STMicroelectronics

# EVALSPEAr320CPU SPEAr320 CPU evaluation board 

UM1015<br>User manual

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## Introduction

This document applies to revision 2.0 SPEAr320 CPU evaluation boards.
This board can be used to evaluate SPEAr320 microprocessors; the evaluation board kit comprises one board, one serial cable interface, and one power supply.

## CPU board features

■ SPEAr320 embedded MPU
■ Up to 2 Gbit DDR2 333 MHz (standard 128 Mbytes)
■ Up to 16 Mbyte Serial Flash memory (standard 8 Mbytes)
■ Two USB 2.0 full host port channels

- One USB 2.0 host device port
- One serial port (up to 115 baud)

■ JTAG Debug ports

Figure 1. SPEAr320 CPU evaluation board


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## 1 Getting started

## Warning: This board contains static sensitive devices.

The EVALSPEAr320CPU board is shipped in protective anti-static packaging. Do not submit the board to high electrostatic potentials, and follow good practices for working with static sensitive devices.

- Wear an anti-static wristband. Wearing a simple anti-static wristband can help prevent ESD from damaging the board.
- Zero potential. Always touch a grounded conducting material before handling the board, and periodically while handling it.
- Use an anti-static mat. When configuring the board, place it on and anti-static mat to reduce the possibility of ESD damage.
- Handle only the edges. Handle the board by its edges only, and avoid touching board components.


### 1.1 Connections

Refer to Figure 14 on page 31.

1. Connect a serial cable from connector J 17 (serial link) to a host PC.
2. On the host PC running Windows or Linux, start the Terminal program.
3. Connect the +5 V voltage adapter (supplied in the EVALSPEAR320CPU package) to the J11 power voltage connector on the CPU board.
4. Apply power to the board.
5. The Terminal program displays a sequence of boot messages followed by the Linux console prompt.
For more information, refer to user manual UM0844 Getting started with Linux for SPEAr, available at www.st.com/spear.

### 1.2 Booting procedure

The SPEAr320 CPU evaluation board can boot a Linux kernel that has been pre-installed in the serial NOR Flash.

At power on, the serial port outputs a brief header message with some uBoot information (uBoot version, SDK version, and some internal hardware information). At this point you can choose to:

- Stop the system directly in uBoot: Press the spacebar on the host computer keyboard before the boot delay time expires (default is 3 seconds).
- Boot Linux: The system logs you in automatically as super user, and displays the Linux shell prompt on the screen.


## 2 Block diagram

Figure 2. EVALSPEAr320CPU board block diagram


### 2.0.1 Dynamic memory subsystem

The Dynamic memory subsystem comprises three major parts:

## Memory chip

The SPEAr320 MPU supports up to 256 Mbytes of memory. Place and route is provided for 2 chips but only one has been populated. The memory used is a Micron DDR2 device, its part number is MT47H64M16HR-3 and its size is 128 Mbits $\times 8$ ( 16 Mbits $\times 8 \times 8$ banks).

## Local power supply

The local power supply is based on a monolithic voltage regulator for the chip set and DDR2/3 (PM6641). It is generated locally in order to minimize the layout impact and also to avoid any noise injection between different subsystems.

## Signal termination

A parallel termination is added on the clock lines to compensate, if needed, for the layout dissymmetry. Two 100k ohm resistors are used for each line in order to obtain an impedance of 50 ohms. All the other terminations are directly inside the pads (both on the SPEAr320 MPU and the memory sides).

### 2.0.2 Static memory subsystem (Serial Flash memory)

The SPEAr320 MPU supports up to 16 Mbytes of Serial Flash memory. Place and route for 2 blocks of 8 Mbytes are provided on the board, but only one is populated. It is based on an M25P64-VMF6P (Numonix) Serial Flash memory device.
Resistor R8 protects the Flash memory from any unwanted write access.

### 2.0.3 USB 2.0 subsystem

## Host ports

The board has two host ports that are fully compliant with the USB 2.0 specification (two controllers with one port each). This means that the two hosts can work in concurrent mode with the maximum possible bandwidth. Each host has also full control of the VBUS supplied by the ST2052 power switch that also provides over current protection in case of a short circuit in the USB cable.

## Device port

The board has one USB 2.0 device port.

### 2.0.4 Debug interface

The JTAG interface can be used for static debugging, which means that it is possible to set a breakpoint, and when the system stops, verify the contents of the memory or registers, or both, and modify them if needed.

