## Low Cost Six Channel LED Backlight Driver with Integrated Power Supply

The 34845 series represents high efficiency LED drivers for use in backlighting LCD displays from 10 " to $17^{\prime \prime}$. Operating from supplies of 5.0 to 21 V , the 34845 series is capable of driving up to 16 LEDs in series in six separate strings. The LED current tolerance in the six strings is within $\pm 2 \%$ maximum and is set using a resistor to GND. PWM dimming is performed by applying a PWM input signal to the PWM pin which modulates the LED channels directly. An Enable Pin (EN) provides for low power standby. Alternatively, a single wire scheme selects power down when PWM is connected to the Wake Pin and held low.

The integrated boost converter uses dynamic headroom control to automatically set the output voltage. There are three device versions for boost frequency; $34845 / \mathrm{C}$ is $600 \mathrm{kHz}, 34845 \mathrm{~A}$ is 1.2 MHz and the $34845 \mathrm{~B} / \mathrm{D}$ is 300 kHz . External compensation allows the use of different inductor/ capacitor combinations.
The 34845 includes fault protection modes for LED short and open, over temperature, over current and over voltage errors. It features an internally fixed OVP value of 60 V (typical) which protects the device in the event of a failure in the externally programmed OVP. The OVP level can be set by using an external resistor divider. This device is powered using SMARTMOS technology.

## Features

- Input voltage of 5.0 to 21 V
- Boost output voltage up to 60 V
- 2.0 A integrated boost FET
- Fixed boost frequency - $300 \mathrm{kHz}, 600 \mathrm{kHz}$ or 1.2 MHz
- OTP, OCP, UVLO fault detection
- LED short/open protection
- Programmable LED current between 3.0 mA and 30 mA
- 24 -Ld $4 \times 4 \times 0.65 \mathrm{~mm} \mu$ QFN Package


## 34845 34845A/B/C/D

## LED DRIVER

98ASA00087D
24-PIN QFN-EP

## Applications

- PC notebooks
- Netbooks
- GPS screens
- Portable DVD players
- Picture frames
- Smaller screen televisions
- Industrial/instrumentation displays
- Health care device displays


Figure 1. 34845 Simplified Application Diagram

## 1 Orderable Parts

Table 1. Device Variations

| Part Number ${ }^{(1)}$ | Temperature ( $\mathrm{T}_{\mathrm{A}}$ ) | Package | Boost Switch Current Limit IBoost_Limit (A) |  |  | Switching Frequency $\mathrm{f}_{\mathrm{S}}(\mathrm{kHz})$ |  |  | Slope Compensation$\mathrm{V}_{\text {SLOPE }}(\mathrm{V} / \mu \mathrm{s})$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max |
| MC34845EP | -40 to $85{ }^{\circ} \mathrm{C}$ | 24 QFN-EP | 1.9 | 2.1 | 2.3 | 540 | 600 | 660 | - | 0.52 | - |
| MC34845AEP |  |  | 1.9 | 2.1 | 2.3 | 1080 | 1200 | 1320 | - | 0.73 | - |
| MC34845BEP |  |  | 2.1 | 2.35 | 2.6 | 270 | 300 | 330 | - | 0.22 | - |
| MC34845CEP |  |  | 1.9 | 2.1 | 2.3 | 540 | 600 | 660 | - | 0.52 | - |
| MC34845DEP |  |  | 2.1 | 2.35 | 2.6 | 270 | 300 | 330 | - | 0.22 | - |

Notes

1. To order parts in Tape and Reel, add the R2 suffix to the part number.

## INTERNAL BLOCK DIAGRAM



Figure 2. 34845 Simplified Internal Block Diagram

## ELECTRICAL CHARACTERISTICS

## ABSOLUTE MAXIMUM RATINGS

Table 2. Absolute Maximum Ratings
All voltages are with respect to ground unless otherwise noted. Exceeding these ratings may cause a malfunction or permanent damage to the device.

| Ratings | Symbol | Value | Unit |
| :---: | :---: | :---: | :---: |

ELECTRICAL RATINGS

| Maximum Pin Voltages | $\mathrm{V}_{\text {MAX }}$ | V |
| :--- | :---: | :---: |
| SWA, SWB, VOUT |  | -0.3 to 65 |
| CH1, CH2, CH3, CH4, CH5, CH6 (Off state) | -0.3 to 45 |  |
| CH1, CH2, CH3, CH4, CH5, CH6 (On state) | -0.3 to 20 |  |
| FAIL | -0.3 to 7.0 |  |
| OVP |  | -0.3 to 7.75 |
| COMP, ISET |  | -0.3 to 2.7 |
| PWM, WAKE |  | -0.3 to 5.5 |
| EN, VIN | $\mathrm{I}_{\text {LED_MAX }}$ | -0.3 to 24 |
| Maximum LED Current per Channel | 33 |  |
| ESD Voltage ${ }^{(2)}$ |  | $\pm 2000$ |
| Human Body Model (HBM) |  | $\pm 200$ |
| Machine Model (MM) |  | mA |

THERMAL RATINGS

| Operating Ambient Temperature Range | $\mathrm{T}_{\mathrm{A}}$ | -40 to 85 | ${ }^{\circ} \mathrm{C}$ |
| :--- | :---: | :---: | :---: |
| Maximum Junction Temperature | $\mathrm{T}_{\mathrm{J}}$ | 150 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $\mathrm{T}_{\mathrm{S}}$ | -40 to 150 | ${ }^{\circ} \mathrm{C}$ |
| Peak Package Reflow Temperature During Reflow ${ }^{(3),(4)}$ | $\mathrm{T}_{\text {PPRT }}$ | Note 4 | ${ }^{\circ} \mathrm{C}$ |
| Thermal Resistance Junction to Ambient ${ }^{(5)}$ | $\mathrm{T}_{\theta J \mathrm{~A}}$ | 36 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Thermal Resistance Junction to Case ${ }^{(6)}$ | $\mathrm{T}_{\text {日JC }}$ | 3.1 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Power Dissipation ${ }^{(5)}$ | $\mathrm{P}_{\mathrm{D}}$ |  | W |
| $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  | 3.4 |  |
| $\mathrm{~T}_{\mathrm{A}}=85^{\circ} \mathrm{C}$ |  | 1.8 |  |

