



PI4ULS5V102

2-Bit Universal Bi-directional Level Shifter with Automatic Direction Control & Advance Package Solution

Features

- 1.2V to 3.6V on A Port and 1.65V to 5.5V on B Port (VCCA ≤ VCCB)
- VCC Isolation Feature If Either VCC Input Is at GND, All Outputs Are in the High-Impedance State
- OE Input Circuit Referenced to VCCA
- Low Power Consumption, 5 µA Max ICC
- Ioff Supports Partial-Power-Down Mode Operation
- Latch-Up Performance Exceeds 100mA Per JESD 78, Class II
- ESD Protection Exceeds JESD 22

A Port

- ◆2500-V Human-Body Model (A114-F)
- ◆200-V Machine Model (A115-A)
- ◆1500-V Charged-Device Model (C101D)

B Port

- ♦15-kV Human-Body Model (A114-F)
- ♦200-V Machine Model (A115-A)
- ♦1500-V Charged-Device Model (C101D)

2D 2 1 С D A2 A1 OE С VCCA В GND VCCB В А B2 B1 А (Bottom View) CSP-8 **B1** 8 1 **B**2 7 GND V_{CCB} 2 PI4ULS5V102 3 V_{cc/} 6 OE A2 4 5 A1 MSOP-8 (Top View)

Pin Assignment

Description

This 2-bit non-inverting translator uses two separate configurable power-supply rails. The A port is designed to track V_{CCA} . V_{CCA} accepts any supply voltage from 1.2V to 3.6V. The B port is designed to track V_{CCB} . V_{CCB} accepts any supply voltage from 1.65V to 5.5V. This allows for universal low-voltage bidirectional translation between any of the 1.2V, 1.5V, 1.8V, 2.5V, 3.3V, and 5V voltage nodes. V_{CCA} should not exceed V_{CCB} .

When the output-enable (OE) input is low, all outputs are placed in the high-impedance state.

This device is fully specified for partial-power-down applications using $I_{\rm off}$. The $I_{\rm off}$ circuitry disables the outputs, preventing damaging current backflow through the device when it is powered down.

To ensure the high-impedance state during power up or power down, OE should be tied to GND through a pull-down resistor; the minimum value of the resistor is determined by the current-sourcing capability of the driver.

Function Block Diagram



Pin Description

Pin Name	Description
B1, B2	Input/output B. Referenced to V _{CCB} .
GND	Ground.
V _{CCA}	A port supply voltage. 1.2 V $\leq V_{CCA} \leq 3.6$ V and $V_{CCA} \leq V_{CCB}$.
A1, A2	Input/output A. Referenced to V _{CCA.}
OE	3-State output. Pull OE low to place all outputs in 3-state mode. Referenced to V_{CCA} .
V _{CCB}	B port supply voltage. 1.65 V \leq V _{CCB} \leq 5.5 V.

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Maximum Ratings^{*1}

			Min	Max	Unit
V _{CCA}	Supply voltage range		-0.5	4.6	V
V _{CCB}	Supply voltage lange		-0.5	6.5	v
V	Input voltago rango	A port	-0.5	4.6	V
νI	input voltage lange	B port	-0.5	6.5	v
V	Voltage range applied to any output in the high-impedance or	A port	-0.5	4.6	V
v _o	power-off state	B port	-0.5	6.5	v
V	Valtage range emplied to any extruct in the high or law state ^{$*2$}	A port	-0.5	$V_{CCA} + 0.5$	V
v _o	voltage range applied to any output in the high of low state	B port	-0.5	$V_{CCB} + 0.5$	v
I _{IK}	Input clamp current, $V_I < 0$			-50	mA
I _{OK}	Output clamp current, $V_0 < 0$			-50	mA
Io	Continuous output current			±50	mA
Io	Continuous current through V _{CCA} , V _{CCB} , or GND			±100	mA
T _{stg}	Storage temperature range		-65	150	°C

*1 Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability. *2 The value of V_{CCA} and V_{CCB} are provided in the recommended operating conditions table.

