Fixed Frequency, PWM, Voltage Mode Single Ended Controllers

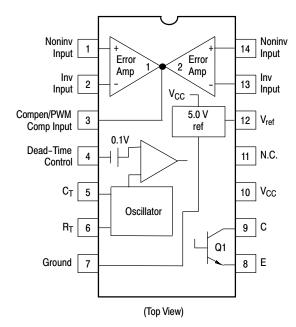
The MC34060A is a low cost fixed frequency, pulse width modulation control circuit designed primarily for single-ended SWITCHMODE™ power supply control.

The MC34060A is specified over the commercial operating temperature range of 0° to $+70^{\circ}$ C, and the MC33060A is specified over an automotive temperature range of -40° to $+85^{\circ}$ C.

Features

- Complete Pulse Width Modulation Control Circuitry
- On-Chip Oscillator with Master or Slave Operation
- On-Chip Error Amplifiers
- On-Chip 5.0 V Reference, 1.5% Accuracy
- Adjustable Dead-Time Control
- Uncommitted Output Transistor Rated to 200 mA Source or Sink
- Undervoltage Lockout
- These are Pb-Free and Halide-Free Devices

PIN CONNECTIONS





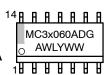
ON Semiconductor®

http://onsemi.com

MARKING DIAGRAMS



SOIC-14 D SUFFIX CASE 751A





PDIP-14 P SUFFIX CASE 646 x = 3 or 4

A = Assembly Location

WL = Wafer Lot
 Y, YY = Year
 WW = Work Week
 G = Pb-Free Package

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 14 of this data sheet.

MAXIMUM RATINGS (Full operating ambient temperature range applies, unless otherwise noted.)

| Rating | Symbol | Value | Unit |
|---|------------------|------------------------|---------|
| Power Supply Voltage | V _{CC} | 42 | V |
| Collector Output Voltage | V _C | 42 | V |
| Collector Output Current (Note 3) | I _C | 500 | mA |
| Amplifier Input Voltage Range | V _{in} | -0.3 to +42 | V |
| Power Dissipation @ T _A ≤ 45°C | P _D | 1000 | mW |
| Operating Junction Temperature | TJ | 125 | °C |
| Storage Temperature Range | T _{stg} | -55 to +125 | °C |
| Operating Ambient Temperature Range For MC340604 For MC330604 | | 0 to +70 -40 to +85 | °C |
| ESD Capability Machine Mode Human Body Mode | | 200 2.0 | V kV |

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

 This device series contains ESD protection and exceeds the following tests:
 Pins 1– 14: Human Body Model 2000 V per JEDEC Standard JESD22–A114E.
 Machine Model Method 200 V per JEDEC Standard JESD22-A115-A.

THERMAL CHARACTERISTICS

| Characteristics | Symbol | P Suffix Package | D Suffix Package | Unit |
|---|-----------------|---------------------|---------------------|------|
| Thermal Resistance, Junction-to-Ambient | $R_{\theta JA}$ | 80 | 120 | °C/W |
| Derating Ambient Temperature | T_A | 45 | 45 | °C |

RECOMMENDED OPERATING CONDITIONS

| Condition/Value | Symbol | Min | Тур | Max | Unit |
|----------------------------------|------------------|---------|-------|--------------------|------|
| Power Supply Voltage | V _{CC} | 7.0 | 15 | 40 | V |
| Collector Output Voltage | V _C | - | 30 | 40 | V |
| Collector Output Current | Ic | - | - | 200 | mA |
| Amplifier Input Voltage | V _{in} | -0.3 | - | V _{CC} -2 | V |
| Current Into Feedback Terminal | I _{fb} | - | - | 0.3 | mA |
| Reference Output Current | I _{ref} | - | _ | 10 | mA |
| Timing Resistor | R _T | 1.8 | 47 | 500 | kΩ |
| Timing Capacitor | C _T | 0.00047 | 0.001 | 10 | μF |
| Oscillator Frequency | f _{osc} | 1.0 | 25 | 200 | kHz |
| PWM Input Voltage (Pins 3 and 4) | _ | -0.3 | _ | 5.3 | V |

^{3.} Maximum thermal limits must be observed.

^{2.} This device contains Latch–Up protection and exceeds \pm 100 mA per JEDEC Standard JESD78.

 $\textbf{ELECTRICAL CHARACTERISTICS} \ (V_{CC} = 15 \ V, \ C_T = 0.01 \ \mu\text{F}, \ R_T = 12 \ k\Omega, \ unless \ otherwise \ noted. For typical values \ T_A = 25 ^{\circ}C,$ for min/max values T_A is the operating ambient temperature range that applies, unless otherwise noted.)