## Notes

2. ESD testing is performed in accordance with the Human Body Model (HBM) (AEC-Q100-2) ( $C_{\text {ZAP }}=100 \mathrm{pF}, \mathrm{R}_{\text {ZAP }}=1500 \Omega$ ), and the Machine Model (MM) (C $\left.\mathrm{C}_{\text {ZAP }}=200 \mathrm{pF}, \mathrm{R}_{\text {ZAP }}=0 \Omega\right)$.
3. Pin soldering temperature limit is for 10 seconds maximum duration. Not designed for immersion soldering. Exceeding these limits may cause malfunction or permanent damage to the device.
4. Freescale's Package Reflow capability meets Pb-free requirements for JEDEC standard J-STD-020C. For Peak Package Reflow Temperature and Moisture Sensitivity Levels (MSL), Go to www.freescale.com, search by part number [e.g. remove prefixes/suffixes and enter the core ID to view all orderable parts. (i.e. MC33xxxD enter 33xxx), and review parametrics.
5. Per JEDEC51-8 Standard for Multilayer PCB.
6. Theoretical thermal resistance is from the die junction to the exposed pad.

## STATIC AND DYNAMIC ELECTRICAL CHARACTERISTICS

Table 3. Static and Dynamic Electrical Characteristics
Characteristics noted under conditions $\mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}, \mathrm{~V}_{\mathrm{OUT}}=35 \mathrm{~V}, \mathrm{I}_{\mathrm{LED}}=30 \mathrm{~mA}, \mathrm{f}_{\mathrm{S}}=600 \mathrm{kHz}, \mathrm{f}_{\mathrm{PWM}}=600 \mathrm{~Hz}-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq$ $85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values noted reflect the approximate parameter means at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ under nominal conditions, unless otherwise noted.

| Characteristic | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| SUPPLY |  |  |  |  |  |
| Supply Voltage | $\mathrm{V}_{\text {IN }}$ | 5.0 | 10 | 21 | V |
| Supply Current when in Shutdown Mode $\mathrm{EN}=\text { Low, PWM = Low }$ | Ishutdown | - | 2.0 | 10 | $\mu \mathrm{A}$ |
| ```Supply Current when Operational Mode Boost = Pulse Skipping, Channels =1% of Duty Cycle EN = High, PWM = Low``` | Ioperational | - | 5.0 | 6.5 | mA |
| Under-voltage Lockout $V_{\text {IN }}$ Rising | UVLO | 4.0 | - | 4.4 | V |
| Under-voltage Hysteresis $V_{\text {IN }}$ Falling | UVLO ${ }_{\text {HYST }}$ | - | 0.25 | - | V |
| $\begin{aligned} & \text { VDC1 Voltage }^{(7)} \\ & C_{\text {VDC } 1}=2.2 \mu \mathrm{~F} \end{aligned}$ | $\mathrm{V}_{\mathrm{DC} 1}$ | 2.4 | 2.5 | 2.6 | V |
| $\begin{aligned} & \text { VDC2 Voltage }{ }^{(7)}\left(\mathrm{V}_{\text {IN }} \text { between } 7.0 \text { and } 21 \mathrm{~V}\right) \\ & \mathrm{C}_{\mathrm{VD} 2 \mathrm{C}}=2.2 \mu \mathrm{~F} \end{aligned}$ | $\mathrm{V}_{\text {DC2 }}$ | 5.7 | 6.0 | 6.3 | V |

BOOST

| Output Voltage Range ${ }^{(8)}$ |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{VIN}=5.0 \mathrm{~V}$ | $\mathrm{V}_{\text {OUT1 }}$ | 8.0 | - | 43 | V |
| $\mathrm{VIN}=21 \mathrm{~V}$ | $\mathrm{V}_{\text {OUT2 }}$ | 24 | - | 60 |  |
| Boost Switch Current Limit | $\mathrm{I}_{\text {BOOST_LIMIT }}$ |  |  |  | A |
| 34845, 34845A, 34845C |  | 1.9 | 2.1 | 2.3 |  |
| 34845B, 34845D |  | 2.1 | 2.35 | 2.6 |  |
| Boost Switch Current Limit Timeout | $\mathrm{t}_{\text {BOOSt_time }}$ | - | 10 | - | ms |
| RDSON of Internal FET $\mathrm{I}_{\mathrm{DRAIN}}=1.0 \mathrm{~A}$ | $\mathrm{R}_{\text {DSON }}$ | - | 300 | 520 | $\mathrm{m} \Omega$ |
| Boost Switch Off state Leakage Current $V_{S W A, S W B}=60 \mathrm{~V}$ | $\mathrm{I}_{\text {BOOSt_LEAK }}$ | - | - | 1.0 | $\mu \mathrm{A}$ |
| Feedback pin Off-state Leakage Current $V_{\text {OUT }}=60 \mathrm{~V}$ | VOUTLEAK | - | - | 500 | $\mu \mathrm{A}$ |
| Peak Boost Efficiency ${ }^{(9)}$ $\mathrm{V}_{\text {OUT }}=33 \mathrm{~V}, \mathrm{RL}=330 \Omega$ | EFF ${ }_{\text {BOOST }}$ | - | 90 | - | \% |

Notes
7. This output is for internal use only and not to be used for other purposes.
8. Minimum and maximum output voltages are dependent on Min/Max duty cycle condition.
9. Boost efficiency test is performed under the following conditions: $\mathrm{f}_{\mathrm{SW}}=600 \mathrm{kHz}, \mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=33 \mathrm{~V}$ and $R_{\mathrm{L}}=330 \Omega$. The following external components are used: $L=10 \mu \mathrm{HDCR}=0.1 \Omega, C_{O U T}=3 \times 1 \mu \mathrm{~F}$ (ceramic), Schottky diode $\mathrm{V}_{\mathrm{F}}=0.35 \mathrm{~V}$.

