CAS24F64

64 Kb I²C CMOS Serial EEPROM

Description

The CAS24F64 is a 64 Kb CMOS Serial EEPROM device, internally organized as 8192 words of 8 bits each.

It features a 32−byte page write buffer and supports the Standard (100 kHz), Fast (400 kHz) and Fast−Plus (1 MHz) I²C protocol.

Features

- Supports Standard, Fast and Fast−Plus I²C Protocol
- 1.7 V to 5.5 V Supply Voltage Range
- 32−Byte Page Write Buffer
- Schmitt Triggers and Noise Suppression Filters on I²C Bus Inputs (SCL and SDA)
- Low Power CMOS Technology
- 1,000,000 Program/Erase Cycles
- 100 Year Data Retention
- This Device is Pb−Free, Halogen Free/BFR Free, and RoHS Compliant

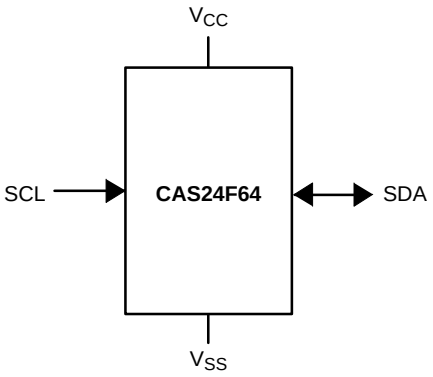

Figure 1. Functional Symbol

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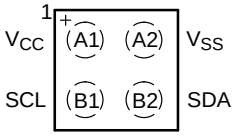
MARKING DIAGRAM

WLCSP4
C4B SUFFIX
CASE 567NH

T = Specific Device Code
Y = Year
W = Work Week

PIN CONFIGURATIONS

(Top View)



WLCSP−4

PIN FUNCTION

Pin Name	Function
SDA	Serial Data
SCL	Serial Clock
V_{CC}	Power Supply
V_{SS}	Ground

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 9 of this data sheet.

Table 1. ABSOLUTE MAXIMUM RATINGS

Parameters	Ratings	Units
Storage Temperature	–65 to +150	°C
Voltage on Any Pin with Respect to Ground (Note 1)	–0.5 to +6.5	V

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

1. The DC input voltage on any pin should not be lower than −0.5 V or higher than V_{CC} + 0.5 V. During transitions, the voltage on any pin may undershoot to no less than −1.5 V or overshoot to no more than V_{CC} + 1.5 V, for periods of less than 20 ns.

Table 2. RELIABILITY CHARACTERISTICS (Note 2)

Symbol	Parameter	Min	Units
N_{END} (Note 3)	Endurance	1,000,000	Program/Erase Cycles
T_{DR}	Data Retention	100	Years

2. These parameters are tested initially and after a design or process change that affects the parameter according to appropriate AEC−Q100 and JEDEC test methods.
3. Page Mode, V_{CC} = 5 V, 25°C.

Table 3. D.C. OPERATING CHARACTERISTICS (V_{CC} = 1.7 V to 5.5 V, T_A = −40°C to +85°C, unless otherwise specified.)

Symbol	Parameter	Test Conditions	Min	Max	Units
I_{CCR}	Read Current	Read, f_{SCL} = 1 MHz		1	mA
I_{CCW}	Write Current	Write, f_{SCL} = 1 MHz		2	mA
I_{SB}	Standby Current	All I/O Pins at GND or V_{CC}		1	μA
I_L	I/O Pin Leakage	Pin at GND or V_{CC}		2	μA
V_{IL}	Input Low Voltage	$V_{CC} \geq 2.2$ V	−0.5	V_{CC} x 0.3	V
		$V_{CC} < 2.2$ V	−0.5	V_{CC} x 0.25	V
V_{IH}	Input High Voltage	$V_{CC} \geq 2.2$ V	V_{CC} x 0.7	V_{CC} + 0.5	V
		$V_{CC} < 2.2$ V	V_{CC} x 0.75	V_{CC} + 0.5	V
V_{OL}	Output Low Voltage	$V_{CC} \geq 2.2$ V, I_{OL} = 3.0 mA		0.4	V
		$V_{CC} < 2.2$ V, I_{OL} = 1.0 mA		0.2	V

Table 4. PIN IMPEDANCE CHARACTERISTICS (V_{CC} = 1.7 V to 5.5 V, T_A = −40°C to +85°C, unless otherwise specified.)