Recommend Operation Conditions (1)(2)

Parameter	Description		V _{CCA}	V _{CCB}	Min	Max	Unit
V _{CCA}	Supply voltage		-	-	1.2	3.6	V
V _{CCB}	Supply voltage		-	-	1.65	5.5	v
		Data	1.2V to	1.65V to	$V_{CCI} *$	V _{CCI}	
V _{IH}	High-level input voltage	OE input	1.2V to 3.6V	1.65V to 5.5V	0.03 V _{CCA} * 0.7	5.5	V
V	Low lovel input veltage	Data inputs	1.2V to 3.6V	1.65V to 5.5V	0	V _{CCI} * 0.35 ⁽³⁾	V
V_{IL}	Low-level liput voltage	OE input	1.2V to 3.6V	1.65V to 5.5V	0	V _{CCA} * 0.3	v
V	Voltage range applied to any output in the	A port	1.2V to	1.65V to	0	3.6	V
v _O	high-impedance or power-off state	B port	3.6V	5.5V	0	5.5	v
		A port inputs	1.2V to 3.6V	1.65V to 5.5V	-	40	
$\Delta t / \Delta v$	Input transition rise or fall rate	B port	1.2V to	1.65V to 3.6V	-	40	ns/V
		inputs	3.6V	4.5V to 5.5V	-	30	
T _A	Operating free-air temperature		-	_	-40	85	°C

(1) The A and B sides of an unused data I/O pair must be held in the same state, i.e., both at V_{CCI} or both at GND.

(2) V_{CCA} must be less than or equal to V_{CCB} and must not exceed 3.6 V.

(3) V_{CCI} is the supply voltage associated with the input port.





DC Electrical Characteristics⁽¹⁾⁽²⁾

Dor	amatan	Test Conditions	V	V		$T_A = 25^{\circ}C$;	-40 to	I Init	
Pal	rameter	Test Conditions	V CCA	V CCB	Min	Тур	Max	Min	Max	Umt
	V 7	I - 20A	1.2V		1.0	1.1	1.2	-	-	V
	V OHA	1 _{0H} – -20μΑ	1.4V to 3.6V	_	-	-	-	V _{CCA} - 0.4	-	v
	V	$I = 20 \mu \Lambda$	1.2V		0.0	0.09	0.4	-	-	V
	V OLA	$I_{OL} = 20 \mu A$	1.4V to 3.6V	-	-	-	-	-	0.4	
	V _{OHB}	$I_{OH} = -20\mu A$	-	1.65V to 5.5V	-	-	-	V _{CCB} - 0.4		V
	V _{OLB}	$I_{OL} = 20 \mu A$	-	1.65V to 5.5V	-	-	-	-	0.4	V
II	OE	$V_I = V_{CCI}$ or GND	1.2 to 3.6V	1.65V to 5.5V	-	-	±1	-	±2	μΑ
т	A port	$V_{\rm I}$ or $V_{\rm O} = 0$ to 3.6V	0V	0V to 5.5V	-	-	±1	-	±2	
l _{off}	B port	$V_{\rm I}$ or $V_{\rm O} = 0$ to 5.5V	0 to 3.6V	0V	-	-	±1	-	±2	μΑ
I _{OZ}	A or B port	A or B OE = GND 1.2 to 3		1.65V to 5.5V	-	-	±1	-	±2	μΑ
			1.2V	1.65V to 5.5V	0.0	0.06	5.0	-	-	
	т	$V_I = V_{CCI}$ or	1.4V to 3.6V	1.65V to 5.5V	-	-	-	-	5	
	ICCA	GND, Io = 0	3.6V	0V	-	-	-	-	2	μΛ
			0V	5.5V	-	-	-	-	-2	
			1.2V	1.65V to 5.5V	0	2.3	5.0	-	-	
	Laan	$V_I = V_{CCI}$ or	1.4V to 3.6V	1.65V to 5.5V	-	-	-	-	5	ΠΔ
	ICCB	GND, Io = 0	3.6V	0V	-	-	-	-	-2	μΛ
			0V	5.5V	-	-	-	-	2	
Lag	+ Loop	$V_I = V_{CCI}$ or	1.2V	1.65V to 5.5V	0.0	2.4	8.0	-	-	ΠΔ
ICC	A ' ICCB	GND, Io = 0	1.4V to 3.6V	1.65V to 5.5V	-	-	-	-	8	μΛ
		$V_I = V_{CCI}$ or GND Io = 0 OF	1.2V	1.65V to 5.5V	0.0	0.05	0.4	-	-	цА
-	I_{CCZA} GND, Io = G		1.4V to 3.6V	1.65V to 5.5V	-	-	-	-	3	μ2 Υ
	Lagan	$V_I = V_{CCI}$ or CND $I_0 = 0$ OF	1.2V	1.65V to 5.5V	0.0	2.3	5.0	-	-	
	LCCZB	= GND	1.4V to 3.6V	1.65V to 5.5V	-	-	-	-	5	μα
Ci	OE		1.2 to 3.6V	1.65V to 5.5V	_	2.5	-	-	3	pF
Cia	A port		1.2 to 2.6V	1 65V to 5 5V	-	5	-	-	6	тE
C10	B port	-	1.2 10 3.0 V	1.03 V 10 3.3 V	-	11	-	-	14	рг