Table 3. Static and Dynamic Electrical Characteristics (continued)
Characteristics noted under conditions $\mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}, \mathrm{~V}_{\mathrm{OUT}}=35 \mathrm{~V}$, $\mathrm{I}_{\mathrm{LED}}=30 \mathrm{~mA}, \mathrm{f}_{\mathrm{S}}=600 \mathrm{kHz}, \mathrm{f}_{\mathrm{PWM}}=600 \mathrm{~Hz}-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq$ $85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values noted reflect the approximate parameter means at $T_{A}=25^{\circ} \mathrm{C}$ under nominal conditions, unless otherwise noted.

| Characteristic | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |

BOOST (CONTINUED)

| Line Regulation $\mathrm{V}_{\mathrm{IN}}=7.0 \mathrm{~V} \text { to } 21 \mathrm{~V}, \mathrm{I}_{\mathrm{CH}}=30 \mathrm{~mA}$ | $\mathrm{I}_{\text {LED }} / \mathrm{V}_{\text {IN }}$ | -0.2 | - | 0.2 | \%/V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Load Regulation $\mathrm{V}_{\mathrm{LED}}=24 \mathrm{~V} \text { to } 40 \mathrm{~V} \text { (all Channels), } \mathrm{I}_{\mathrm{CH}}=30 \mathrm{~mA}$ | $\mathrm{I}_{\text {LED }} / \mathrm{V}_{\text {LED }}$ | -0.2 | - | 0.2 | \%/V |
| Minimum Duty Cycle | $\mathrm{D}_{\text {MIN }}$ | - | 10 | 15 | \% |
| Maximum Duty Cycle | $\mathrm{D}_{\text {MAX }}$ | 88 | 90 | - | \% |
| OVP Internally Fixed Value (no external voltage resistor divider) | V OVP_INT | 56 | 60 | 64 | V |
| OVP Programming Range ${ }^{(10)}$ (set through an external resistor divider) | Vovp_Ext | 15 | - | 60 | V |
| OVP Reference Voltage | $\mathrm{V}_{\text {REF_OVP }}$ | 6.3 | 6.9 | 7.5 | V |
| OVP Sink Current | $\mathrm{I}_{\text {SINK_OVP }}$ | - | 0.2 | - | $\mu \mathrm{A}$ |
| Switching Frequency $\begin{gathered} 34845,34845 \mathrm{C} \\ 34845 \mathrm{~A} \\ 34845 \mathrm{~B}, 34845 \mathrm{D} \end{gathered}$ | $\mathrm{f}_{\mathrm{S}}$ | $\begin{gathered} 540 \\ 1080 \\ 270 \end{gathered}$ | $\begin{gathered} 600 \\ 1200 \\ 300 \\ \hline \end{gathered}$ | $\begin{array}{r} 660 \\ 1320 \\ 330 \\ \hline \end{array}$ | kHz |
| Soft Start Time (Fs=600 kHz, 100\% PWM duty) | $\mathrm{t}_{\text {ss }}$ | - | 3.0 | - | ms |
| Soft Start VOUT Overshoot (Fs=600 kHz, 100\% PWM duty) | SS_vout | - | - | OVP | V |
| Boost Switch Rise Time | BOOST_t ${ }_{\text {R }}$ | - | 8.0 | - | ns |
| Boost Switch Fall Time | BOOST_t ${ }_{\text {F }}$ | - | 6.0 | - | ns |
| Current sense Amplifier Gain | $\mathrm{A}_{\text {CSA }}$ | - | 9.0 | - |  |
| OTA Transconductance | $\mathrm{G}_{\mathrm{M}}$ | - | 200 | - | $\mu \mathrm{S}$ |
| Transconductance Sink and Source Current Capability | $\mathrm{I}_{\text {ss }}$ | - | 100 | - | $\mu \mathrm{A}$ |
| Slope Compensation $\begin{gathered} 34845,34845 \mathrm{C} \\ 34845 \mathrm{~A} \\ 34945 \mathrm{~B}, 34845 \mathrm{D} \end{gathered}$ | $\mathrm{V}_{\text {SLOPE }}$ | - | $\begin{aligned} & 0.52 \\ & 0.73 \\ & 0.22 \\ & \hline \end{aligned}$ | - | V/ $\mu \mathrm{s}$ |

## Notes

10. The OVP level must be set 5.0 V above the worst-case LED string voltage.

Table 3. Static and Dynamic Electrical Characteristics (continued)
Characteristics noted under conditions $\mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}, \mathrm{~V}_{\mathrm{OUT}}=35 \mathrm{~V}, \mathrm{I}_{\mathrm{LED}}=30 \mathrm{~mA}, \mathrm{f}_{\mathrm{S}}=600 \mathrm{kHz}, \mathrm{f}_{\mathrm{PWM}}=600 \mathrm{~Hz}-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq$ $85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values noted reflect the approximate parameter means at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ under nominal conditions, unless otherwise noted.