To select the debug feature, set Switch SW1 bits [2:1].
Table 1. Switch SW1 bits [2:1]

| Bit 2 | Bit 1 | Description |
| :---: | :---: | :--- |
| 0 | 0 | No debug features available |
| 0 | 1 | The ARM JTAG is connected to J4 |

For more information on the ETM interface, refer to the trace box manufacturer's documentation (www.lauterbach.com, www.agilent.com, www.yokogawa.com).

### 2.0.5 Serial interface

One serial interface port is available. Typically used as an OS monitor, this port is available on the J 17 connector. It is possible to simulate a cross cable by changing the position of the J22 jumpers.

Figure 3. Serial cable setting


### 2.0.6 Real time clock (battery powered)

The real time clock (RTC) is powered by an external battery (3V) in order to prevent data loss even if the main power supply is switched off.

### 2.0.7 General power supply

From a 5 V external $\mathrm{AC} / \mathrm{DC}$ regulator power source, this block generates all the required voltages as follows:

- 1.2V (Switching regulator PM6641) to supply the internal logic of the SPEAr320 MPU
- 1.8 V (Switching regulator PM6641) for the DDR2 memory
- 2.5 V (LDO regulator) for the analog portion of SPEAr320
- 3.3V (Switching regulator PM6641) to supply the other interfaces

A power monitor is also present to provide the general reset of the board.

### 2.0.8 Reset button

A manual reset button (P1) on the top of the board (see Figure 14 on page 31) resets the microprocessor on the core board.

## 3 Expansion connectors

The CPU board has two 86-pin connectors (J12 and J13) that are used to extend the board. On the board the connectors are horizontally center-aligned, and the distance between the mechanical holes is 3400.00 th.

Table 2 lists connector J12 pins.
Table 3 on page 13 lists connector J 13 pins.
Note: $\quad$ Connector through hole pins (10 pins) are connected to GND
Figure 4. 86-pin connectors (J12 and J13)


Table 2. CPU board extension connector J12

| Pin | Description | Pin | Description |
| :---: | :--- | :---: | :--- |
| 1 | +1.8 V | 2 | +5 V |
| 3 | +1.8 V | 4 | +5 V |
| 5 | +1.8 V | 6 | +5 V |
| 7 | +1.8 V | 8 | +5 V |
| 9 | PL_GPIO2 (RS232-TX LVTTL) ${ }^{(1)}$ | 10 | PL_GPIO44 |
| 11 | PL_GPIO3 (RS232-RX LVTTL) ${ }^{(2)}$ | 12 | PL_GPIO39 |
| 13 | RS232-TX $^{(3)}$ | 14 | PL_GPIO40 |
| 15 | RS232-RX $^{(4)}$ | 16 | PL_GPIO38 |
| 17 | PL_GPIO42 | 18 | PL_GPIO29 |
| 19 | PL_GPIO43 | 20 | PL_GPIO37 |
| 21 | PL_GPIO34 | 22 | PL_GPIO30 |
| 23 | PL_GPIO33 | 24 | PL_GPIO28 |
| 25 | PL_GPIO16 | 26 | PL_GPIO26 |
| 27 | PL_GPIO24 | 28 | PL_GPIO27 |
| 29 | PL_GPIO20 | 30 | PL_GPIO9 |
| 31 | PL_GPIO23 | 32 | PL_GPIO13 |
| 33 | PL_GPIO18 | 34 | PL_GPIO8 |

Table 2. CPU board extension connector J12 (continued)

| Pin | Description | Pin | Description |
| :---: | :---: | :---: | :---: |
| 35 | PL_GPIO11 | 36 | PL_GPIO6 |
| 37 | PL_GPIO19 | 38 | PL_GPIO4 |
| 39 | PL_GPIO15 | 40 | PL_GPIO5 |
| 41 | PL_GPIO14 | 42 | NC |
| 43 | PL_GPIO36 | 44 | NC |
| 45 | PL_GPIO41 | 46 | NC |
| 47 | PL_GPIO35 | 48 | NC |
| 49 | PL_GPIO31 | 50 | +2.5V |
| 51 | PL_GPIO32 | 52 | +2.5V |
| 53 | PL_GPIO25 | 54 | +2.5V |
| 55 | PL_GPIO22 | 56 | +2.5V |
| 57 | PL_GPIO21 | 58 | INRESET |
| 59 | PL_GPIO17 | 60 | nRESET |
| 61 | PL_GPIO12 | 62 | +1.2V |
| 63 | PL_GPIO10 | 64 | +1.2V |
| 65 | PL_GPIO7 | 66 | +1.2V |
| 67 | PL_GPIO1 | 68 | +1.2V |
| 69 | PL_GPIOO | 70 | +3.3V |
| 71 | NC | 72 | +3.3V |
| 73 | NC | 74 | +3.3V |
| 75 | NC | 76 | +3.3V |
| 77 | GND ${ }^{(5)}$ | 78 | GND ${ }^{(5)}$ |
| 79 |  | 80 |  |
| 81 |  | 82 |  |
| 83 |  | 84 |  |
| 85 |  | 86 |  |