Symbol	Parameter	Conditions	Max	Units
C_{IN} (Note 4)	SDA I/O Pin Capacitance	V_{IN} = 0 V	8	pF
C_{IN} (Note 4)	Input Capacitance (other pins)	V_{IN} = 0 V	6	pF

4. These parameters are tested initially and after a design or process change that affects the parameter according to appropriate AEC−Q100 and JEDEC test methods.

Table 5. A.C. CHARACTERISTICS (V_{CC} = 1.7 V to 5.5 V, T_A = −40°C to +85°C.) (Note 5)

Symbol	Parameter	Standard		Fast		Fast−Plus		Units
		Min	Max	Min	Max	Min	Max	
F_{SCL}	Clock Frequency		100		400		1,000	kHz
$t_{HD:STA}$	START Condition Hold Time	4		0.6		0.26		μs
t_{LOW}	Low Period of SCL Clock	4.7		1.3		0.45		μs
t_{HIGH}	High Period of SCL Clock	4		0.6		0.35		μs
$t_{SU:STA}$	START Condition Setup Time	4.7		0.6		0.26		μs
$t_{HD:DAT}$	Data In Hold Time	0		0		0		ns
$t_{SU:DAT}$	Data In Setup Time	250		100		50		ns
t_R (Note 6)	SDA and SCL Rise Time		1,000		300		100	ns
t_F (Note 6)	SDA and SCL Fall Time		300		300		100	ns
$t_{SU:STO}$	STOP Condition Setup Time	4		0.6		0.26		μs
t_{BUF}	Bus Free Time Between STOP and START	4.7		1.3		0.5		μs
t_{AA}	SCL Low to Data Out Valid		3.5		0.9		0.40	μs
t_{DH}	Data Out Hold Time	100		100		100		ns
T_i (Note 6)	Noise Pulse Filtered at SCL and SDA Inputs		50		50		50	ns
t_{WR}	Write Cycle Time		4		4		4	ms
t_{PU} (Notes 6, 7)	Power−up to Ready Mode		0.35		0.35		0.35	ms

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

5. Test conditions according to “A.C. Test Conditions” table.
6. Tested initially and after a design or process change that affects this parameter.
7. t_{PU} is the delay between the time V_{CC} is stable and the device is ready to accept commands.

Table 6. A.C. TEST CONDITIONS

Input Levels	0.20 x V_{CC} to 0.8 x V_{CC} for $V_{CC} \geq$ 2.2 V & 0.15 x V_{CC} to 0.85 x V_{CC} for V_{CC} < 2.2 V
Input Rise and Fall Times	≤ 50 ns
Input Reference Levels	0.3 x V_{CC}, 0.7 x V_{CC}
Output Reference Levels	0.5 x V_{CC}
Output Load	Current Source: I_{OL} = 3 mA ($V_{CC} \geq$ 2.2 V); I_{OL} = 1 mA (V_{CC} < 2.2 V); C_L = 100 pF

Power−On Reset (POR)

Each CAS24F64 incorporates Power−On Reset (POR) circuitry which protects the internal logic against powering up in the wrong state. The device will power up into Standby mode after V_{CC} exceeds the POR trigger level and will power down into Reset mode when V_{CC} drops below the POR trigger level. This bi−directional POR behavior protects the device against 'brown−out' failure following a temporary loss of power.

Pin Description

SCL: The Serial Clock input pin accepts the clock signal generated by the Master.

