

# TDA8944AJ

2 x 7 W BTL audio amplifier with DC gain control

Rev. 01 — 01 March 2002

Product data

## 1. General description

The TDA8944AJ is a dual-channel audio power amplifier with DC gain control. It has an output power of  $2 \times 7$  W at an  $8 \Omega$  load and a 12 V supply. The circuit contains two Bridge-Tied Load (BTL) amplifiers with an all-NPN output stage and standby/mute logic. The overall gain can be adjusted from +30 dB down to -50 dB using a DC control voltage. This feature can be used for volume control or a preset gain. The TDA8944AJ comes in a 17-pin DIL-bent-SIL (DBS) power package and is pin compatible with the TDA8944J.

## 2. Features

- Gain/volume adjustment via a DC control pin
- Soft clipping
- Operating at a low supply voltage
- Standby and mute mode
- No on/off switching plops
- Low standby current
- High supply voltage ripple rejection
- Outputs short-circuit protected to ground, supply and across the load
- Thermally protected
- Printed-circuit board compatible with TDA8946AJ and TDA8580J.

## 3. Applications

- Mains fed applications (e.g. TV sound)
- PC audio
- Portable audio.

## 4. Quick reference data

Table 1: Quick reference data

| Symbol    | Parameter                 | Conditions                                       | Min | Typ  | Max | Unit    |
|-----------|---------------------------|--|-----|------|-----|---------|
| $V_{CC}$  | supply voltage            |  | 4.5 | 12   | 18  | V       |
| $I_q$     | quiescent supply current  | $V_{CC} = 12$ V; $R_L = \infty$                  | -   | 40   | 50  | mA      |
| $I_{stb}$ | standby supply current    |  | -   | -    | 10  | $\mu$ A |
| $P_o$     | output power              | THD = 10%; $R_L = 8 \Omega$ ;<br>$V_{CC} = 12$ V | 6   | 7    | -   | W       |
| THD       | total harmonic distortion | $P_o = 1$ W                                      | -   | 0.07 | 0.5 | %       |



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Table 1: Quick reference data...continued

| Symbol       | Parameter                       | Conditions | Min | Typ | Max | Unit |
|--------------|---------------------------------|------------|-----|-----|-----|------|
| $G_{V(max)}$ | maximum voltage gain            |            | 29  | 30  | 31  | dB   |
| $G_{V(cr)}$  | voltage gain control range      |            | -   | 80  | -   | dB   |
| SVRR         | supply voltage ripple rejection |            | -   | 55  | -   | dB   |

### 5. Ordering information

Table 2: Ordering information

| Type number | Package |  | Version  |
|-------------|---------|--|----------|
|             | Name    | Description  |          |
| TDA8944AJ   | DBS17P  | plastic DIL-bent-SIL power package; 17 leads (lead length 12 mm) | SOT243-1 |

### 6. Block diagram

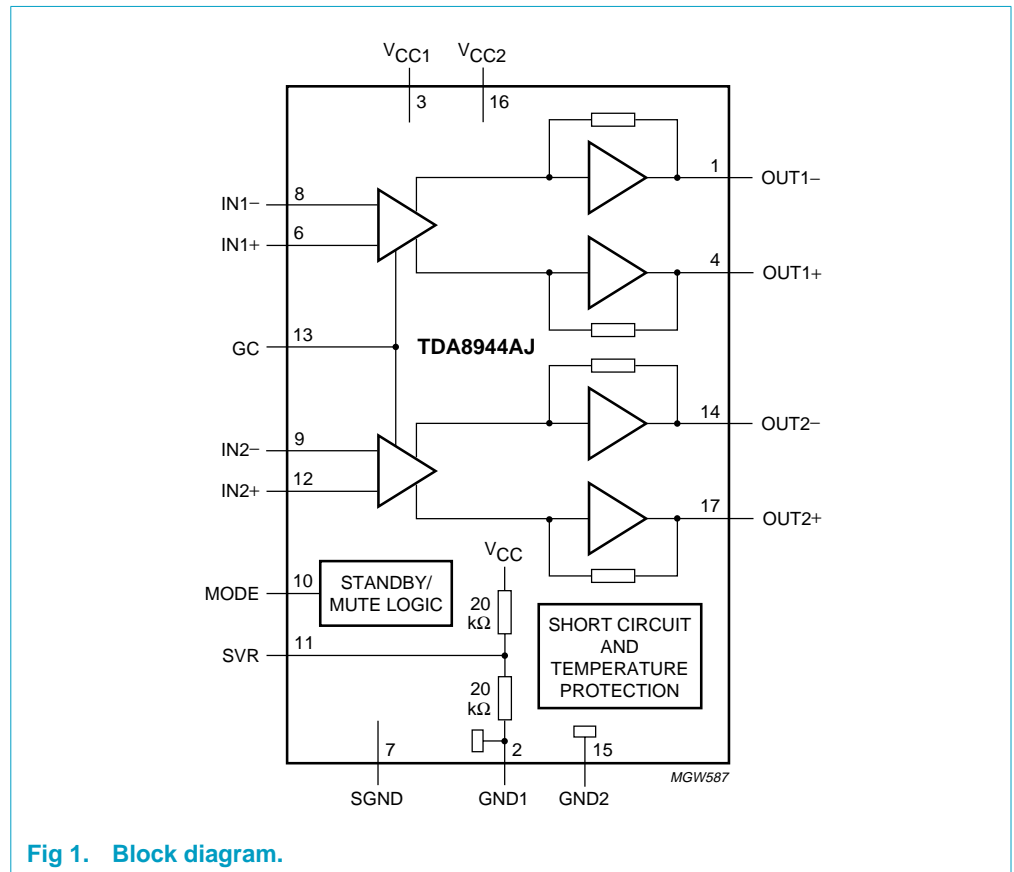


Fig 1. Block diagram.

