Dual supply translating transceiver; auto direction sensing; 3-state

Rev. 1 — 7 August 2012

**Product data sheet** 

## 1. General description

The NTB0104-Q100 is a 4-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 4-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ).  $V_{CC(A)}$  can be supplied with any voltage between 1.2 V and 3.6 V.  $V_{CC(B)}$  can be supplied with any voltage between 1.65 V and 5.5 V. The range in supply voltages makes the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins An and OE are referenced to  $V_{CC(A)}$  and pins Bn are referenced to  $V_{CC(B)}$ . A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using  $I_{OFF}$ . The  $I_{OFF}$  circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

### 2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
  - Specified from –40 °C to +85 °C and from –40 °C to +125 °C
- Wide supply voltage range:
  - V<sub>CC(A)</sub>: 1.2 V to 3.6 V and V<sub>CC(B)</sub>: 1.65 V to 5.5 V
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
  - MIL-STD-883, method 3015 Class 2 exceeds 2500 V for A port
  - ◆ MIL-STD-883, method 3015 Class 3B exceeds 15000 V for B port
  - HBM JESD22-A114E Class 2 exceeds 2500 V for A port
  - HBM JESD22-A114E Class 3B exceeds 15000 V for B port
  - MM JESD22-A115-A exceeds 200 V (C = 200 pf, R = 0 Ω)
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options



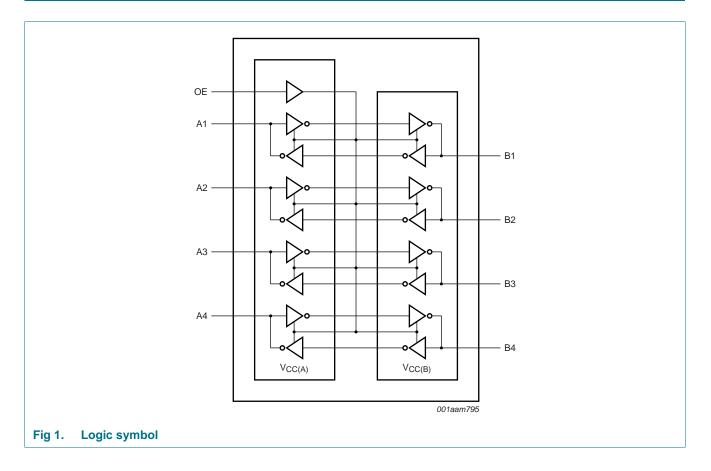
## 3. Ordering information

Type number	Package						
	Temperature range	Name	Description	Version			
NTB0104UK-Q100	–40 °C to +125 °C	WLCSP12	wafer level chip-size package, 12 bumps; body $1.20 \times 1.60 \times 0.56$ mm. (Backside Coating included)	NTB0104UK-Q100			

## 4. Marking

Table 2. Marking	
Type number	Marking code
NTB0104UK-Q100	t04

## 5. Functional diagram

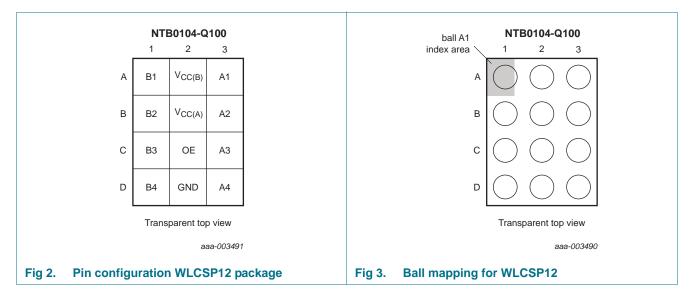


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## 6. Pinning information

### 6.1 Pinning



### 6.2 Pin description

Table 3.     Pin description							
Symbol	Ball	Description					
V <sub>CC(A)</sub>	B2	supply voltage A					
A1, A2, A3, A4	A3, B3, C3, D3	data input or output (referenced to V <sub>CC(A)</sub> )					
n.c.	-	not connected					
GND	D2	ground (0 V)					
OE	C2	output enable input (active HIGH; referenced to $V_{CC(A)}$ )					
B4, B3, B2, B1	D1, C1, B1, A1	data input or output (referenced to $V_{CC(B)}$ )					
V <sub>CC(B)</sub>	A2	supply voltage B					

## 7. Functional description

#### Table 4.Function table

Supply voltage		Input	iput Input/output		
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	OE	An	Bn	
1.2 V to $V_{CC(B)}$	1.65 V to 5.5 V	L	Z	Z	
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	Н	input or output	output or input	
GND <sup>[2]</sup>	GND <sup>[2]</sup>	Х	Z	Z	

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

[2] When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into power-down mode.