1. If J 20 Jumper is set to pin2-3, otherwise NC.
2. If J21 Jumper is set to pin2-3, otherwise NC
3. If J22 Jumper is set to pin2-4 and pin1-3, otherwise RS232-RX.
4. If J22 Jumper is set to pin2-4 and pin1-3, otherwise RS232-TX.
5. Physically connected to the internal metal plane of the connector. Pins 77 through 81 and 82 through 86 are shorted together.

Table 3. CPU board extension connector J13

| Pin | Description | Pin | Description |
| :---: | :---: | :---: | :---: |
| 1 | PL_GPIO47 | 2 | +3.3V |
| 3 | PL_GPIO49 | 4 | PL_GPIO63 |
| 5 | PL_GPIO56 | 6 | PL_GPIO46 |
| 7 | PL_GPIO58 | 8 | PL_GPIO57 |
| 9 | PL_GPIO64 | 10 | PL_GPIO61 |
| 11 | PL_GPIO45 | 12 | PL_GPIO66 |
| 13 | PL_GPIO48 | 14 | PL_GPIO69 |
| 15 | PL_GPIO50 | 16 | PL_GPIO72 |
| 17 | PL_GPIO55 | 18 | PL_GPIO73 |
| 19 | PL_GPIO59 | 20 | PL_GPIO70 |
| 21 | PL_GPIO60 | 22 | PL_GPIO67 |
| 23 | PL_GPIO65 | 24 | PL_GPIO71 |
| 25 | PL_GPIO62 | 26 | PL_GPIO75 |
| 27 | PL_GPIO68 | 28 | PL_GPIO82 |
| 29 | PL_GPIO52 | 30 | PL_GPIO76 |
| 31 | PL_GPIO53 | 32 | PL_GPIO85 |
| 33 | PL_GPIO51 | 34 | PL_GPIO87 |
| 35 | PL_GPIO54 | 36 | PL_GPIO95 |
| 37 | PL_GPIO74 | 38 | PL_GPIO79 |
| 39 | PL_GPIO77 | 40 | PL_GPIO94 |
| 41 | PL_GPIO78 | 42 | ADC VREFN |
| 43 | PL_GPIO81 | 44 | AINO |
| 45 | PL_GPIO80 | 46 | GND |
| 47 | PL_GPIO84 | 48 | AIN1 |
| 49 | PL_GPIO83 | 50 | GND |
| 51 | PL_GPIO86 | 52 | AIN2 |
| 53 | PL_GPIO91 | 54 | GND |
| 55 | PL_GPIO90 | 56 | AIN3 |
| 57 | PL_GPIO96 | 58 | GND |
| 59 | PL_GPIO88 | 60 | AIN4 |
| 61 | PL_GPIO89 | 62 | GND |
| 63 | PL_GPIO92 | 64 | AIN5 |
| 65 | PL_GPIO93 | 66 | GND |
| 67 | PL_GPIO97 | 68 | AIN6 |
| 69 | PL_CLK4 | 70 | GND |

Table 3. CPU board extension connector J13 (continued)

| Pin | Description | Pin | Description |
| :---: | :---: | :---: | :---: |
| 71 | PL_CLK3 | 72 | AIN7 |
| 73 | PL_CLK2 | 74 | GND |
| 75 | PL_CLK1 | 76 | ADC VREFP |
| 77 | GND ${ }^{(1)}$ | 78 | GND ${ }^{(1)}$ |
| 79 |  | 80 |  |
| 81 |  | 82 |  |
| 83 |  | 84 |  |
| 85 |  | 86 |  |

1. Physically connected to the internal metal plane of the connector. Pins 77 through 81 and 82 through 86 are shorted together.

