## INTEGRATED CIRCUITS

## DATA SHEET

For a complete data sheet, please also download:

- The IC06 74HC/HCT/HCU/HCMOS Logic Family Specifications
- The IC06 74HC/HCT/HCU/HCMOS Logic Package Information
- The IC06 74HC/HCT/HCU/HCMOS Logic Package Outlines

# **74HC/HCT166** 8-bit parallel-in/serial-out shift register

Product specification
File under Integrated Circuits, IC06

December 1990

Philips Semiconductors





### 74HC/HCT166

#### **FEATURES**

- · Synchronous parallel-to-serial applications
- Synchronous serial data input for easy expansion
- · Clock enable for "do nothing" mode
- · Asynchronous master reset
- For asynchronous parallel data load see "165"
- · Output capability: standard
- · I<sub>CC</sub> category: MSI

#### **GENERAL DESCRIPTION**

The 74HC/HCT166 are high-speed Si-gate CMOS devices and are pin compatible with low power Schottky TTL (LSTTL). They are specified in compliance with JEDEC standard no. 7A.

The 74HC/HCT166 are 8-bit shift registers which have a fully synchronous serial or parallel data entry selected by

an active LOW parallel enable  $(\overline{PE})$  input. When  $\overline{PE}$  is LOW one set-up time prior to the LOW-to-HIGH clock transition, parallel data is entered into the register. When  $\overline{PE}$  is HIGH, data is entered into the internal bit position  $Q_0$  from serial data input  $(D_s)$ , and the remaining bits are shifted one place to the right  $(Q_0 \to Q_1 \to Q_2,$  etc.) with each positive-going clock transition.

This feature allows parallel-to-serial converter expansion by tying the  $Q_7$  output to the  $D_s$  input of the succeeding stage.

The clock input is a gated-OR structure which allows one input to be used as an active LOW clock enable  $(\overline{CE})$  input. The pin assignment for the CP and  $\overline{CE}$  inputs is arbitrary and can be reversed for layout convenience. The LOW-to-HIGH transition of input  $\overline{CE}$  should only take place while CP is HIGH for predictable operation. A LOW on the master reset  $(\overline{MR})$  input overrides all other inputs and clears the register asynchronously, forcing all bit positions to a LOW state.

#### **QUICK REFERENCE DATA**

GND = 0 V;  $T_{amb} = 25 \, ^{\circ}C$ ;  $t_r = t_f = 6 \, \text{ns}$ 

SYMBOL	PARAMETER	CONDITIONS	TYP	UNIT		
STIVIBUL	PARAMETER	CONDITIONS	нс	нст	ONII	
t <sub>PHL</sub> / t <sub>PLH</sub>	propagation delay <u>CP</u> to Q <sub>7</sub> MR to Q <sub>7</sub>	$C_L = 15 \text{ pF}; V_{CC} = 5 \text{ V}$	15 14	20 19	ns ns	
f <sub>max</sub>	maximum clock frequency		63	50	MHz	
Cı	input capacitance		3.5	3.5	pF	
C <sub>PD</sub>	power dissipation capacitance per package	notes 1 and 2	41	41	pF	

#### Notes

1.  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu W$ ):

$$P_D = C_{PD} \times V_{CC}^2 \times f_i + \sum (C_1 \times V_{CC}^2 \times f_o)$$
 where:

f<sub>i</sub> = input frequency in MHz

 $f_0$  = output frequency in MHz

 $\sum (C_L \times V_{CC}^2 \times f_0) = \text{sum of outputs}$ 

C<sub>L</sub> = output load capacitance in pF

V<sub>CC</sub> = supply voltage in V

2. For HC the condition is  $V_I = GND$  to  $V_{CC}$ For HCT the condition is  $V_I = GND$  to  $V_{CC} - 1.5$  V

#### **ORDERING INFORMATION**

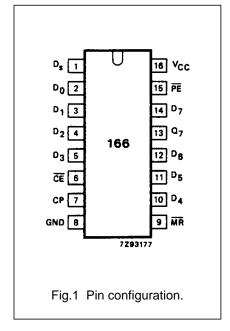
See "74HC/HCT/HCU/HCMOS Logic Package Information".