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## 8. Limiting values

#### Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

			-		-
Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B		-0.5	+6.5	V
VI	input voltage		<u>[1]</u> –0.5	+6.5	V
Vo	output voltage	Active mode	<u>[1][2][3]</u> –0.5	V <sub>CCO</sub> + 0.5	V
		Power-down or 3-state mode	<u>[1]</u> –0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>1</sub> < 0 V	-50	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V	-50	-	mA
lo	output current	$V_{O} = 0 V$ to $V_{CCO}$	[2] _	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>	-	100	mA
I <sub>GND</sub>	ground current		-100	-	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40 \ ^{\circ}C$ to +125 $^{\circ}C$	-	250	mW
-					

[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V<sub>CCO</sub> is the supply voltage associated with the output.

[3]  $V_{CCO}$  + 0.5 V should not exceed 6.5 V.

## 9. Recommended operating conditions

#### Table 6. Recommended operating conditions<sup>[1][2]</sup>

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		1.2	3.6	V
V <sub>CC(B)</sub>	supply voltage B		1.65	5.5	V
VI	input voltage		0	5.5	V
V <sub>O</sub> output voltage		Power-down or 3-state mode; $V_{CC(A)} = 1.2 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$			
		A port	0	3.6	V
		B port	0	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
$\Delta t / \Delta V$	input transition rise and fall rate	$V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	40	ns/V

[1] Hold the A and B sides of an unused I/O pair in the same state, either both at  $V_{CCI}$  or both at GND.

[2]  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

## **10. Static characteristics**

#### Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

0	Demonster	Or a differen		<b>T</b>		11
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>OH</sub>	HIGH-level output voltage	A port; $V_{CC(A)} = 1.2$ V; $I_O = -20 \ \mu A$	-	1.1	-	V
V <sub>OL</sub>	LOW-level output voltage	A port; $V_{CC(A)}$ = 1.2 V; $I_O$ = 20 $\mu$ A	-	0.09	-	V
I <sub>I</sub>	input leakage current	OE input; V <sub>I</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	-	±1	μA
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0$ V to $V_{CCO}$ ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	<u>[1]</u> -	-	±1	μA
I <sub>OFF</sub>	power-off leakage current	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 0 V to 5.5 V	-	-	±1	μA
		B port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V	-	-	±1	μΑ
I <sub>CC</sub>	supply current	$V_I = 0 V \text{ or } V_{CCI}; I_O = 0 A$	[2]			
		$I_{CC(A)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	0.05	-	μA
		$I_{CC(B)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	3.3	-	μA
		$I_{CC(A)} + I_{CC(B)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	3.5	-	μA
CI	input capacitance	OE input; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	-	2.8	-	pF
C <sub>I/O</sub>	input/output	A port; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	-	4.0	-	pF
	capacitance	B port; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	7.5	-	pF

[1]  $V_{CCO}$  is the supply voltage associated with the output.

[2]  $V_{CCI}$  is the supply voltage associated with the input.