SDA: The Serial Data I/O pin accepts input data and delivers output data. In transmit mode, this pin is open drain. Data is acquired on the positive edge, and is delivered on the negative edge of SCL.

Functional Description

The CAS24F64 supports the Inter−Integrated Circuit (I^2C) Bus protocol. The protocol relies on the use of a Master device, which provides the clock and directs bus traffic, and Slave devices which execute requests. The CAS24F64 operates as a Slave device. Both Master and Slave can transmit or receive, but only the Master can assign those roles.

I^2C Bus Protocol

The 2−wire I^2C bus consists of two lines, SCL and SDA, connected to the V_{CC} supply via pull−up resistors. The Master provides the clock to the SCL line, and either the Master or the Slaves drive the SDA line. A '0' is transmitted by pulling a line LOW and a '1' by letting it stay HIGH. Data transfer may be initiated only when the bus is not busy (see A.C. Characteristics). During data transfer, SDA must remain stable while SCL is HIGH.

START/STOP Condition

An SDA transition while SCL is HIGH creates a START or STOP condition (Figure 2). The START consists of a HIGH to LOW SDA transition, while SCL is HIGH. Absent the START, a Slave will not respond to the Master. The STOP completes all commands, and consists of a LOW to HIGH SDA transition, while SCL is HIGH.

Device Addressing

The Master addresses a Slave by creating a START condition and then broadcasting an 8−bit Slave address. For the CAS24F64, the first four bits of the Slave address are set to 1010 (Ah); the next three bits, A_2, A_1 and A_0, must match the logic state of the similarly named input pins. The devices in WLCSP 4−bumps respond only to the Slave Address with A2 A1 A0 = 000. The R/$\overline{W}$ bit tells the Slave whether the Master intends to read (1) or write (0) data (Figure 3).

Acknowledge

During the 9th clock cycle following every byte sent to the bus, the transmitter releases the SDA line, allowing the receiver to respond. The receiver then either acknowledges (ACK) by pulling SDA LOW, or does not acknowledge (NoACK) by letting SDA stay HIGH (Figure 4). Bus timing is illustrated in Figure 5.

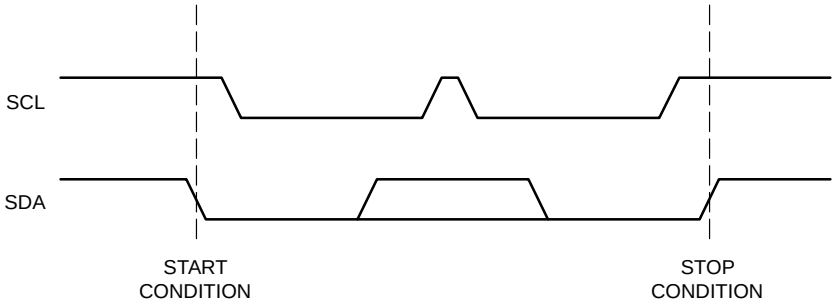
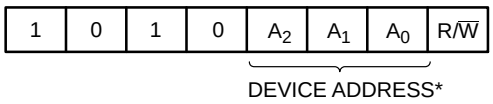


Figure 2. Start/Stop Timing



* The devices in WLCSP 4−bumps respond only to the Slave Address with A2 A1 A0 = 000.