| Characteristic | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LED DRIVER |  |  |  |  |  |
| $\begin{aligned} & \text { LED Driver Sink Current } \\ & \quad \mathrm{R}_{\text {ISET }}=51 \mathrm{k} \Omega 0.1 \%, \mathrm{PWM}=3.3 \mathrm{~V} \\ & \mathrm{R}_{\mathrm{ISET}}=5.1 \mathrm{k} \Omega 0.1 \%, \mathrm{PWM}=3.3 \mathrm{~V} \end{aligned}$ | ILED | $\begin{aligned} & 2.88 \\ & 29.4 \end{aligned}$ | $\begin{aligned} & 3.0 \\ & 30 \end{aligned}$ | $\begin{aligned} & 3.12 \\ & 30.6 \end{aligned}$ | mA |
| ISET Pin Voltage $\mathrm{R}_{\text {ISET }}=5.1 \mathrm{k} \Omega 0.1 \%$ | $\mathrm{V}_{\text {ISET }}$ | 2.011 | 2.043 | 2.074 | V |
| Regulated Minimum Voltage Across LED Drivers Pulse Width > 400ns | $\mathrm{V}_{\text {MIN }}$ | 0.675 | 0.75 | 0.825 | V |
| LED Current Channel to Channel Tolerance $\begin{aligned} & 10 \mathrm{~mA} \leq \mathrm{I}_{\text {LED }} \leq 30 \mathrm{~mA} \\ & 3.0 \mathrm{~mA} \leq \mathrm{I}_{\text {LED }}<10 \mathrm{~mA} \end{aligned}$ | Itolerance | $\begin{aligned} & -2.0 \\ & -4.0 \end{aligned}$ | - | $\begin{aligned} & 2.0 \\ & 4.0 \end{aligned}$ | \% |
| Off State leakage Current, All Channels $V_{\mathrm{CH}}=45 \mathrm{~V}$ | $\mathrm{I}_{\text {CH_LEAK }}$ | - | - | 1.0 | $\mu \mathrm{A}$ |
| LED Channels Rise and Fall Time | $\mathrm{t}_{\mathrm{R}} / \mathrm{t}_{\mathrm{F}}$ | - | 50 | 75 | ns |
| LED Open Protection, Channel Disabled if $\mathrm{V}_{\mathrm{CH}} \leq \mathrm{O}_{\text {FDV }}$ | OfDV | - | - | 0.55 | V |
| LED Short Protection Voltage, Channel Disabled if $\mathrm{V}_{\mathrm{CH}} \geq \mathrm{S}_{\text {FDV }}$ (channel on time $\geq 10 \mu \mathrm{~s}$ ) | $\mathrm{S}_{\text {FDV }}$ | 6.5 | 7.0 | 7.5 | V |

FAIL PIN

| Off State Leakage Current <br> $V_{\text {FAIL }}=5.5 \mathrm{~V}$ | $\mathrm{I}_{\text {FAIL_LEAK }}$ |  |  |  | $\mu \mathrm{A}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| On State Voltage Drop <br> $I_{\text {SINK }}=4.0 \mathrm{~mA}$ | V OL | - | - | 5.0 |  |

## OVER-TEMPERATURE SHUTDOWN

| Over-temperature Threshold (shutdown mode) <br> Rising <br> Hysteresis OTT $_{\text {SHUTDOWN }}$ |  |  | ${ }^{\circ} \mathrm{C}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |

## PWM INPUT

| PWM Dimming Mode LED Current Control $\begin{aligned} & \mathrm{PWM}=3.3 \mathrm{~V}, \mathrm{f}_{\mathrm{PWM}}=600 \mathrm{~Hz} 10 \% \text { duty; } \\ & \mathrm{PWM}=3.3 \mathrm{~V}, \mathrm{f}_{\text {PWM }}=600 \mathrm{~Hz} 50 \% \text { duty } \\ & \mathrm{PWM}=3.3 \mathrm{~V}, \mathrm{f}_{\mathrm{PWM}}=600 \mathrm{~Hz} 100 \% \text { duty } \end{aligned}$ | PWM ${ }_{\text {CONTROL }}$ | $\begin{gathered} 9.9 \\ 49.5 \\ - \end{gathered}$ | $\begin{gathered} 10 \\ 50 \\ 100 \end{gathered}$ | $\begin{gathered} 10.1 \\ 50.5 \\ - \end{gathered}$ | \% |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input Minimum Pulse PWM Pin ( $\mathrm{V}_{\mathrm{PWM}}=3.3 \mathrm{~V}$ ) <br> Start-up (Wake Mode) <br> Operational (Wake Mode) <br> Start-up (Enable Mode) <br> Operational (Enable Mode) | $\mathrm{t}_{\text {PWM_IN }}$ | $\begin{gathered} 1.6 \\ - \\ 0.4 \end{gathered}$ | $\begin{gathered} 0.2 \\ - \\ 0.2 \end{gathered}$ |  | $\mu \mathrm{S}$ |
| Input Frequency Range for PWM Pin | $\mathrm{f}_{\text {PWM }}$ | DC | - | 100 | kHz |
| WAKE |  |  |  |  |  |
| Shutdown Mode Timeout | $\mathrm{t}_{\text {SHUTDOWN }}$ | 27 | 30 | 33 | ms |

Table 3. Static and Dynamic Electrical Characteristics (continued)
Characteristics noted under conditions $\mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}, \mathrm{~V}_{\mathrm{OUT}}=35 \mathrm{~V}$, $\mathrm{I}_{\mathrm{LED}}=30 \mathrm{~mA}, \mathrm{f}_{\mathrm{S}}=600 \mathrm{kHz}, \mathrm{f}_{\mathrm{PWM}}=600 \mathrm{~Hz}-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}} \leq$ $85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values noted reflect the approximate parameter means at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ under nominal conditions, unless otherwise noted.