#### Table 8.Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V);  $T_{amb} = 25$  °C.

V <sub>CC(A)</sub>	V <sub>CC(B)</sub>							Unit	
	1.8	1.8 V		5 V	3.3 V		5.	0 V	
	I <sub>CC(A)</sub>	I <sub>CC(B)</sub>							
1.2 V	10	10	10	10	10	20	10	1050	nA
1.5 V	10	10	10	10	10	10	10	650	nA
1.8 V	10	10	10	10	10	10	10	350	nA
2.5 V	-	-	10	10	10	10	10	40	nA
3.3 V	-	-	-	-	10	10	10	10	nA

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#### Dual supply translating transceiver; auto direction sensing; 3-state

#### Table 9. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		–40 °C to	o +85 ℃	–40 °C to	+125 °C	Unit
				Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	A or B port and OE input	<u>[1]</u>					
	input voltage	$V_{CC(A)} = 1.2 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$		0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
V <sub>IL</sub>	LOW-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
V <sub>OH</sub>		A or B port; $I_0 = -20 \ \mu A$	[2]					
output voltag	output voltage	A port; $V_{CC(A)} = 1.4$ V to 3.6 V		$V_{CCO}-0.4$	-	$V_{CCO}-0.4$	-	V
		B port; $V_{CC(B)}$ = 1.65 V to 5.5 V		$V_{CCO}-0.4$	-	$V_{CCO}-0.4$	-	V
V <sub>OL</sub>	LOW-level	A or B port; $I_0 = 20 \ \mu A$	[2]					
	output voltage	A port; $V_{CC(A)} = 1.4$ V to 3.6 V		-	0.4	-	0.4	V
		B port; $V_{CC(B)}$ = 1.65 V to 5.5 V		-	0.4	-	0.4	V
I <sub>I</sub>	input leakage current	$\begin{array}{l} \text{OE input; V}_{I} = 0 \text{ V to } 3.6 \text{ V;} \\ \text{V}_{\text{CC}(A)} = 1.2 \text{ V to } 3.6 \text{ V;} \\ \text{V}_{\text{CC}(B)} = 1.65 \text{ V to } 5.5 \text{ V} \end{array}$		-	±2	-	±5	μΑ
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0$ V or $V_{CCO}$ ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	[2]	-	±2	-	±10	μΑ
I <sub>OFF</sub>	power-off leakage	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 0 V to 5.5 V		-	±2	-	±10	μA
	current	B port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V		-	±2	-	±10	μΑ

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Symbol	Parameter	Conditions	–40 °C t	to +85 °C	–40 °C to	o +125 ℃	Unit
		-	Min	Max	Min	Max	
I <sub>CC</sub>	supply current	$V_{I} = 0 V \text{ or } V_{CCI}; I_{O} = 0 A$ [1]					
		I <sub>CC(A)</sub>					
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	15	μA
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	20	μA
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$	-	2	-	15	μA
		$V_{CC(A)} = 0 V; V_{CC(B)} = 5.5 V$	-	-2	-	-15	μA
		I <sub>CC(B)</sub>					
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	15	μA
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	20	μA
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$	-	-2	-	-15	μA
		$V_{CC(A)} = 0 V; V_{CC(B)} = 5.5 V$	-	2	-	15	μA
		$I_{CC(A)} + I_{CC(B)}$					
		$V_{CC(A)} = 1.4 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$	-	10	-	40	μΑ

#### Static characteristics ... continued Table 9.

At recommended operating conditions: voltages are referenced to GND (ground = 0 V).

[1] V<sub>CCI</sub> is the supply voltage associated with the input.

V<sub>CCO</sub> is the supply voltage associated with the output. [2]

## **11. Dynamic characteristics**

Table 10. Typical dynamic characteristics for temperature 25 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 6; for waveforms see Figure 4 and Figure 5.

Symbol	Parameter	Conditions			V <sub>C</sub>	С(В)		Unit
				1.8 V	2.5 V	3.3 V	5.0 V	
$V_{CC(A)} = 1$	1.2 V; T <sub>amb</sub> = 25 °C							
t <sub>pd</sub>	propagation delay	A to B		5.9	4.8	4.4	4.2	ns
		B to A		5.6	4.8	4.5	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		0.5	0.5	0.5	0.5	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	8.3	8.3	8.3	8.3	ns
		OE to B; no external load	[2]	10.4	9.4	9.3	8.8	ns
		OE to A		81	69	83	68	ns
		OE to B		81	69	83	68	ns
t <sub>t</sub>	transition time	A port		4.0	4.0	4.1	4.1	ns
		B port		2.6	2.0	1.7	1.4	ns

