CAT4106

LED Driver, 4-Channel, 6 Watt with Diagnostics

ON Semiconductor®

Description

The CAT4106 is an integrated multi−channel LED driver and high power DC/DC converter suitable for powering backlighting applications up to a total of 6 watts. Up to four matched LED strings can be accurately programmed with uniform drive current set by a single external resistor. Each output channel is suitable for LED string voltages of up to 36 V. The driver automatically adjusts the output voltage to drive the highest forward voltage string with the minimum headroom voltage maximizing the efficiency.

High resolution dimming control is achieved by the EN/PWM logic pin which supports multiple frequencies. This ensures precise PWM dimming control while the device remains fully biased. In addition, when held at logic low, the device to enter a full shutdown "zero" current mode.

External programming resistors set the minimum and maximum voltage limits for the acceptable "window of operation" for LED strings. Any channel which fails to regulate within the window (Open or Short LED) is detected and flagged on the FAULT logic output (active low, open−drain).

The device is available in a 16−lead TQFN 4 mm x 4 mm and TSSOP with exposed pad packages.

Features

- Four LED Channels with Tight Current Matching
- Integrated DC/DC Boost Converter
- Up to 6 W LED Total Output Power
- Up to 92% Efficiency
- Low Dropout LED Channels (500 mV at 175 mA)
- High Frequency PWM Interface (up to 2 kHz)
- Adjustable Short/Open LED Detection
- Programmable LED Channel Current
- Adjustable LED Channel Voltage
- Thermal Shutdown Protection
- 16−lead TQFN 4 x 4 mm and TSSOP Packages
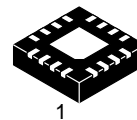- These Devices are Pb−Free, Halogen Free/BFR Free and are RoHS Compliant

Applications

- LCD Backlight Lighting
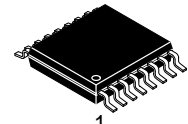- Automotive and General Purpose Lighting

TQFN−16
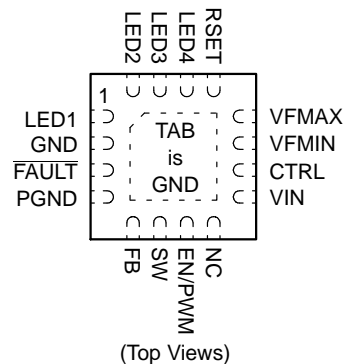**HV4 SUFFIX**
CASE 510AE

TSSOP−16
YP SUFFIX
CASE 948AP

PIN CONNECTIONS

LED1	LED2
GND	LED3
FAULT	LED4
PGND	RSET
FB	VFMAX
SW	VFMIN
EN/PWM	CTRL
NC	VIN

TAB is GND

(Top Views)
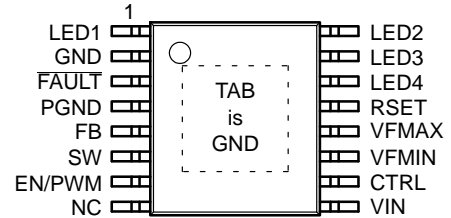
MARKING DIAGRAMS
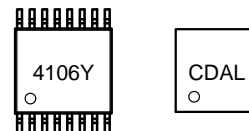
4106Y

CDAL

CDAL = CAT4106HV4−GT2
4106Y = CAT4106YP−T2

ORDERING INFORMATION

Device	Package	Shipping
CAT4106HV4−GT2 (Note 1)	TQFN−16 (Pb−Free)	2,000/ Tape & Reel
CAT4106YP−T2 (Note 1)	TSSOP−16 (Pb−Free)	2,000/ Tape & Reel

1. NiPdAu Plated Finish (RoHS−compliant)
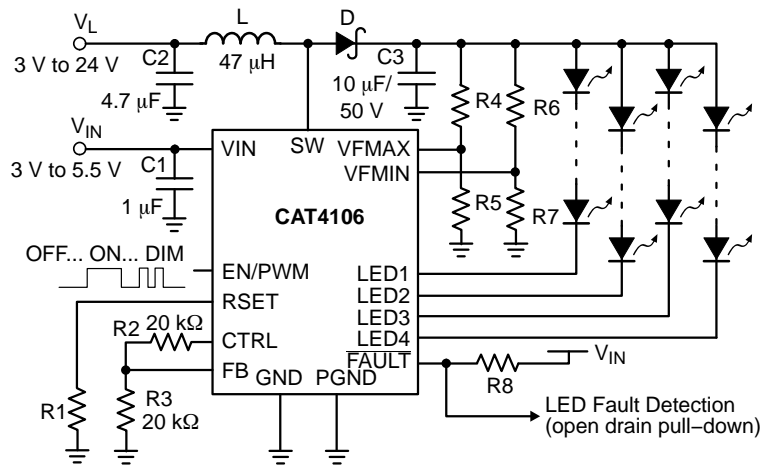2. Matte−Tin Plated Finish (RoHS−compliant)

June, 2014 – Rev. 4

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Figure 1. Typical Application Circuit

Table 1. ABSOLUTE MAXIMUM RATINGS

Parameters	Ratings	Units
VIN, RSET, EN/PWM, CTRL, FB, FAULT	−0.3 V to 6	V
VFMIN, VFMAX	−0.3 V to 6	V
LED1, LED2, LED3, LED4	−0.3 V to 25	V
SW (internally clamped to 40 V)	50	V
Storage Temperature Range	−65 to +150	°C
Junction Temperature Range	−40 to +150	°C
Lead Temperature	300	°C

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

Table 2. RECOMMENDED OPERATING CONDITIONS

Parameter	Range	Units
VIN	3.0 to 5.5	V
Inductor Drive Voltage	3.0 to 24	V
LED String Forward Voltage per channel	up to 36	V
Ambient Temperature Range	−40 to +85	°C
I_{LED} per LED pin	10 to 175	mA

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.
3. Typical application circuit with external components is shown above.

Table 3. RECOMMENDED EN/PWM TIMING
(For $3.0 \leq$ VIN ≤ 5.5 V, over full ambient temperature range −40 to +85°C.)

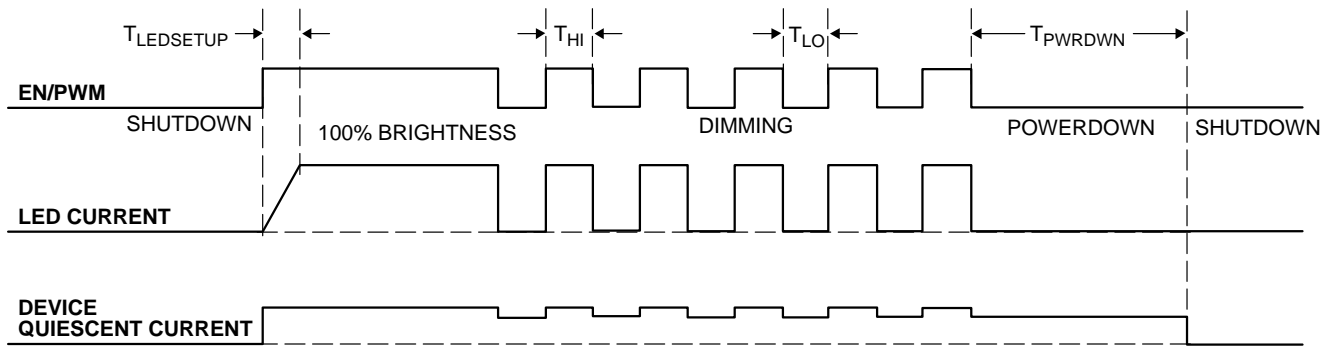| Symbol	Name	Conditions	Min	Typ	Max	Units
$T_{LEDSETUP}$	LED setup time from shutdown		10	40	100	µs
T_{LO}	EN/PWM low time		0.2		2000	µs
T_{HI}	EN/PWM high time		100			µs
T_{PWRDWN}	EN/PWM low time to shutdown delay				8	ms
T_{LEDSET}	LED current settling time	I_{LED} = 100 mA		0.2		µs

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Figure 2. CAT4106 EN/PWM Timing

