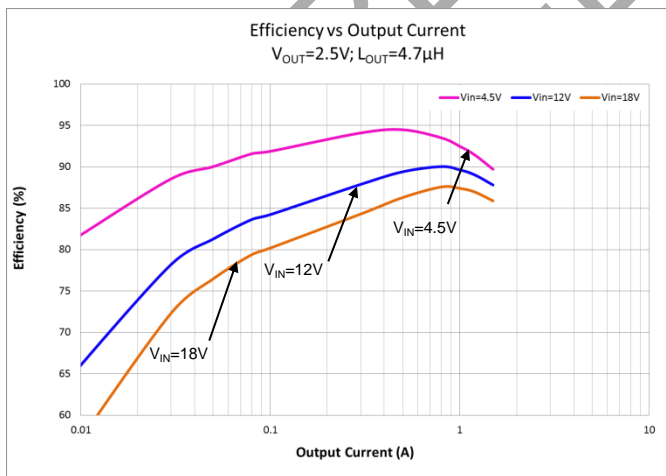
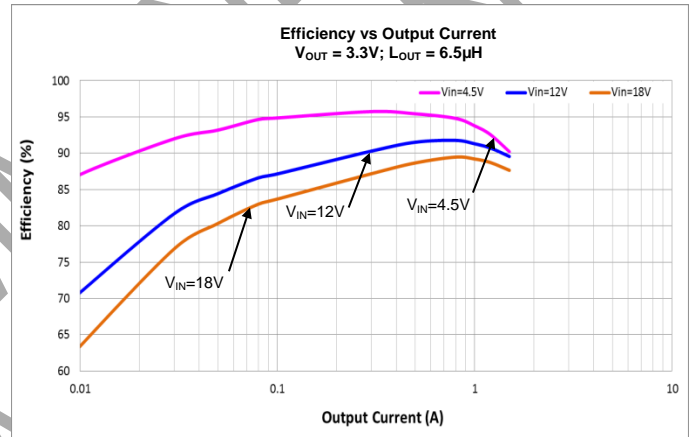
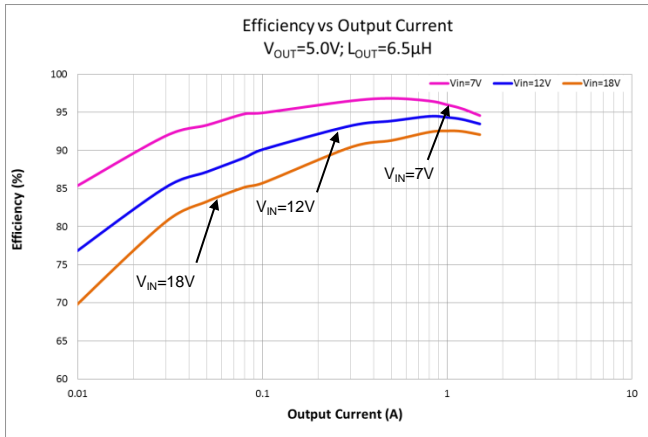
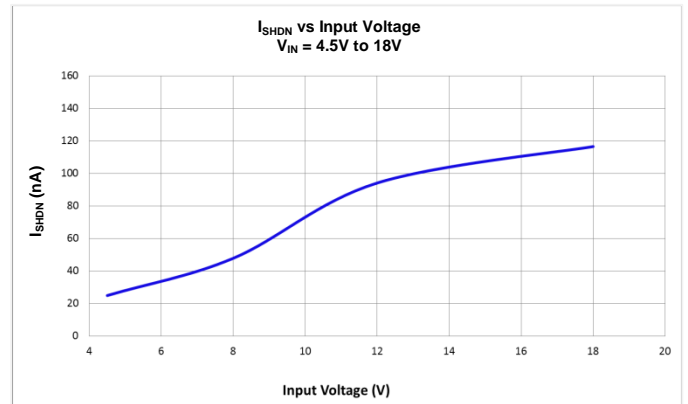
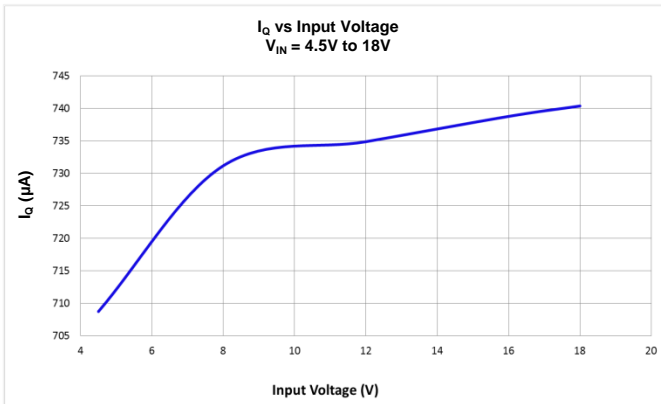
**Electrical Characteristics** (@ $T_A = +25^\circ\text{C}$ ,  $V_{IN} = 12\text{V}$ , unless otherwise specified.)