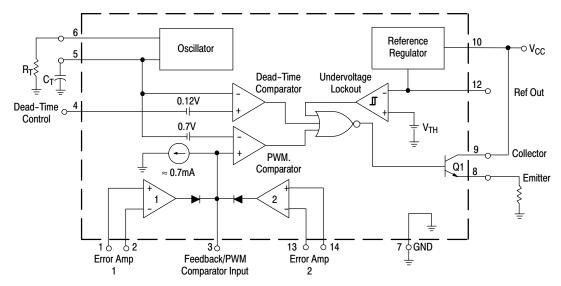
| Characteristics | Symbol | Min | Тур | Max | Unit |
|---|----------------------|---------------------------------|---------------|---------------------|------|
| REFERENCE SECTION | - | | | | |
| Reference Voltage (I_O = 1.0 mA, T_A 25°C) T_A = T_{low} to T_{high} - MC34060A - MC33060A | V _{ref} | 4.925 4.9 4.85 | 5.0 - - | 5.075 5.1 5.1 | V |
| Line Regulation (V _{CC} = 7.0 V to 40 V, I _O = 10 mA) | Reg _{line} | - | 2.0 | 25 | mV |
| Load Regulation (I _O = 1.0 mA to 10 mA) | Reg _{load} | - | 2.0 | 15 | mV |
| Short Circuit Output Current (V _{ref} = 0 V) | I _{SC} | 15 | 35 | 75 | mA |
| DUTPUT SECTION | • | • | | • | |
| Collector Off-State Current (V _{CC} = 40 V, V _{CE} = 40 V) | I _{C(off)} | - | 2.0 | 100 | μΑ |
| Emitter Off-State Current (V _{CC} = 40 V, V _{CE} = 40 V, V _E = 0 V) | I _{E(off)} | - | - | -100 | μΑ |
| Collector–Emitter Saturation Voltage (Note 4) Common–Emitter $(V_E = 0 \text{ V, } I_C = 200 \text{ mA})$ Emitter–Follower $(V_C = 15 \text{ V, } I_E = -200 \text{ mA})$ | V _{sat(C)} | - | 1.1 | 1.5 2.5 | V |
| Output Voltage Rise Time (T _A = 25°C) Common–Emitter (See Figure 12) Emitter–Follower (See Figure 13) | t _r | - - | 100 100 | 200 200 | ns |
| Output Voltage Fall Time (T _A = 25°C) Common–Emitter (See Figure 12) Emitter–Follower (See Figure 13) | t _r | - - | 40 40 | 100 100 | ns |
| ERROR AMPLIFIER SECTION | | | | | |
| Input Offset Voltage (V _{O[Pin 3]} = 2.5 V) | V _{IO} | - | 2.0 | 10 | mV |
| Input Offset Current (V _{C[Pin 3]} = 2.5 V) | I _{IO} | - | 5.0 | 250 | nA |
| Input Bias Current (V _{O[Pin 3]} = 2.5 V) | I _{IB} | - | -0.1 | -2.0 | μΑ |
| Input Common Mode Voltage Range (V _{CC} = 40 V) | V _{ICR} | 0 to V _{CC} -2.0 | - | - | V |
| Inverting Input Voltage Range | V _{IR(INV)} | -0.3 to V _{CC} -2.0 | _ | - | V |
| Open–Loop Voltage Gain $(\Delta V_O = 3.0 \text{ V, } V_O = 0.5 \text{ V to } 3.5 \text{ V, } R_L = 2.0 \text{ k}\Omega)$ | A _{VOL} | 70 | 95 | - | dB |
| Unity-Gain Crossover Frequency ($V_O = 0.5 \text{ V}$ to 3.5 V, $R_L = 2.0 \text{ k}\Omega$) | f _c | - | 600 | - | kHz |
| Phase Margin at Unity–Gain ($V_O = 0.5 \text{ V}$ to 3.5 V, $R_L = 2.0 \text{ k}\Omega$) | φ _m | - | 65 | - | deg. |
| Common Mode Rejection Ratio (V _{CC} = 40 V, V _{in} = 0 V to 38 V)) | CMRR | 65 | 90 | - | dB |
| Power Supply Rejection Ratio (ΔV_{CC} = 33 V, V_{O} = 2.5 V, R_{L} = 2.0 k Ω) | PSRR | - | 100 | - | dB |
| Output Sink Current (V _{O[Pin 3]} = 0.7 V) | I ₀ - | 0.3 | 0.7 | - | mA |
| Output Source Current (V _{O[Pin 3]} = 3.5 V) | I _O + | -2.0 | -4.0 | - | mA |

^{4.} Low duty cycle techniques are used during test to maintain junction temperature as close to ambient temperatures as possible. $T_{low} = -40^{\circ}\text{C for MC33060A} \qquad T_{high} = +85^{\circ}\text{C for MC33060A} \\ = 0^{\circ}\text{C for MC34060A} \qquad = +70^{\circ}\text{C for MC34060A}$

ELECTRICAL CHARACTERISTICS (continued) (V_{CC} = 15 V, C_T = 0.01 μ F, R_T = 12 $k\Omega$, unless otherwise noted. For typical values T_A = 25°C, for min/max values T_A is the operating ambient temperature range that applies, unless otherwise noted.)