Figure 3. Slave Address Bits

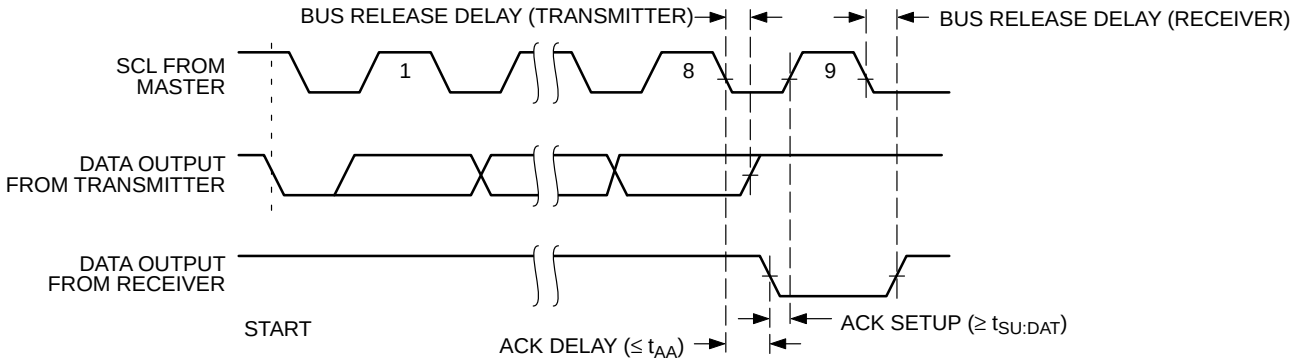


Figure 4. Acknowledge Timing

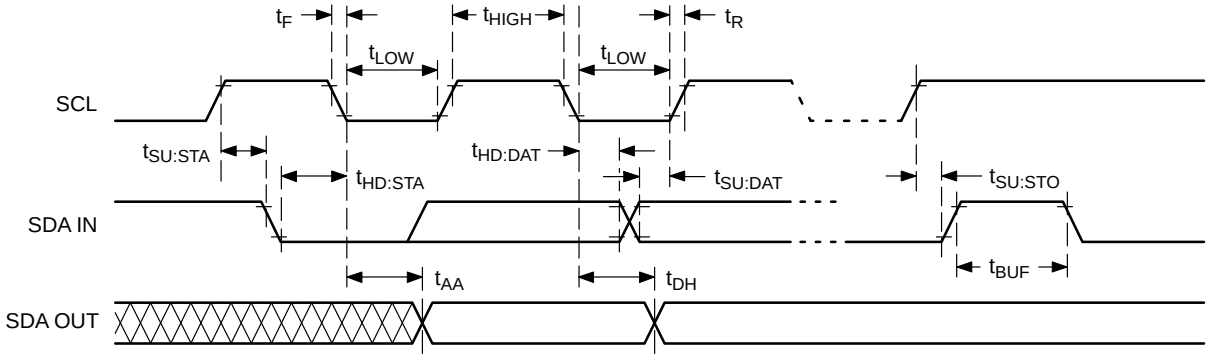


Figure 5. Bus Timing

WRITE OPERATIONS

Byte Write

To write data to memory, the Master creates a START condition on the bus and then broadcasts a Slave address with the R/$\overline{W}$ bit set to '0'. The Master then sends two address bytes and a data byte and concludes the session by creating a STOP condition on the bus. The Slave responds with ACK after every byte sent by the Master (Figure 6). The STOP starts the internal Write cycle, and while this operation is in progress (t_{WR}), the SDA output is tri−stated and the Slave does not acknowledge the Master (Figure 7).

Page Write

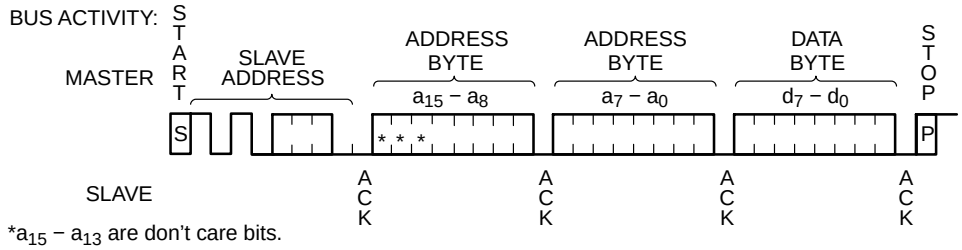
The Byte Write operation can be expanded to Page Write, by sending more than one data byte to the Slave before issuing the STOP condition (Figure 8). Up to 32 distinct data bytes can be loaded into the internal Page Write Buffer starting at the address provided by the Master. The page address is latched, and as long as the Master keeps sending data, the internal byte address is incremented up to the end of page, where it then wraps around (within the page). New data can therefore replace data loaded earlier. Following the STOP, data loaded during the Page Write session will be written to memory in a single internal Write cycle (t_{WR}).