## 7. Pinning information

### 7.1 Pinning

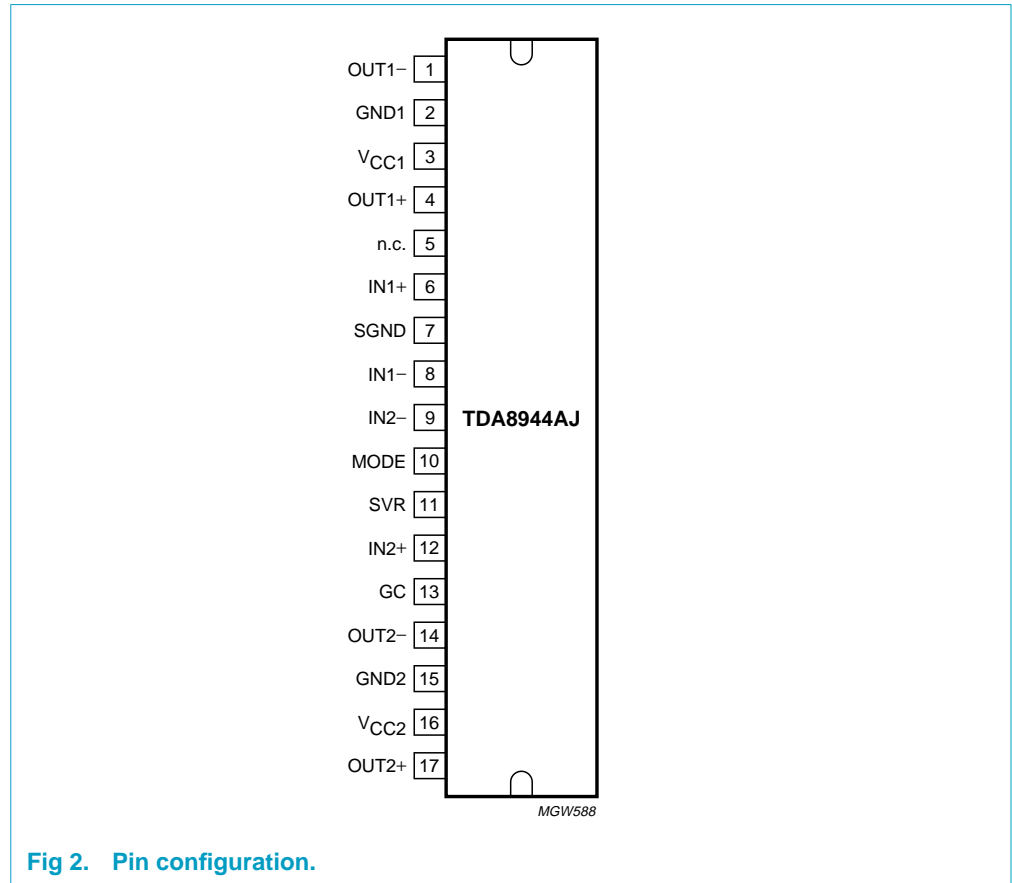


Fig 2. Pin configuration.

### 7.2 Pin description

Table 3: Pin description

| Symbol           | Pin | Description                                       |
|------------------|-----|---|
| OUT1-            | 1   | negative loudspeaker terminal 1                   |
| GND1             | 2   | ground channel 1                                  |
| V <sub>CC1</sub> | 3   | supply voltage channel 1                          |
| OUT1+            | 4   | positive loudspeaker terminal 1                   |
| n.c.             | 5   | not connected                                     |
| IN1+             | 6   | positive input 1                                  |
| SGND             | 7   | signal ground                                     |
| IN1-             | 8   | negative input 1                                  |
| IN2-             | 9   | negative input 2                                  |
| MODE             | 10  | mode selection input (standby, mute, operating)   |
| SVR              | 11  | half supply voltage decoupling (ripple rejection) |
| IN2+             | 12  | positive input 2                                  |

Table 3: Pin description...continued

| Symbol           | Pin | Description                     |
|------------------|-----|---------------------------------|
| GC               | 13  | DC gain control                 |
| OUT2-            | 14  | negative loudspeaker terminal 2 |
| GND2             | 15  | ground channel 2                |
| V <sub>CC2</sub> | 16  | supply voltage channel 2        |
| OUT2+            | 17  | positive loudspeaker terminal 2 |

## 8. Functional description

The TDA8944AJ is a stereo BTL audio power amplifier capable of delivering  $2 \times 7$  W output power to an  $8 \Omega$  load at THD = 10%, using a 12 V power supply and an external heatsink. The gain of both amplifiers can be adjusted through a DC control voltage (pin GC). This feature can be used for volume control or a preset gain.

With the three-level MODE input the device can be switched from 'standby' to 'mute' and to 'operating' mode.

The TDA8944AJ outputs are protected by an internal thermal shutdown protection mechanism and a short-circuit protection.

### 8.1 Input configuration

The TDA8944AJ inputs can be driven symmetrical (floating) as well as asymmetrical. In the asymmetrical mode one input pin is connected via a capacitor to the signal source and the other input is connected to the signal ground. This signal ground should be as close as possible to the SVR (electrolytic) capacitor ground. Note that the DC level of the input pins is half of the supply voltage  $V_{CC}$ , so coupling capacitors for both pins are necessary.

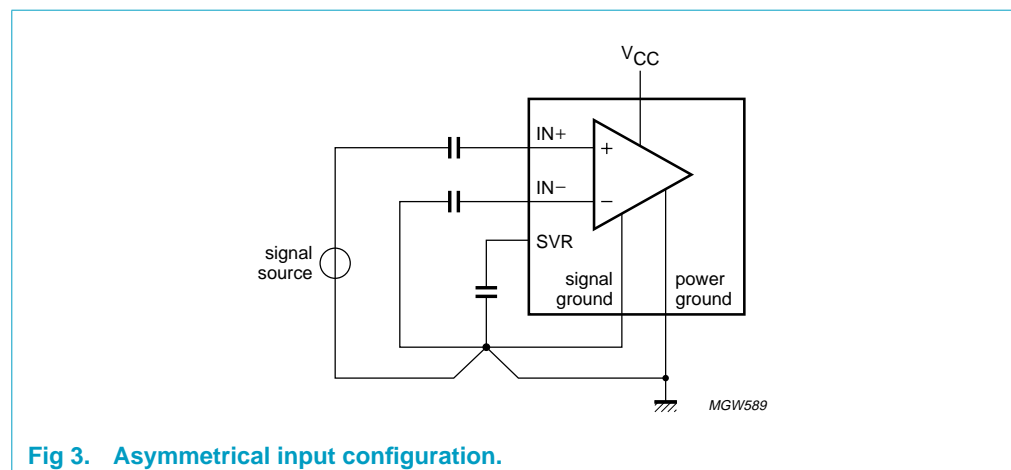


Fig 3. Asymmetrical input configuration.

The input cut-off frequency is:

$$f_{i(\text{cut-off})} = \frac{1}{2\pi(0.5 \times R_i \times C_i)} \quad (1)$$

For  $R_i = 32 \text{ k}\Omega$  and  $C_i = 220 \text{ nF}$ :

$$f_{i(\text{cut-off})} = \frac{1}{2\pi(0.5 \times 32 \times 10^3 \times 220 \times 10^{-9})} = 45.2 \text{ Hz} \quad (2)$$

As shown in [Equation 2](#), large capacitors values for the inputs are not necessary; so the switch-on delay during charging of the input capacitors can be minimized. This results in a good low frequency response and good switch-on behaviour.

**Remark:** To prevent high frequency oscillations do not leave the inputs open, connect a capacitor of 4.7 nF across the input pins close to the device (see [Figure 15](#)).

## 8.2 Power amplifier

The power amplifier is a Bridge-Tied Load (BTL) amplifier with an all-NPN output stage, capable of delivering a peak output current of 2 A.

The BTL principle offers the following advantages:

- Lower peak value of the supply current
- The ripple frequency on the supply voltage is twice the signal frequency
- No expensive DC-blocking capacitor
- Good low frequency performance.

### 8.2.1 Output power measurement

The output power as a function of the supply voltage is measured on the output pins at THD = 10%; see [Figure 10](#). The maximum output power is limited by the supply voltage of 12 V and the maximum available output current: 2 A repetitive peak current.