| 71 4 7 7 8 1 3 | | _ | | | |
|---|-------------------------------|------------------------|----------------------|----------------------|------|
| Characteristics | Symbol | Min | Тур | Max | Unit |
| PWM COMPARATOR SECTION (Test circuit Figure 11) | | | | | |
| Input Threshold Voltage (Zero Duty Cycle) | V _{TH} | - | 3.5 | 4.5 | V |
| Input Sink Current $(V_{[Pin 3]} = 0.7 \text{ V})$ | II | 0.3 | 0.7 | - | mA |
| DEAD-TIME CONTROL SECTION (Test circuit Figure 11) | | | | | |
| Input Bias Current (Pin 4) (V _{in} = 0 V to 5.25 V) | I _{IB(DT)} | - | -1.0 | -10 | μΑ |
| Maximum Output Duty Cycle $(V_{in}=0~V,~C_T=0.01~\mu\text{F},~R_T=12~k\Omega)\\ (V_{in}=0~V,~C_T=0.001~\mu\text{F},~R_T=47~k\Omega)$ | DC _{max} | 90 - | 96 92 | 100 - | % |
| Input Threshold Voltage (Pin 4) (Zero Duty Cycle) (Maximum Duty Cycle) | V _{TH} | _ 0 | 2.8 | 3.3 - | V |
| OSCILLATOR SECTION | | | | | |
| $ \begin{array}{l} \text{Frequency} \\ (C_T = 0.01 \; \mu\text{F}, \; R_T = 12 \; k\Omega, \; T_A = 25^{\circ}\text{C}) \\ T_A = T_{low} \; \text{to} \; T_{high} - \text{MC34060A} \\ \qquad \qquad - \; \text{MC33060A} \\ (C_T = 0.001 \; \mu\text{F}, \; R_T = 47 \; k\Omega) \end{array} $ | f _{osc} | 9.7 9.5 9.0 – | 10.5 - - 25 | 11.3 11.5 11.5 | kHz |
| Standard Deviation of Frequency* $(C_T = 0.001 \; \mu\text{F, R}_T = 47 \; k\Omega)$ | σf _{osc} | _ | 1.5 | - | % |
| Frequency Change with Voltage (V _{CC} = 7.0 V to 40 V) | $\Delta f_{ m osc}(\Delta V)$ | _ | 0.5 | 2.0 | % |
| Frequency Change with Temperature $(\Delta T_A = T_{low} \text{ to } T_{high}) \\ (C_T = 0.01 \ \mu\text{F, R}_T = 12 \ \text{k}\Omega)$ | $\Delta f_{ m osc}(\Delta T)$ | - - | 4.0 | - - | % |
| UNDERVOLTAGE LOCKOUT SECTION | | | | | |
| Turn-On Threshold (V _{CC} increasing, I _{ref} = 1.0 mA) | V _{th} | 4.0 | 4.7 | 5.5 | V |
| Hysteresis | V _H | 50 | 150 | 300 | mV |
| TOTAL DEVICE | | | | | |
| Standby Supply Current (Pin 6 at V _{ref} , all other inputs and outputs open) (V _{CC} = 15 V) (V _{CC} = 40 V) | Icc | _ _ | 5.5 7.0 | 10 15 | mA |
| Average Supply Current (V[Pin 4] = 2.0 V, C_T = 0.001 μ F, R_T = 47 $k\Omega$). See Figure 11. | I _S | - | 7.0 | - | mA |

 $⁽V_{[Pin \ 4]} = 2.0 \ V, \ C_T = 0.001 \ \mu\text{F}, \ H_T = 47 \ \text{NS2}). \ \text{OCC. 193.5} \dots$ *Standard deviation is a measure of the statistical distribution about the mean as derived from the formula; $\sigma = -\sqrt{\frac{N}{\sum (x_n - x)^2}} \frac{N}{N-1}$



This device contains 46 active transistors.

Figure 1. Block Diagram

Description

The MC34060A is a fixed–frequency pulse width modulation control circuit, incorporating the primary building blocks required for the control of a switching power supply (see Figure 1). An internal–linear sawtooth oscillator is frequency–programmable by two external components, R_T and C_T . The approximate oscillator frequency is determined by:

$$f_{\rm osc} \cong \frac{1.2}{R_{\rm T} \bullet C_{\rm T}}$$

For more information refer to Figure 3.

Output pulse width modulation is accomplished by comparison of the positive sawtooth waveform across capacitor C_T to either of two control signals. The output is enabled only during that portion of time when the sawtooth voltage is greater than the control signals. Therefore, an increase in control–signal amplitude causes a corresponding linear decrease of output pulse width. (Refer to the Timing Diagram shown in Figure 2.)

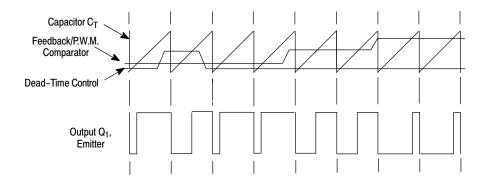


Figure 2. Timing Diagram

APPLICATIONS INFORMATION

The control signals are external inputs that can be fed into the dead-time control, the error amplifier inputs, or the feed-back input. The dead-time control comparator has an effective 120 mV input offset which limits the minimum output dead time to approximately the first 4% of the sawtooth-cycle time. This would result in a maximum duty cycle of 96%. Additional dead time may be imposed on the output by setting the dead time-control input to a fixed voltage, ranging between 0~V to 3.3~V.

The pulse width modulator comparator provides a means for the error amplifiers to adjust the output pulse width from the maximum percent on-time, established by the dead time control input, down to zero, as the voltage at the feedback pin varies from 0.5 V to 3.5 V. Both error amplifiers have a common mode input range from -0.3 V to ($V_{\rm CC}$ -2.0 V), and may be used to sense power supply output voltage and current. The error–amplifier outputs are active high and are ORed together at the noninverting input of the pulse–width modulator comparator. With this configuration, the amplifier that demands minimum output on time, dominates control of the loop.