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Symbol	Parameter	Conditions	<u>-</u>	<u>iguro o</u> , n	V <sub>CC</sub>		una <u>rigaro</u>	Unit
				1.8 V	2.5 V	3.3 V	5.0 V	_
t <sub>sk(o)</sub>	output skew time	between channels	3]	0.2	0.2	0.2	0.2	ns
t <sub>W</sub>	pulse width	data inputs		15	13	13	13	ns
f <sub>data</sub>	data rate			70	80	80	80	Mbps

#### Table 10. Typical dynamic characteristics for temperature 25 °C<sup>[1]</sup> ... continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 6; for waveforms see Figure 4 and Figure 5.

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $t_{t}$  is the same as  $t_{THL}$  and  $t_{TLH}$ 

[2] Delay between OE going LOW and when the outputs are actually disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

#### Table 11. Dynamic characteristics for temperature range –40 °C to +85 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 6; for wave forms see Figure 4 and Figure 5.

Symbol	Parameter	Conditions					Vcc	С(В)				Unit
				1.8 V ±	: 0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.5 V ± 0.1 V											
t <sub>pd</sub>	propagation	A to B		1.4	12.9	1.2	10.1	1.1	10.0	0.8	9.9	ns
	delay	B to A		0.9	14.2	0.7	12.0	0.4	11.7	0.3	13.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.9	1.0	12.9	1.0	12.9	1.0	12.9	ns
		OE to B; no external load	[2]	1.0	18.7	1.0	15.8	1.0	15.1	1.0	14.4	ns
		OE to A		-	320	-	260	-	260	-	280	ns
		OE to B		-	200	-	200	-	200	-	200	ns
tt	transition	A port		0.9	5.1	0.9	5.1	0.9	5.1	0.9	5.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbps
V <sub>CC(A)</sub> =	$1.8 V \pm 0.15 V$											
t <sub>pd</sub>	propagation	A to B		1.6	11.0	1.4	7.7	1.3	6.8	1.2	6.5	ns
	delay	B to A		1.5	12.0	1.3	8.4	1.0	7.6	0.9	7.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	11.7	1.0	11.7	1.0	11.7	1.0	11.7	ns
		OE to B; no external load	[2]	1.0	16.9	1.0	14.5	1.0	13.7	1.0	12.7	ns
		OE to A		-	260	-	230	-	230	-	230	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		0.8	4.1	0.8	4.1	0.8	4.1	0.8	4.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns

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Symbol	Parameter	Conditions					Vcc	:(В)				Unit
				1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	E 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	-
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		20	-	17	-	17	-	17	-	ns
f <sub>data</sub>	data rate			-	49	-	60	-	60	-	60	Mbp
V <sub>CC(A)</sub> =	2.5 V ± 0.2 V											
t <sub>pd</sub>	propagation	A to B		-	-	1.1	6.3	1.0	5.2	0.9	4.7	ns
	delay	B to A		-	-	1.2	6.6	1.1	5.1	0.9	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	9.7	1.0	9.7	1.0	9.7	ns
		OE to B; no external load	[2]	-	-	1.0	12.9	1.0	12.0	1.0	11.0	ns
		OE to A		-	-	-	200	-	200	-	200	ns
		OE to B		-	-	-	200	-	200	-	200	ns
<sup>t</sup> t	transition	A port		-	-	0.7	3.0	0.7	3.0	0.7	3.0	ns
	time	B port		-	-	0.7	3.2	0.5	2.5	0.4	2.7	ns
sk(o)	output skew time	between channels	<u>[3]</u>	-	-	-	0.5	-	0.5	-	0.5	ns
tw	pulse width	data inputs		-	-	12	-	10	-	10	-	ns
data	data rate			-	-	-	85	-	100	-	100	Mbp
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
pd	propagation	A to B		-	-	-	-	0.9	4.7	0.8	4.0	ns
	delay	B to A		-	-	-	-	1.0	4.9	0.9	3.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
dis	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.4	1.0	9.4	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	11.3	1.0	10.4	ns
		OE to A		-	-	-	-	-	260	-	260	ns
		OE to B		-	-	-	-	-	200	-	200	ns
t	transition	A port		-	-	-	-	0.7	2.5	0.7	2.5	ns
	time	B port		-	-	-	-	0.5	2.5	0.4	2.7	ns
sk(o)	output skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
tw	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbp

Table 11. Dynamic characteristics for temperature range -40 °C to +85 °C[1] ...continued

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $t_t$  is the same as  $t_{\mathsf{THL}}$  and  $t_{\mathsf{TLH}}$ 

[2] Delay between OE going LOW and when the outputs are disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions					Vcc	(В)				Unit
				1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	1
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{CC(A)} =$	1.5 V ± 0.1 V			1	1							
t <sub>pd</sub>	propagation	A to B		1.4	15.9	1.2	13.1	1.1	13.0	0.8	12.9	ns
	delay	B to A		0.9	17.2	0.7	15.0	0.4	14.7	0.3	16.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	13.5	1.0	13.5	1.0	13.5	1.0	13.5	ns
		OE to B; no external load	[2]	1.0	19.9	1.0	16.8	1.0	16.1	1.0	15.2	ns
		OE to A		-	340	-	280	-	280	-	300	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.9	7.1	0.9	7.1	0.9	7.1	0.9	7.1	ns
	time	B port		0.9	6.5	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
tw	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbp
$V_{CC(A)} =$	1.8 V ± 0.15 V											
t <sub>pd</sub>	propagation	A to B		1.6	14.0	1.4	10.7	1.3	9.8	1.2	9.5	ns
	delay	B to A		1.5	15.0	1.3	11.4	1.0	10.6	0.9	10.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.3	1.0	12.3	1.0	12.3	1.0	12.3	ns
		OE to B; no external load	[2]	1.0	18.1	1.0	15.3	1.0	14.5	1.0	13.5	ns
		OE to A		-	280	-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.8	6.2	0.8	6.1	0.8	6.1	0.8	6.1	ns
	time	B port		0.9	5.8	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		22	-	19	-	19	-	19	-	ns
f <sub>data</sub>	data rate			-	45	-	55	-	55	-	55	Mbp
$V_{CC(A)} =$	2.5 V ± 0.2 V											
t <sub>pd</sub>	propagation	A to B		-	-	1.1	9.3	1.0	8.2	0.9	7.7	ns
	delay	B to A		-	-	1.2	9.6	1.1	8.1	0.9	7.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	10.1	1.0	10.1	1.0	10.1	ns
		OE to B; no external load	[2]	-	-	1.0	13.5	1.0	12.7	1.0	11.7	ns
		OE to A		-	-	-	220	-	220	-	220	ns
		OE to B		-	-	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		-	-	0.7	5.0	0.7	5.0	0.7	5.0	ns
-	time	B port		-	_	0.7	4.6	0.5	4.8	0.4	4.7	ns

Table 12. Dynamic characteristics for temperature range –40 °C to +125 °C[1]

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions					Vcc	С(В)				Unit
				1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V =	E 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs;		-	-	14	-	13	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	75	-	80	-	100	Mbps
$V_{CC(A)} =$	3.3 V ± 0.3 V											
t <sub>pd</sub>	propagation	A to B		-	-	-	-	0.9	7.7	0.8	7.0	ns
	delay	B to A		-	-	-	-	1.0	7.9	0.9	6.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.9	1.0	9.9	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	12.1	1.0	10.9	ns
		OE to A		-	-	-	-	-	280	-	280	ns
		OE to B		-	-	-	-	-	220	-	220	ns
tt	transition	A port		-	-	-	-	0.7	4.5	0.7	4.5	ns
	time	B port		-	-	-	-	0.5	4.1	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

**Table 12.** Dynamic characteristics for temperature range  $-40 \,^{\circ}$ C to  $+125 \,^{\circ}$ C<sup>[1]</sup> Voltages are referenced to GND (ground = 0.V); for test circuit see Figure 6; for wave forms see Figure 4 and Figure 5

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{en} \mbox{ is the same as } t_{PZL} \mbox{ and } t_{PZH}.$ 

 $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ .  $t_{t}$  is the same as  $t_{THL}$  and  $t_{TLH}$ 