### 8.2.2 Headroom

Typical CD music requires at least 12 dB (factor 15.85) dynamic headroom - compared to the average power output - for transferring the loudest parts without distortion. At  $V_{CC} = 12 \text{ V}$ ,  $R_L = 8 \text{ }\Omega$  and  $P_o = 4 \text{ W}$  at THD = 0.2% (see [Figure 8](#)), the Average Listening Level (ALL) - music power - without any distortion yields:

$$P_{o(\text{ALL})} = \frac{4 \text{ W}}{15.85} = 252.4 \text{ mW} \quad (3)$$

The power dissipation can be derived from [Figure 12 on page 11](#) for 0 dB respectively 12 dB headroom.

Table 4: Power rating as function of headroom

| Headroom | Power output (THD = 0.2%)              | Power dissipation   |
|----------|--|---------------------|
| 0 dB     | $P_o = 4 \text{ W}$                    | $P = 7.8 \text{ W}$ |
| 12 dB    | $P_{o(\text{ALL})} = 252.4 \text{ mW}$ | $P = 4.0 \text{ W}$ |

For the average listening level a power dissipation of 4 W can be used for a heatsink calculation.

### 8.3 Mode selection

The TDA8944AJ has three functional modes, which can be selected by applying the proper DC voltage to pin MODE.

**Standby** — In this mode the current consumption is very low and the outputs are floating. The device is in standby mode when  $V_{\text{MODE}} > (V_{\text{CC}} - 0.5 \text{ V})$ , or when the MODE pin is left floating.

**Mute** — In this mode the amplifier is DC-biased but not operational (no audio output). This allows the input coupling capacitors to be charged to avoid pop-noise. The device is in mute mode when  $3.5 \text{ V} < V_{\text{MODE}} < (V_{\text{CC}} - 1.5 \text{ V})$ .

**Operating** — In this mode the amplifier is operating normally. The operating mode is activated at  $V_{\text{MODE}} < 1.0 \text{ V}$ .

#### 8.3.1 Switch-on and switch-off

To avoid audible plops during supply voltage switch-on or switch-off, the device is set to standby mode before the supply voltage is applied (switch-on) or removed (switch-off).

The switch-on and switch-off time can be influenced by an RC-circuit on the MODE pin. Rapid on/off switching of the device or the rapid switching of the MODE pin may cause 'click-and-pop-noise'. This can be prevented by proper timing of the RC-circuit on the MODE pin.

### 8.4 DC gain control

The gain of both amplifiers can be adjusted (logarithmic) by applying an external DC voltage source on pin GC (see Figure 6). The DC voltage source range is 0.5 to 4.0 V. This feature can be used for volume control or a preset gain.

The maximum voltage gain is set at +30 dB and the control range is more than 80 dB, so the minimal gain is less than -50 dB. When pin GC is not connected, the gain is set at +24 dB.

### 8.5 Supply Voltage Ripple Rejection (SVRR)

The SVRR is measured with an electrolytic capacitor of 10  $\mu\text{F}$  on pin SVR at a bandwidth of 10 Hz to 80 kHz. Figure 14 illustrates the SVRR as function of the frequency. A larger capacitor value on the SVR pin improves the ripple rejection behavior at the lower frequencies.

### 8.6 Built-in protection circuits

The TDA8944AJ contains two types of protection circuits, i.e. short-circuit and thermal shutdown.

#### 8.6.1 Short-circuit protection

**Short-circuit to ground or supply line** — This is detected by a so-called ‘missing current’ detection circuit which measures the current in the positive supply line and the current in the ground line. A difference between both currents larger than 0.8 A, switches the power stage to the standby mode; high impedance of the outputs and very low supply current.

**Short-circuit across the load** — This is detected by an absolute-current measurement. An absolute-current larger than 2 A, switches the power stage to standby mode; high impedance of the outputs and a very low supply current.

#### 8.6.2 Thermal shutdown protection

The junction temperature is measured by a temperature sensor; at a junction temperature of approximately 150 °C this detection circuit switches the power stage to the standby mode; high impedance of the outputs and very low supply current.

## 9. Limiting values

**Table 5: Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol              | Parameter  | Conditions    | Min  | Max                   | Unit |
|---------------------|--|---------------|------|-----------------------|------|
| V <sub>CC</sub>     | supply voltage                                       | no signal     | -0.3 | +25                   | V    |
|                     |  | operating     | -0.3 | +18                   | V    |
| V <sub>I</sub>      | input voltage  |               | -0.3 | V <sub>CC</sub> + 0.3 | V    |
| I <sub>ORM</sub>    | repetitive peak output current                       |               | -    | 2                     | A    |
| T <sub>stg</sub>    | storage temperature                                  | non-operating | -55  | +150                  | °C   |
| T <sub>amb</sub>    | operating ambient temperature                        |               | -40  | +85                   | °C   |
| P <sub>tot</sub>    | total power dissipation                              |               | -    | 18                    | W    |
| V <sub>CC(sc)</sub> | supply voltage to guarantee short-circuit protection |               | -    | 15                    | V    |

## 10. Thermal characteristics

**Table 6: Thermal characteristics**

| Symbol                | Parameter   | Conditions           | Value | Unit |
|-----------------------|---|----------------------|-------|------|
| R <sub>th(j-a)</sub>  | thermal resistance from junction to ambient       | in free air          | 40    | K/W  |
| R <sub>th(j-mb)</sub> | thermal resistance from junction to mounting base | both channels driven | 4.5   | K/W  |

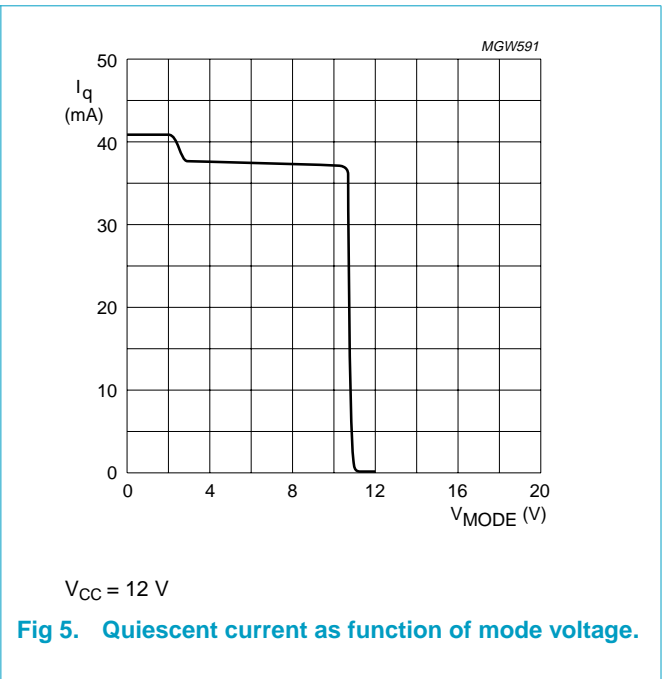
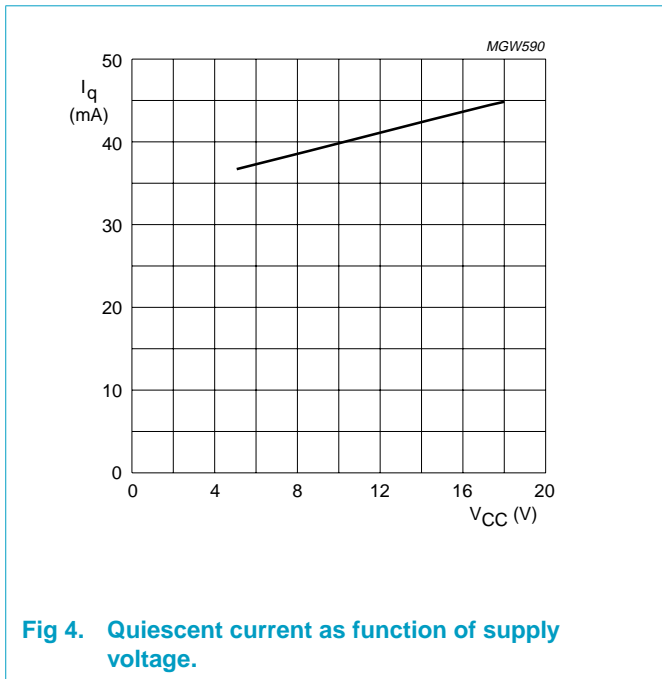
### 11. Static characteristics