Table 4. ELECTRICAL OPERATING CHARACTERISTICS

VIN = 5 V, VL (inductor drive voltage) = 12 V, T_{AMB} = 25°C (over recommended operating conditions unless specified otherwise)

Symbol	Description	Conditions	Min	Typ	Max	Units
I_Q	VIN Operating Current	Switching (I_{LED} = 30 mA) Not Switching (I_{LED} = 30 mA) Switching (I_{LED} = 60 mA) Not Switching (I_{LED} = 60 mA)		2.5 2.0 3.4 2.9	3.5 3.0 4.4 3.9	mA
I_{SD}	VIN input shutdown Current	V_{EN} = 0 V			1	μA
V_{IH} V_{IL} R_{EN}	**EN/PWM** Logic High Threshold Logic Low Threshold Internal Pull−Down Resistor	Device Enable Level Disable/PWM Level	 0.4 100	0.8 0.7 200	1.3 300	V V kΩ
V_{UVLO}	Undervoltage lockout (UVLO)	VIN pin voltage		2.0		V
T_{SD}	Thermal Shutdown Threshold			150		°C
T_{HYS}	Thermal Hysteresis			20		°C
V_{RSET}	RSET regulation voltage	10 μA < I_{RSET} < 2 mA	1.17	1.20	1.23	V
I_{LED}/I_{RSET}	RSET to LED Current gain ratio	30 mA LED current		100		
V_{DO}	LED Channel Dropout Voltage	I_{LED} = 175 mA		0.5		V
ΔI_{LED}	LED Channel Matching	0.5 V < V_{LED} < 5 V	−5	±1	+5	%
$I_{LED-OFF}$	LED Channel leakage	Channel is Off			1	μA
V_{VFMAX}	O/C Detect voltage threshold		1.15	1.20	1.25	V
V_{VFMIN}	S/C Detect voltage threshold		1.15	1.20	1.25	V
V_{CTRL} I_{CTRL}	CTRL pin voltage accuracy CTRL pin maximum load	Offset to Lowest LED output	− 0.1 25	0	+ 0.1	V μA
$\overline{I_{FAULT}}$	Pull−down Drive Current Open Drain Leakage Current	$\overline{FAULT}$ is Active (0.1 V bias) $\overline{FAULT}$ is Inactive	1	2	 1	mA μA
V_{FB} I_{FB}	FB Pin control voltage FB pin input leakage current	Normal switching mode regulation	285	300	315 1	mV μA
F_{SW} I_{SWMAX} R_{SW} DC_{MAX} DC_{MIN} I_{SWLEAK} OVP_{SW}	**SW Pin** Switching Frequency Switch Pin Current Limit Switch Pin On−resistance Maximum Duty Cycle Minimum Duty Cycle Switch Leakage Current Over Voltage Protection Detect	 I_{SW} = 500 mA Prior to Current Limiting Prior to Pulse−Skipping V_{SW} = 20 V Enters Low Power mode	0.7 0.8	1.0 1.0 1.0 96 5 40	1.3 5	MHz A Ω % % μA V

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

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Figure 3. Quiescent Current vs. RSET Current

Figure 4. RSET Voltage vs. VIN Supply

Figure 5. RSET Voltage vs. Temperature

Figure 6. I_{LED}/I_{RSET} Gain vs. LED Current

Figure 7. LED Channel Current vs. LED Pin Voltage

Figure 8. LED Channel Current vs. VIN Supply

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TYPICAL ELECTRICAL OPERATING CHARACTERISTICS

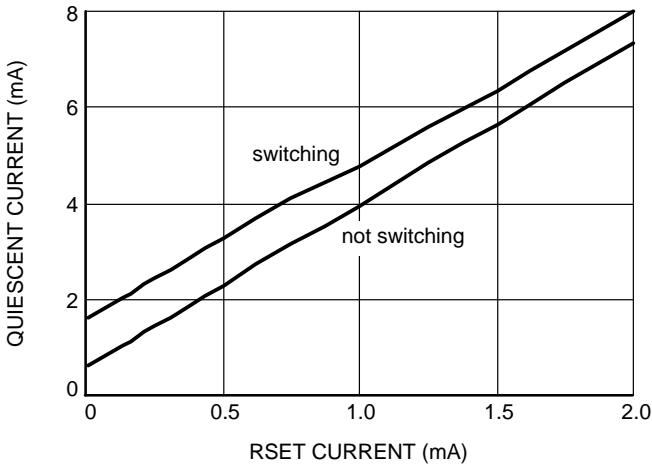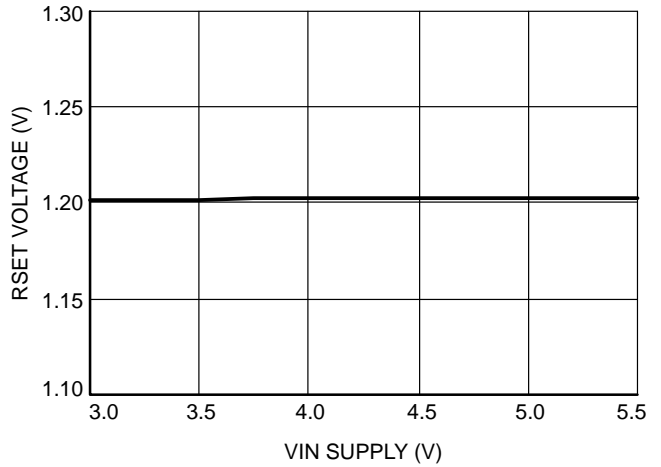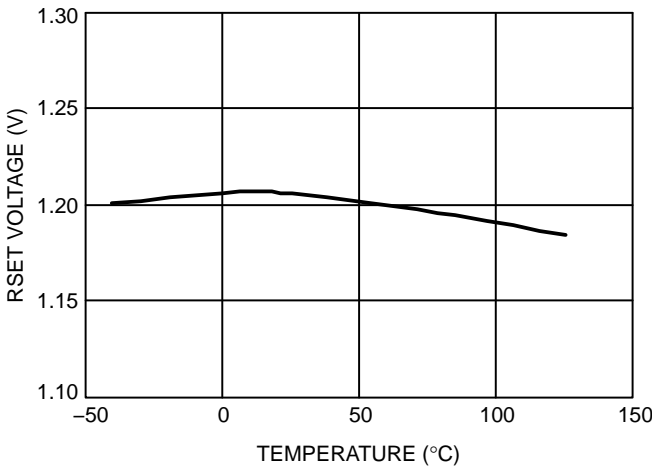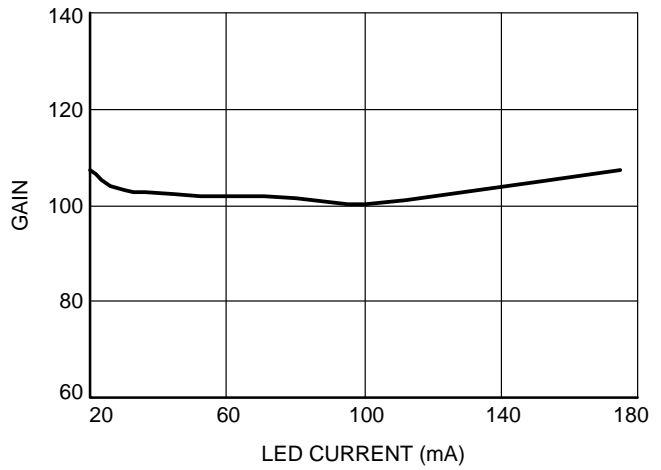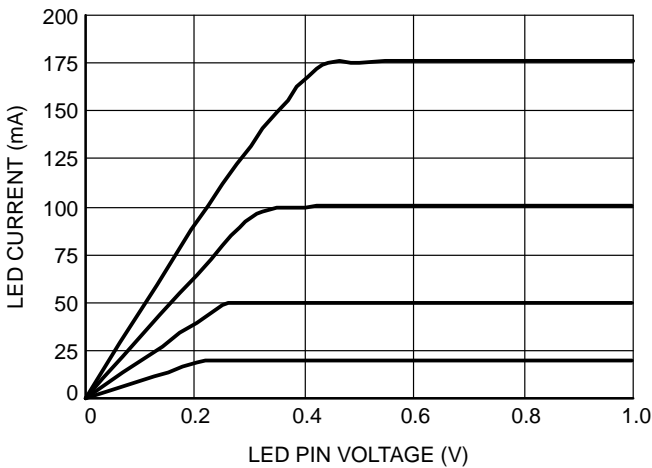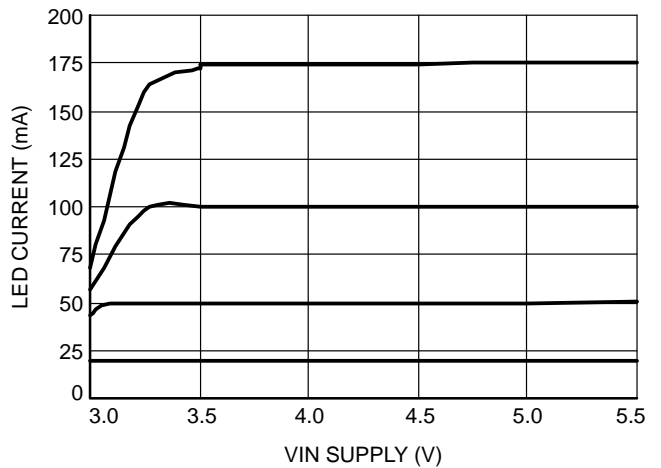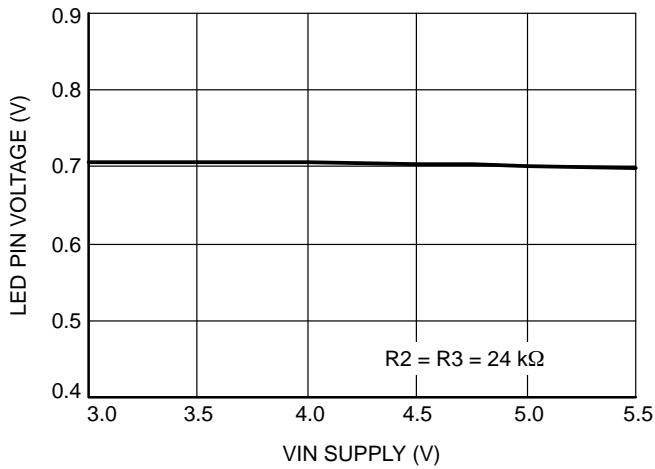(VIN = 5 V, VL = 12 V, T_{AMB} = 25°C, typical application circuit unless otherwise specified.)
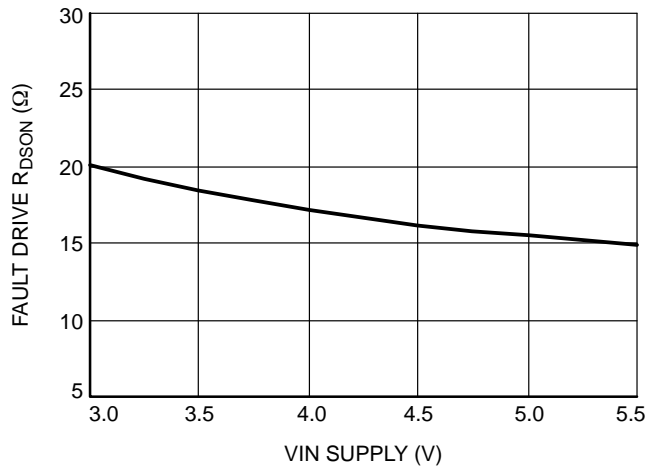
Figure 9. LED Channel Voltage vs. VIN Supply