|  | Characteristic | Symbol | Min | Typ | Max | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| LOGIC INPUTS (PWM) |  |  |  |  |  |  |
|      <br> Input Low Voltage $\mathrm{V}_{\mathrm{ILL}}$ -0.3 - 0.5 <br> Input High Voltage $\mathrm{V}_{\mathrm{IHL}}$ 1.5 - 5 <br> Input Current $\mathrm{I}_{\mathrm{SINK}}$ -1.0 - 1.0 |  |  |  |  |  |  |$.$| $\mu \mathrm{A}$ |
| :--- |

LOGIC INPUTS (EN)

| Input Low Voltage | $\mathrm{V}_{\mathrm{ILL}}$ | -0.3 | - | 0.5 | V |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Input High Voltage | $\mathrm{V}_{\mathrm{IHL}}$ | 2.1 | - | 21 | V |
| Input Current $\left(\mathrm{V}_{\mathrm{EN}}=12 \mathrm{~V}\right)$ | $\mathrm{I}_{\mathrm{SINK}}$ | - | 6.0 | 10 | $\mu \mathrm{~A}$ |

LOGIC INPUTS (WAKE)

| Input Low Voltage | $\mathrm{V}_{\mathrm{ILL}}$ | -0.3 | - | 0.5 | V |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Input High Voltage | $\mathrm{V}_{\mathrm{IHL}}$ | 2.1 | - | 5.5 | V |
| Input Current | $\mathrm{I}_{\mathrm{SINK}}$ | -1.0 | - | 1.0 | $\mu \mathrm{~A}$ |

[^0]
## PIN CONNECTIONS

TRANSPARENT
TOP VIEW


Figure 3. 34845 Pin Connections
Table 4. 34845 Pin Definitions

| Pin Number | Pin Name |  |
| :---: | :---: | :--- |
| 1 | VIN | Main voltage supply Input. IC Power input supply voltage, is used internally to produce internal voltage regulation <br> for logic functioning, and also as an input voltage for the boost regulator. |
| 2 | PGNDB | Power ground. This is the ground terminal for the internal Boost FET. |
| 3 | SWB | Boost switch node connection B. Switching node of boost converter. |
| 4 | SWA | Boost switch node connection A. Switching node of boost converter. |
| 5 | PGNDA | Power ground. This is the ground terminal for the internal Boost FET. |
| 6 | EN | Enable pin (active high, internal pull-down). |
| $7-12$ | CH1 - CH6 | LED string connections 1 to 6. LED current drivers. Each line has the capability of driving up to 30 mA. |
| $13,19,21$ | GAIL | Ground Reference for all internal circuits other than the Boost FET. The Exposed Pad (EP) should be used for <br> thermal heat dissipation. |
| 14 | Fault detected pin (open drain): |  |
| No Failure $=$ Low-impedance pull-down |  |  |
| Failure = High-impedance |  |  |
| When a fault situation is detected, this pin goes into high impedance. |  |  |

# FUNCTIONAL DESCRIPTION 

## INTRODUCTION

LED backlighting has been popular for use in small LCD displays for many years. This technology is now rapidly replacing the incumbent Cold Cathode Fluorescent Lamp (CCFL) in mid-size displays such as those used use in notebooks, monitors and industrial/ consumer displays. LEDs offer a number of advantages compared to the CCFL, including lower power, thinner, longer lifetime, low voltage drive, accurate wide-range dimming control and advanced architectures for improved image quality. LEDs are also void of hazardous materials such as mercury which is used in CCFL.
LED backlights use different architecture depending on the size of the display and features required. For displays in the 10 " to $17 "+$ range such as those used in notebooks, edge-lit backlights offer very thin designs down to 2 mm or less. The efficiency of the LED backlight also extends battery life in portable equipment compared to CCFL. In large size panels, direct backlights support advanced architectures such as local dimming, in which power consumption and contrast ratio are drastically improved. Edge lighting can also be used in large displays when low cost is the driving factor.
The 34845 targets mid size panel applications in the 10 " to $17^{\prime \prime}+$ range with edge-lit backlights. The device supports LED currents up to 30 mA and supports up to six strings of LEDs. This enables backlights up to 10 W to be driven from a single device. The device includes a boost converter to deliver the required LED voltage from either a 2 or 3 cell Li-ion battery, or a direct 12 V input supply. The current drivers match the current between devices to provide superior uniformity across the display. The 34845 provides for a wide range of PWM dimming from a direct PWM control input.

## FUNCTIONAL DEVICE OPERATION

## POWER SUPPLY

The 34845 supports 5.0 V to 21 V at the VIN input pin. Two internal regulators generate internal rails for internal operation. Both rails are de-coupled using capacitors on the VDC1 and VDC2 pins.
The VIN, VDC1, and VDC2 supplies each have their own UVLO mechanisms. When any voltage is below the UVLO threshold, the device stops operating. All UVLO comparators have hysteresis to ensure constant on/off cycling does not occur.
The power up sequence for applying VIN respect to the ENABLE and PWM signals is important since the 34845 device will behave differently depending on how the sequence of these signals is applied. For the case where VIN is applied before the ENABLE and PWM signals, the device will have no limitation in terms of how fast the VIN ramp should be. However for the case where the PWM and ENABLE signals are applied before VIN, the ramp up time of VIN between 0 V and 5 V should be no longer than 2 ms . Figures 4 and 5 illustrate the two different power up conditions.


Figure 4. Power up sequence case 1, VIN applied before the ENABLE and PWM signals. No limitation for VIN ramp up time.


