



## High Performance Sensorless Motor Control IC

### Description

IRMCF171 is a high performance flash memory based motion control IC designed primarily for appliance applications. IRMCF171 is designed to achieve low cost yet high performance control solutions for advanced inverterized appliance motor control. IRMCF171 contains two computation engines integrated into one monolithic chip. One is the Flexible Motion Control Engine (MCE™) for sensorless control of permanent magnet or induction motors; the other is an 8-bit high-speed microcontroller (8051). The user can program a motion control algorithm by connecting control elements using a graphic compiler. Key components of the complex sensorless control algorithms, such as the Angle Estimator, are provided as complete pre-defined control blocks. A unique analog/digital circuit and algorithm fully supports single or leg shunt current reconstruction. The MCE and 8051 microcontroller communicate via dual port RAM for signal monitoring and command input. An advanced graphic compiler for the MCE™ is seamlessly integrated into the MATLAB/Simulink environment, while third party JTAG-based emulator tools are supported for 8051 software development including a flash programmer. IRMCF171 comes in a 48 pin QFP package.

### Features

- MCE™ (Flexible Motion Control Engine) - Dedicated computation engine for high efficiency sinusoidal sensorless motor control
- Built-in hardware peripheral for single or two shunt current feedback reconstruction and analog circuits
- Supports induction machine and both interior and surface permanent magnet motor sensorless control
- Loss minimization Space Vector PWM
- Two-channel analog output (PWM)
- Embedded 8-bit high speed microcontroller (8051) for flexible I/O and man-machine control
- JTAG programming port for emulation/debugger
- Serial communication interface (UART)
- I2C/SPI serial interface
- Three general purpose timers/counters
- Two special timers: periodic timer, capture timer
- Watchdog timer with independent internal clock
- Internal 64 Kbyte flash memory
- 3.3V single supply

### Product Summary

Maximum clock input ( $f_{\text{crystal}}$ )	60 MHz
Maximum Internal clock (SYSCLK)	120MHz
Maximum 8051 clock (8051CLK)	30MHz
MCE™ computation data range	16 bit signed
8051 Program Flash	52KB
8051/MCE Data RAM	4KB
MCE Program RAM	12KB
GateKill latency (digital filtered)	2 $\mu$ sec
PWM carrier frequency	20 bits/ SYSCLK
A/D input channels	7
A/D converter resolution	12 bits
A/D converter conversion speed	2 $\mu$ sec
Analog output (PWM) resolution	8 bits
UART baud rate (typ)	57.6Kbps
Number of digital I/O (max)	14
Package (lead free)	QFP48
Typical 3.3V operating current	30mA

Base Part Number	Package Type	Standard Pack		Orderable Part Number
		Form	Quantity	
IRMCF171	LQFP48	Tape and Reel	2000	IRMCF171TR
IRMCF171	LQFP48	Tray	2500	IRMCF171TY

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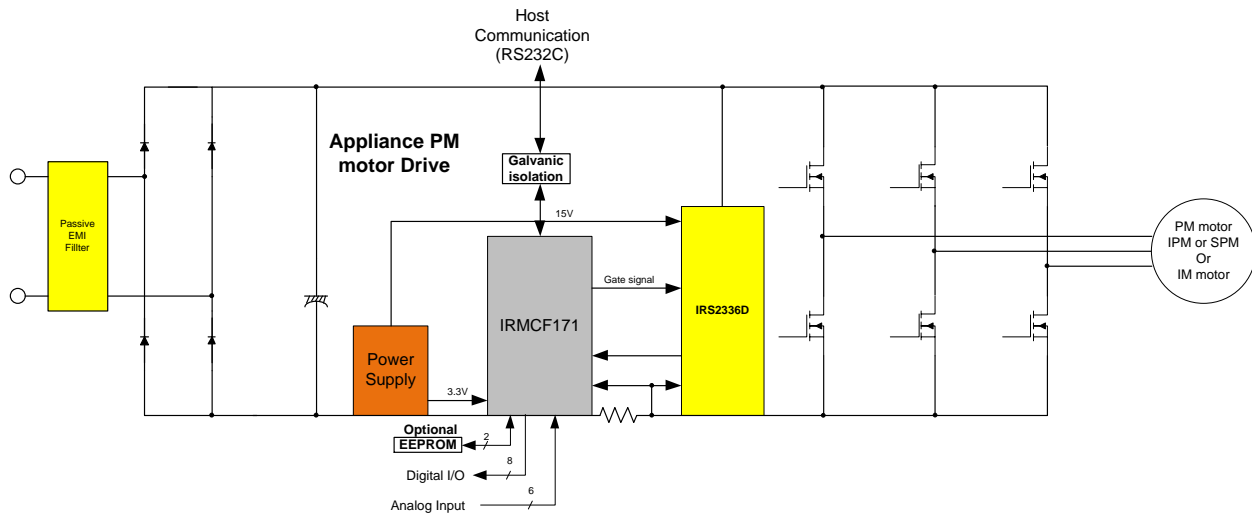
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## 1 Overview