The MC34060A has an internal 5.0 V reference capable of sourcing up to 10 mA of load currents for external bias circuits. The reference has an internal accuracy of $\pm 5\%$ with a typical thermal drift of less than 50 mV over an operating temperature range of 0° to $+70^{\circ}$ C.

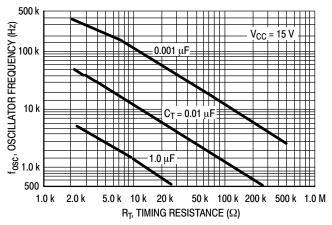


Figure 3. Oscillator Frequency versus Timing Resistance

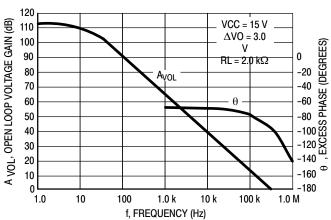


Figure 4. Open Loop Voltage Gain and Phase versus Frequency

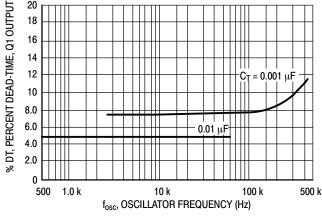


Figure 5. Percent Deadtime versus Oscillator Frequency

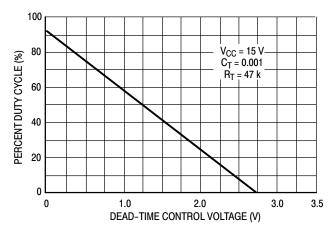


Figure 6. Percent Duty Cycle versus Dead-Time Control Voltage

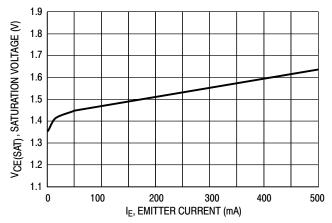


Figure 7. Emitter–Follower Configuration
Output Saturation Voltage versus
Emitter Current

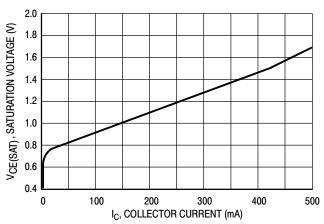


Figure 8. Common-Emitter Configuration
Output Saturation Voltage versus
Collector Current