Figure 10. FAULT Drive R_{DSON} vs. VIN Supply
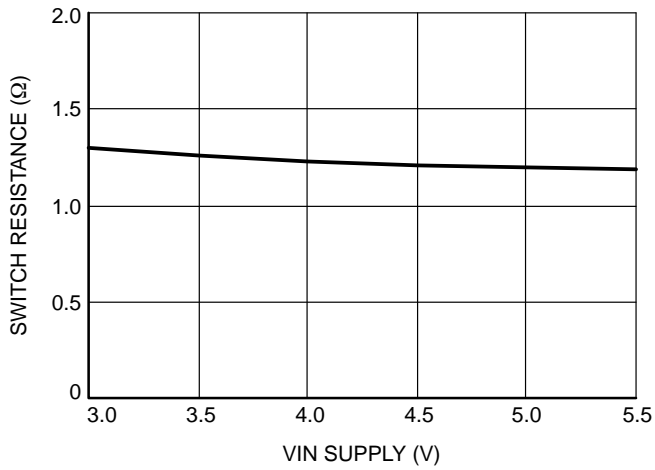
Figure 11. Switch Resistance vs. VIN Supply
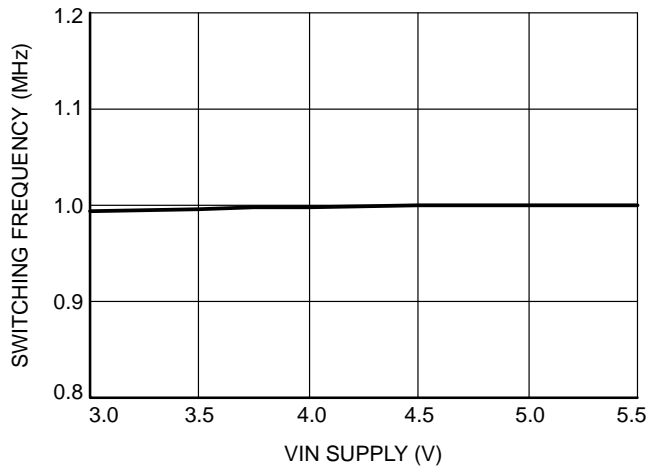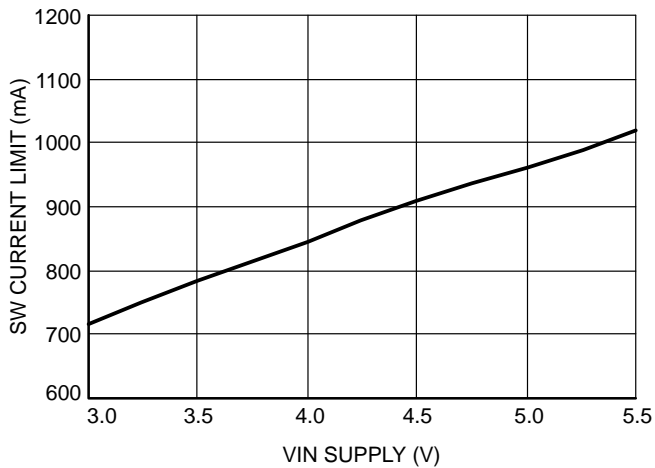
Figure 12. Switching Frequency vs. VIN Supply
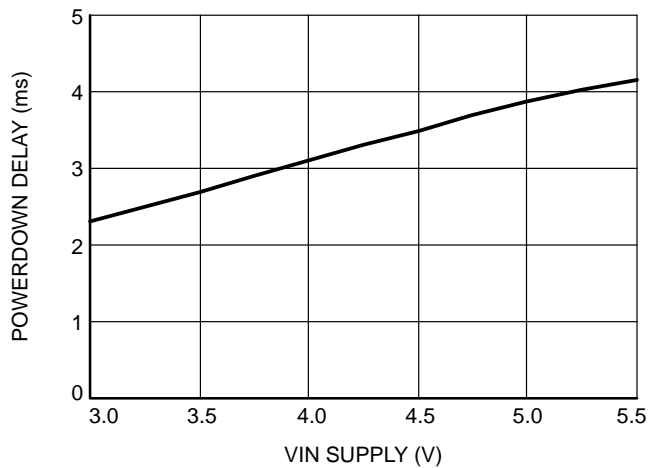
Figure 13. Switching Current Limit vs. VIN Supply