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
$I_{SHDN}$	Shutdown Supply Current	$V_{EN} = 0\text{V}$	—	—	1.0	$\mu\text{A}$
$I_Q$	Supply Current (Quiescent)	$V_{EN} = 2.0\text{V}$ , $V_{FB} = 0.85\text{V}$	—	0.725	—	$\text{mA}$
$R_{DS(ON)1}$	High-Side Switch On-Resistance (Note 8)	—	—	200	—	$\text{m}\Omega$
$R_{DS(ON)2}$	Low-Side Switch On-Resistance (Note 8)	—	—	120	—	$\text{m}\Omega$
$I_{LIMIT\_PEAK}$	HS Peak Current Limit (Note 8)	Minimum duty cycle, $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$	2.5	3.0	—	A
$I_{SW\_LKG}$	Switch Leakage Current	$V_{EN} = 0\text{V}$ , $V_{SW} = 12\text{V}$	—	—	1	$\mu\text{A}$
$f_{SW}$	Oscillator Frequency	$V_{FB} = 0.75\text{V}$	400	500	600	$\text{kHz}$
$D_{MAX}$	Maximum Duty Cycle	$V_{FB} = 700\text{mV}$	88	92	—	%
$t_{ON}$	Minimum On Time	—	—	90	—	ns
$V_{FB}$	Feedback Voltage (Note 8)	$T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$	776	800	824	mV
$V_{EN\_RISING}$	EN Rising Threshold	—	1.4	1.5	1.6	V
$V_{EN\_FALLING}$	EN Falling Threshold	—	1.23	1.32	1.41	V
$I_{EN}$	EN Input Current	$V_{EN} = 2\text{V}$	—	2.85	—	$\mu\text{A}$
		$V_{EN} = 0\text{V}$	—	0	—	$\mu\text{A}$
$INUV_{VTH}$	$V_{IN}$ Undervoltage Threshold Rising	—	3.7	4.05	4.4	V
$INUV_{HYS}$	$V_{IN}$ Undervoltage Threshold Hysteresis	—	—	250	—	mV
$t_{SS}$	Soft-Start Period	—	—	1	—	ms
$T_{SHDN}$	Thermal Shutdown (Note 8)	—	—	+160	—	$^\circ\text{C}$
$T_{HYS}$	Thermal Hysteresis (Note 8)	—	—	+20	—	$^\circ\text{C}$