**Table 7: Static characteristics**

$V_{CC} = 12\text{ V}$ ;  $T_{amb} = 25\text{ }^\circ\text{C}$ ;  $R_L = 8\text{ }\Omega$ ;  $V_{MODE} = 0\text{ V}$ ;  $V_i = 0\text{ V}$ ; measured in test circuit **Figure 15**; unless otherwise specified.

| Symbol               | Parameter                          | Conditions              | Min            | Typ  | Max            | Unit          |
|----------------------|------------------------------------|-------------------------|----------------|------|----------------|---------------|
| $V_{CC}$             | supply voltage                     | operating               | 4.5            | 12   | 18             | V             |
| $I_q$                | quiescent supply current           | $R_L = \infty$          | [1] -          | 40   | 50             | mA            |
| $I_{stb}$            | standby supply current             | $V_{MODE} = V_{CC}$     | -              | -    | 10             | $\mu\text{A}$ |
| $V_O$                | DC output voltage                  |                         | [2] -          | 6    | -              | V             |
| $\Delta V_{OUT}$ [3] | differential output voltage offset |                         | -              | -    | 170            | mV            |
| $V_{MODE}$           | mode selection input voltage       | operating mode          | 0              | -    | 1.0            | V             |
|                      |                                    | mute mode               | 3.5            | -    | $V_{CC} - 1.5$ | V             |
|                      |                                    | standby mode            | $V_{CC} - 0.5$ | -    | $V_{CC}$       | V             |
| $I_{MODE}$           | mode selection input current       | $0 < V_{MODE} < V_{CC}$ | -              | -    | 20             | $\mu\text{A}$ |
| $V_{GC}$             | gain control voltage (pin GC)      | pin GC not connected    | -              | 2.75 | -              | V             |
| $I_{GC}$             | current into pin GC                | $V_{GC} = 0\text{ V}$   | -              | 600  | -              | $\mu\text{A}$ |

- [1] With a load connected at the outputs the quiescent current will increase, the maximum of this increase being equal to the differential output voltage offset ( $\Delta V_{OUT}$ ) divided by the load resistance ( $R_L$ ).
- [2] The DC output voltage with respect to ground is approximately  $0.5V_{CC}$ .
- [3]  $\Delta V_{OUT} = |V_{OUT+} - V_{OUT-}|$ .





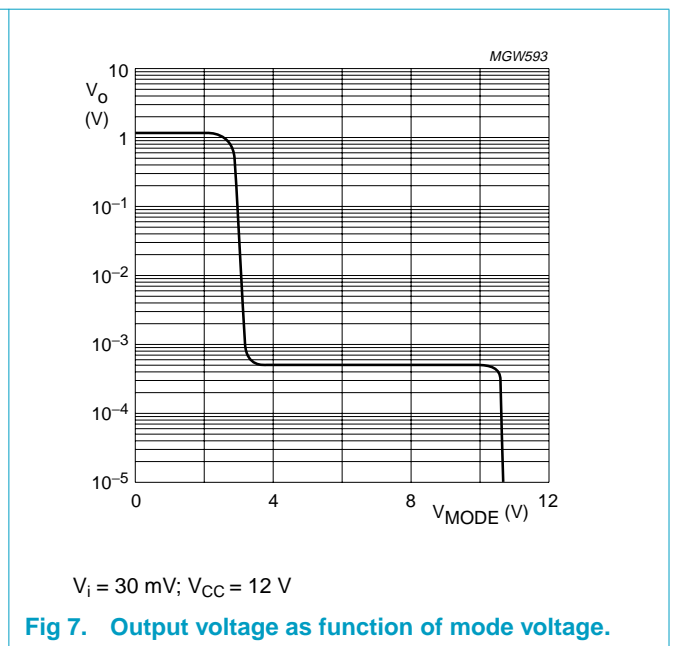
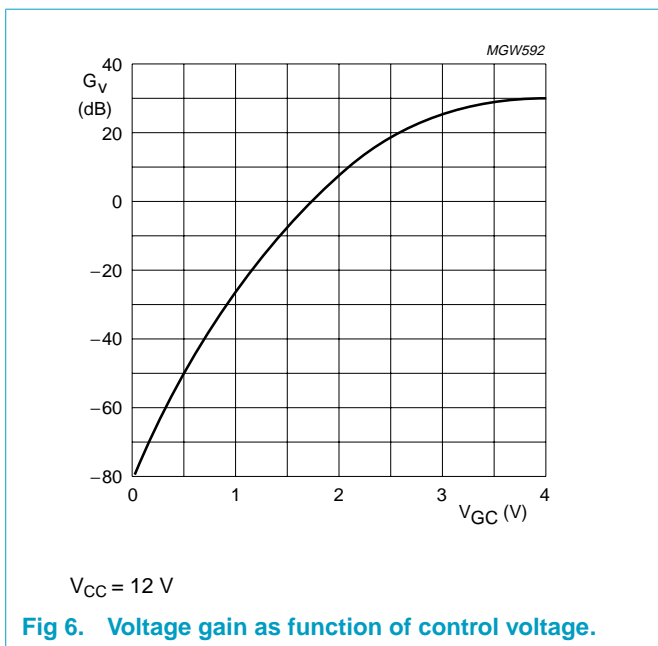
## 12. Dynamic characteristics

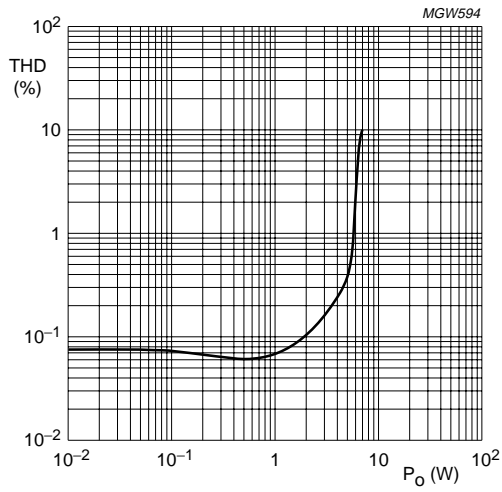
**Table 8: Dynamic characteristics**

$V_{CC} = 12\text{ V}$ ;  $T_{amb} = 25\text{ }^\circ\text{C}$ ;  $R_L = 8\text{ }\Omega$ ;  $f = 1\text{ kHz}$ ;  $V_{MODE} = 0\text{ V}$ ;  $G_v = 30\text{ dB}$ ;  $V_{GC} = 4.0\text{ V}$ ; measured in test circuit *Figure 15*; unless otherwise specified.