Figure 14. Powerdown Delay vs. VIN Supply

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TYPICAL ELECTRICAL OPERATING CHARACTERISTICS

(VIN = 5 V, VL = 12 V, T_{AMB} = 25°C, typical application circuit unless otherwise specified.)
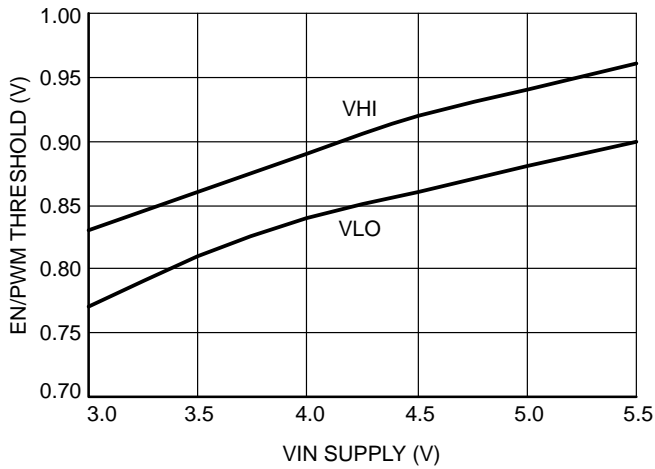

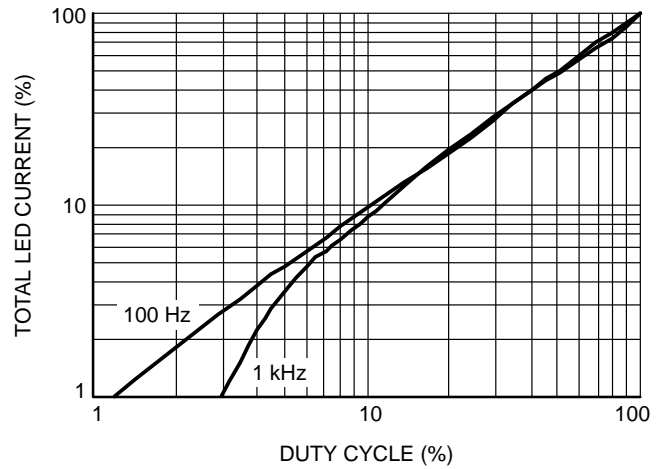Figure 15. EN/PWM Threshold vs. VIN Supply
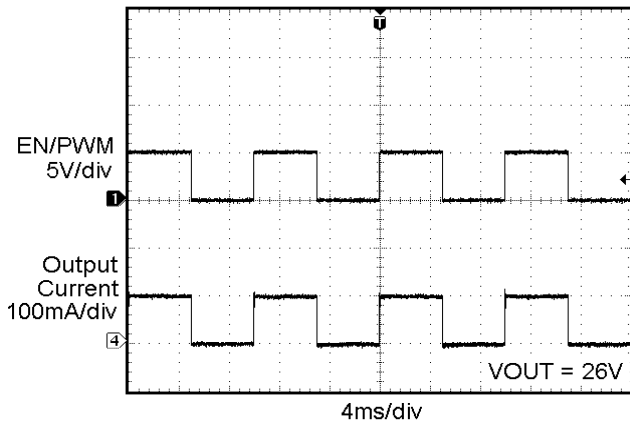

Figure 16. PWM Duty Cycle vs. LED Current

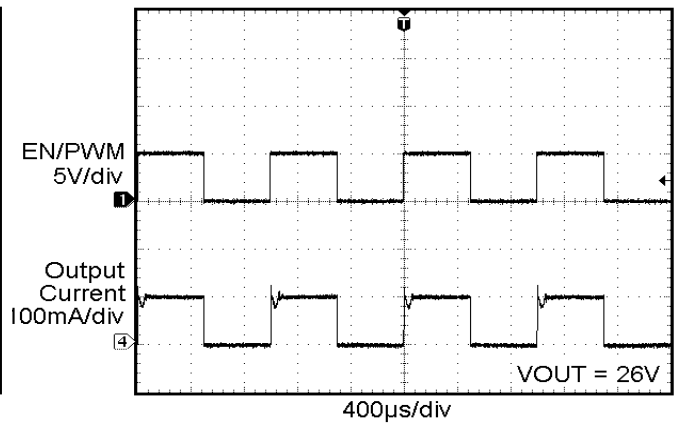Figure 17. PWM Dimming 100 Hz

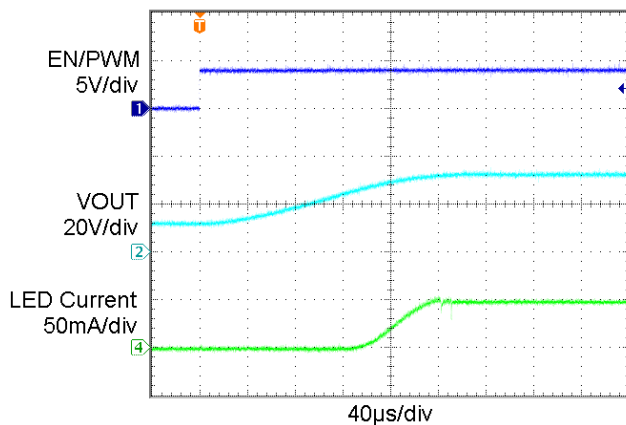Figure 18. PWM Dimming 1 kHz

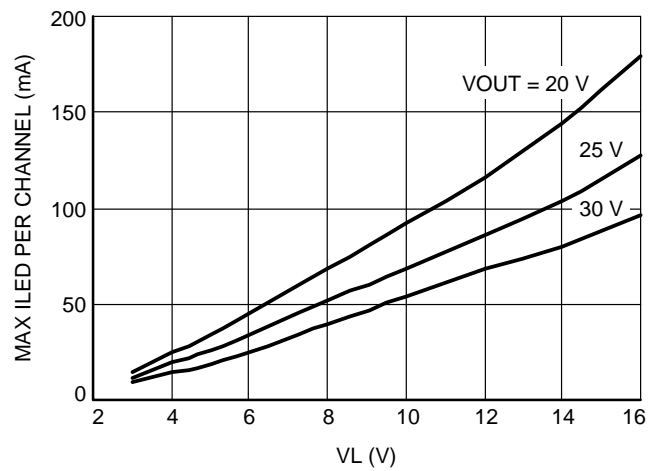Figure 19. Power−Up 4 x 10 LEDs, 50 mA per Channel

Figure 20. Maximum LED Current vs. VL Supply

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TYPICAL ELECTRICAL OPERATING CHARACTERISTICS

(VIN = 5 V, VL = 12 V, 20 mA per channel (80 mA total output current), T_{AMB} = 25°C, typical application circuit unless otherwise specified.)
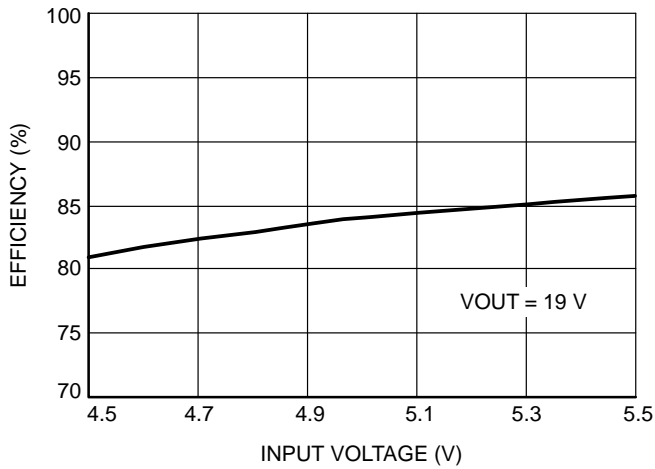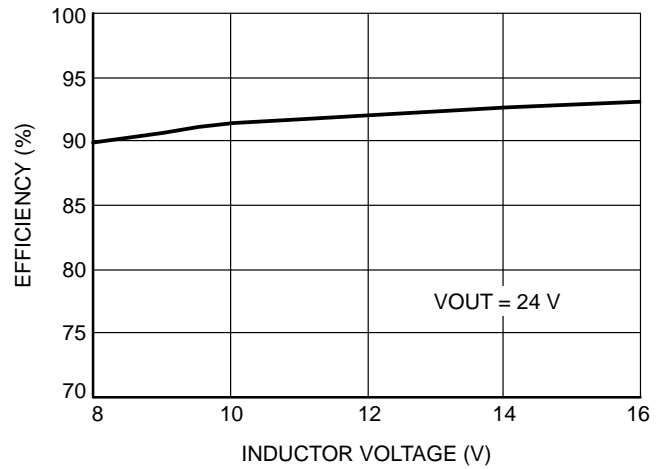
Figure 21. Efficiency vs. VIN (VIN = VL)
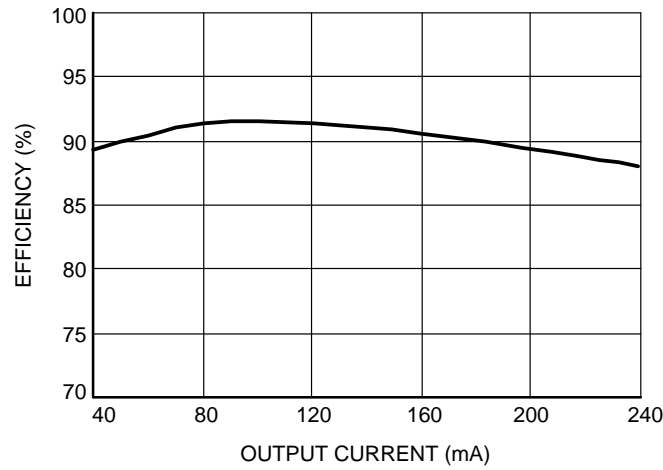
Figure 22. Efficiency vs. VL (VIN = 5 V)

