

Data brief

Three-phase brushless DC motor driver expansion board based on STSPIN830 for STM32 Nucleo





Features

- Operative voltage from 7 to 45 V
- Output current up to 1.5 A_{rms}
- · Supporting single shunt and three-shunt sensing
- · Standby mode
- Flexible direct driving settable between 3 or 6 PWM inputs
- · Current limiter with adjustable reference
- Overcurrent, short-circuit and interlocking protections
- · Thermal shutdown and undervoltage lockout
- BEMF sensing circuitry
- Bus voltage and PCB temperature sensing
- · Input connector for Hall effect-based sensors and encoder
- Fully compatible with STM32 Motor Control SDK (X-CUBE-MCSDK-Y)

Description

The X-NUCLEO-IHM16M1 motor driver expansion board is based on the STSPIN830 monolithic driver for three-phase brushless motors.

It represents an affordable, easy-to-use solution for driving brushless motors in your STM32 Nucleo project, implementing single and three-shunt current sensing.

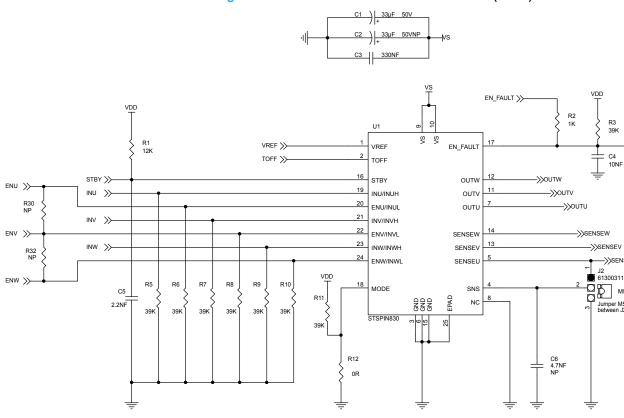
The STSPIN830 embeds a PWM current limiter with adjustable threshold together with a full set of protections.

The X-NUCLEO-IHM16M1 expansion board is compatible with the Arduino and ST morpho connectors, so it can be plugged to an STM32 Nucleo development board and stacked with additional STM32 Nucleo expansion boards.

Product summary		
Three-phase brushless DC motor driver expansion board based on STSPIN830 for STM32 Nucleo	X-NUCLEO- IHM16M1	
Three-phase brushless monolithic motor driver	STSPIN830	
STM32 Nucleo development board	oard STM32 Nucleo	
STM32 Motor Control SDK	X-CUBE-MCSDK- Y	
	Home and Professional Appliances	
Applications	PMSM/BLDC Motor	
	Industrial Tools	
	Drones	

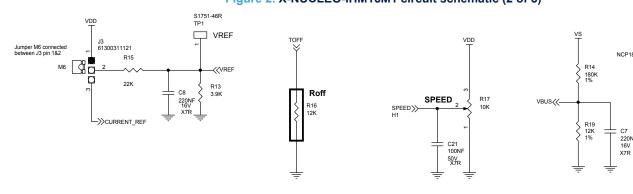
1 X-NUCLEO-IHM16M1 schematic diagrams

Figure 1. X-NUCLEO-IHM16M1 circuit schematic (1 of 5)



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Figure 2. X-NUCLEO-IHM16M1 circuit schematic (2 of 5)



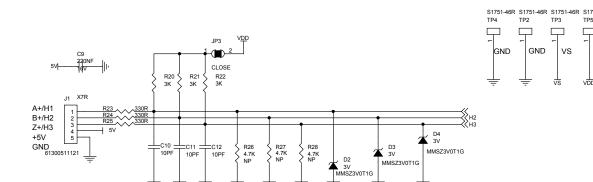
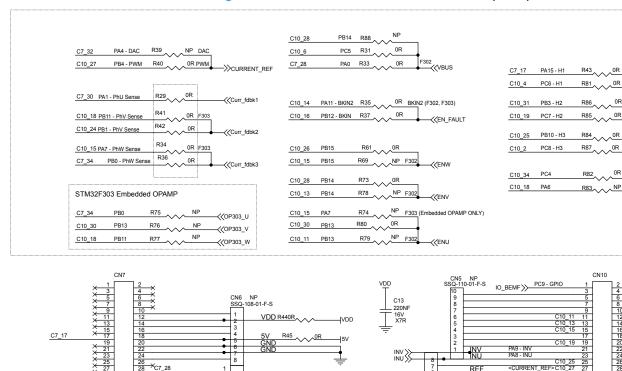
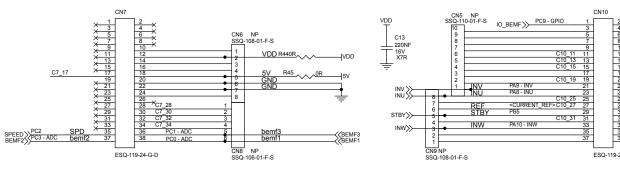


Figure 3. X-NUCLEO-IHM16M1 circuit schematic (3 of 5)













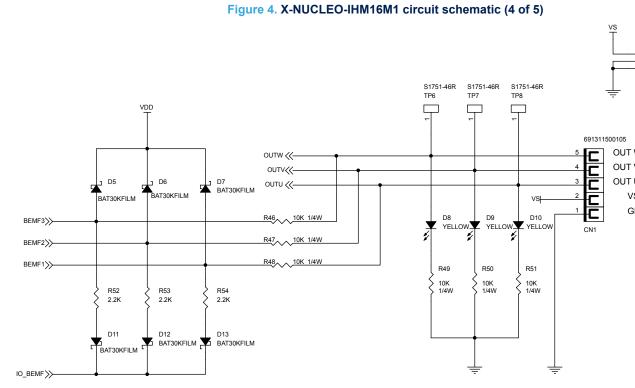


Figure 5. X-NUCLEO-IHM16M1 circuit schematic (5 of 5) R55 2.2K U2D TSV994 OP303_U R56 680R 8 SENSEU <<--{{Curr_fdbk1 R57 0.33R 1/2W 1206 R58 2.2K GND C14 680PF Jumper M7 connected between J5 pin 1&2 JP4 OPEN C15 NP М7 J5 1 2 OP303_V U2B TSV994 R62 680R Vcc SENSEV <<--{{Curr_fdbk2 R63 0.33R 1/2W 1206 M8 Jumper M8 connected between J6 pin 1&2 C17 680PF _ N J6 61300211121 C18 1 D 2 JP7 OPEN NP VDD OP303_W R67 2.2K U2C TSV994 R68 680R Vcc SENSEW <<-GND C19 680PF

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Revision history

Table 1. Document revision history

Date	Version	Changes
15-May-2018	1	Initial release.
20-Jul-2021	2	Updated cover page features and product summary table.

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