IRMCF171 is a new generation International Rectifier integrated circuit device primarily designed as a one-chip solution for complete inverterized appliance motor control applications. Unlike a traditional microcontroller or DSP, the IRMCF171 provides a built-in closed loop sensorless control algorithm using the unique flexible Motion Control Engine (MCETM) for permanent magnet motors as well as induction motors. The MCE™ consists of a collection of control elements, motion peripherals, a dedicated motion control sequencer and dual port RAM to map internal signal nodes. IRMCF171 also employs a unique single shunt current reconstruction circuit in addition to two leg shunt current sensing circuit to eliminate additional analog/digital circuitry and enables a direct shunt resistor interface to the IC. Motion control programming is achieved using a dedicated graphical compiler integrated into the MATLAB/Simulink™ development environment. Sequencing, user interface, host communication, and upper layer control tasks can be implemented in the 8051 high-speed 8-bit microcontroller. The 8051 microcontroller is equipped with a JTAG port to facilitate emulation and debugging tools. Figure 1 shows a typical application schematic using the IRMCF171.

IRMCF171 contains 64 Kbytes of Flash program memory. The IRMCK171 contains 32 Kbytes OTP memory and is intended for high volume production purposes while the IRMCF171 is intended for flexible volume production. Both the Flash and ROM versions come in a 48-pin QFP package with identical pin configuration to facilitate PC board layout and transition to mass production.