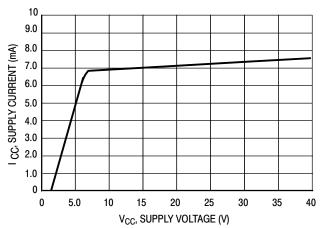


Figure 9. Standby Supply Current versus Supply Voltage

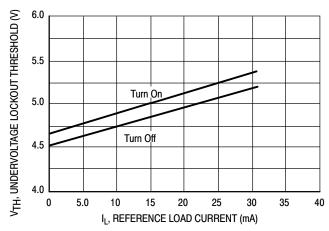


Figure 10. Undervoltage Lockout Thresholds versus Reference Load Current

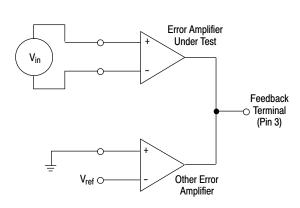


Figure 11. Error Amplifier Characteristics

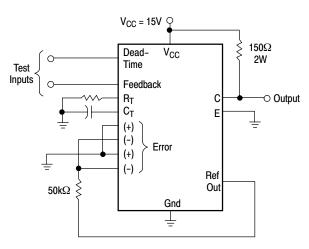


Figure 12. Deadtime and Feedback Control

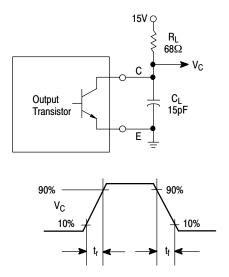


Figure 13. Common–Emitter Configuration and Waveform

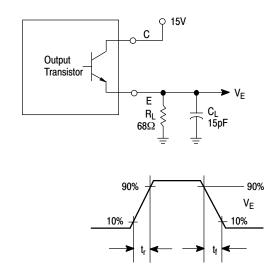


Figure 14. Emitter-Follower Configuration and Waveform

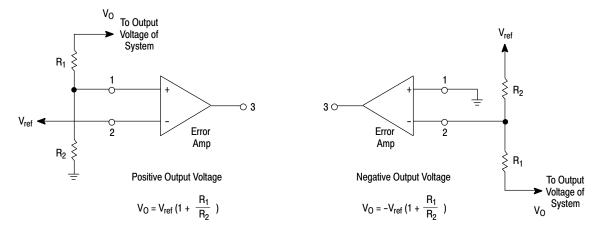


Figure 15. Error Amplifier Sensing Techniques

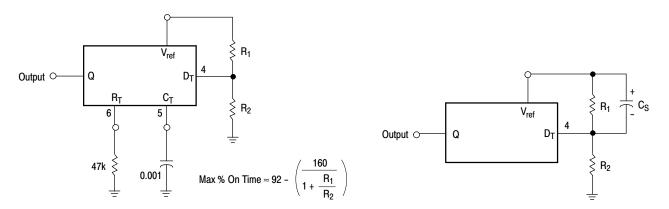


Figure 16. Deadtime Control Circuit

Figure 17. Soft-Start Circuit

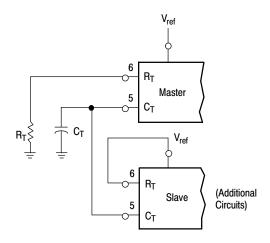
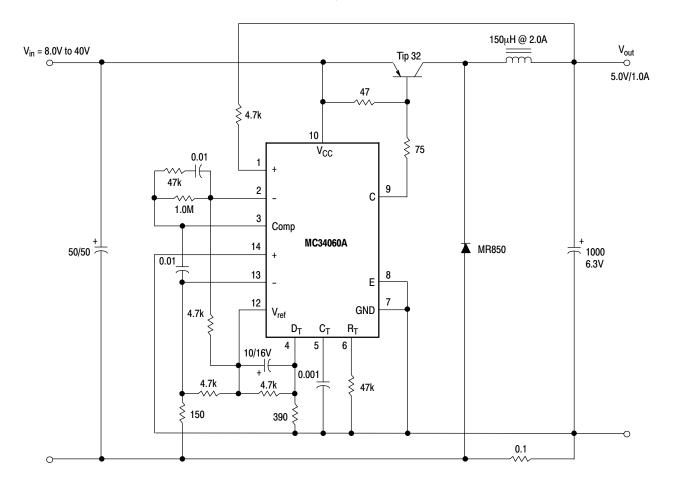
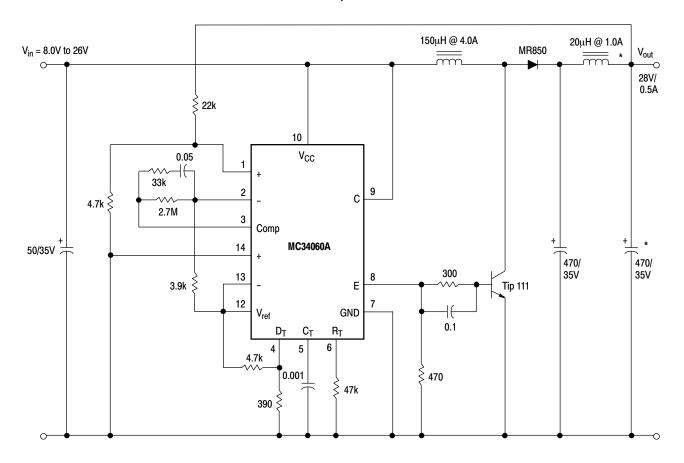


Figure 18. Slaving Two or More Control Circuits



| Test | Conditions | Results | |
|-----------------------|--|--------------------|--|
| Line Regulation | V_{in} = 8.0 V to 40 V, I_{O} = 1.0 A | 25 mV 0.5% | |
| Load Regulation | V_{in} = 12 V, I_{O} = 1.0 mA to 1.0 A | 3.0 mV 0.06% | |
| Output Ripple | V _{in} = 12 V, I _O = 1.0 A | 75 mV p-p P.A.R.D. | |
| Short Circuit Current | V _{in} = 12 V, R _L = 0.1 Ω | 1.6 A | |
| Efficiency | V _{in} = 12 V, I _O = 1.0 A | 73% | |

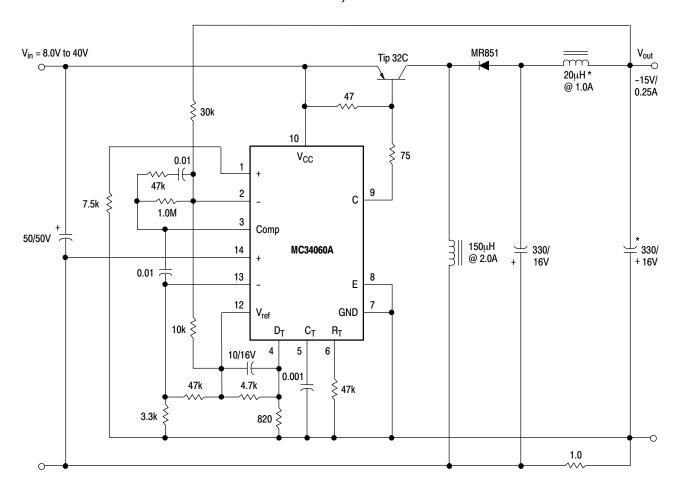
Figure 19. Step-Down Converter with Soft-Start and Output Current Limiting



| Test | Conditions | Results |
|-----------------|--|--------------------|
| Line Regulation | V_{in} = 8.0 V to 26 V, I_{O} = 0.5 A | 40 mV 0.14% |
| Load Regulation | V_{in} = 12 V, I_{O} = 1.0 mA to 0.5 A | 5.0 mV 0.18% |
| Output Ripple | V _{in} = 12 V, I _O = 0.5 A | 24 mV p-p P.A.R.D. |
| Efficiency | $V_{in} = 12 \text{ V}, I_{O} = 0.5 \text{ A}$ | 75% |