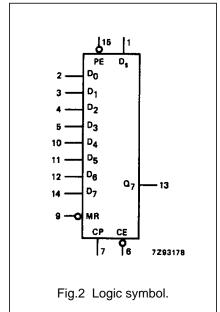
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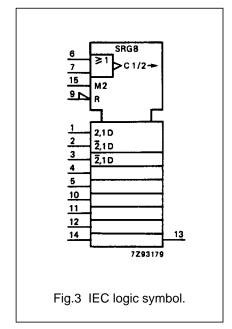
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#### **PIN DESCRIPTION**

PIN NO.	SYMBOL	NAME AND FUNCTION
1	Ds	serial data input
2, 3, 4, 5, 10, 11, 12, 14	D <sub>0</sub> to D <sub>7</sub>	parallel data inputs
6	CE	clock enable input (active LOW)
7	СР	clock input (LOW-to-HIGH edge-triggered)
8	GND	ground (0 V)
9	MR	asynchronous master reset (active LOW)
13	Q <sub>7</sub>	serial output from the last stage
15	PE	parallel enable input (active LOW)
16	V <sub>CC</sub>	positive supply voltage

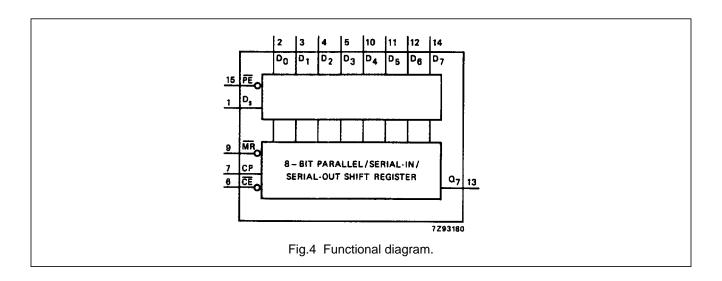






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#### **FUNCTION TABLE**

OPERATING MODES			INPU	TS		Q <sub>n</sub> R	REGISTER	OUTPUT	
OPERATING MODES	PE	CE	СР	Ds	D <sub>0</sub> -D <sub>7</sub>	$Q_0$	Q <sub>1</sub> -Q <sub>6</sub>	Q <sub>7</sub>	
parallel load	l I	I I	<b>↑</b>	X X	l - l h - h	L H	L - L H - H	L H	
serial shift	h h	l I	<b>↑</b>	l h	X - X X - X	L H	q <sub>0</sub> - q <sub>5</sub> q <sub>0</sub> - q <sub>5</sub>	9 <sub>6</sub>	
hold "do nothing"	Х	h	Х	Х	X - X	$q_0$	q <sub>1</sub> - q <sub>6</sub>	q <sub>7</sub>	

#### Notes

1. H = HIGH voltage level

h = HIGH voltage level one set-up time prior to the LOW-to-HIGH CP transition

L = LOW voltage level

I = LOW voltage level one set-up time prior to the LOW-to-HIGH CP transition

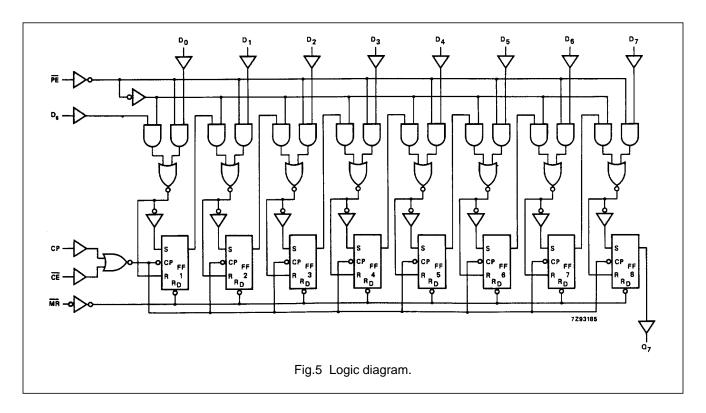
 ${\bf q}$  = lower case letters indicate the state of the referenced output one set-up time prior to the LOW-to-HIGH CP transition

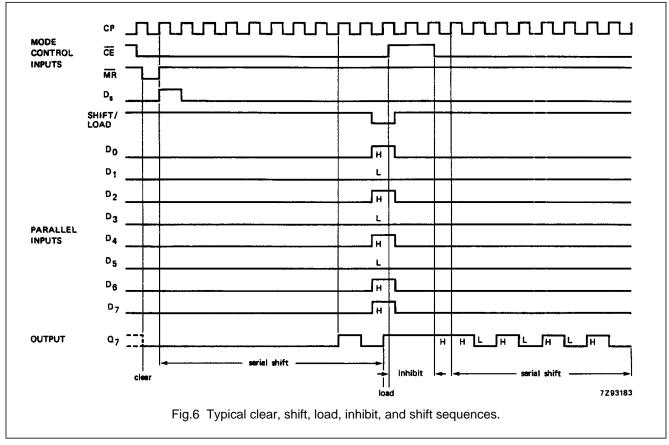
X = don't care

↑ = LOW-to-HIGH CP transition

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#### DC CHARACTERISTICS FOR 74HC

For the DC characteristics see "74HC/HCT/HCU/HCMOS Logic Family Specifications".