(1) V_{CCI} is the supply voltage associated with the input port. (2) V_{CCO} is the supply voltage associated with the output port.





AC Electrical Characteristics

Timing requirements

a. $T_A = 25^{\circ}C$, $V_{CCA} = 1.2V$

			$V_{CCB} = 1.8V$	$V_{CCB} = 2.5V$	$V_{CCB} = 3.3V$	$V_{CCB} = 5V$	Unit
			ТҮР	ТҮР	ТҮР	ТҮР	Umi
Data rate			20	20	20	20	Mbps
t _W	t_W Pulse duration Data inputs		50	50	50	50	ns

b. $T_A = 25^{\circ}C$, $V_{CCA} = 1.5 \pm 0.1V$

		V _{CCB} =1.8±0.15V		$V_{CCB}=2.5\pm0.2V$		$V_{CCB}=3.3\pm0.3V$		$V_{CCB}=5\pm0.5V$		Unit	
			MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Umt
Data rate		-	40	-	40	-	40	-	40	Mbp s	
t _W Pulse duration Data inputs		25	-	25	-	25	-	25	-	ns	

c. $T_A = 25^{\circ}C$, $V_{CCA} = 1.8 \pm 0.15V$

			V_{CCB} =1.8±0.15V		$V_{CCB}=2.5\pm0.2V$		$V_{CCB}=3.3\pm0.3V$		$V_{CCB}=5\pm0.5V$		Unit
			MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Umt
Data rate		-	60	-	60	-	60	-	60	Mbps	
tw	Pulse duration	Data inputs	17	-	17	-	17	-	17	-	ns

d. $T_A = 25 \degree C$, $V_{CCA} = 2.5 \pm 0.2 V$

			V _{CCB} =2.5±0.2V		$V_{CCB}=3.3\pm0.3V$		$V_{CCB}=5\pm0.5V$		IIn:4
			MIN	MAX	MIN	MAX	MIN	MAX	Unit
Data rate		-	100	-	100	-	100	Mbps	
t _W Pulse duration Data inputs		10	-	10	-	10	-	ns	

e. $T_A = 25^{\circ}C$, $V_{CCA} = 3.3 \pm 0.3V$

			V _{CCB} =3.3	±0.3V	V _{CCB} =	Unit	
			MIN	MAX	Omt		
Data rate			-	100	-	100	Mbps
t _W 10 -		10	-	10	-	ns	