## 4 Switch and jumper settings

### 4.1 Switch 1 settings

Table 4. Switch 1 (SoC functional configuration)

| Bit | Description |
| :---: | :--- |
| 1 | Test - see Debug configuration below |
| 2 | Reserved |
| 3 | Reserved |
| 4 | Reserved |
| 5 | Reserved |
| 6 | BootSel - see Debug configuration below |

Table 5. Switch 1 (debug configuration)

| Test bit |  | Debug configuration |
| :---: | ---: | :--- |
| 2 | 1 |  |
| 0 | 0 | Normal Mode (No debug enabled) |
| 0 | 1 | ARM1 JTAG connected to J4 |
| 1 | 0 | Reserved |

Table 6. Switch 1 (functional configuration)

| Test bit |  |  |  |  |
| :---: | :---: | :---: | :---: | :--- |
| 6 | 5 | 4 | 3 |  |
| 1 | 0 | 1 | 1 | Configuration 3 |
|  |  |  |  |  |

Note: $\quad$ When Switch SW1-x is in the ON position, the bit value is 0 . When Switch 1 is in the OFF position, the bit value is 1 .

Bits 3, 4, 5 and 6 enable you to set the Functional configuration. The default configuration is Configuration 3. For other configurations, refer to the SPEAr320 user manual available at www.st.com/spear.

### 4.2 Switch 2 settings

Table 7. Switch 2 settings

| Boot from | SW2-1 | SW2-2 | SW2-3 | sW2-4 | sW2-5 | sW2-6 | sW2-7 | sW2-8 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| USB_BOOT | Off | On | Off | On | Off | On | Off | On |
| ETH (parameter from I2C <br> ROM) | On | Off | Off | On | Off | On | Off | On |
| ETH (parameter from SPI <br> ROM) | Off | On | On | Off | Off | On | Off | On |
| Serial NOR (default setting) | On | Off | On | Off | Off | On | Off | On |
| Parallel NOR 8 (EMI with ACK) | Off | On | Off | On | On | Off | Off | On |
| Parallel NOR 16 (EMI with <br> ACK) | On | Off | Off | On | On | Off | Off | On |
| Parallel NAND 8 | Off | On | On | Off | On | Off | Off | On |
| Parallel NAND 16 | On | Off | On | Off | On | Off | Off | On |
| Reserved for SPI | Off | On | Off | On | Off | On | On | Off |
| Reserved for 12C | On | Off | Off | On | Off | On | On | Off |
| UART_BOOT | On | On | Off | Off | On | On | Off |  |
| BootROM bypass | Off | On | Off | Off | On | On | Off |  |
| Parallel NOR 8 (EMI without <br> ACK) | Off | On | Off | On | On | Off | On | Off |
| Parallel NOR 16 (EMI without <br> ACK) | On | Off | Off | On | On | Off | On | Off |
| Reserved | Off | On | On | Off | On | Off | On | Off |
| Reserved | On | Off | On | Off | On | Off | On | Off |

Note: If SW2-1 and SW2-2 are both off, BO (pin PL_GPIO51) is in HiZ state, and can be controlled from the application board.

If SW2-3 and SW2-4 are both off, B1 (pin PL_GPIO52) is in HiZ state, and can be controlled from the application board.
If SW2-5 and SW2-6 are both off, B2 (pin PL_GPIO53) is in HiZ state, and can be controlled from the application board.
If SW2-7 and SW2-8 are both off, B3 (pin PL_GPIO54) is in HiZ state, and can be controlled from the application board.

SW2-1 and SW2-2 on: invalid condition SW2-3 and SW2-4 on: invalid condition SW2-5 and SW2-6 on: invalid condition SW2-7 and SW2-8 on: invalid condition

### 4.3 Jumpers and connectors

The jumpers and connectors numbered below refer to the CPU board schematics (available on www.st.com/spear).

## Sheet 4

- Connector J3 is a standard 20-pin 2.54 mm connector used for JTAG connections.
- Jumper J5 enables the power supply to the Real Time Clock block. If jumper J5 is closed, the RTC is powered (standard).
- Connector J10 is a 2 vie 1.25 mm pitch connector for battery back-up with cable.


## Sheet 5

- Connector J 11 is a standard power connector for the ADC power supply with a 2.1-mm central pitch.


## Sheet 6

- Jumpers J6, J7, J8 and J9 are serial jumpers for the SPEAr power rail.

All jumpers MUST be closed. This configuration is used for power measurements.