Output capability: standard

I<sub>CC</sub> category: MSI

#### **AC CHARACTERISTICS FOR 74HC**

 $GND = 0 V; t_r = t_f = 6 ns; C_L = 50 pF$ 

		T <sub>amb</sub> (°C)								TEST CONDITIONS	
SYMBOL	PARAMETER				74HC	UNIT		WAVEFORMS			
STIVIBUL		+25		-40 to +85		-40 to +125		UNIT	V <sub>CC</sub>	WAVEFORMS	
		min.	typ.	max.	min.	max.	min.	max.		(1)	
t <sub>PHL</sub> / t <sub>PLH</sub>	propagation delay CP to Q <sub>7</sub>		50 18 14	150 30 26		190 38 33		225 45 38	ns	2.0 4.5 6.0	Fig.7
t <sub>PHL</sub>	propagation delay MR to Q <sub>7</sub>		47 17 14	160 32 27		200 40 34		240 48 41	ns	2.0 4.5 6.0	Fig.8
t <sub>THL</sub> / t <sub>TLH</sub>	output transition time		19 7 6	75 15 13		95 19 16		110 22 19	ns	2.0 4.5 6.0	Fig.7
t <sub>W</sub>	clock pulse width HIGH or LOW	80 16 14	17 6 5		100 20 17		120 24 20		ns	2.0 4.5 6.0	Fig.7
t <sub>W</sub>	master reset pulse width LOW	100 20 17	25 9 7		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig.8
t <sub>rem</sub>	removal time MR to CP	0 0 0	-19 -7 -6		0 0 0		0 0 0		ns	2.0 4.5 6.0	Fig.8
t <sub>su</sub>	set-up time D <sub>n</sub> , CE to CP	80 16 14	14 5 4		100 20 17		120 24 20		ns	2.0 4.5 6.0	Fig.9
t <sub>su</sub>	set-up time PE to CP	100 20 17	33 12 10		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig.8
t <sub>h</sub>	hold time D <sub>n</sub> , CE to CP	2 2 2	-8 -3 -2		2 2 2		2 2 2		ns	2.0 4.5 6.0	Fig.8
t <sub>h</sub>	hold time PE to CP	0 0 0	-28 -10 -8		0 0 0		0 0 0		ns	2.0 4.5 6.0	Fig.9
f <sub>max</sub>	maximum clock pulse frequency	6.0 30 35	19 57 68		4.8 24 28		4.0 20 24		MHz	2.0 4.5 6.0	Fig.7

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#### DC CHARACTERISTICS FOR 74HCT

For the DC characteristics see "74HC/HCT/HCU/HCMOS Logic Family Specifications".

Output capability: standard

I<sub>CC</sub> category: MSI

#### Note to HCT types

The value of additional quiescent supply current ( $\Delta I_{CC}$ ) for a unit load of 1 is given in the family specifications. To determine  $\Delta I_{CC}$  per input, multiply this value by the unit load coefficient shown in the table below.

INPUT	UNIT LOAD COEFFICIENT
D <sub>0</sub> to D <sub>7</sub>	0.35
Ds	0.35
CP	0.80
CP CE	0.80
MR	0.40
PE	0.60

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#### **AC CHARACTERISTICS FOR 74HCT**