Switching characteristics

a. $T_A = 25^{\circ}C$,	$V_{CCA} = 1.2V$	V									
Domomotor	From	То	V _{CCB} =1.8V	$V_{CCB}=2.5V$	$V_{CCB}=3.3V$	V _{CCB} =5V	Unit				
rarameter	(INPUT)	(OUTPUT)	ТҮР	ТҮР	ТҮР	ТҮР	Umt				
4	А	В	6.9	5.7	5.3	5.5					
ι _{pd}	В	А	7.4	6.4	6	5.8	ns				
4	OE	А	0.2	0.2	0.2	0.2					
L _{en}	UE	В	0.2	0.2	0.2	0.2	μs				
+	OE	А	0.4	0.4	0.4	0.4					
ldis	UE	В	0.2	0.2	0.2	0.2	μs				
t_{rA}, t_{fA}	A-port r ti	ise and fall mes	4.2	4.2	4.2	4.2	ns				
t_{rB},t_{fB}	B-port r ti	ise and fall mes	2.1	1.5	1.2	1.1	ns				
t _{SK(O)}	Channel-to-channel skew		0.5	0.5	0.5	1.4	ns				
Max data rate	-		-		-		20	20	20	20	Mbps





b. $T_A = 25^{\circ}C$, $V_{CCA} = 1.5 \pm 0.1V$

Danamatan	From	То	V _{CCB} =1.	8±0.15V	$V_{CCB} = 2$	2.5±0.2V	V _{CCB} =3	.3±0.3V	$V_{CCB} = 5 \pm 0.5 V$		TI:4
Parameter	(INPUT)	(OUTPUT)	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Umi
+	Α	В	1.4	12.9	1.2	10.1	1.1	10	0.8	9.9	na
ι _{pd}	В	А	0.9	14.2	0.7	12	0.4	11.7	0.3	13.7	115
+	OF	А	-	0.5	-	0.5	-	0.5	-	0.5	
Len	UE	В	-	0.5	-	0.5	-	0.5	-	0.5	μs
t	OF	А	-	0.5	-	0.5	-	0.5	-	0.5	
ldis	UE	В	-	0.5	-	0.5	-	0.5	-	0.5	μs
t_{rA}, t_{fA}	A-port rise and fall times		1.4	5.1	1.4	5.1	1.4	5.1	1.4	5.1	ns
t_{rB}, t_{fB}	B-port rise and fall times		0.9	4.5	0.6	3.2	0.5	2.8	0.4	2.7	ns
t _{SK(O)}	Channel-to-channel skew		-	0.5	-	0.5	-	0.5	-	0.5	ns
Max data rate			40	-	40	-	40	-	40	-	Mbps

c. $T_A = 25^{\circ}C$, $V_{CCA} = 1.8 \pm 0.15V$

Donomotor	From	То	V _{CCB} =1.	8±0.15V	$V_{CCB}=2$.5±0.2V	$V_{CCB}=3.3\pm0.3V$		$V_{CCB}=5\pm0.5V$		Unit
rarameter	(INPUT)	(OUTPUT)	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Unit
+	Α	В	1.6	11	1.4	7.7	1.3	6.8	1.2	6.5	na
Lpd	В	А	1.5	12	1.3	8.4	1	7.6	0.9	7.1	115
+	OE	А	-	0.3	-	0.25		0.25	-	0.25	
Len	UE	В	-	0.3	-	0.25		0.25	-	0.25	μs
+	OE	А	-	0.5	-	0.5		0.5	-	0.5	
ldis	UE	В	-	0.5	-	0.5		0.5	-	0.5	μs
t_{rA}, t_{fA}	A-port r ti	ise and fall mes	1	4.2	1	4.1	1	4.1	1	4.1	ns
t_{rB}, t_{fB}	B-port r ti	ise and fall mes	0.9	4.5	0.6	3.2	0.5	2.8	0.4	2.7	ns
t _{SK(O)}	Channel-to-channel skew		-	0.5	-	0.5	-	0.5	-	0.5	ns
Max data rate			60	-	60	-	60	-	60	-	Mbps