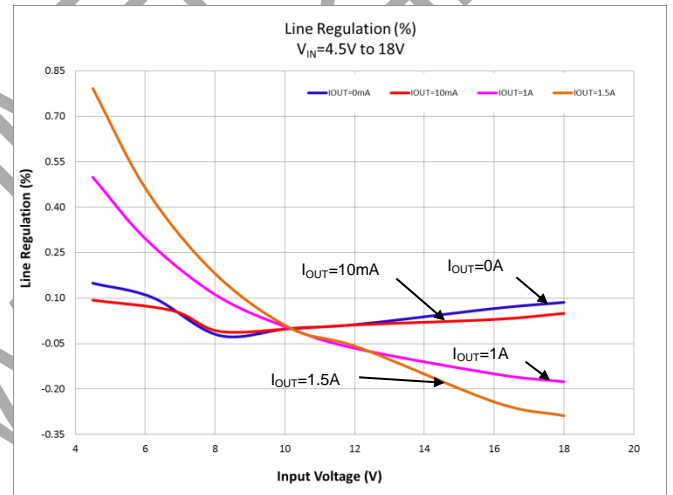
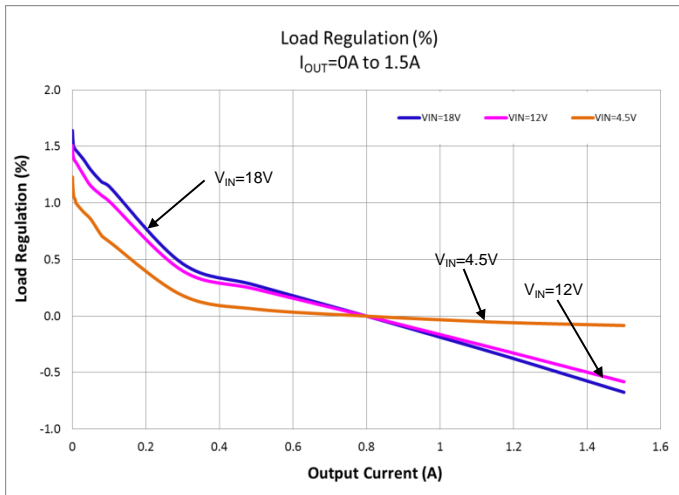
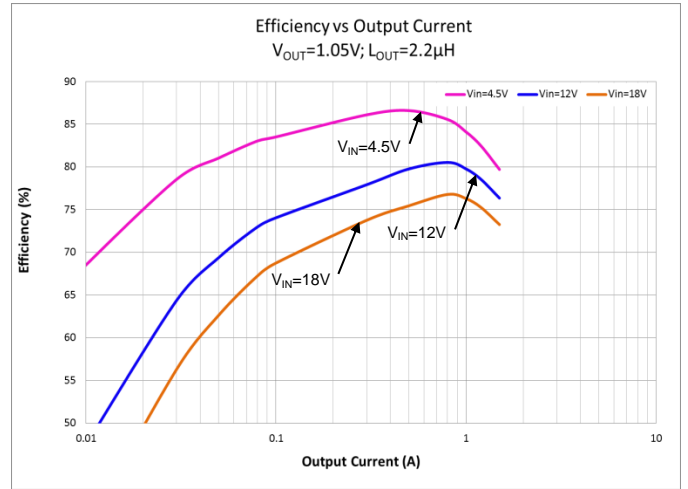
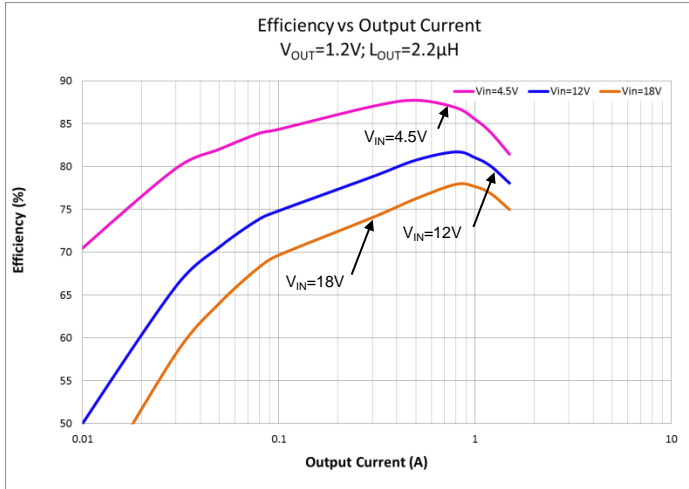
Note: 8. Compliance to the datasheet limits is assured by one or more methods: production test, characterization, and/or design.

NOT RECOMMENDED FOR NEW DESIGN

**Typical Performance Characteristics** (@ $T_A = +25^\circ\text{C}$ ,  $V_{IN} = 12\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ ,  $L = 6.5\mu\text{H}$ , unless otherwise specified.)