**Figure 1. Typical Application Block Diagram Using IRMCF171**

## 2 Pinout

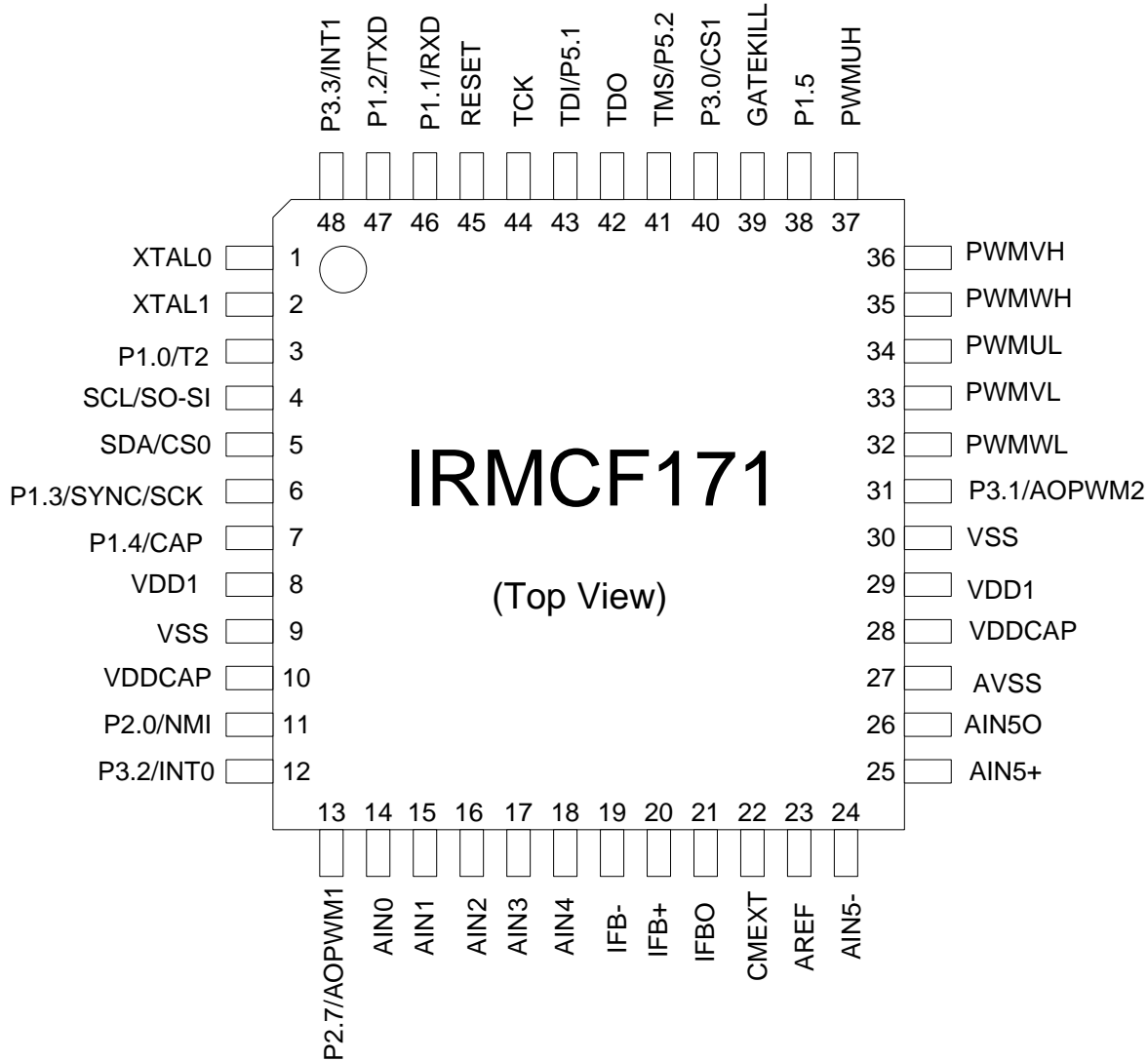
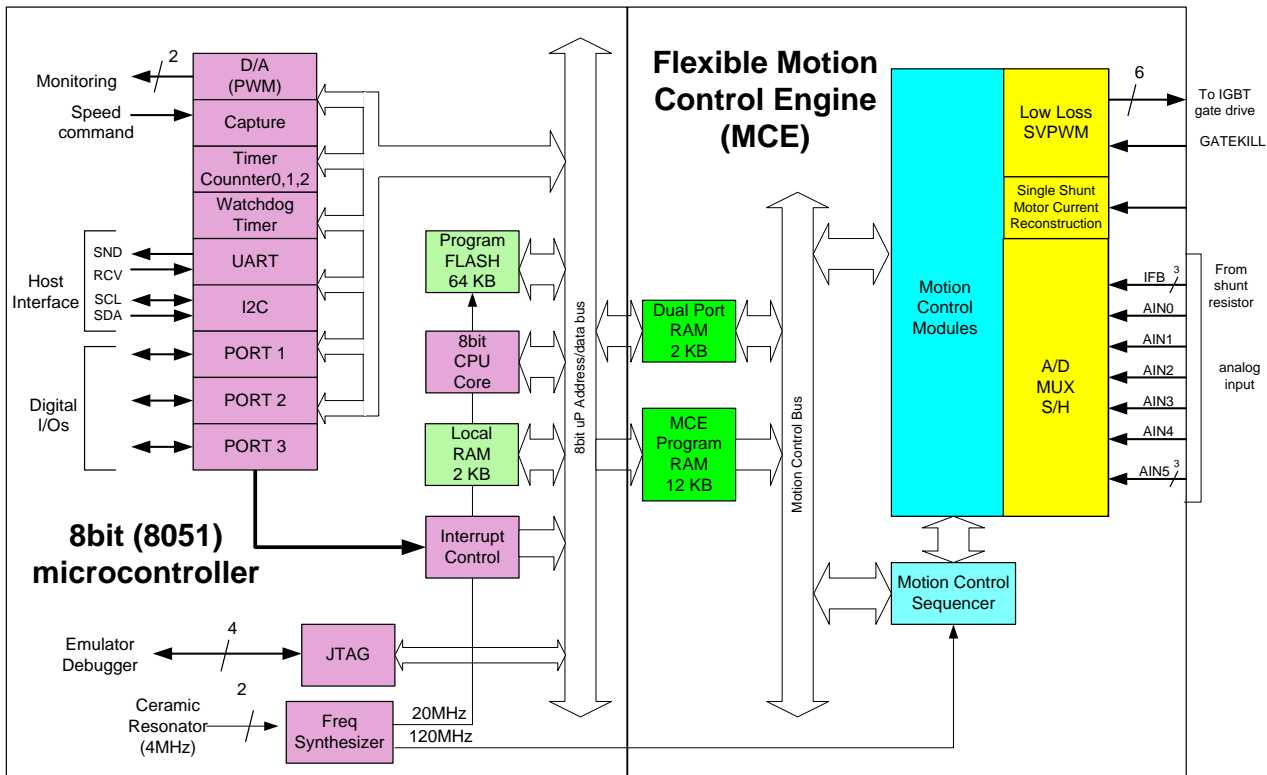