| Symbol         | Parameter                       | Conditions                                     | Min   | Typ  | Max | Unit          |
|----------------|---------------------------------|--|-------|------|-----|---------------|
| $P_o$          | output power                    | THD = 10%                                      | 6     | 7    | -   | W             |
|                |                                 | THD = 0.5%                                     | -     | 5    | -   | W             |
| THD            | total harmonic distortion       | $P_o = 1\text{ W}$                             | -     | 0.07 | 0.5 | %             |
| $G_{v(max)}$   | maximum voltage gain            |  | 29    | 30   | 31  | dB            |
| $G_{v(cr)}$    | gain control range              | $0.5 < V_{GC} < 4.0\text{ V}$                  | -     | 80   | -   | dB            |
| $V_{i(rms)}$   | input voltage (RMS value)       | $G_v = 0\text{ dB}$ ; THD <1%                  | 1.0   | -    | -   | V             |
| $Z_{i(dif)}$   | differential input impedance    |  | 50    | 65   | -   | k $\Omega$    |
| $V_{n(o)}$     | noise output voltage            | $V_{GC} = 4.0\text{ V}$                        | [1] - | 120  | 150 | $\mu\text{V}$ |
|                |                                 | $V_{GC} = 1.0\text{ V}$                        | [1] - | 30   | -   | $\mu\text{V}$ |
| SVRR           | supply voltage ripple rejection | $f_{ripple} = 1\text{ kHz}$                    | [2] - | 55   | -   | dB            |
|                |                                 | $f_{ripple} = 100\text{ Hz to } 20\text{ kHz}$ | [2] - | 55   | -   | dB            |
| $V_{o(mute)}$  | output voltage                  | mute mode                                      | [3] - | 30   | 50  | $\mu\text{V}$ |
| $\alpha_{cs}$  | channel separation              | $R_{source} = 0\text{ }\Omega$                 | 50    | 75   | -   | dB            |
| $ \Delta G_v $ | channel unbalance               | $G_v = 0\text{ dB}$ ; $V_{GC} = 1.8\text{ V}$  | -     | -    | 1   | dB            |

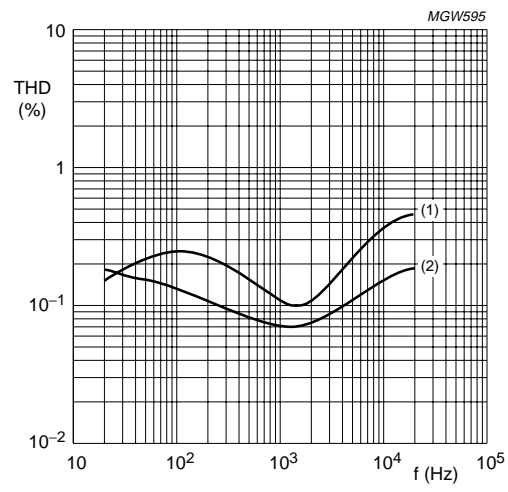
- [1] The noise output voltage is measured at the output in a frequency range from 20 Hz to 20 kHz (unweighted), with a source impedance  $R_{source} = 0\text{ }\Omega$  at the input.
- [2] Supply voltage ripple rejection is measured at the output, with a source impedance  $R_{source} = 0\text{ }\Omega$  at the input. The ripple voltage is a sine wave with a frequency  $f_{ripple}$  and an amplitude of 700 mV (RMS), which is applied to the positive supply rail.
- [3] Output voltage in mute mode is measured with  $V_{GC} = 0\text{ V}$  and an input voltage of 1 V (RMS) in a bandwidth of 20 kHz, thus including noise.





$V_{CC} = 12\text{ V}$

Fig 8. Total harmonic distortion as function of output power.

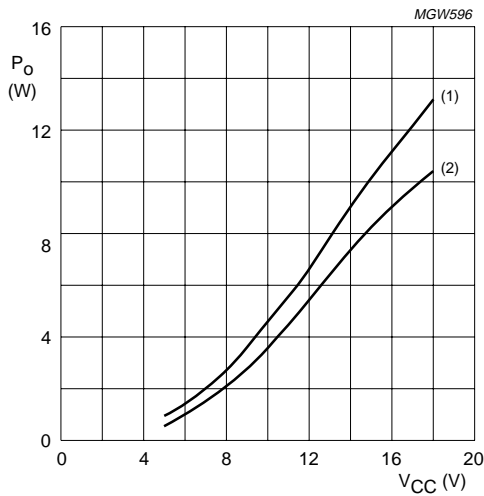


$V_{CC} = 12\text{ V}$ ; no bandpass filter applied

(1)  $P_o = 0.1\text{ W}$

(2)  $P_o = 1\text{ W}$

Fig 9. Total harmonic distortion as function of frequency.

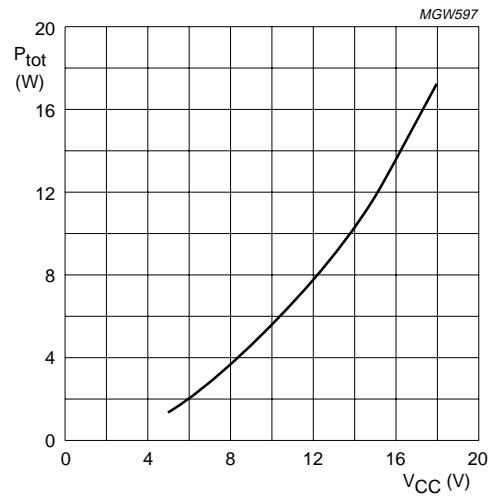


$R_L = 8\ \Omega$

(1) THD = 10%

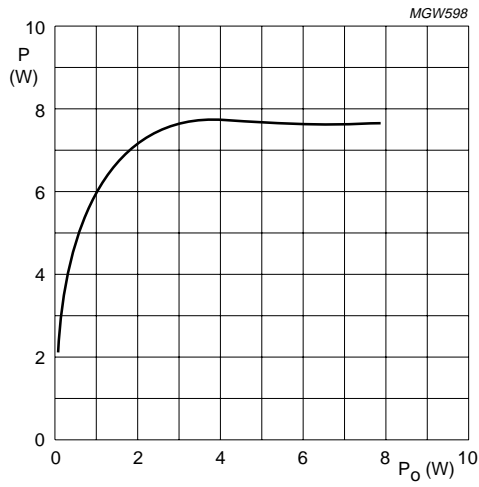
(2) THD = 1%

Fig 10. Output power as function of supply voltage.