 $GND = 0 V; t_r = t_f = 6 ns; C_L = 50 pF$ 

		T <sub>amb</sub> (°C)								TEST CONDITIONS	
SYMBOL	PARAMETER	74HCT									WAVEFORMS
		+25			-40 to +85		-40 to +125		UNIT	V <sub>CC</sub> (V)	WAVEFORMS
		min.	typ.	max.	min.	max.	min.	max.		(,,	
t <sub>PHL</sub> / t <sub>PLH</sub>	propagation delay CP to Q <sub>7</sub>		23	40		50		60	ns	4.5	Fig.7
t <sub>PHL</sub>	propagation delay MR to Q <sub>7</sub>		22	40		50		60	ns	4.5	Fig.8
t <sub>THL</sub> / t <sub>TLH</sub>	output transition time		7	15		19		22	ns	4.5	Fig.7
t <sub>W</sub>	clock pulse width HIGH or LOW	20	9		25		30		ns	4.5	Fig.7
t <sub>W</sub>	master reset pulse width LOW	25	11		31		38		ns	4.5	Fig.8
t <sub>rem</sub>	removal time MR to CP	0	-7		0		0		ns	4.5	Fig.8
t <sub>su</sub>	set-up time D <sub>n</sub> , CE to CP	16	8		20		24		ns	4.5	Fig.9
t <sub>su</sub>	set-up time PE to CP	30	15		38		45		ns	4.5	Fig.8
t <sub>h</sub>	hold time D <sub>n</sub> , $\overline{\text{CE}}$ to CP	0	-3		0		0		ns	4.5	Fig.9
t <sub>h</sub>	hold time PE to CP	0	-13		0		0		ns	4.5	Fig.9
f <sub>max</sub>	maximum clock pulse width	25	45		20		17		MHz	4.5	Fig.7

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#### **AC WAVEFORMS**

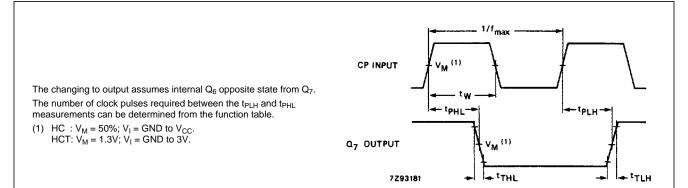


Fig.7 Waveforms showing the clock (CP) to output (Q<sub>7</sub>) propagation delays, the clock pulse width, the output transition times and the maximum clock frequency.

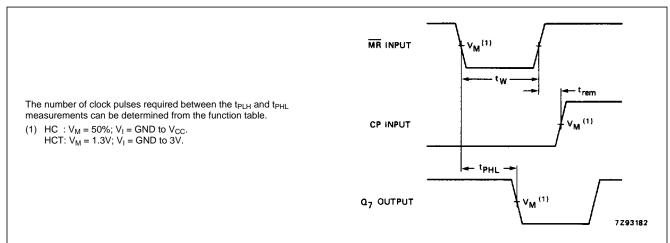
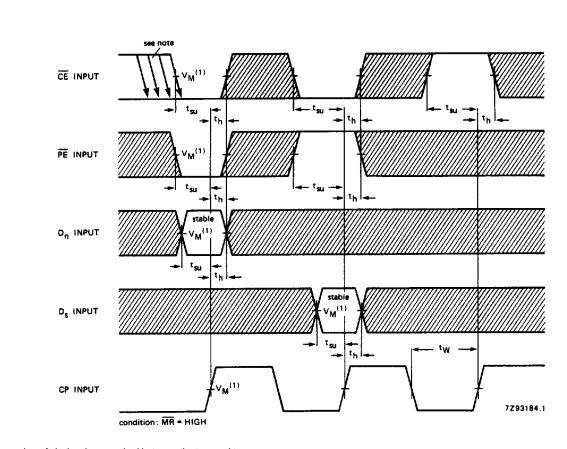


Fig.8 Waveforms showing the master reset (MR) pulse width, the master reset to output (Q<sub>7</sub>) propagation delay and the master reset to clock (CP) removal time.

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The number of clock pulses required between the  $t_{\rm PLH}$  and  $t_{\rm PHL}$  measurements can be determined from the function table.

 $\overline{\text{CE}}$  may change only from HIGH-to-LOW while CP is LOW.

The shaded areas indicate when the input is permitted to change for predictable output performance.

(1) HC :  $V_M = 50\%$ ;  $V_I = GND$  to  $V_{CC}$ . HCT:  $V_M = 1.3V$ ;  $V_I = GND$  to 3V.

Fig.9 Waveforms showing the set-up and hold times from the serial data input ( $D_s$ ), the data inputs ( $D_n$ ), the clock enable input (LOW  $\overline{CE}$ ), the clock enable input  $\overline{CE}$  and the parallel enable input to the clock (CP).

#### **PACKAGE OUTLINES**

See "74HC/HCT/HCU/HCMOS Logic Package Outlines".