^{*}Optional circuit to minimize output ripple

Figure 20. Step-Up Converter



| Test | Conditions Results | | |
|-----------------------|---|--------------------|--|
| Line Regulation | V_{in} = 8.0 V to 40 V, I_{O} = 250 mA | 52 mV 0.35% | |
| Load Regulation | $V_{in} = 12 \text{ V}, I_{O} = 1.0 \text{ to } 250 \text{ mA}$ | 47 mV 0.32% | |
| Output Ripple | $V_{in} = 12 \text{ V}, I_{O} = 250 \text{ mA}$ | 10 mV p-p P.A.R.D. | |
| Short Circuit Current | V_{in} = 12 V, R_L = 0.1 Ω | 330 mA | |
| Efficiency | $V_{in} = 12 \text{ V}, I_{O} = 250 \text{ mA}$ | 86% | |

^{*}Optional circuit to minimize output ripple

Figure 21. Step-Up/Down Voltage Inverting Converter with Soft-Start and Current Limiting

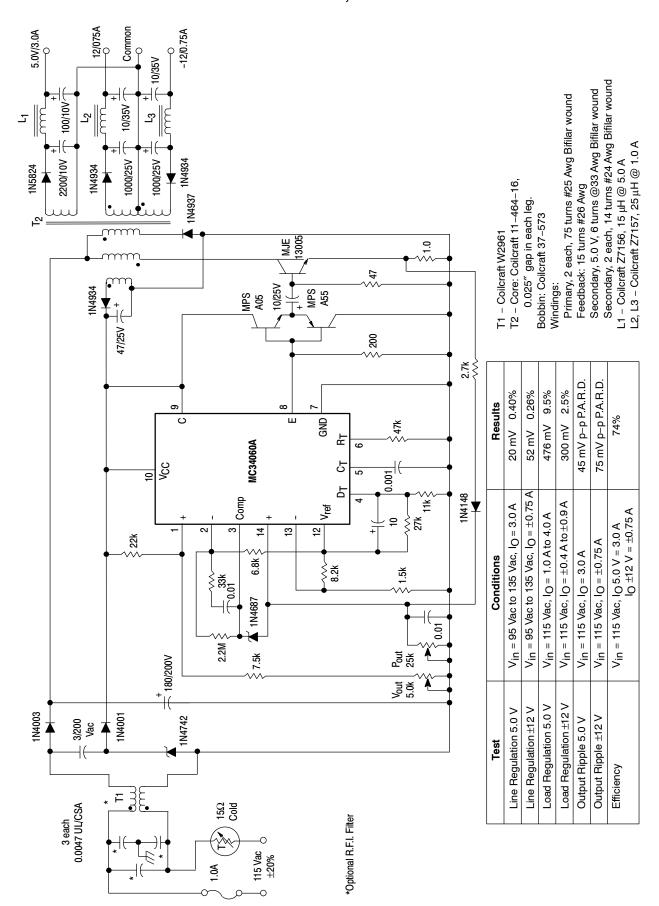


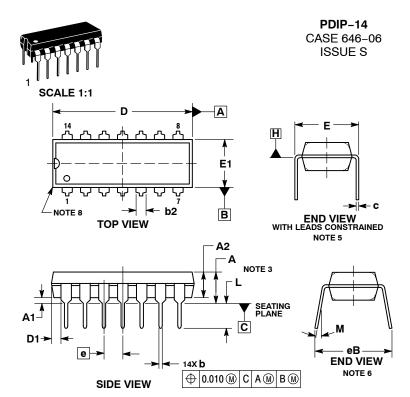
Figure 22. 33 W Off-Line Flyback Converter with Soft-Start and Primary Power Limiting

ORDERING INFORMATION

| Device | Operating Temperature Range | Package | Shipping [†] |
|--------------|--------------------------------|----------------------|-----------------------|
| MC34060ADG | | SOIC-14 (Pb-Free) | 55 Units / Rail |
| MC34060ADR2G | T _A = 0° to +70°C | SOIC-14 (Pb-Free) | 2500 / Tape & Reel |
| MC34060APG | | PDIP-14 (Pb-Free) | 25 Units / Rail |
| MC33060ADG | | SOIC-14 (Pb-Free) | 55 Units / Rail |
| MC33060ADR2G | T _A = -40° to +85°C | SOIC-14 (Pb-Free) | 2500 / Tape & Reel |
| MC33060APG | | PDIP-14 (Pb-Free) | 25 Units / Rail |

[†]For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

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DATE 22 APR 2015

NOTES:

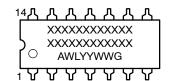
- 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
 2. CONTROLLING DIMENSION: INCHES.
 3. DIMENSIONS A, A1 AND L ARE MEASURED WITH THE PACKAGE SEATED IN JEDEC SEATING PLANE GAUGE GS-3.
 4. DIMENSIONS D, D1 AND E1 DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS. MOLD FLASH OR PROTRUSIONS ARE
- NOT TO EXCEED 0.10 INCH.
 DIMENSION E IS MEASURED AT A POINT 0.015 BELOW DATUM PLANE H WITH THE LEADS CONSTRAINED PERPENDICULAR TO DATUM C.
- DIMENSION 8B IS MEASURED AT THE LEAD TIPS WITH THE LEADS UNCONSTRAINED.

 DATUM PLANE H IS COINCIDENT WITH THE BOTTOM OF THE LEADS, WHERE THE LEADS EXIT THE BODY.