d. $T_A = 25^{\circ}C$, $V_{CCA} = 2.5 \pm 0.2V$

Donomotor	From	То	V _{CCB} =2	.5±0.2V	V _{CCB} =3.3±0.3V V _{CCB} =5±0.5V		5±0.5V	Unit	
Parameter	(INPUT)	(OUTPUT)	MIN	MAX	MIN	MAX	MIN	MAX	Unit
+	А	В	1.1	6.3	1.0	5.2	0.9	4.7	na
t _{pd}	В	А	1.2	6.6	1.1	5.1	0.9	4.4	IIS
t _{en}	OE	А	-	0.25	-	0.2	-	0.2	
		В	-	0.25	-	0.2	-	0.2	μs
t _{dis}	OE	А	-	0.5	-	0.4	-	035	
		UE	В	-	0.5	-	0.4	-	0.35
t_{rA}, t_{fA}	A-port rise and	fall times	0.8	3.0	0.8	3.0	0.8	3.0	ns
t_{rB}, t_{fB}	B-port rise and fall times		0.7	3.0	0.5	2.8	0.4	2.7	ns
t _{SK(O)}	Channel-to-cha	nnel skew	-	0.5	-	0.5	-	0.5	ns
Max data rate			100	-	100	-	100	-	Mbps





e. $T_A = 25^{\circ}C$, $V_{CCA} = 3.3 \pm 0.3V$

Donomotor	From	То	V _{CCB} =3	V _{CCB} =3.3±0.3V V _{CCB} =5±0.5V				
Parameter	(INPUT)	(OUTPUT)	MIN	MAX	MIN	MAX	Umt	
+	А	В	0.9	4.7	0.8	4.0	na	
ι _{pd}	В	А	1.0	4.9	0.9	3.8	115	
t _{en}	OE	А	-	0.2	-	0.2		
		В	-	0.2	-	0.2	μs	
t	OE	А	-	0.3	-	0.3		
Ldis	UE	В	-	0.3	-	0.3	μs	
t_{rA}, t_{fA}	A-port rise and	d fall times	0.7	2.8	0.7	2.8	ns	
t_{rB}, t_{fB}	B-port rise and	d fall times	0.5	2.7	0.4	2.7	ns	
t _{SK(O)}	Channel-to-ch	annel skew	-	0.5	-	0.5	ns	
Max data rate			100	-	100	_	Mbps	

Operating characteristics

			V _{CCA}							
			1.2V	1.2V	1.5V	1.8V	2.5V	2.5V	3.3V	
			V _{CCB}							
	Parameter	Test Conditions							3.3V	Unit
			5V	1.8V	1.8V	1.8V	2.5V	5V	to	
									5.5V	
			TYP	TYP	TYP	TYP	TYP	TYP	TYP	
C	A-port input, B-port output.	C _L =0, f=10 MHz,	7.8	10	9	8	8	8	9	
C _{pdA}	B-port input, A-port output.	$tr = t_f = 1ns$,	12	11	11	11	11	11	11	
C	A-port input, B-port output.	OE=V _{CCA}	38.1	28	28	28	29	30	30	
C_{pdB}	B-port input, A-port output.	(outputs enabled)	25.4	18	18	18	18	21	21	nE
C _{pdA}	A-port input, B-port output.	$C_L=0, f=10 \text{ MHz},$	0.01	0.01	0.01	0.01	0.01	0.01	0.01	рг
	B-port input, A-port output.	$tr = t_f = 1ns$,	0.01	0.01	0.01	0.01	0.01	0.01	0.01	
C _{pdB}	A-port input, B-port output.	OE=GND	0.01	0.01	0.01	0.01	0.01	0.01	0.03	
	B-port input, A-port output.	(outputs disabled)	0.01	0.01	0.01	0.01	0.01	0.02	0.04	





Test circuit

1> Load circuit for Max data rate, pulse duration propagation delay output rise and fall time measurement