Figure 5. Power up sequence case 2, VIN applied after BOOST CONVERTER the ENABLE and PWM signals. VIN ramp up time between 0 V and 5 V should be not higher than $\mathbf{2 m s}$
The boost converter uses a Dynamic Headroom Control (DHC) loop to automatically set the output voltage needed to drive the LED strings. The DHC is designed to operate under specific pulse width conditions in the LED drivers. It operates for pulse widths higher than 400 ns . If the pulse widths are shorter than specified, the DHC circuit will not operate and the voltage across the LED drivers will increase to a value given by the OVP, minus the total LED voltage in the LED string. It is therefore imperative to select the proper OVP level to avoid exceeding the max off state voltage of the LED drivers $(45 \mathrm{~V})$.
The boost operates in current mode and is compensated externally through a type 2 network on the COMP pin. A modification of the compensation network is suggested to minimize the amplitude of the ripple at $\mathrm{V}_{\text {OUT }}$. The details of the suggested compensation network are shown in Figures 10 and 11.
An integrated 2.0A minimum FET supplies the required output current. An Over-current Protection circuit limits the output current cycle-by-cycle to $\mathrm{l}_{\mathrm{OCP}}$. If the condition exists longer than 10 ms , then the device will shut down. The frequency of the boost converter is internally set to $300 \mathrm{kHz}, 600 \mathrm{kHz}$ or 1.2 MHz , depending on the device's version.
The boost also includes a soft start circuit. Each time the IC comes out of shutdown mode, the soft start period lasts for $\mathrm{t}_{\text {SS }}$. Over-voltage Protection is also included. The device has an internally fixed OVP value of 60V (typical) which serves as a secondary fault protection mechanism, in the event the externally programmed OVP fails (i.e. resistor divider opens up). While the internal 60V OVP detector can be used exclusively without the external OVP network, this is only recommended for applications where the LED string voltage approaches 55 V or more. The OVP level can be set by using an external resistor divider connected between the output voltage and ground with its output connected to the OVP pin. The OVP can be set up to 60 V by varying the resistor divider to match the OVP internal reference of 6.9 V (typical).

## LED DRIVER

The six channel LED driver provides current matching for six LED strings to within $\pm 2 \%$ maximum. The current in the strings is set using a resistor tied to GND from the ISET pin. The LED current level is given by the equation: RSET = 153/ ILED. The accuracy of the RSET resistor should be $0.1 \%$ for best performance.

## LED ERROR DETECT

If an LED is open, the output voltage ramps to the OVP level. If there is still no current in the LED string, the LED channel is turned off and the output voltage ramps back down to normal operating level.
If LEDs are shorted and the voltage in any of the channels is greater than the SFDV threshold ( 7.0 V typical), then the device will turn off that channel. However if the on-time of the channels is less than $10 \mu \mathrm{~s}$, the SFDV circuit will not disable any of the channels, regardless of the voltage across them.
All the LED errors can be cleared by recycling the EN pin or applying a complete power-on-reset (POR).

## WAKE OPERATION

The WAKE pin provides the means to set the device for low power consumption (shutdown mode) without the need of an extra logic signal for enable. This is achieved by connecting the WAKE and PWM pins together, and tying the EN pin to ground. In this configuration, the PWM signal is used to control the LED channels, while allowing low power consumption by setting the device into its shutdown mode every time the PWM signal is kept low for longer time than the WAKE time out of 27 ms .

## OVER-TEMPERATURE SHUTDOWN AND TEMPERATURE CONTROL CIRCUITS

The 34845 includes over-temperature protection. If the internal temperature exceeds the over-temp threshold OTT SHUTDOWN , then the device shuts down all functions. Once the temperature falls below the low level threshold, the device is re-enabled.

## FAIL PIN

The FAIL pin is at its low-impedance state when no error is detected. However, if an error such as an LED channel open or boost over-current is detected, the FAIL pin goes into high-impedance. Once a failure is detected, the FAIL pin can be cleared by recycling the EN pin or applying a complete power-on-reset (POR). If the detected failure is an Over-current time-out, the EN pin or a POR must be cycled/executed to restart the part.

## TYPICAL PERFORMANCE CURVES



Figure 6. Typical System Efficiency vs Duty Cycle (FPWM=25kHz)


Figure 7. Typical ILED Dimming Linearity (FPWM=25kHz)


Figure 8. Typical Operating Waveforms (FPWM=25kHz, 50\% duty)


Figure 9. Low Duty Dimming Operation Waveforms (FPWM=25 kHz, 1\% duty)

## TYPICAL APPLICATIONS



Figure 10. Typical Application Circuit for Single Wire Control, $\mathrm{f}_{\mathrm{S}}=\mathbf{6 0 0} \mathrm{KHz}$ $\left(\mathrm{V}_{\mathrm{IN}}=9.0 \mathrm{~V}, \mathrm{I}_{\mathrm{LED}} /\right.$ channel $=20 \mathrm{~mA} /$ channel, $10 \mathrm{LEDs} /$ channel, $\left.\mathrm{OVP}=35 \mathrm{~V}, \mathrm{~V}_{\mathrm{PWM}}=3.3 \mathrm{~V}\right)$


Figure 11. Typical Application Circuit for Single Wire Control, $\mathrm{f}_{\mathrm{S}}=1.2 \mathrm{MHz}$ $\left(\mathrm{V}_{\mathrm{IN}}=9.0 \mathrm{~V}, \mathrm{I}_{\mathrm{LED}}=20 \mathrm{~mA} /\right.$ channel, 10 LEDs/channel, $\left.\mathrm{OVP}=35 \mathrm{~V}, \mathrm{~V}_{\mathrm{PWM}}=3.3 \mathrm{~V}\right)$