 PACKAGE CONTOUR IS OPTIONAL (ROUNDED OR SQUARE CORDINERS)
- CORNERS).

| | INC | HES | MILLIMETER | |
|-----|-------|-------|------------|-------|
| DIM | MIN | MAX | MIN | MAX |
| Α | | 0.210 | | 5.33 |
| A1 | 0.015 | | 0.38 | |
| A2 | 0.115 | 0.195 | 2.92 | 4.95 |
| b | 0.014 | 0.022 | 0.35 | 0.56 |
| b2 | 0.060 | TYP | 1.52 TYP | |
| С | 0.008 | 0.014 | 0.20 | 0.36 |
| D | 0.735 | 0.775 | 18.67 | 19.69 |
| D1 | 0.005 | | 0.13 | |
| Е | 0.300 | 0.325 | 7.62 | 8.26 |
| E1 | 0.240 | 0.280 | 6.10 | 7.11 |
| е | 0.100 | BSC | 2.54 BSC | |
| eB | | 0.430 | | 10.92 |
| L | 0.115 | 0.150 | 2.92 | 3.81 |
| М | | 10° | | 10° |

GENERIC MARKING DIAGRAM*



XXXXX = Specific Device Code = Assembly Location

WL = Wafer Lot YY = Year WW = Work Week = Pb-Free Package

*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot " ■", may or may not be present.

STYLES ON PAGE 2

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| DESCRIPTION: | PDIP-14 | | PAGE 1 OF 2 | |

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PDIP-14 CASE 646-06 ISSUE S

DATE 22 APR 2015

| STYLE 1: PIN 1. COLLECTOR 2. BASE 3. EMITTER 4. NO CONNECTION 5. EMITTER 6. BASE 7. COLLECTOR 8. COLLECTOR 9. BASE 10. EMITTER 11. NO CONNECTION 12. EMITTER 13. BASE 14. COLLECTOR | STYLE 2: CANCELLED | STYLE 3: CANCELLED | STYLE 4: PIN 1. DRAIN 2. SOURCE 3. GATE 4. NO CONNECTION 5. GATE 6. SOURCE 7. DRAIN 8. DRAIN 9. SOURCE 10. GATE 11. NO CONNECTION 12. GATE 13. SOURCE 14. DRAIN |
|---|--|--|--|
| STYLE 5: PIN 1. GATE 2. DRAIN 3. SOURCE 4. NO CONNECTION 5. SOURCE 6. DRAIN 7. GATE 8. GATE 9. DRAIN 10. SOURCE 11. NO CONNECTION 12. SOURCE 13. DRAIN 14. GATE | STYLE 6: PIN 1. COMMON CATHODE 2. ANODE/CATHODE 3. ANODE/CATHODE 4. NO CONNECTION 5. ANODE/CATHODE 6. NO CONNECTION 7. ANODE/CATHODE 8. ANODE/CATHODE 9. ANODE/CATHODE 10. NO CONNECTION 11. ANODE/CATHODE 12. ANODE/CATHODE 13. NO CONNECTION 14. COMMON ANODE | STYLE 7: PIN 1. NO CONNECTION 2. ANODE 3. ANODE 4. NO CONNECTION 5. ANODE 6. NO CONNECTION 7. ANODE 8. ANODE 9. ANODE 10. NO CONNECTION 11. ANODE 12. ANODE 13. NO CONNECTION 14. COMMON CATHODE | STYLE 8: PIN 1. NO CONNECTION 2. CATHODE 3. CATHODE 4. NO CONNECTION 5. CATHODE 6. NO CONNECTION 7. CATHODE 8. CATHODE 9. CATHODE 10. NO CONNECTION 11. CATHODE 12. CATHODE 13. NO CONNECTION 14. COMMON ANODE |
| STYLE 9: PIN 1. COMMON CATHODE 2. ANODE/CATHODE 3. ANODE/CATHODE 4. NO CONNECTION 5. ANODE/CATHODE 6. ANODE/CATHODE 7. COMMON ANODE 8. COMMON ANODE 9. ANODE/CATHODE 10. ANODE/CATHODE 11. NO CONNECTION 12. ANODE/CATHODE 13. ANODE/CATHODE 14. COMMON CATHODE | STYLE 10: PIN 1. COMMON CATHODE 2. ANODE/CATHODE 3. ANODE/CATHODE 4. ANODE/CATHODE 5. ANODE/CATHODE 6. NO CONNECTION 7. COMMON ANODE 8. COMMON CATHODE 9. ANODE/CATHODE 10. ANODE/CATHODE 11. ANODE/CATHODE 12. ANODE/CATHODE 13. NO CONNECTION 14. COMMON ANODE | STYLE 11: PIN 1. CATHODE 2. CATHODE 3. CATHODE 4. CATHODE 5. CATHODE 6. CATHODE 7. CATHODE 8. ANODE 9. ANODE 10. ANODE 11. ANODE 12. ANODE 13. ANODE 14. ANODE | STYLE 12: PIN 1. COMMON CATHODE 2. COMMON ANODE 3. ANODE/CATHODE 4. ANODE/CATHODE 5. ANODE/CATHODE 6. COMMON ANODE 7. COMMON CATHODE 8. ANODE/CATHODE 9. ANODE/CATHODE 10. ANODE/CATHODE 11. ANODE/CATHODE 12. ANODE/CATHODE 13. ANODE/CATHODE 14. ANODE/CATHODE 14. ANODE/CATHODE |