Acknowledge Polling

As soon (and as long) as internal Write is in progress, the Slave will not acknowledge the Master. This feature enables the Master to immediately follow−up with a new Read or Write request, rather than wait for the maximum specified Write time (t_{WR}) to elapse. Upon receiving a NoACK response from the Slave, the Master simply repeats the request until the Slave responds with ACK.

Delivery State

The CAS24F64 is shipped erased, i.e., all bytes are FFh.



*a_{15} − a_{13} are don't care bits.

Figure 6. Byte Write Sequence

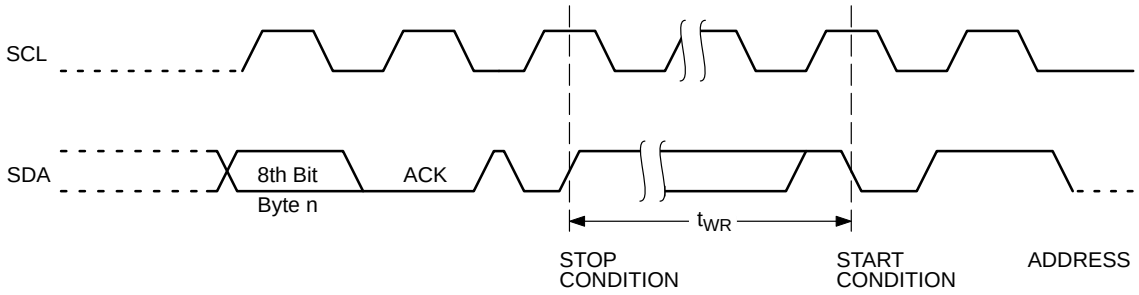


Figure 7. Write Cycle Timing

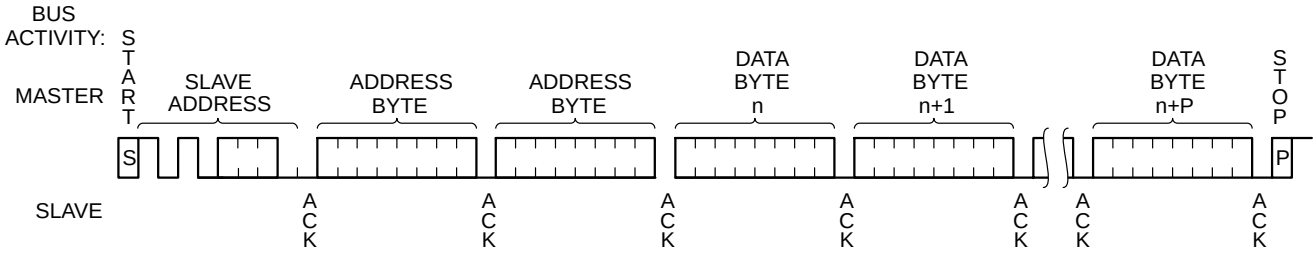


Figure 8. Page Write Sequence

READ OPERATIONS

Immediate Read

To read data from memory, the Master creates a START condition on the bus and then broadcasts a Slave address with the R/$\overline{W}$ bit set to ‘1’. The Slave responds with ACK and starts shifting out data residing at the current address. After receiving the data, the Master responds with NoACK and terminates the session by creating a STOP condition on the bus (Figure 9). The Slave then returns to Standby mode.

Selective Read

To read data residing at a specific address, the selected address must first be loaded into the internal address register. This is done by starting a Byte Write sequence, whereby the Master creates a START condition, then broadcasts a Slave address with the R/$\overline{W}$ bit set to ‘0’ and then sends two address bytes to the Slave. Rather than completing the Byte Write sequence by sending data, the Master then creates a START condition and broadcasts a Slave address with the R/$\overline{W}$ bit set to ‘1’. The Slave responds with ACK after every byte sent by the Master and then sends out data residing at the selected address. After receiving the data, the Master responds with NoACK and then terminates the session by creating a STOP condition on the bus (Figure 10).