Figure 23. Efficiency vs. Output Current
(9−LED String)

Table 5. PIN DESCRIPTION

Name	TQFN−16 TSSOP−16	Function
LED1	1	LED1 cathode terminal
GND	2	Signal Ground reference
$\overline{\text{FAULT}}$	3	Open/Short LED Fault detection output (active−low)
PGND	4	Power Ground Reference (DC/DC Power Switch)
FB	5	Feedback reference (300 mV) for setting LED channel operating voltage
SW	6	Internal power FET switch drain connection
EN/PWM	7	Device Enable (active high) and PWM control input
N.C.	8	Not connected
VIN	9	Supply voltage for the device
CTRL	10	LED channel operating voltage (lowest of all 4 channels)
VFMIN	11	Comparator input for setting the LED string short−circuit voltage limit
VFMAX	12	Comparator input for setting the LED string open−circuit voltage limit
RSET	13	RSET resistor pin for setting the LED channel operating current
LED4	14	LED4 cathode terminal
LED3	15	LED3 cathode terminal
LED2	16	LED2 cathode terminal
TAB	TAB	Thermal pad (connect to GND and PGND)

Pin Descriptions

VIN is the supply pin for the device. The supply input current needed for normal operation is approximately 2 mA plus 3 times I_{RSET} pin current. During intervals of PWM dimming, or whenever the converter is not switching, the supply current will decrease by around 1 mA. The voltage applied at VIN should be kept between 3 V and 5.5 V. A small ceramic bypass capacitor of 0.1 μF or greater is recommended to be in close proximity to the VIN pin.

EN/PWM is the device Enable and PWM dimming control input for all LED channels. Guaranteed levels of logic high and logic low are set at 1.3 V and 0.4 V respectively. During normal PWM dimming, the entire device remains fully biased and only the LED channels are pulsed on/off. The device will only enter zero current shutdown mode after the EN/PWM is help low for at least 5 ms typically. This pin has an internal pull−down resistor of 200 kΩ.

RSET is the voltage regulated control pin for sensing the desired programming current level to be applied on all LED channels. During normal operation, the RSET pin is kept at 1.2 V and accurately monitors the current level in the externally applied R1 resistor. The current transfer ratio from RSET pin current to LED pin current is 100.

LED1 to LED4 provide the regulated current source for driving each of the LED strings with a tightly matched constant current. To ensure optimal performance, the bias voltage on the LED channels should be set at a nominal 0.6 V or higher. Each channel is capable of driving a current

up to 175 mA. All channels immediately enter a high impedance mode whenever the EN/PWM is taken LOW.

CTRL pin is a multiplexer output which selects the lowest operating voltage appearing on any of the four LED output drive channels. This control signal represents the cathode terminal voltage of the LED string with greatest forward voltage (V_F). An external resistor network from CTRL to FB can be used to set the lowest operating voltage of each channel. External current loading of the CTRL pin is recommended to be less than 25 μA.

FB is the voltage feedback control pin for the internal high power DC/DC converter. This pin has a high impedance input and its voltage remains accurately regulated to 0.3 V during normal steady state operation.

SW pin is the drain terminal of the high voltage CMOS power switch which has a typical on−resistance of 1 Ω and is current limited to 1 A typically. An overvoltage protection circuit places the device in a soft−clamping low power mode if the voltage transients exceed 40 V.

VFMIN pin uses a pair of external resistors (R6 & R7) to program the worst case, minimum LED string forward voltage (V_{FMIN}) expected in the specific application. If any LED string enters full regulation before the output voltage reaches V_{FMIN}, the output will continue to rise to V_{FMIN} where it will signal an LED short−circuit and a fault condition will be flagged. The detection only works during

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power−up and works best when V_{FMIN} is set at least twice the value of V_L. The VFMIN input circuitry consists of a comparator referenced to 1.2 V. A typical value for resistor R7 is around 20 kΩ. R6 can be calculated as follows:

$$R6 = R7 \times \left(\frac{V_{FMIN}}{1.2\ V} - 1\right)$$

If this detection feature is not needed, the VFMIN pin must be tied to ground.

VFMAX pin uses a pair of external resistors (R4 & R5) to program the worst case, maximum LED string forward voltage (V_{FMAX}) expected in the specific application. If any LED string fails to become regulated before the programmed voltage is reached, the string will be considered to contain LEDs which are open−circuit and a fault condition will be flagged. When an open−circuit is flagged, the individual channel that causes the open−circuit is internally flagged and subsequently ignored. In the event that all channels are detected as being Open−LED, the Output Voltage (top LED Anode) will stabilize at the V_{FMAX} programmed voltage. The VFMAX input circuitry consists of a comparator referenced to 1.2 V.

A typical value for resistor R5 is 20 kΩ. R4 can be calculated as follows:

$$R4 = R5 \times \left(\frac{V_{FMAX}}{1.2\ V} - 1\right)$$

If this detection feature is not needed, the VFMAX pin must be tied to ground.

$\overline{FAULT}$ is an open−drain, active−low, logic signal which becomes active during an LED short−circuit or open−circuit condition. The pin must be connected to a pull−up resistor of around 100 kΩ tied to VIN. The drive pull−down resistance (when active) is typically less than 100 Ω. The diagnostic sequence used to determine a fault condition is initiated when the device is first enabled.

PGND pin is the source connection terminal of the high voltage CMOS power switch in the DC/DC converter. The inductor supply bypass capacitor should be connected in close proximity to the PGND pin. The return current from PGND should be connected to the PCB ground plane.

GND is the ground reference pin for the device. All analog control voltages are referenced to this pin. In addition, all LED drive currents are conducted through the GND pin.