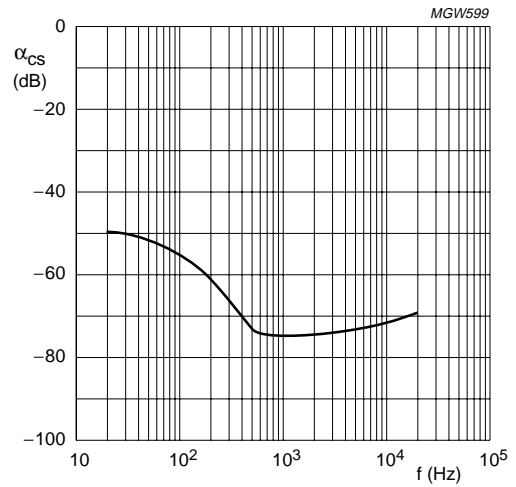
$R_L = 8\ \Omega$

Fig 11. Total power dissipation (worst-case) as function of supply voltage.



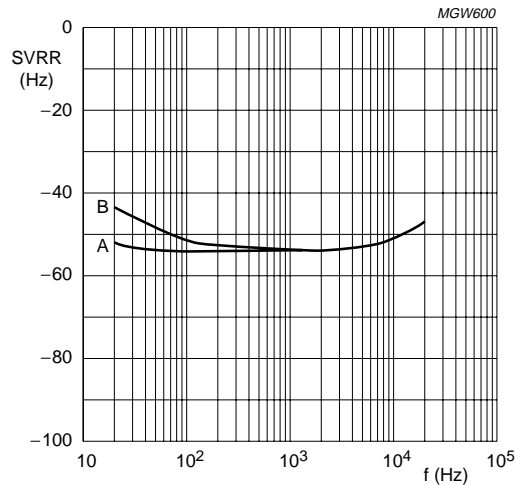
$V_{CC} = 12\text{ V}; R_L = 8\ \Omega$

Fig 12. Power dissipation as function of output power.



$V_{CC} = 12\text{ V};$  no bandpass filter applied

Fig 13. Channel separation as function of frequency.



$V_{CC} = 12\text{ V}; R_{\text{source}} = 0\ \Omega; V_{\text{ripple}} = 707\text{ mV (RMS)}$ ; a bandpass filter of 10 Hz to 80 kHz has been applied.

Curve A: inputs short-circuited

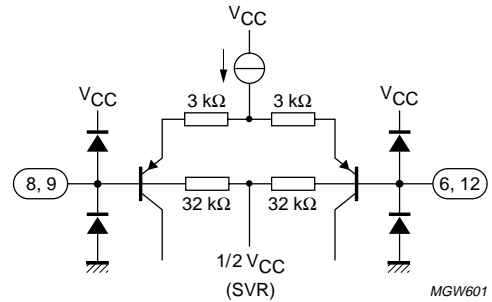
Curve B: inputs short-circuited and connected to ground.

Fig 14. Supply voltage ripple rejection as function of frequency.

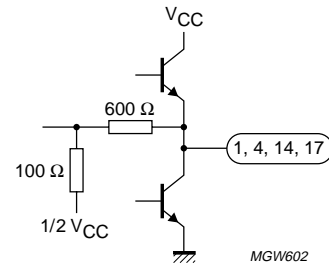
13. Internal circuitry

Table 9: Internal circuitry

| Pin      | Symbol        | Equivalent circuit |
|----------|---------------|--------------------|
| 6 and 8  | IN1+ and IN1- |                    |
| 12 and 9 | IN2+ and IN2- |                    |



|           |                 |
|-----------|-----------------|
| 1 and 4   | OUT1- and OUT1+ |
| 14 and 17 | OUT2- and OUT2+ |



|    |      |
|----|------|
| 10 | MODE |
|----|------|

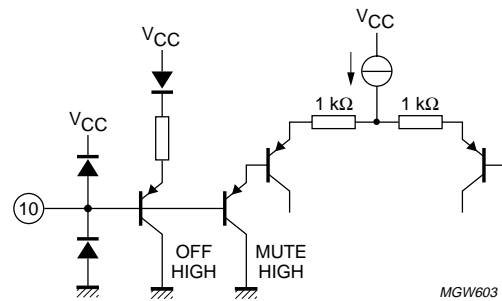
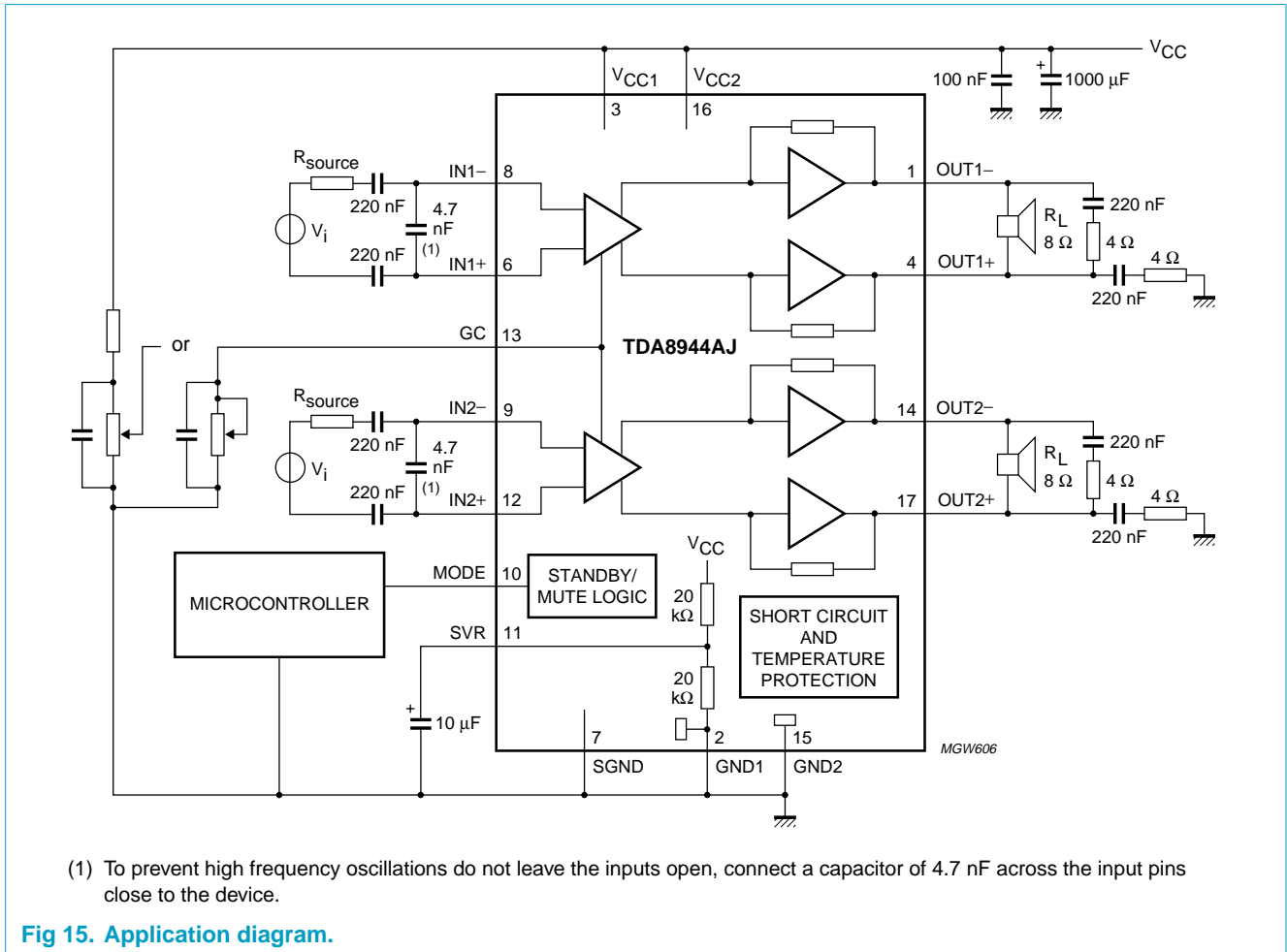