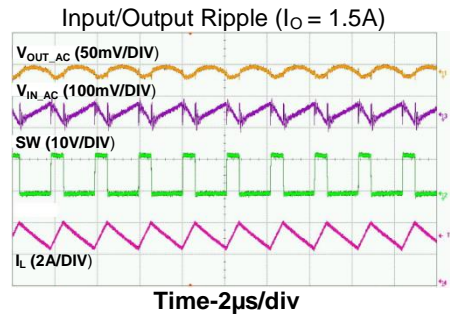
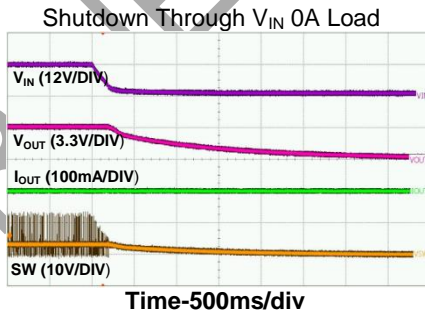
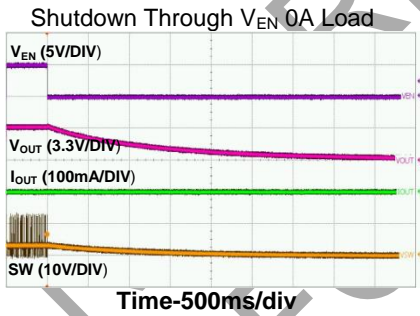
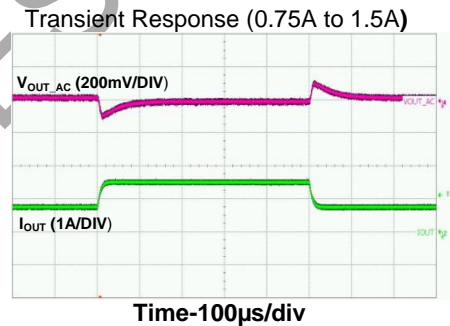
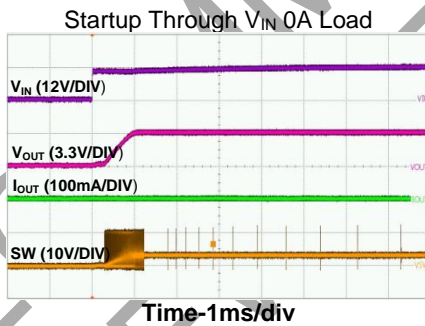
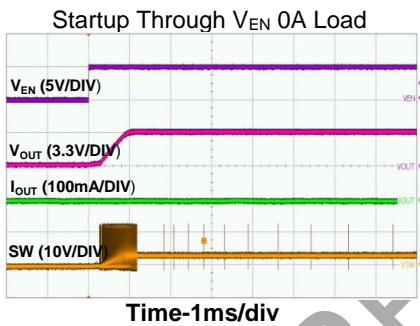
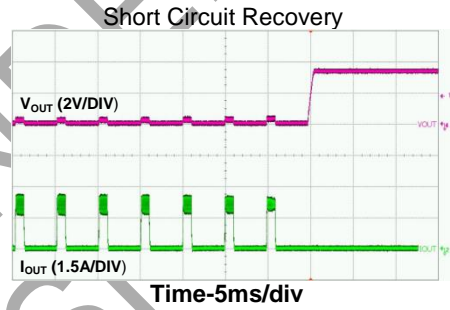
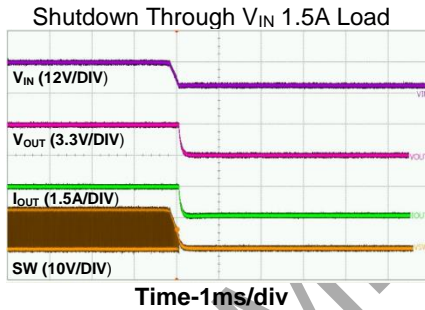
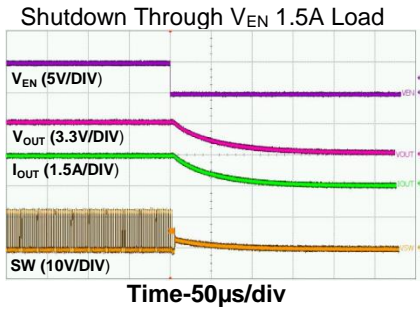
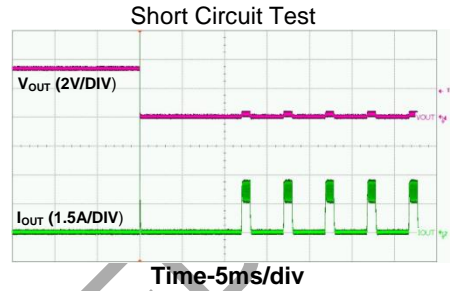
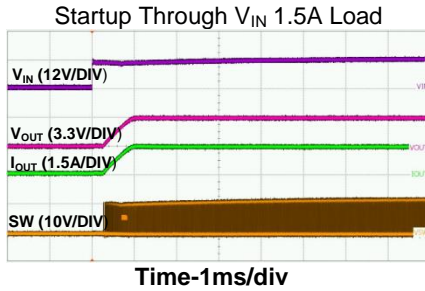
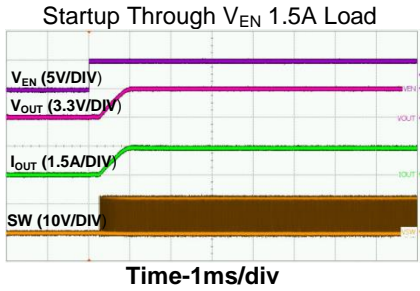