TAB is the thermal pad connection of the package and should be connected to PCB ground plane.
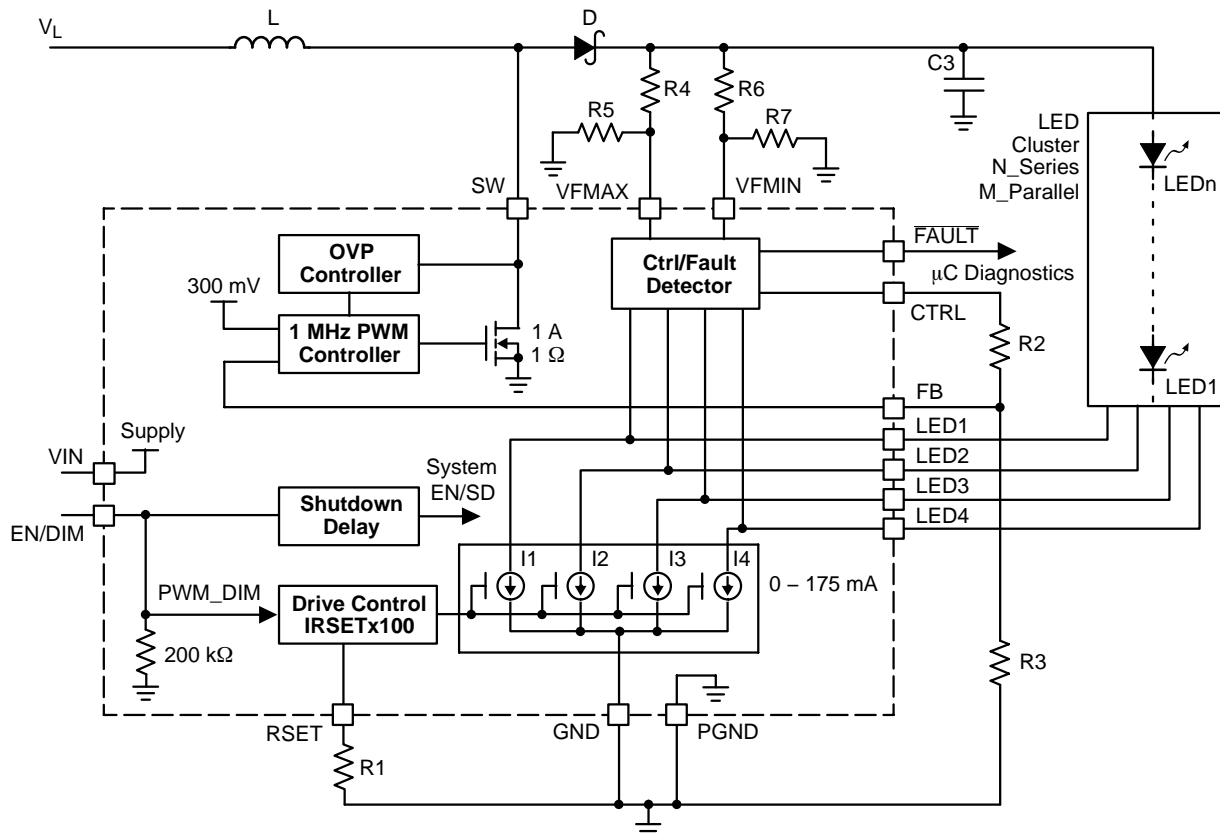
Block Diagram

Figure 24. CAT4106 Simplified Functional Block Diagram

Device Operation

In a typical application, the CAT4106 drives an LED array consisting of up to four separate strings. A single external resistor value is used to select the drive level in all output channels. Each channel provides a very well regulated and tightly matched bias current on all LED strings.

An integrated DC/DC boost converter is used to generate the high voltage output required to power the LED strings. Up to a maximum of 6 W of LED power can be delivered when powered from a 12 V supply.

To offer improved performance, the device also allows the user to set the operating voltage level on the output drive channels. A pair of external resistors is used to control the nominal channel voltage, during normal operation. The resulting output voltage (LED anodes) will be equal to the sum of the adjusted channel voltage plus the maximum forward voltage present on any string.

The CAT4106 provides four tightly matched current sinks to accurately regulate LED current in each channel. Up to 175 mA per channel can be programmed by selecting a suitable value for the external R1 resistor (connected between RSET and GND pins).

LED Current Setting

The CAT4106 provides four tightly matched current sinks to accurately regulate LED current in each channel. The LED current is set by the external resistor R1 connected between the RSET pin and ground. The following formula gives the relationship between the resistor value and the LED current per channel.

$$R1 \approx 103 \times \frac{1.2 \text{ V}}{\text{LED current per channel}}$$

Table 6. RESISTOR R1 AND LED CURRENT

LED Current per Channel (mA)	R1 (Ω)
10	12.4 k
20	6.19 k
30	4.12 k
50	2.49 k
100	1.24 k
150	820

Setting the Channel Voltage

Each LED channel typically requires less than 0.5 V of headroom for full load operation. The lowest channel operating voltage can be controlled and programmed via the external resistor network connected between, CTRL, FB and GND as shown in Figure 24.

$$\text{Lowest LED pin voltage} = V_{FB} \times \frac{R2 + R3}{R3}$$

For most applications, a gain of 2x (R2 equals R3) is recommended. The CTRL output pin has optimal performance when loaded with around 15 μA, which equates to an R3 resistor value of 20 kΩ.

LED Detection

The CAT4106 detects failure conditions related to the LED load, such as if one of the LED strings has been disconnected (Open–LED) or if one LED string has a lower LED pin voltage than expected (Short–LED). Either condition is flagged by turning on the open–drain output on the FAULT pin. The Open–LED detection is active in normal operation. The Short–LED detection is only active during power–up, just after the EN/PWM input goes from low to high. If in normal operation (LEDs are in regulation) a short–LED condition occurs, it will not be detected.
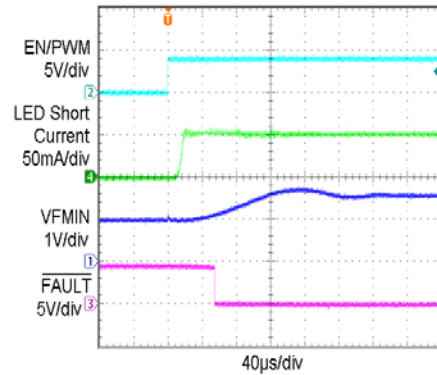

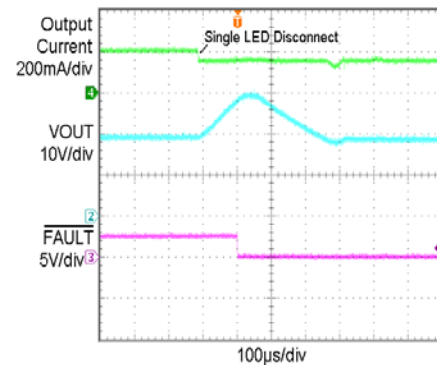**Figure 25. Cold Power–Up Short–LED Detection**

Figure 26. Normal Operation Open–LED Detection

The test condition in Figure 25 is with one LED pin shorted to the output (top LED anode). The test condition in Figure 26 is with one LED pin floating or disconnected. In both cases, the CAT4106 is set to drive 50 mA per channel.

Setting VFMIN Level (Short–LED)

The VFMIN level represents the minimum level expected for the LED string voltage "window of operation". This voltage setting is based on the number of series LEDs being used and the expected minimum forward voltage V_F during normal operation.

Example: Consider a string of 6 LEDs in series, with each LED having a V_F range of 3.5 V ± 0.5 V. Since the minimum V_F of each LED is 3.0 V the overall lowest expected string voltage would be 18 V. Any string voltage of less than 18 V is considered as a short–circuit fault in one or more of the series LEDs.

The external resistor R6 value needed to set a VFMIN level of 18 V is calculated as follows:

$$R6 = R7 \times \left(\frac{18\,V}{1.2\,V} - 1 \right)$$

For R7 = 20 kΩ, R6 = 280 kΩ.

Setting VFMAX Level (Open−LED)

The VFMAX level represents the maximum level expected for the LED string voltage "window of operation". This voltage setting is based on the number of series LEDs being used and the expected maximum V_F during normal operation.

Example: Consider a string of 6 LEDs in series, with each LED having a V_F range of 3.5 V ± 0.5 V. Since the maximum V_F of each LED is 4.0 V, the overall maximum expected string voltage would be 24 V. Any string voltage which appears greater than 24 V would be considered as containing an open−circuit in one or more of the series LEDs. The external resistor R4 value needed to set a VFMAX level of 24 V is calculated as follows:

$$R4 = R5 \times \left(\frac{24\,V}{1.2\,V} - 1 \right)$$

For R5 = 20 kΩ, R4 = 380 kΩ.

In normal operation, the LED string which has the largest V_F will be used to set the VCTRL/VFB voltage levels. If the largest string voltage tries to exceed VFMAX setting, it will no longer be allowed to control the voltage level of VCTRL/VFB (i.e. it will be ignored) and subsequently the next largest LED string voltage will then be used in the control loop. All remaining functional LED channels will continue to operate as normal. If a disconnected LED string is reconnected, the FAULT flag remains on and the channel disabled until the device has been re−enabled with the EN pin going from low to high.