Table 9: Internal circuitry...continued

| Pin | Symbol | Equivalent circuit |
|-----|--------|--------------------|
| 11  | SVR    |                    |
| 13  | GC     |                    |

## 14. Application information



### 14.1 Printed-circuit board

#### 14.1.1 Layout and grounding

For a high system performance level certain grounding techniques are essential. The input reference grounds have to be tied with their respective source grounds and must have separate tracks from the power ground tracks; this will prevent the large (output) signal currents from interfering with the small AC input signals. The small-signal ground tracks should be physically located as far as possible from the power ground tracks. Supply and output tracks should be as wide as possible for delivering maximum output power.

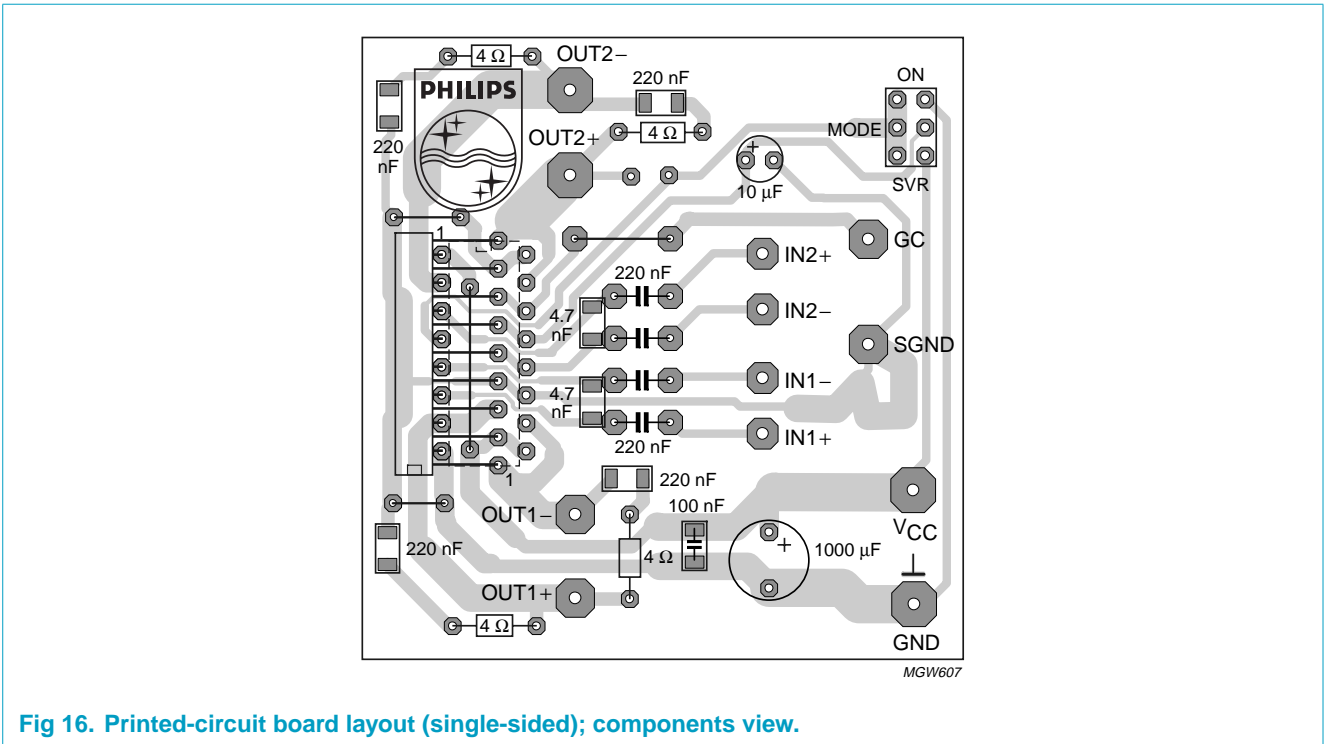


Fig 16. Printed-circuit board layout (single-sided); components view.

### 14.1.2 Power supply decoupling

Proper supply bypassing is critical for low-noise performance and high supply voltage ripple rejection. The respective capacitor location should be as close as possible to the device and grounded to the power ground. Proper power supply decoupling also prevents oscillations.

For suppressing higher frequency transients (spikes) on the supply line a capacitor with low ESR - typical 100 nF - has to be placed as close as possible to the device. For suppressing lower frequency noise and ripple signals, a large electrolytic capacitor - e.g. 1000 µF or greater - must be placed close to the device.

The bypass capacitor on the SVR pin reduces the noise and ripple on the midrail voltage. For good THD and noise performance a low ESR capacitor is recommended.

## 14.2 Thermal behaviour and heatsink calculation

The measured maximum thermal resistance of the IC package,  $R_{th(j-mb)}$  is 4.5 K/W. A calculation for the heatsink can be made, with the following parameters:

- $T_{amb} = 50 \text{ }^\circ\text{C}$
- $V_{CC} = 12 \text{ V}$  and  $R_L = 8 \text{ } \Omega$
- $T_{j(max)} = 150 \text{ }^\circ\text{C}$

$R_{th(tot)}$  is the total thermal resistance between the junction and the ambient including the heatsink. In the heatsink calculations the value of  $R_{th(mb-h)}$  is ignored.

At  $V_{CC} = 12\text{ V}$  and  $R_L = 8\ \Omega$  the measured worst-case sine-wave dissipation is 8 W; see [Figure 12](#). For  $T_{j(\max)} = 150\text{ }^\circ\text{C}$  the temperature rise - caused by the power dissipation - is:  $150 - 50 = 100\text{ }^\circ\text{C}$ .

$$P \times R_{th(\text{tot})} = 100\text{ }^\circ\text{C}$$

$$R_{th(\text{tot})} = 100/8 = 12.5\text{ K/W}$$

$$R_{th(\text{h-a})} = R_{th(\text{tot})} - R_{th(\text{j-mb})} = 12.5 - 4.5 = 8.0\text{ K/W.}$$

The calculation above is for an application at worst-case (stereo) sine-wave output signals. In practice music signals will be applied, which decreases the maximum power dissipation to approximately half of the sine-wave power dissipation (see [Section 8.2.2](#)). This allows for the use of a smaller heatsink:

$$P \times R_{th(\text{tot})} = 100\text{ }^\circ\text{C}$$

$$R_{th(\text{tot})} = 100/(0.5 \times 8) = 25\text{ K/W}$$

$$R_{th(\text{h-a})} = R_{th(\text{tot})} - R_{th(\text{j-mb})} = 25 - 4.5 = 20.5\text{ K/W.}$$

To increase the lifetime of the IC,  $T_{j(\max)}$  should be reduced to  $125\text{ }^\circ\text{C}$ . This requires a heatsink of approximately 14 K/W for music signals.