**Typical Performance Characteristics** (Cont.) (@ $T_A = +25^\circ\text{C}$ ,  $V_{IN} = 12\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ ,  $L = 6.5\mu\text{H}$ , unless otherwise specified.)



NOT FOR NEW

**Typical Performance Characteristics** (Cont.) (@ $T_A = +25^\circ\text{C}$ ,  $V_{IN} = 12\text{V}$ ,  $V_{OUT} = 3.3\text{V}$ ,  $L = 6.5\mu\text{H}$ ,  $C_1 = 22\mu\text{F}$ ,  $C_2 = 22\mu\text{F}$ , unless otherwise specified.)



## Application Information

### Theory of Operation

The AP65111A is a 1.5A current mode control, synchronous buck regulator with integrated power MOSFETs. Current mode control assures excellent line regulation, load regulation, and a wide loop bandwidth for fast response to load transients. Figure 2 depicts the functional block diagram of AP65111A.

The operation of one switching cycle can be explained as follows: The rising edge of the 500kHz oscillator clock signal sets the RS Flip-Flop. Its output turns on HS MOSFET. When the HS MOSFET is on, inductor current starts to increase. The current sense amplifier with a gain of 0.22V/A is used to detect the inductor current. Since the current mode control is subject to sub-harmonic oscillations that start at half duty cycle, ramp slope compensation of 0.9V/T is added to the current sense signal. When the sum of the current sense amplifier output and the slope compensation signal exceeds the EA output voltage, the RS Flip-Flop is reset and HS MOSFET is turned off.

Then synchronous LS MOSFET turns on until the next clock cycle begins. There is a “dead time” between the HS turn off and LS turn on that prevents the switches from “shooting through” across the input supply to ground.

If the sum of the current sense amplifier output and the slope compensation signal does not exceed the EA output, then the falling edge of the oscillator clock resets the Flip-Flop, and forces the HS MOSFET to turn off.

The voltage loop is compensated internally.

### Enable

The enable (EN) input allows the user to control turning on or off the regulator. The AP65111A has an internal pull down resistor on the EN pin and when the EN is not actively pulled up the part turns off.

### Quiescent Current

Above the 'EN Rising Threshold', the internal regulator is turned on and the quiescent current can be measured when  $V_{FB} > 0.8V$ .

### Automated No-Load and Light-Load Operation

The AP65111A operates in light load high efficiency mode during low load current operation. The advantage of this light load efficiency mode is lower power losses at no-load and light-load conditions. The AP65111A automatically detects the inductor's valley current and enters the light load high efficiency mode when value falls below zero Ampere. Once the inductor's valley current exceeds this zero Ampere, the AP65111A transitions from light load high efficiency mode to continuous PWM mode.