Figure 12. Typical Application Circuit for Single Wire Control, $\mathrm{f}_{\mathrm{S}}=\mathbf{3 0 0} \mathbf{~ k H z}$ $\left(\mathrm{V}_{\mathrm{IN}}=8.0 \mathrm{~V}, \mathrm{I}_{\mathrm{LED}}=20 \mathrm{~mA} /\right.$ channel, 14 LEDs/channel, $\left.\mathrm{OVP}=49 \mathrm{~V}, \mathrm{~V}_{\mathrm{PWM}}=3.3 \mathrm{~V}\right)$

## COMPONENTS CALCULATION

The following formulas are intended for the calculation of all external components related with the boost converter and network compensation.
In order to calculate the Duty Cycle, the internal losses of the MOSFET and Diode should be taken into consideration:

$$
\mathrm{D}=\frac{\mathrm{V}_{\mathrm{OUT}}+\mathrm{V}_{\mathrm{D}}-\mathrm{V}_{\mathrm{IN}}}{\mathrm{~V}_{\mathrm{OUT}}+\mathrm{V}_{\mathrm{D}}-\mathrm{V}_{\mathrm{SW}}}
$$

The average input current depends directly on the output current when the internal switch is off.

$$
\mathrm{I}_{\mathrm{IN}-\mathrm{AVG}}=\frac{\mathrm{I}_{\mathrm{OUT}}}{1-\mathrm{D}}
$$

## Inductor

For calculating the Inductor, consider the losses of the internal switch and winding resistance of the inductor:

$$
\mathrm{L}=\frac{\left(\mathrm{V}_{\mathrm{IN}}-\mathrm{V}_{\mathrm{SW}}-\left(\mathrm{I}_{\mathrm{IN}-\mathrm{AVG}} \times \mathrm{R}_{\mathrm{INDUCTOR}}\right)\right) \times \mathrm{D}}{\mathrm{I}_{\mathrm{IN}-\mathrm{AVG}} \times \mathrm{r} \times \mathrm{F}_{\mathrm{SW}}}
$$

It is important to look for an inductor rated at least for the maximum input current:

$$
\mathrm{I}_{\mathrm{IN}-\mathrm{MAX}}=\mathrm{I}_{\mathrm{IN}-\mathrm{AVG}}+\frac{\mathrm{V}_{\mathrm{IN}} \times\left(\mathrm{V}_{\mathrm{OUT}}-\mathrm{V}_{\mathrm{IN}}\right)}{2 \times \mathrm{L} \times \mathrm{F}_{\mathrm{SW}} \times \mathrm{V}_{\mathrm{OUT}}}
$$

## Input Capacitor

The input capacitor should handle at least the following RMS current.

$$
\mathrm{I}_{\mathrm{RMS}}-\mathrm{C}_{\mathrm{IN}}=\left(\frac{\mathrm{V}_{\mathrm{IN}} \times\left(\mathrm{V}_{\mathrm{OUT}}-\mathrm{V}_{\mathrm{IN}}\right)}{2 \times \mathrm{L} \times \mathrm{F}_{\mathrm{SW}} \times \mathrm{V}_{\mathrm{OUT}}}\right) \times 0.3
$$

## Output Capacitor

For the output capacitor selection the transconductance should be taken in consideration.

$$
\mathrm{C}_{\mathrm{OUT}}=\frac{\mathrm{R}_{\mathrm{COMP}} \times 5 \times \mathrm{G}_{\mathrm{M}} \times \mathrm{I}_{\mathrm{OUT}} \times \mathrm{L}}{(1-\mathrm{D}) \times \mathrm{V}_{\mathrm{OUT}} \times 0.35}
$$

The output voltage ripple ( $\Delta \mathrm{V}_{\text {OUT }}$ ) depends on the ESR of the Output capacitor. For a low output voltage ripple, it is recommended to use ceramic capacitors that have a very low ESR. Since ceramic capacitor are costly, electrolytic or tantalum capacitors can be mixed with ceramic capacitors for a less expensive solution.

$$
\mathrm{ESR}_{\mathrm{C}_{\mathrm{OUT}}}=\frac{\mathrm{V}_{\mathrm{OUT}} \times \Delta \mathrm{V}_{\mathrm{OUT}} \times \mathrm{F}_{\mathrm{SW}} \times \mathrm{L}}{\mathrm{~V}_{\mathrm{OUT}} \times(1-\mathrm{D})}
$$

The output capacitor should at least handle the following RMS current.

$$
\mathrm{I}_{\mathrm{RMS}-\mathrm{C}_{\mathrm{OUT}}}=\mathrm{I}_{\mathrm{OUT}} \times \sqrt{\frac{\mathrm{D}}{1-\mathrm{D}}}
$$

## Network Compensation

Since this Boost converter is current controlled, a Type II compensation is needed.
Note that before calculating the network compensation, all boost converter components need to be known.
For this type of compensation it is recommended to push out the Right Half Plane Zero to higher frequencies where it will not significantly affect the overall loop.

$$
\mathrm{f}_{\mathrm{RHPZ}}=\frac{\mathrm{V}_{\mathrm{OUT}} \times(1-\mathrm{D})^{2}}{\mathrm{I}_{\mathrm{OUT}} \times 2 \pi \times \mathrm{L}}
$$

The crossover frequency must be set much lower than the location of the Right half plane zero:

$$
\mathrm{f}_{\mathrm{CROSS}}=\frac{\mathrm{f}_{\mathrm{RHPZ}}}{5}
$$

Since our system has a fixed slope compensation, RCOMP should be fixed for all configurations, i.e. Rcomp $=2$ Kohm
$\mathrm{C}_{\mathrm{COMP1}}$ and $\mathrm{C}_{\mathrm{COMP2}}$ should be calculated as follows:

$$
\begin{aligned}
\mathrm{C}_{\text {COMP } 1} & =\frac{2}{\pi \times \mathrm{f}_{\mathrm{CROSS}} \times{ }^{\mathrm{R}} \mathrm{COMP}} \\
\mathrm{C}_{\text {COMP2 }} & =\frac{2 \mathrm{G}_{\mathrm{M}}}{6.28 \times \mathrm{F}_{\mathrm{SW}}}
\end{aligned}
$$