[2] Delay between OE going LOW and when the outputs are disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions				V <sub>CC(A)</sub>				Unit
			1.2 V 1.2 V 1.5 V 1.8 V 2.5 V 2.5 V 3.3 V							
			V <sub>CC(B)</sub>							
		1.8 V	5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V		
T <sub>amb</sub> = 2	25 °C									
C <sub>PD</sub>	power	outputs enabled; $OE = V_{CC(A)}$								
	dissipation capacitance	A port: (direction A to B)	5	5	5	5	5	5	5	pF
	capacitance	A port: (direction B to A)	8	8	8	8	8	8	8	рF
		B port: (direction A to B)	18	18	18	18	18	18	18	pF
		B port: (direction B to A)	13	16	12	12	12	12	13	pF
		outputs disabled; OE = GND								
		A port: (direction A to B)	0.12	0.12	0.04	0.05	0.08	0.08	0.07	pF
		A port: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction A to B)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction B to A)	0.07	0.09	0.07	0.07	0.05	0.09	0.09	рF

## **Table 13.** Typical power dissipation capacitance Voltages are referenced to GND (ground = 0.V) [1][2]

[1]  $C_{PD}$  is used to determine the dynamic power dissipation (P<sub>D</sub> in  $\mu$ W).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:

 $f_i$  = input frequency in MHz;

 $f_o = output frequency in MHz;$ 

 $C_L$  = load capacitance in pF;

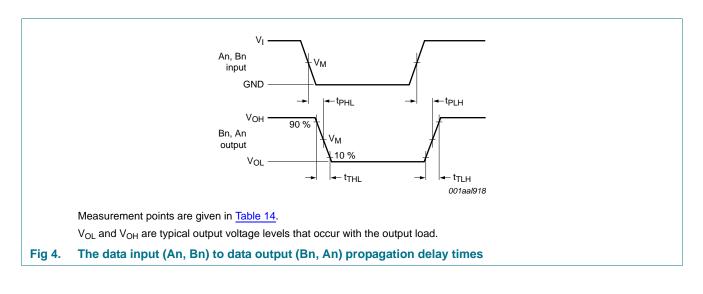
V<sub>CC</sub> = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_0)$  = sum of the outputs.

[2]  $f_i = 10$  MHz;  $V_I = GND$  to  $V_{CC}$ ;  $t_f = t_f = 1$  ns;  $C_L = 0$  pF;  $R_L = \infty \Omega$ .

## 12. Waveforms

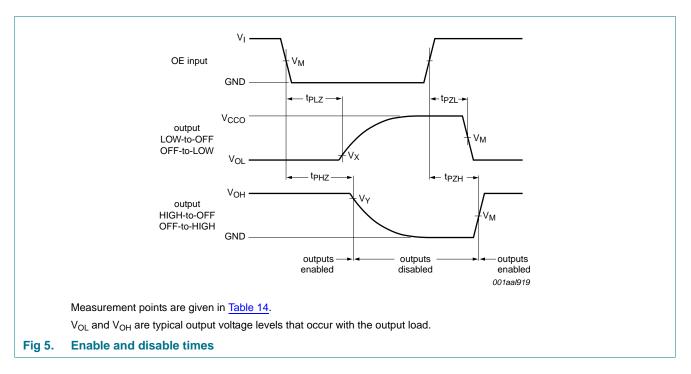


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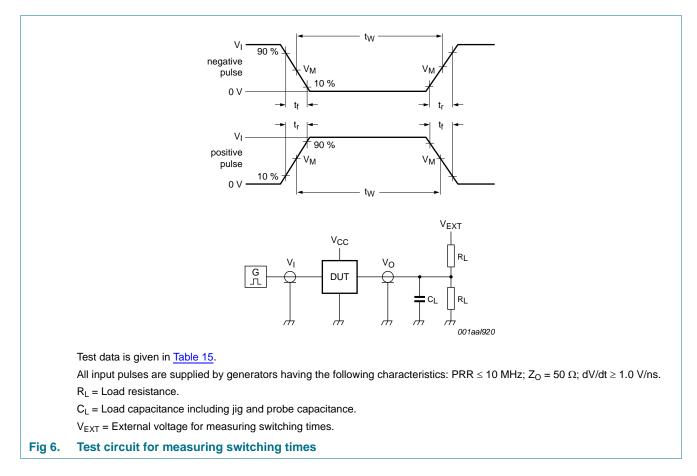
#### Table 14. Measurement points<sup>[1]</sup>