### Current Limit Protection

In order to reduce the total power dissipation and to protect the application, AP65111A has cycle-by-cycle current limiting implementation. The voltage drop across the internal high-side MOSFET is sensed and compared with the internally set current limit threshold. This voltage drop is sensed at about 30ns after the HS turns on. When the peak inductor current exceeds the set current limit threshold, current limit protection is activated. When the FB voltage pin dropped below 0.4V, the device enters Hiccup mode to periodically restart the part. This protection mode greatly reduces the power dissipated on chip and reduces the thermal stress to help protect the device. AP65111A will exit Hiccup mode when the over current situation is resolved.

### Undervoltage Lockout (UVLO)

Undervoltage Lockout is implemented to prevent the IC from insufficient input voltages. The AP65111A has a UVLO comparator that monitors the input voltage and the internal bandgap reference. If the input voltage falls below 4.05V, the AP65111A will disable. In this event, both HS and LS MOSFETs are turned off.

### Overvoltage Protection

When the AP65111A FB pin exceeds 115% of the nominal regulation voltage of 0.8V, the overvoltage comparator is tripped and internal regulator would stop switching. The  $V_{OUT}$  would stay high voltage as tripped point and slowly discharged by output capacitance.

### Thermal Shutdown

The AP65111A has on-chip thermal protection that prevents damage to the IC when the die temperature exceeds safe margins. It implements a thermal sensing to monitor the operating junction temperature of the IC. Once the die temperature rises to approximately +160°C, the thermal protection feature gets activated. The internal thermal sense circuitry turns the IC off thus preventing the power switch from damage. A hysteresis in the thermal sense circuit allows the device to cool down to approximately +120°C before the IC is enabled again through soft start. This thermal hysteresis feature prevents undesirable oscillations of the thermal protection circuit.



**Application Information (Cont.)**

**Setting the Output Voltage**

The output voltage can be adjusted from 0.8V using an external resistor divider. Table 1 shows a list of resistor selection for common output voltages. A serial resistor  $R_T$  is also recommended for improving the system stability, especially for low  $V_{OUT}$  (<3.3V). An optional CFF of 10pF to 100pF used to boost the phase margin. Resistor R1 is selected based on a design tradeoff between efficiency and output voltage accuracy. For high values of R1 there is less current consumption in the feedback network. R1 can be determined by the following equation:

$$R_1 = R_2 \cdot \left( \frac{V_{OUT}}{0.8} - 1 \right)$$

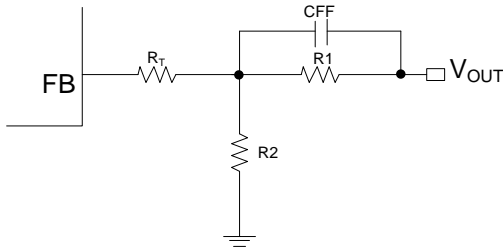


Figure 3. Feedback Divider Network

$V_{OUT}$ (V)	R1 (k $\Omega$ )	R2 (k $\Omega$ )	$R_T$ (k $\Omega$ )	L1 ( $\mu$ H)
1.05	10	32.4	150	2.2
1.2	15	30.1	130	2.2
1.8	40.2	32.4	100	3.3
2.5	40.2	19.1	59	4.7
3.3	40.2	13	59	6.5
5	40.2	7.68	59	6.5

Table 1. Recommended Component Selection

**Inductor**

Calculating the inductor value is a critical factor in designing a buck converter. For most designs, the following equation can be used to calculate the inductor value;

$$L = \frac{V_{OUT} \cdot (V_{IN} - V_{OUT})}{V_{IN} \cdot \Delta I_L \cdot f_{SW}}$$

Where  $\Delta I_L$  is the inductor ripple current and  $f_{SW}$  is the buck converter switching frequency.

Choose the inductor ripple current to be 30% to 40% of the maximum load current. The maximum inductor peak current is calculated from:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Peak current determines the required saturation current rating, which influences the size of the inductor. Saturating the inductor decreases the converter efficiency while increasing the temperatures of the inductor and the internal MOSFETs. Hence, choose an inductor with appropriate saturation current rating is important.

A 1 $\mu$ H to 10 $\mu$ H inductor with a DC current rating of at least 25% higher than the maximum load current is recommended for most applications.