## 15. Test information

### 15.1 Quality information

The “*General Quality Specification for Integrated Circuits, SNW-FQ-611D*” is applicable (ordering code 9397 750 05459).

#### 15.1.1 Test conditions

$T_{\text{amb}} = 25\text{ }^\circ\text{C}$ ;  $V_{CC} = 12\text{ V}$ ;  $f = 1\text{ kHz}$ ;  $R_L = 8\ \Omega$ ; audio pass band 22 Hz to 22 kHz; unless otherwise specified.

**Remark:** In the graphs as function of frequency no bandpass filter was applied; see [Figure 9](#) and [13](#).



16. Package outline

DBS17P: plastic DIL-bent-SIL power package; 17 leads (lead length 12 mm)

SOT243-1

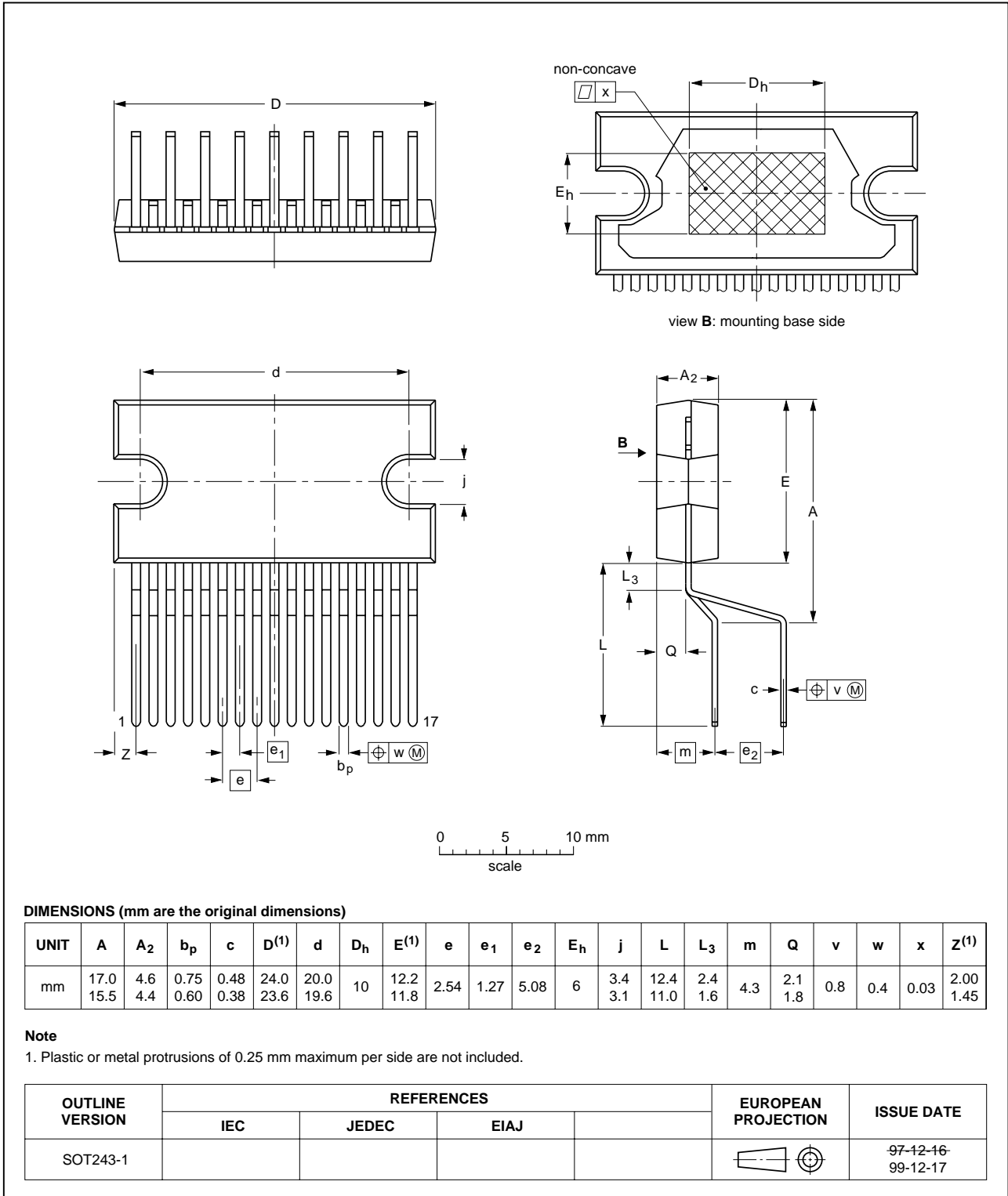


Fig 17. DBS17P package outline.

## 17. Soldering

### 17.1 Introduction to soldering through-hole mount packages

This text gives a brief insight to wave, dip and manual soldering. A more in-depth account of soldering ICs can be found in our *Data Handbook IC26; Integrated Circuit Packages* (document order number 9398 652 90011).

Wave soldering is the preferred method for mounting of through-hole mount IC packages on a printed-circuit board.

### 17.2 Soldering by dipping or by solder wave

The maximum permissible temperature of the solder is 260 °C; solder at this temperature must not be in contact with the joints for more than 5 seconds. The total contact time of successive solder waves must not exceed 5 seconds.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified maximum storage temperature ( $T_{stg(max)}$ ). If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

### 17.3 Manual soldering

Apply the soldering iron (24 V or less) to the lead(s) of the package, either below the seating plane or not more than 2 mm above it. If the temperature of the soldering iron bit is less than 300 °C it may remain in contact for up to 10 seconds. If the bit temperature is between 300 and 400 °C, contact may be up to 5 seconds.

### 17.4 Package related soldering information

**Table 10: Suitability of through-hole mount IC packages for dipping and wave soldering methods**

| Package                   | Soldering method |                         |
|---------------------------|------------------|-------------------------|
|                           | Dipping          | Wave                    |
| DBS, DIP, HDIP, SDIP, SIL | suitable         | suitable <sup>[1]</sup> |

[1] For SDIP packages, the longitudinal axis must be parallel to the transport direction of the printed-circuit board.

## 18. Revision history

**Table 11: Revision history**

| Rev | Date     | CPCN | Description                   |
|-----|----------|------|-------------------------------|
| 01  | 20020301 | -    | Product data (9397 750 09433) |

## 19. Data sheet status

| Data sheet status <sup>[1]</sup> | Product status <sup>[2]</sup> | Definition   |
|----------------------------------|-------------------------------|--|
| Objective data                   | Development                   | This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.  |
| Preliminary data                 | Qualification                 | This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.                                     |
| Product data                     | Production                    | This data sheet contains data from the product specification. Philips Semiconductors reserves the right to make changes at any time in order to improve the design, manufacturing and supply. Changes will be communicated according to the Customer Product/Process Change Notification (CPCN) procedure SNW-SQ-650A. |

[1] Please consult the most recently issued data sheet before initiating or completing a design.

[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL <http://www.semiconductors.philips.com>.

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**Limiting values definition** — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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Printed in The Netherlands

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Date of release: 01 March 2002

Document order number: 9397 750 09433



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