Supply voltage	Input	Output		
V <sub>cco</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>
1.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	$V_{OH} - 0.1 V$
$1.5~V\pm0.1~V$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> – 0.1 V
$1.8~V\pm0.15~V$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
$2.5~\text{V}\pm0.2~\text{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
$3.3~\text{V}\pm0.3~\text{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	$V_{OH} - 0.3 V$
$5.0~V\pm0.5~V$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> – 0.3 V

[1] V<sub>CCI</sub> is the supply voltage associated with the input and V<sub>CCO</sub> is the supply voltage associated with the output.

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#### Table 15. Test data

Supply voltage	je	Input		Load		V <sub>EXT</sub>		
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	VI <mark>[1]</mark>	∆t/∆V	CL	R <sub>L</sub> [2]	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]
1.2 V to 3.6 V $$	1.65 V to 5.5 V	V <sub>CCI</sub>	$\leq$ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>

[1] V<sub>CCI</sub> is the supply voltage associated with the input.

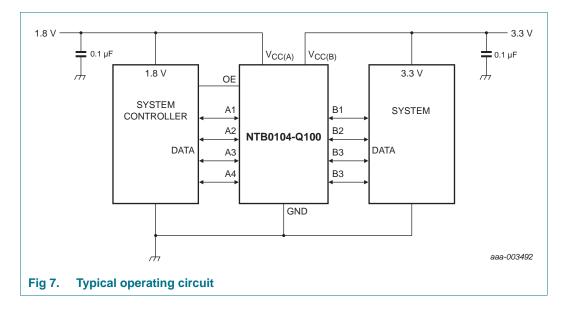
[2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L = 1 M\Omega$ . For measuring enable and disable times,  $R_L = 50 k\Omega$ .

[3]  $V_{CCO}$  is the supply voltage associated with the output.

## **13. Application information**

### **13.1 Applications**

Voltage level-translation applications. The NTB0104-Q100 can be used to interface between devices or systems operating at different supply voltages. See <u>Figure 7</u> for a typical operating circuit using the NTB0104-Q100.

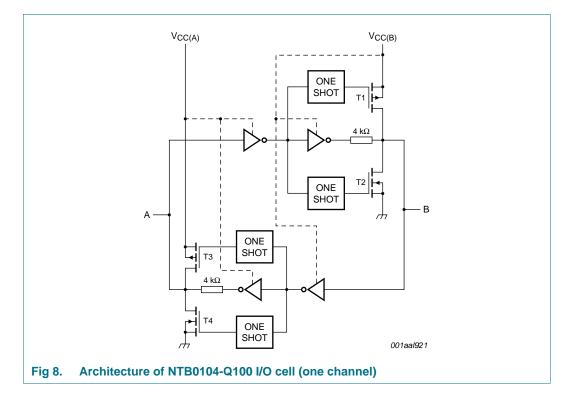


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#### 13.2 Architecture

The architecture of the NTB0104-Q100 is shown in Figure 8. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NTB0104-Q100 can maintain a defined output level. However, the output architecture has been designed so that when data on the bus starts flowing in the opposite direction, an external driver can overdrive the output drivers. The output one shots detect rising or falling edges on the A or B ports. During a rising edge, the one shots turn on the PMOS transistors (T1, T3) for a short duration, accelerating the low-to-high transition. Similarly, during a falling edge, the one shots turn on the NMOS transistors (T2, T4) for a short duration, accelerating the high-to-low transition. During output transitions, the typical output impedance is 70  $\Omega$  at V<sub>CCO</sub> = 1.2 V to 1.8 V, 50  $\Omega$  at V<sub>CCO</sub> = 1.8 V to 3.3 V and 40  $\Omega$  at V<sub>CCO</sub> = 3.3 V to 5.0 V.