If all LED channels are detected as being open−circuit, then the boost converter will limit the output voltage to the VFMAX setting. This eliminates the need for an external protection zener.

Enable and PWM Dimming Control

EN/PWM input signal provides two independent functions. The first function is to enable and disable the entire device. The second function is to apply PWM dimming on the output channels while the chip remains fully enabled. Applying logic high on the EN/PWM input will power up the device. The device will continue to remain powered up, even in the presence of PWM signals being applied. To disable the device into complete system shutdown mode, a logic low must be applied to the EN/PWM input for typically 5 ms.

The duty cycle applied at the EN/PWM is directly applied to all the output channels. Each time the input is taken low, all output channels will immediately be switched off and the channels will resume normal operation when the PWM is taken back high. The response time of the channels when switching ON or OFF is typically 0.2 μs.

During PWM dimming, the recommended minimum pulse width interval (either High or Low) is 0.2 μs. The recommended maximum pulse width during PWM dimming is 2.0 ms, however this only applies to the Low pulse interval. Pulse durations extending past 2.0 ms may cause the device to enter full shutdown mode. The LED channel response time is longer if the device has been in shutdown mode.

For most applications, a maximum dimming resolution can be achieved with PWM clock frequencies in the range of 500 Hz to 2 kHz. Pulse width intervals of 1 μs, allows up to 1000:1 dimming ratio at 1 kHz PWM frequency.

One or Two LED String Applications

The CAT4106 can be used to drive one or two strings of LEDs by connecting together some LED pins. Also for applications requiring LED current greater than 175 mA, LED channels can be tied together, assuming the supply is suitable to drive the load. Figure 27 shows a typical application for driving a single string of LEDs. Note: VFMIN is disabled for one string.
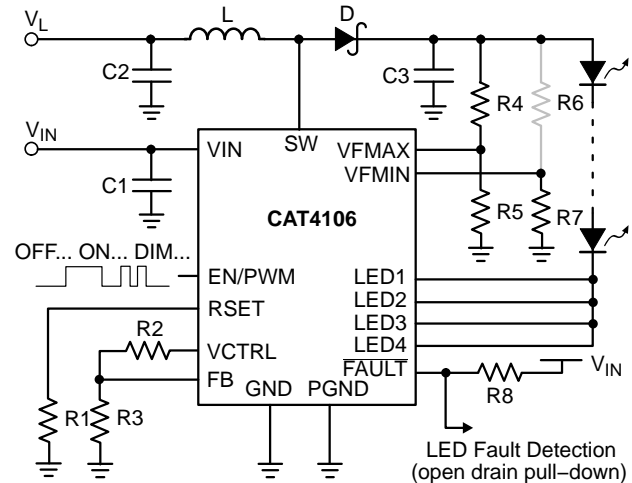

Figure 27. Application Circuit for One LED String

Figure 28 shows a typical application for driving two strings of LEDs. The LED current is equal to two times the channel current.
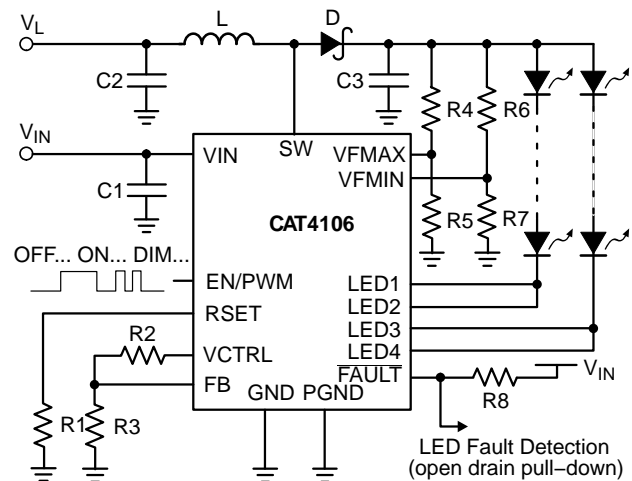

Figure 28. Application Circuit for Two LED Strings

Application Information
External Component Selection

Capacitors

The CAT4106 requires small ceramic capacitors of 1 μF on the VIN pin (C1), 4.7 μF on the inductor input (C2), and 10 μF on the output (C3). Under normal condition, a 4.7 μF input capacitor (C2) is sufficient. The voltage rating of each capacitor should be compatible with the maximum voltage applied. For the output, a 50 V rated capacitor (C3) is recommended in case the LED becomes disconnected (Open–LED condition). X5R and X7R capacitor types are ideal due to their stability across temperature range.

Inductor

A 47 μH inductor is recommended for most applications. In cases where the efficiency is critical, inductances with lower series resistance are preferred. Inductors with current rating of 1 A or higher are recommended for most applications. Coiltronics DR73–470 inductor rated at 1.08 A is recommended for most applications.

Schottky Diode

The current rating of the Schottky diode (D) must exceed the peak current flowing through it. A 1 A rated Schottky diode is recommended. The Schottky diode performance is rated in terms of its forward voltage at a given current. In order to achieve the best efficiency, this forward voltage should be as low as possible. The response time is also critical since the driver is operating at 1 MHz. NXP PMEG6010CEJ (60 V / 1 A rated) Schottky barrier rectifier is recommended for most applications.

Recommended Layout

The board layout should provide good thermal dissipation through the PCB. Multiple via can be used to connect the tab of the CAT4106 to a large ground plane underneath the package.

Input capacitor C1 should be placed as close to the driver IC as possible. The RSET resistor (R1) and channel voltage setting resistor (R3) should have a Kelvin connection to the GND pin of the CAT4106.
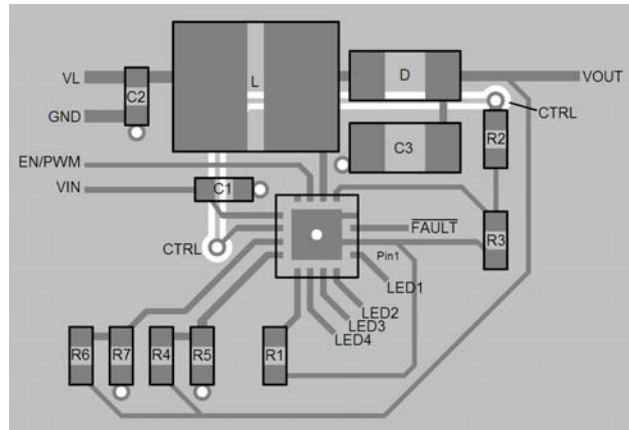
Figure 29. Recommended Layout for TQFN–16

Example of Ordering Information

4. All packages are RoHS−compliant (Lead−free, Halogen−free).
5. The standard plated finish is NiPdAu.
6. TSSOP only available in Matte−Tin plated finish.
7. For additional temperature options, please contact your nearest ON Semiconductor Sales office.
8. For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