Sequential Read

If, after receiving data sent by the Slave, the Master responds with ACK, then the Slave will continue transmitting until the Master responds with NoACK followed by STOP (Figure 11). During Sequential Read the internal byte address is automatically incremented up to the end of memory, where it then wraps around to the beginning of memory.

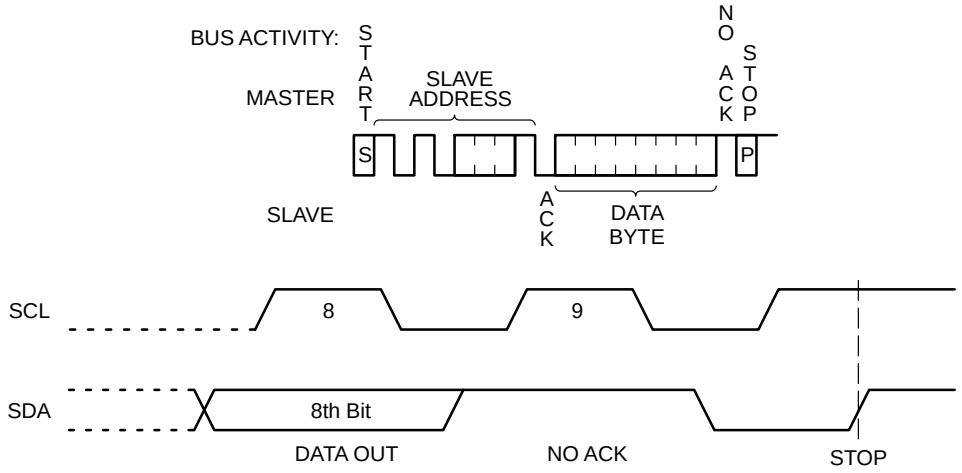


Figure 9. Immediate Read Sequence and Timing

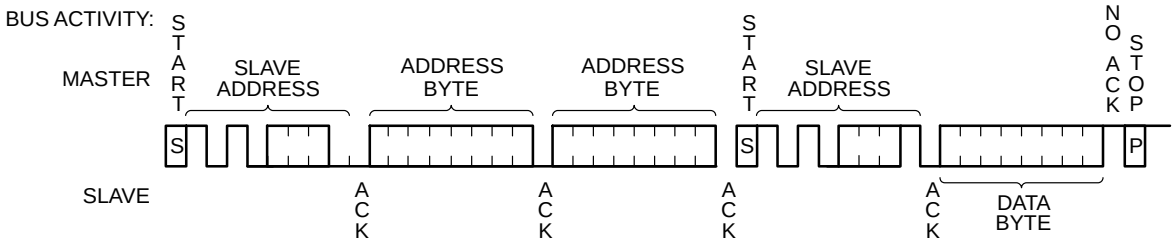


Figure 10. Selective Read Sequence

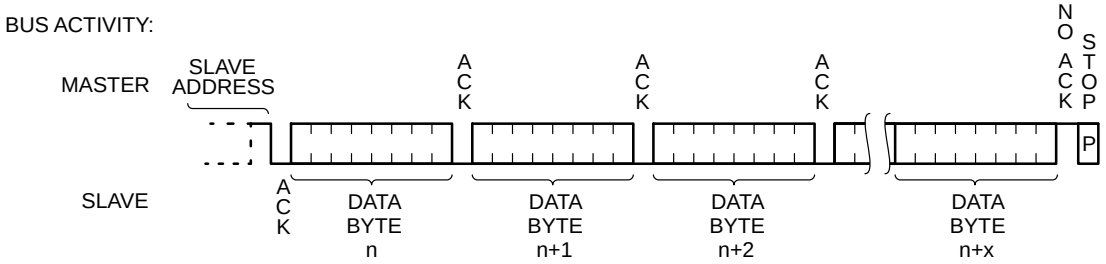
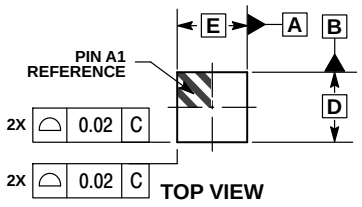
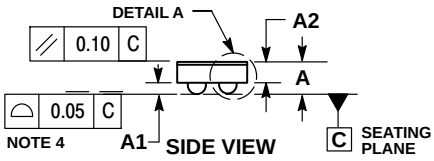