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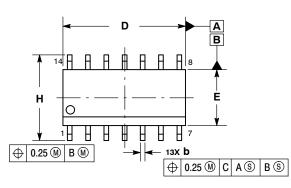


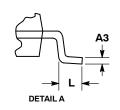


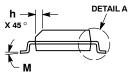
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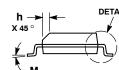
SOIC-14 NB CASE 751A-03 ISSUE L

DATE 03 FEB 2016









- NOTES:
 1. DIMENSIONING AND TOLERANCING PER
 - ASME Y14.5M, 1994.
 CONTROLLING DIMENSION: MILLIMETERS.
- DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS OF AT
- MAXIMUM MATERIAL CONDITION.
 DIMENSIONS D AND E DO NOT INCLUDE
 MOLD PROTRUSIONS.
- 5. MAXIMUM MOLD PROTRUSION 0.15 PER SIDE

| | MILLIMETERS | | INCHES | |
|-----|-------------|------|-----------|-------|
| DIM | MIN | MAX | MIN | MAX |
| Α | 1.35 | 1.75 | 0.054 | 0.068 |
| A1 | 0.10 | 0.25 | 0.004 | 0.010 |
| АЗ | 0.19 | 0.25 | 0.008 | 0.010 |
| b | 0.35 | 0.49 | 0.014 | 0.019 |
| D | 8.55 | 8.75 | 0.337 | 0.344 |
| Е | 3.80 | 4.00 | 0.150 | 0.157 |
| œ | 1.27 BSC | | 0.050 BSC | |
| Н | 5.80 | 6.20 | 0.228 | 0.244 |
| h | 0.25 | 0.50 | 0.010 | 0.019 |
| L | 0.40 | 1.25 | 0.016 | 0.049 |
| М | 0 ° | 7° | 0 ° | 7° |

GENERIC MARKING DIAGRAM*

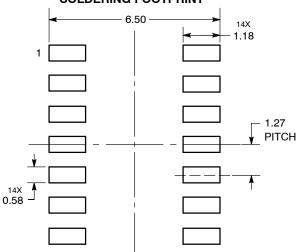


XXXXX = Specific Device Code Α = Assembly Location

WL = Wafer Lot Υ = Year WW = Work Week = Pb-Free Package

*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot "•", may or may not be present. Some products may not follow the Generic Marking.

SOLDERING FOOTPRINT*



DIMENSIONS: MILLIMETERS

C SEATING PLANE

STYLES ON PAGE 2

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^{*}For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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DATE 03 FEB 2016

| STYLE 1: PIN 1. COMMON CATHODE 2. ANODE/CATHODE 3. ANODE/CATHODE 4. NO CONNECTION 5. ANODE/CATHODE 6. NO CONNECTION 7. ANODE/CATHODE 8. ANODE/CATHODE 9. ANODE/CATHODE 10. NO CONNECTION 11. ANODE/CATHODE 12. ANODE/CATHODE 13. NO CONNECTION 14. COMMON ANODE | STYLE 2: CANCELLED | STYLE 3: PIN 1. NO CONNECTION 2. ANODE 3. ANODE 4. NO CONNECTION 5. ANODE 6. NO CONNECTION 7. ANODE 8. ANODE 9. ANODE 10. NO CONNECTION 11. ANODE 12. ANODE 13. NO CONNECTION 14. COMMON CATHODE | STYLE 4: PIN 1. NO CONNECTION 2. CATHODE 3. CATHODE 4. NO CONNECTION 5. CATHODE 6. NO CONNECTION 7. CATHODE 8. CATHODE 9. CATHODE 10. NO CONNECTION 11. CATHODE 12. CATHODE 13. NO CONNECTION 14. COMMON ANODE |
|---|---|---|---|
| STYLE 5: PIN 1. COMMON CATHODE 2. ANODE/CATHODE 3. ANODE/CATHODE 4. ANODE/CATHODE 5. ANODE/CATHODE 6. NO CONNECTION 7. COMMON ANODE 8. COMMON CATHODE 9. ANODE/CATHODE 10. ANODE/CATHODE 11. ANODE/CATHODE 12. ANODE/CATHODE 13. NO CONNECTION 14. COMMON ANODE | STYLE 6: PIN 1. CATHODE 2. CATHODE 3. CATHODE 4. CATHODE 5. CATHODE 6. CATHODE 7. CATHODE 8. ANODE 9. ANODE 10. ANODE 11. ANODE 12. ANODE 13. ANODE 14. ANODE | STYLE 7: PIN 1. ANODE/CATHODE 2. COMMON ANODE 3. COMMON CATHODE 4. ANODE/CATHODE 5. ANODE/CATHODE 6. ANODE/CATHODE 7. ANODE/CATHODE 8. ANODE/CATHODE 9. ANODE/CATHODE 10. ANODE/CATHODE 11. COMMON CATHODE 12. COMMON ANODE 13. ANODE/CATHODE 14. ANODE/CATHODE | STYLE 8: PIN 1. COMMON CATHODE 2. ANODE/CATHODE 3. ANODE/CATHODE 4. NO CONNECTION 5. ANODE/CATHODE 6. ANODE/CATHODE 7. COMMON ANODE 8. COMMON ANODE 9. ANODE/CATHODE 10. ANODE/CATHODE 11. NO CONNECTION 12. ANODE/CATHODE 13. ANODE/CATHODE 14. COMMON CATHODE |

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