MECHANICAL CASE OUTLINE
PACKAGE DIMENSIONS

TQFN16, 4x4
CASE 510AE–01
ISSUE A

DATE 18 MAR 2009

TOP VIEW

SIDE VIEW

BOTTOM VIEW

DETAIL A

PIN#1 ID

PIN#1 INDEX AREA
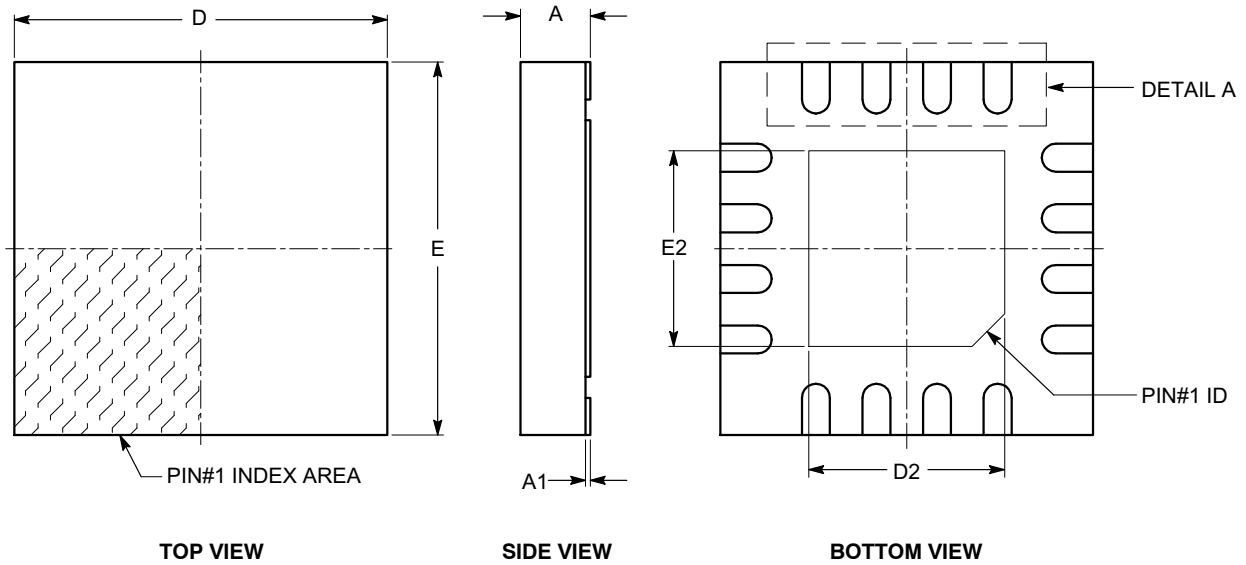
SYMBOL	MIN	NOM	MAX
A	0.70	0.75	0.80
A1	0.00	0.02	0.05
A3	0.20 REF		
b	0.25	0.30	0.35
D	3.90	4.00	4.10
D2	2.00	---	2.25
E	3.90	4.00	4.10
E2	2.00	---	2.25
e	0.65 BSC		
L	0.45	---	0.65

DETAIL A

FRONT VIEW

Notes:

(1) All dimensions are in millimeters.
(2) Complies with JEDEC MO-220.
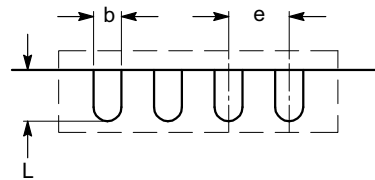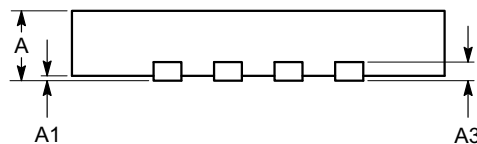
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DESCRIPTION:	TQFN16, 4X4		PAGE 1 OF 1

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TSSOP16, 4.4x5 EXPOSED PAD
CASE 948AP–01
ISSUE A

DATE 18 MAR 2009

PIN#1
IDENTIFICATION

TOP VIEW

END VIEW

EXPOSED THERMAL PAD ZONE

BOTTOM VIEW
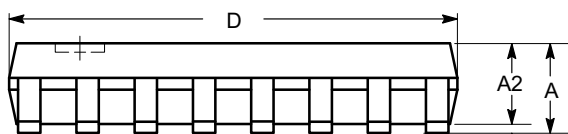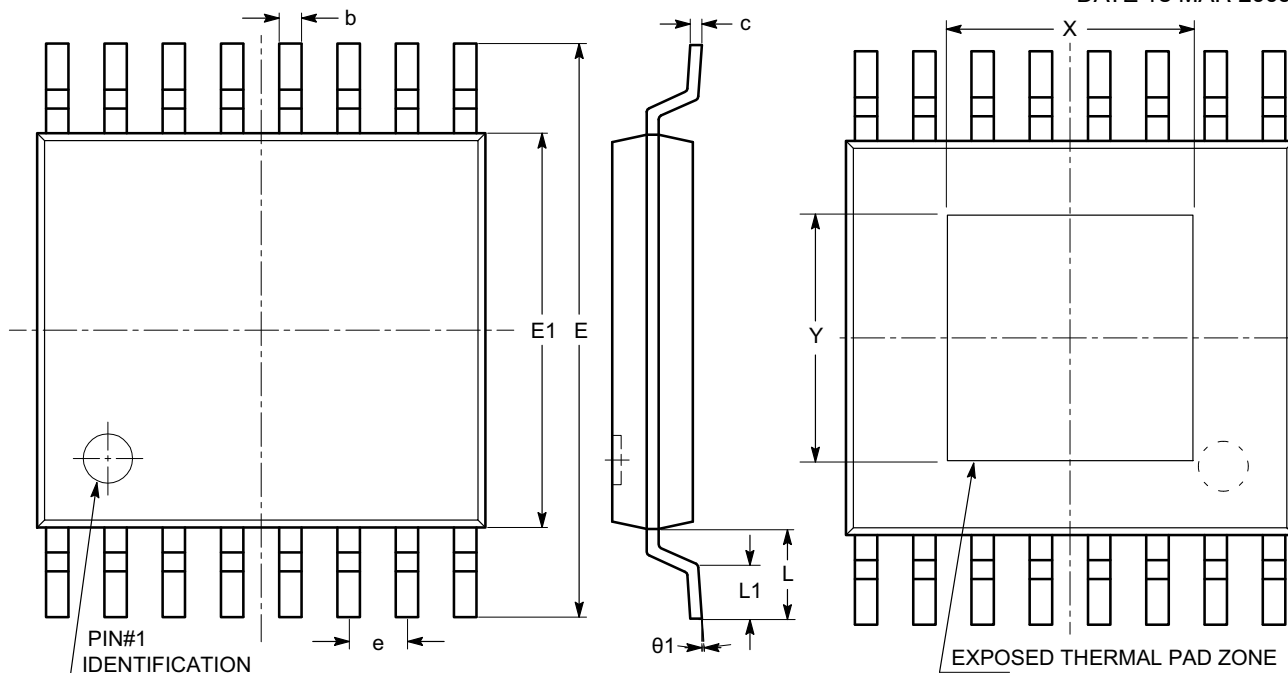
SIDE VIEW

SYMBOL	MIN	NOM	MAX
A			1.10
A1	0.05		0.15
A2	0.85		0.95
b	0.19		0.30
c	0.13		0.20
D	4.90		5.10
E	6.30		6.50
E1	4.30		4.50
e		0.65 BSC	
L		1.00 REF	
L1	0.45		0.75
N	0.90		1.00
P	6.50		6.70
R	4.60		4.80
S	0.37		0.47
θ	0º		8º
X		2.74 REF	
Y		2.74 REF	
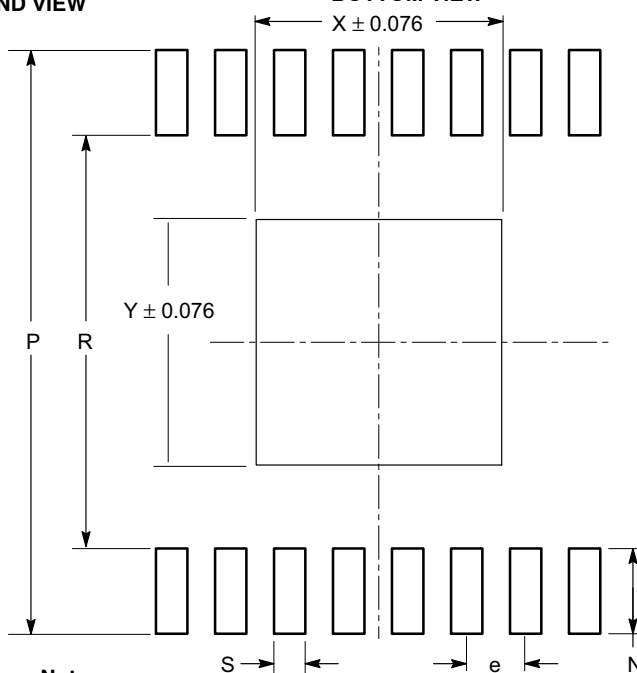
LAND PATTERN

Notes:
(1) All dimensions are in millimeters. Angles in degrees.
(2) Complies with JEDEC MO-153 variations ABT.

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DESCRIPTION:	TSSOP16, 4.4X5 EXPOSED PAD		PAGE 1 OF 1

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PUBLICATION ORDERING INFORMATION

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