Figure 2. Pinout of IRMCF171

### 3 IRMCF171 Block Diagram and Main Functions

IRMCF171 block diagram for leg shunt mode is shown in Figure 3.



**Figure 3. IRMCF171 Block Diagram**

IRMCF171 contains the following functions for sensorless AC motor control applications:

#### Motion Control Engine (MCE™)

- Sensorless FOC (complete sensorless field oriented control)
- Proportional plus Integral block
- Low pass filter
- Differentiator and lag (high pass filter)
- Ramp
- Limit
- Angle estimate (sensorless control)
- Inverse Clark transformation
- Vector rotator
- Bit latch
- Peak detect
- Transition
- Multiply-divide (signed and unsigned)
- Adder
- Divide (signed and unsigned)

#### 8051 microcontroller

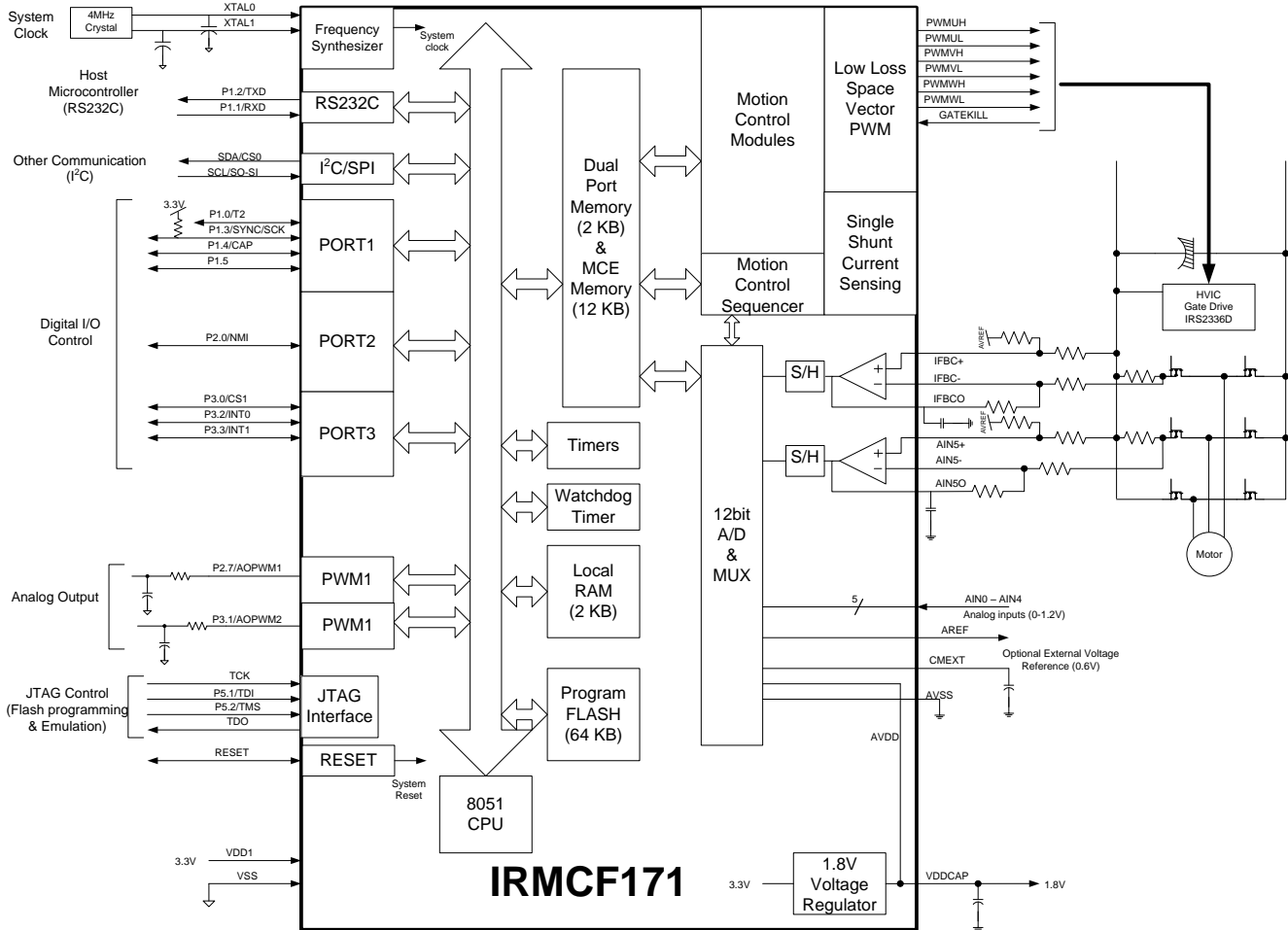
- Two 16 bit timer/counters
- One 16 bit periodic timer
- One 16 bit watchdog timer
- One 16 bit capture timer
- Up to 14 discrete digital I/Os
- Seven-channel 12 bit A/D
  - Buffered (current sensing) two channels (0 – 1.2V input)
  - Unbuffered five channels (0 – 1.2V input)
- JTAG port (4 pins)
- Up to two channels of analog output (8 bit PWM)
- UART
- I<sup>2</sup>C/SPI port
- 2K byte data RAM

- Subtractor
  - Comparator
  - Counter
  - Accumulator
  - Switch
  - Shift
  - ATAN (arc tangent)
  - Function block (any curve fitting, nonlinear function)
  - 16 bit wide Logic operations (AND, OR, XOR, NOT, NEGATE)
  - MCE™ program memory and dual port RAM (6K byte)
  - MCE™ control sequencer
- 64K byte Flash memory



## 4 Application connection and Pin function

Figure 4 shows the application connections in leg shunt mode. Figure 5 shows the application connections in single shunt mode.