The recommended values of these capacitors for an acceptable performance of the system in different operating conditions are Ccomp1=33nF and Ccomp2=220pF.
In order to improve the transient response of the boost a resistor network can be implemented from the PWM pin to ground with a connection to the compensation network. This configuration should inject a 1 V signal to the COMP pin and the equivalent Thevenin resistance of the divider should be close to RCOMP, (i.e. for 2 k COMP resistor, $\mathrm{R}_{\mathrm{COMP}}=3.3 \mathrm{k}$ and $\mathrm{R}_{\text {SHUNT }}=10 \mathrm{k}$. See Figure 10, Figure 11 and Figure 12 for implementation guidelines.
If a faster transient response is needed, a higher voltage (e.g. 1.3 V ) should be injected to the COMP pin; so the resistor divider should be modified accordingly but keeping the equivalent Thevenin resistance of the divider close to Rcomp.

## Variable definition

D = Duty cycle
$\mathrm{V}_{\text {OUT }}=$ Output voltage
$V_{D}=$ Diode voltage
$\mathrm{V}_{\text {IN }}=$ Input voltage
$V_{S W}=$ Internal switch voltage drop.
$\Delta V_{\text {OUT }}=$ Output voltage ripple
$\mathrm{I}_{\mathrm{IN}-\mathrm{AVG}}=$ Average input current $=\mathrm{I}_{\mathrm{L}-\mathrm{AVG}}$
$\mathrm{I}_{\mathrm{OUT}}=$ Output current
$\mathrm{I}_{\mathrm{IN}-\mathrm{MAX}}=$ Maximum input current
$r=$ Current ripple ratio at the inductor $=\Delta \mathrm{I}_{\mathrm{L}} / \mathrm{I}_{\mathrm{L}-\mathrm{AVG}}$
$I_{\text {RMS-CIN }}=$ RMS current for the input capacitor
$I_{\text {RMS-COUT }}=$ RMS current for output capacitor
$\mathrm{L}=$ Inductor.
$\mathrm{R}_{\text {INDUCTOR }}=$ Inductor winding resistor
$\mathrm{F}_{\text {SW }}=$ Boost switching frequency
$\mathrm{C}_{\text {OUT }}=$ Output capacitor
$\mathrm{R}_{\text {COMP }}=$ Compensation resistor
$\mathrm{G}_{\mathrm{M}}=$ OTA transconductance
$E S R_{\text {COUT }}=E S R$ of the output capacitor
$\mathrm{f}_{\mathrm{RHPZ}}=$ Right half plane zero frequency
$\mathrm{f}_{\text {CROSS }}=$ Crossover frequency
$\mathrm{C}_{\text {COMP1 }}=$ Compensation capacitor
$\mathrm{C}_{\text {COMP2 }}=$ Shunt compensation capacitor

## Component Suggestions

The Component Suggestions only apply to the conditions shown. Therefore, adjustments are necessary for different application conditions.

Table 5. Component Suggestion Table

| Application Case | Vin(min) | Vin(Max) | Vo(max) | VOVP | fBoost | ILED per channel | Rovp_upper | Rovp_lower | L(min) | L(min) Continuous mode | Cin(min) | Cout(min) | Rcomp at $\mathrm{V}_{\mathrm{PWM}}=3.3 \mathrm{~V}$ | Rshunt at $\mathrm{V}_{\mathrm{PWM}}=3.3 \mathrm{~V}$ | Ccomp1 | Ccomp2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 9V | 12 V | 30 V | 35 V | 600 kHz | 20 mA | 680kOhm | 167kOhm | 22 uH | 33 H | 1x10uF; X7R; 25V | $\begin{aligned} & 2 \times 4.7 \mathrm{uF} \\ & \mathrm{X} 7 \mathrm{R} ; 50 \mathrm{~V} \end{aligned}$ | 3.3kOhm | 10kOhm | 33 nF | 220pF |
| 2 | 6 V | 12 V | 43 V | 48 V | 300 kHz | 23 mA | 680kOhm | 114kOhm | 22 uH | 33 uH | 1x10uF; <br> X7R; 25V | $\begin{aligned} & \hline 4 \times 2.2 \mathrm{uF} ; \\ & \text { X7R; } 100 \mathrm{~V} \\ & \hline \end{aligned}$ | 2kOhm | 16kOhm | 56nF | 220pF |

## PACKAGING

## PACKAGE DIMENSIONS

For the most current package revision, visit www.freescale.com and perform a keyword search using the " 98 A " listed below.



## EP SUFFIX

REVISION A


EP SUFFIX
24-PIN
98ASAOOO87D
REVISION A

```
NOTES:
1. ALL DIMENSIONS ARE IN MILLIMETERS.
2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
3. THIS IS NON JEDEC REGISTERED PACKAGE.
4. COPLANARITY APPLIES TO LEADS AND DIE ATTACH PAD.
5. MIN. METAL GAP SHOULD BE 0.145MM.
```



> EP SUFFIX
> 24-PIN
> 98ASA00087D
> REVISION A

## REVISION HISTORY

| Revision | Date | Description of Changes |
| :---: | :---: | :--- |
| 6.0 | $12 / 2011$ | •Changed the max rating for the OVP pin from 7.0V to 7.75V in the Absolute Maximum Ratings Table <br> on page 4. <br> Updated Freescale form and style. <br> 7.0 $6 / 2014$ | | UnNo technical changes. Revised back page. Updated document properties. Added SMARTMOS <br> sentence to first paragraph. |
| :--- |

## $\checkmark$ RoHS

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