## Sheet 7

- Jumper J22 is a 4-pin symmetric IDC (or strip) connector that switches RX and TX signals for different types of RS-232 cables ${ }^{(\mathrm{a})}$ :
- Two pins are connected to the ST3232 Receive/Transmit side.
- Two pins are connected to the RS-232 Receive/Transmit connector side.
- Connector J 17 is a connector for standard IDC-to-DSUB converters.
- Jumper J20 switches between RS-232 transmit signals or GPIO2:
- If jumper is on pins 1 and 2, pin PL_GPIO2 is connected to U12 (ST3232) and the COM0 is available on J17.
- If jumper is on pins 2 and 3, pin PL_GPIO2 is connected to the expansion connector J12 pin 9. In this case the COM0 is available on CN13.
- Jumper J21 switches between RS-232 receive signals or GPIO3:
- If jumper is on pins 1 and 2, pin PL_GPIO3 is connected to U12 (ST3232) and the COM0 is available on J 17 .
- If jumper is on pins 2 and 3, pin PL_GPIO3 is connected to the expansion connector J12 pin 11. In this case the COM0 is available on CN13.

[^0]
## 5 Board components

Table 8. CPU board components

| Component | Designator | Footprint | Description |
| :---: | :---: | :---: | :---: |
| Capacitor | C1 C2 C3 <br> C4 C5 C6 <br> C7 C8 C9 <br> C10 C11 <br> C12 C13 <br> C14 C15 <br> C16 C17 <br> C18 C19 <br> C20 C21 <br> C22 C23 <br> C24 C25 <br> C26 C27 <br> C28 C29 <br> C30 C31 <br> C32 C33 <br> C34 C35 <br> C36 C37 <br> C38 C39 <br> C40 C41 <br> C42 C43 <br> C44 C45 <br> C46 C47 <br> C48 C49 <br> C50 C56 <br> C57 C58 <br> C59 C60 <br> C99 C100 <br> C101 C102 | 0402 | Ceramic capacitor 0.1uF 10\% 10V X5R 0402 |
| Resistor | $\begin{aligned} & \text { R42 R43 } \\ & \text { R44 R45 } \\ & \text { R46 R47 } \\ & \text { R48 R50 } \end{aligned}$ | 0603 | Resistor 06030 ohm |
| Resistor | $\begin{array}{\|l} \hline \text { R30 R31 } \\ \text { R32 R33 } \\ \text { R34 R35 } \\ \text { R36 R37 } \\ \text { R38 R72 } \\ \text { R73 R74 } \end{array}$ | 0603 | Resistor 0603 1k ohm 1\% 0.1W |
| Inductor | L3 | LPS3.9X3.9 | Power Inductor 1uH 1.7A 3.9x3.9mm SMD |
| Capacitor | C89 | 0603 | Ceramic capacitor 2.2nF 10\% 50V X7R 0603 |
| Inductor | L1 L2 | LPS3.9X3.9 | Power Inductor 2.2uH 1.2A 3.9x3.9mm SMD |
| Resistor | R59 R60 | 0603 | Resistor 06034.3 ohm 1\% 0.1W |
| Resistor | R27 R28 | 0603 | Resistor 0603 4.7k ohm 1\% 0.1W |

Table 8. CPU board components (continued)

| Component | Designator | Footprint |  |
| :--- | :--- | :--- | :--- |
|  | R10 R11 <br> R12 R13 <br> R14 R15 <br> R16 R17 <br> R18 R19 <br> R20 R21 <br> R22 R23 <br> R24 R25 <br> R26 |  |  |

Table 8. CPU board components (continued)

| Component | Designator | Footprint | Description |
| :--- | :--- | :--- | :--- |
| Resistor | R1 R53 | 0805 | Resistor 0805 121k ohm 0.1\% 0.1W |
| Resistor | R55 R56 <br> R57 | 0603 | Resistor 0603 150 Kohm 1\% 0.1W |
| Resistor | R39 R40 | 0603 | Resistor 0603 150 ohm 1\% 0.1W |
| Resistor | R75 | 0603 | Resistor 0603 330 ohm 1\% 0.1W |
| Resistor | R58 | 0603 | Resistor 0603 390k ohm 1\% 0.1W |
| Resistor | R8 R9 | 0603 | Resistor 0603 470 ohm 1\% 0.1W |
| Capacitor | C90 | 0603 | Ceramic capacitor 470 pF 10\% 50V X7R 0603 |
| Resistor | R41 | 0603 | Resistor 0603 680 ohm 1\% 0.1W |
| Battery | U8 | BR2032 | BATT BR2032: Coin type Lithium batterie 3V straight d20mm |
| Ferrite bead | FB3 FB4 <br> FB5 FB6 | FB7 | F85 |