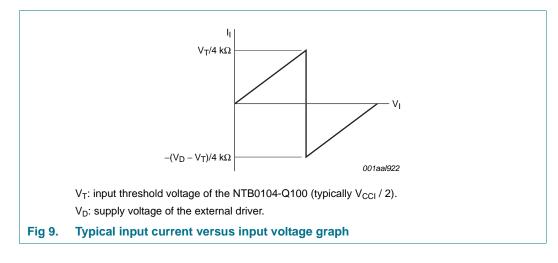


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#### 13.3 Input driver requirements

For correct operation, the device driving the data I/Os of the NTB0104-Q100 must have a minimum drive capability of  $\pm 2$  mA. See <u>Figure 9</u> for a plot of typical input current versus input voltage.



### 13.4 Power-up

During operation,  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ . However, during power-up,  $V_{CC(A)} \ge V_{CC(B)}$  does not damage the device. This means that either power supply can be ramped up first. There is no special power-up sequencing required. The NTB0104-Q100 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

#### 13.5 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{dis}$  with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ( $t_{en}$ ) indicates the amount of time to allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, tie pin OE to GND through a pull-down resistor. The current-sourcing capability of the driver determines the minimum value of the resistor.

#### 13.6 Pull-up or pull-down resistors on I/O lines

As mentioned previously, the NTB0104-Q100 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistor used, must be higher than 50 k $\Omega$ . Consequently, the NTB0104-Q100 is not recommended for use in open-drain driver applications such as 1-Wire or I<sup>2</sup>C. For these applications, the NTS0104-Q100 level translator is recommended.

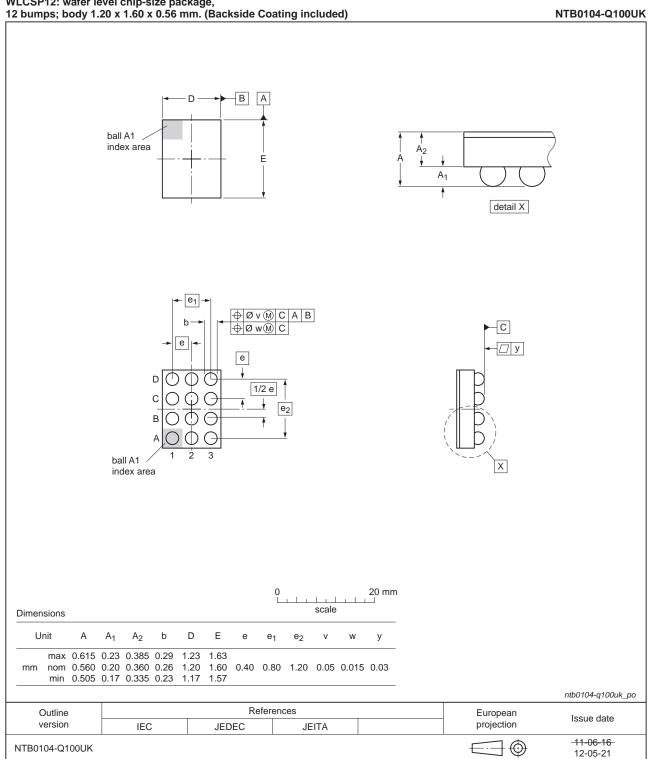
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## 14. Package outline

WLCSP12: wafer level chip-size package,



#### Fig 10. Package outline WLCSP12 package

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## **15. Abbreviations**

Description
Charged Device Model
Complementary Metal Oxide Semiconductor
Device Under Test
ElectroStatic Discharge
Human Body Model
Machine Model

## 16. Revision history

Table 17. Revision his	story			
Document ID	Release date	Data sheet status	Change notice	Supersedes
NTB0104_Q100 v.1	20120807	Product data sheet	-	-

## 17. Legal information

### 17.1 Data sheet status

Document status[1][2]	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

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[2] The term 'short data sheet' is explained in section "Definitions".

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## NTB0104-Q100

Dual supply translating transceiver; auto direction sensing; 3-state

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