2> Load circuit for enable/disable time measurement



3> Timing Definitions for Propagation Delays and Enable/Disable Measurement



4> Voltage waveforms pulse duration



5> Notes

- A. C_L includes probe and jig capacitance.
- B. All input pulses are supplied by generators having the following characteristics: PRR_10 MHz, $Z_0 = 50$ W, $dv/dt \ge 1$ V/ns.
- C. The outputs are measured one at a time, with one transition per measurement.
- D. t_{PLH} and t_{PHL} are the same as tpd.
- E. V_{CCI} is the V_{CC} associated with the input port.
- F. V_{CCO} is the V_{CC} associated with the output port.
- G. All parameters and waveforms are not applicable to all devices.





Principles of operation

Applications

The PI4ULS5V102 can be used in level-translation applications for interfacing devices or systems operating at different interface voltages with one another.

Architecture

The PI4ULS5V102 architecture (*see Figure1*) does not require a direction-control signal to control the direction of data flow from A to B or from B to A. In a dc state, the output drivers of the PI4ULS5V102 can maintain a high or low, but are designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing the opposite direction.

The output one shots detect rising or falling edges on the A or B ports. During a rising edge, the one shot turns on the PMOS transistors (T1, T3) for a short duration, which speeds up the low-to-high transition. Similarly, during a falling edge, the one shot turns on the NMOS transistors (T2, T4) for a short duration, which speeds up the high-to-low transition. The typical output impedance during output transition is 70 Ω at V_{CCO}=1.2 V to 1.8 V, 50 Ω at V_{CCO}=1.8 V to 3.3 V, and 40 Ω at V_{CCO}=3.3 V to 5 V.

Input Driver Requirements

Typical I_{IN} vs V_{IN} characteristics of the PI4ULS5V102 are shown in *Figure 2*. For proper operation, the device driving the data I/Os of the PI4ULS5V102 must have drive strength of at least ± 2 mA.

Power Up

During operation, ensure that $V_{CCA} \le V_{CCB}$ at all times. During power-up sequencing, VCCA \ge VCCB does not damage the device, so any power supply can be ramped up first. The PI4ULS5V102 has circuitry that disables all output ports when either V_{CC} is switched off ($V_{CCA/B} = 0$ V).

Enable and Disable

The PI4ULS5V102 has an OE input that is used to disable the device by setting OE = low, which places all I/Os in the high-impedance (Hi-Z) state. The disable time (t_{dis}) indicates the delay between when OE goes low and when the outputs acutally get disabled (Hi-Z). The enable time (ten) indicates the amount of time the user must allow for the one-shot circuitry to become operational after OE is taken high.

Pull-up or Pull-down Resistors on I/O Lines

The PI4ULS5V102 is designed to drive capacitive loads of up to 70 pF. The output drivers of the PI4ULS5V102 have low dc drive strength. If pullup or pulldown resistors are connected externally to the data I/Os, their values must be kept higher than 50 k Ω to ensure that they do not contend with the output drivers of the PI4ULS5V102.

For the same reason, the PI4ULS5V102 should not be used in applications such as I2C or 1-Wire where an open-drain driver is connected on the bidirectional data I/O.











Note:

A. VT is the input threshold voltage of the PI4ULS5V102 (typically $V_{CCI}/2$). B. VD is the supply voltage of the external driver.





Mechanical Information

CSP-8



13-0194





MSOP-8



For latest package info.

 $please \ check: \ http://www.diodes.com/design/support/packaging/pericom-packaging/packaging-mechanicals-and-thermal-characteristics/packaging/p$

Ordering Information

Part Number	Package Code	Package
PI4ULS5V102GAEX	GA	8-Pin, 0.95x1.94 Wafer Level (CSP)
PI4ULS5V102UEX	U	8-Pin, Mini Small Outline Package (MSOP)

Notes:

• Thermal characteristics can be found on the company web site at www.diodes.com/design/support/packaging/

• E = Pb-free and Green

• X suffix = Tape/Reel





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