For highest efficiency, the inductor's DC resistance should be less than 20m $\Omega$ . Use a larger inductance for improved efficiency under light load conditions.

**Input Capacitor**

The input capacitor reduces the surge current drawn from the input supply and the switching noise from the device. The input capacitor has to sustain the ripple current produced during the on time on the upper MOSFET. It must hence have a low ESR to minimize the losses.

The RMS current rating of the input capacitor is a critical parameter that must be higher than the RMS input current. As a rule of thumb, select an input capacitor which has RMS rating that is greater than half of the maximum load current.

Due to large  $dI/dt$  through the input capacitors, low  $R_{ESR}$  electrolytic or ceramics should be used. If a tantalum must be used, it must be surge protected. Otherwise, capacitor failure could occur. For most applications, a 22 $\mu$ F ceramic capacitor is sufficient.

**Output Capacitor**

The output capacitor keeps the output voltage ripple small, ensures feedback loop stability and reduces the overshoot of the output voltage. The output capacitor is a basic component for the fast response of the power supply. During load transient, the output capacitor supplies the current to the load for the first few cycles. This caused the output voltage to drop and sets the duty cycle to maximum, but the current slope is limited by the inductor value.

**Application Information** (Cont.)

Maximum capacitance required can be calculated from the following equation:

ESR of the output capacitor dominates the output voltage ripple. The amount of ripple can be calculated from the equation below:

$$V_{out\_capacitor} = \Delta I_{inductor} * ESR$$

An output capacitor with high capacitance and low ESR is the best option. For most applications, a 22µF ceramic capacitor will be sufficient.

$$C_o = \frac{L(I_{out} + \frac{\Delta I_{inductor}}{2})^2}{(\Delta V + V_{out})^2 - V_{out}^2}$$

Where ΔV is the maximum output voltage overshoot.

**PC Board Layout**

The layout is very important in high frequency switching converter design. With power devices switching efficiently at 500kHz, the resulting current transitions from one device to another cause voltage spikes across the interconnecting impedances and parasitic circuit elements. These voltage spikes can degrade efficiency, radiate noise into the circuit, and lead to device overvoltage stress. Careful component layout and printed circuit board design minimizes these voltage spikes. As an example, consider the turn-off transition of the HS MOSFET. Prior to turn-off, the HS MOSFET is carrying the full load current. During turn-off, current stops flowing in the HS MOSFET and is picked up by the internal body diode. Any parasitic inductance in the switched current path generates a large voltage spike during the switching interval. Careful component selection, tight layout of the critical components and short, wide traces minimize the magnitude of voltage spikes. There are two sets of critical components in the regulator switching converter. The switching components are the most critical because they switch large amounts of energy and therefore tend to generate large amounts of noise. Next are the small signal components, which connect to sensitive nodes for controlling the regulator.

The switching components should be placed close to the regulator first. Minimize the length of the connections between the input capacitors and the power switches by placing them nearby. Position both the ceramic and bulk input capacitors as close to the upper MOSFET drain as possible. The critical small signal components include feedback components and BST capacitor. Place the compensation components close to the FB pin. The feedback resistors should be located as close as possible to the FB pin with vias tied straight to the ground plane. See Figure 4 for reference.

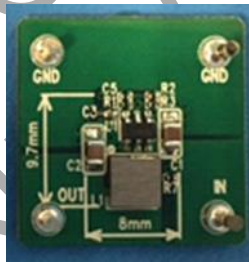


Figure 4. PC Board Layout

**External Bootstrap Diode**

It is recommended that an external bootstrap diode be added when the input voltage is no greater than 5V or the 5V rail is available in the system. This helps to improve the efficiency of the regulator. This solution is also applicable for D > 65%. The bootstrap diode can be a low cost device such as B130 or a Schottky diode that has a low V<sub>F</sub>. See below for Diodes Incorporated’s recommended diodes.