Table 8. CPU board components (continued)

| Component | Designator | Footprint | Description |
| :--- | :--- | :--- | :--- |
| Connector | J12 J13 | MIS-038 | SAMTEC-MIS-038; SAMTEC MIS series 76pin 0.64mm pitch |
| Rectifier | D4 | DPAK | SCR TS420-B_1; Schottky barrier rectifier 1A 60V SMD |
| Embedded <br> microprocessor | U1 | SG-BGA-6004 | SPEAR300; STmicroelectronics Spear330 |
| Power distribution <br> switch | U4 | SO8 | ST2052; STm Current limited power distribution switches |
| RS-232 driver <br> and receiver | U12 | SO16 | ST3232C; STm RS-232 driver and receiver |
| Voltage regulator | U9 | SOT223 | ST LD1117S25TR; STm low drop fixed positive voltage <br> regulator 2.5V 800mA |
| Reset circuit | U7 | SOT143-4 | STM811; STm Reset generator and power monitor 3.3V <br> SOT143-4 |
| Voltage regulator | U10 | VFQFPN-48 | ST PM6641; STm DDR2/3 Voltage Regulator 48pin VFQFPN |
| Connector | J5 J6 J7 <br> J8 J9 | 2X1-2.54-MD | STRIP-2X1-2.54-MD; Strip vertical male 2X1 2.54mm |
| Connector | J22 | 2X2-2.54-MD | STRIP-2X2-2.54-MD; Strip vertical male 2X2 2.54mm |
| Connector | J20 J21 | 3X1-2.54-MD | STRIP-3X1; Strip vertical male 3X1 2.54mm |
| Overvoltage <br> protection | U16 | TDFN-10 | ST STBP120C; STm overvoltage protection device Vout max <br> $5.5 V$ |
| ESD <br> protection circuit | U13 U14 <br> U15 | SOT23-6L | ST USBLC6-2SC6; STm USB 2.0 ESD protections |
| Switch | P1 | SW-PB-SMD6x6.6 | SW-PB-SMD; Mechanical key switch SMD 6x6.6mm <br> h4.3mm |
| Connector | J2 | USB-A-RA-DB | USB A-TYPE RA DOUBLE; USB double A-type connector <br> right angle |
| Connector | J1 | USB-B-RA-1 | USB B-TYPE RA SH; USB B-type connector right angle |
| Ferrite bead | FB1 FB2 | 0805 | WURTH 742792023; Ferrite Wurth 742792023 SMD 500mA |

## 6 Schematics

Figure 5. Schematic interconnections


In Figure 5:

- 02: DDR2 intrface and power
- 03: USB interface
- 04: Miscellaneous (serial flash, RTC power, boot options, JTAG, reset)
- 05: Power supply
- 06: PL_GPIO interface, extended boot options
- 07: Daughterboard and UART connectors

Figure 6. DDR interface schematic


Figure 7. USB interface schematic


Figure 8. USB power and optional part schematic

## USB Power





Figure 10. Power supply schematic



Figure 12. Daughterboard interface schematic


Figure 13. Schematic revision history


## $7 \quad$ Board layout

Figure 14. SPEAr320 CPU evaluation board layout (top view)


Figure 15. SPEAr320 CPU evaluation board layout (bottom view)


## 8 Revision history

### 8.1 Hardware revision history

Revision 2.0 SPEAr320 CPU evaluation boards are documented in revision 1 of the EVALSPEAr320CPU user manual.

Earlier board revisions are documented in UM0842, the EVALSPEAr320PLC user manual.

### 8.2 Document revision history

Table 9. Document revision history

| Date | Revision | Changes |
| :---: | :---: | :--- |
| 22-Oct-2010 | 1 | Initial release. |

## Appendix A License agreements

## DEMO PRODUCT LICENSE AGREEMENT

By using this Demonstration Product, You are agreeing to be bound by the terms and conditions of this agreement. Do not use this Demonstration Product until You have read and agreed to the following terms and conditions. The use of the Demonstration Product implies automatically the acceptance of the following terms and conditions.

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10-Nov-2008

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[^0]:    a. With 2 jumpers (inserted) it is possible to switch between two jumper inserted vertically and two jumpers inserted horizontally. This enables the serial cable (null modem cable) to be adapted to the CPU board.