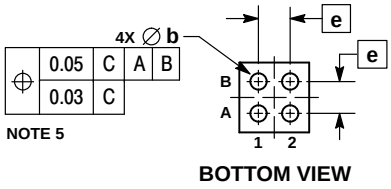
Figure 11. Sequential Read Sequence

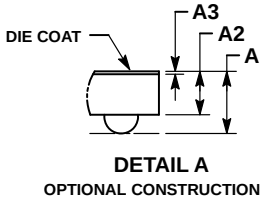
PACKAGE DIMENSIONS

WLCSP4 0.77x0.77, 0.35P
CASE 567NH
ISSUE O





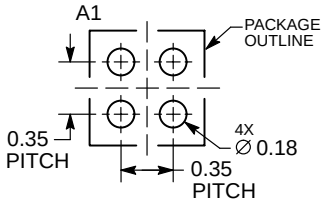




NOTES:
1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
2. CONTROLLING DIMENSION: MILLIMETERS.
3. DATUM C, THE SEATING PLANE, IS DEFINED BY THE SPHERICAL CROWNS OF THE CONTACT BALLS.
4. COPLANARITY APPLIES TO SPHERICAL CROWNS OF CONTACT BALLS.
5. DIMENSION b IS MEASURED AT THE MAXIMUM CONTACT BALL DIAMETER PARALLEL TO DATUM C.

	MILLIMETERS	
DIM	MIN	MAX
A	0.28	0.38
A1	0.08	0.12
A2	0.23 REF	
A3	0.025 REF	
b	0.16	0.20
D	0.77 BSC	
E	0.77 BSC	
e	0.35 BSC	

RECOMMENDED SOLDERING FOOTPRINT*



DIMENSIONS: MILLIMETERS

*For additional information on our Pb−Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

ORDERING INFORMATION

Device Order Number	Specific Device Marking	Package Type	Temperature Range	Lead Finish	Shipping
CAS24F64C4BTR	T	WLCSP−4	(−40°C to +85°C)	SnAgCu	Tape & Reel, 5,000 Units / Reel

8. All packages are RoHS−compliant (Lead−free, Halogen−free).
9. For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.
10. **Caution: The EEPROM devices delivered in WLCSP must never be exposed to ultra violet light. When exposed to ultra violet light the EEPROM cells lose their stored data.**

ON Semiconductor is licensed by Philips Corporation to carry the I^2C Bus Protocol.

PUBLICATION ORDERING INFORMATION

LITERATURE FULFILLMENT:
Literature Distribution Center for ON Semiconductor
19521 E. 32nd Pkwy, Aurora, Colorado 80011 USA
Phone: 303−675−2175 or 800−344−3860 Toll Free USA/Canada
Fax: 303−675−2176 or 800−344−3867 Toll Free USA/Canada
Email: orderlit@onsemi.com

N. American Technical Support: 800−282−9855 Toll Free USA/Canada
Europe, Middle East and Africa Technical Support:
Phone: 421 33 790 2910
Japan Customer Focus Center
Phone: 81−3−5817−1050

ON Semiconductor Website: **www.onsemi.com**

Order Literature: http://www.onsemi.com/orderlit

For additional information, please contact your local Sales Representative

CAS24F64/D