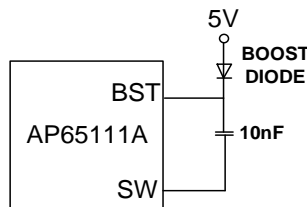
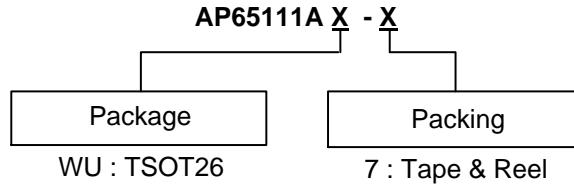


Figure 5. External Bootstrap Compensation Components

**Recommended Diodes:**

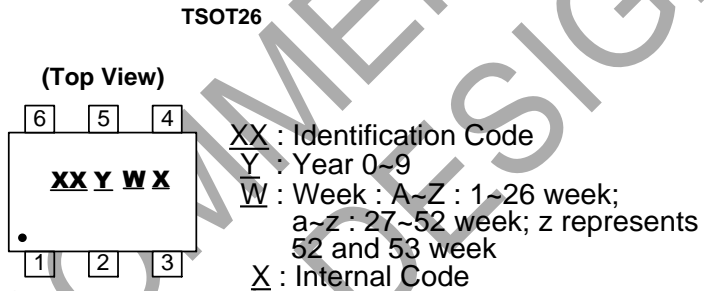
Part Number	Voltage/Current Rating
B130	30V, 1A
SK13	30V, 1A

**Ordering Information**



Part Number	Package Code	Package	Identification Code	Tape and Reel	
				Quantity	Part Number Suffix
AP65111AWU-7	WU	TSOT26	R3	3,000	-7

**Marking Information**

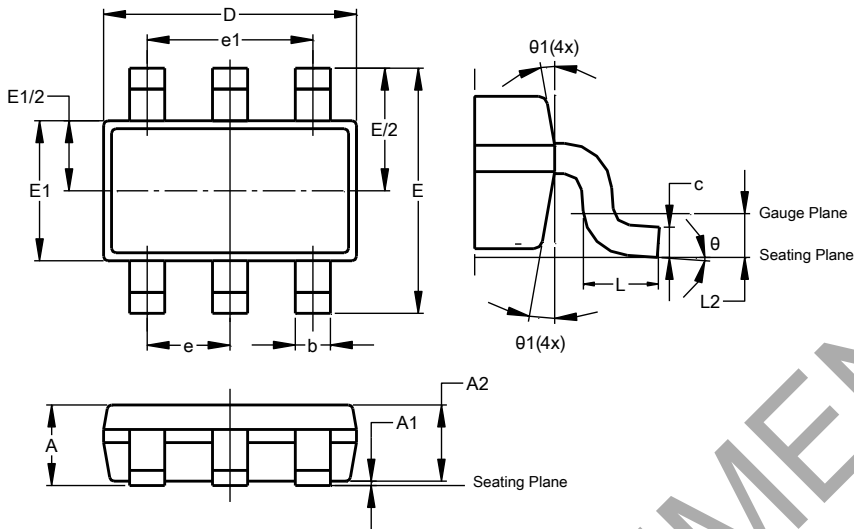


Part Number	Package	Identification Code
AP65111AWU-7	TSOT26	R3

**Package Outline Dimensions**

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

**TSOT26**

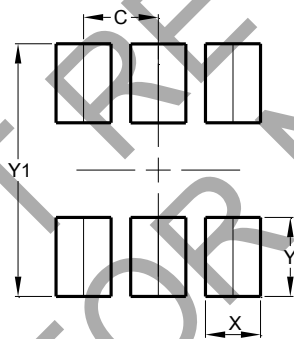


TSOT26			
Dim	Min	Max	Typ
A	-	1.00	-
A1	0.010	0.100	-
A2	0.840	0.900	-
D	2.800	3.000	2.900
E	2.800 BSC		
E1	1.500	1.700	1.600
b	0.300	0.450	-
c	0.120	0.200	-
e	0.950 BSC		
e1	1.900 BSC		
L	0.30	0.50	-
L2	0.250 BSC		
$\theta$	0°	8°	4°
$\theta 1$	4°	12°	-
All Dimensions in mm			

**Suggested Pad Layout**

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**TSOT26**



Dimensions	Value (in mm)
C	0.950
X	0.700
Y	1.000
Y1	3.199

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