**Figure 4. IRMCF171 Leg Shunt Connection Diagram**

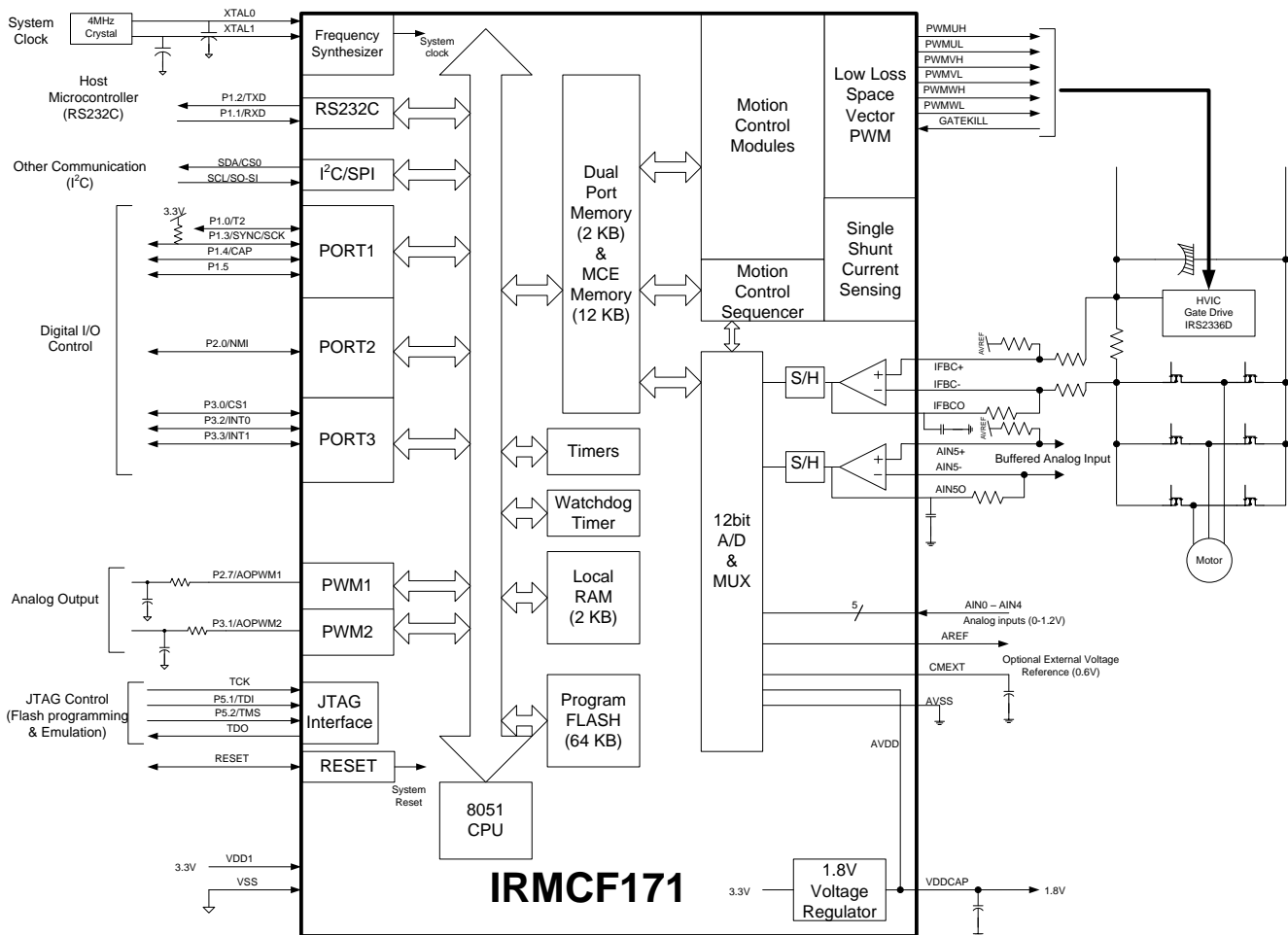


Figure 5. IRMCF171 Single Shunt Connection Diagram

## 4.1 8051 Peripheral Interface Group

### UART Interface

P1.2/TXD	Output, Transmit data from IRMCF171
P1.1/RXD	Input, Receive data to IRMCF171

### Discrete I/O Interface

P1.0/T2	Input/output port 1.0, can be configured as Timer/Counter 2 input
P1.1/RXD	Input/output port 1.1, can be configured as RXD input
P1.2/TXD	Input/output port 1.2, can be configured as TXD output
P1.3/SYNC/SCK	Input/output port 1.3, can be configured as SYNC output or SPI clock output
P1.4/CAP	Input/output port 1.4, can be configured as Capture Timer input
P1.5	Input/output port 1.5
P2.0/NMI	Input/output port 2.0, can be configured as non-maskable interrupt input
P2.7/AOPWM1	Input/output port 2.7, can be configured as AOPWM1 output
P3.0/INT2/CS1	Input/output port 3.0, can be configured as INT2 input or SPI chip select 1
P3.1/AOPWM2	Input/output port 3.1, can be configured as AOPWM2 output
P3.2/NINT0	Input/output port 3.2, can be configured as INT0 input
P3.3/NINT1	Input/output port 3.3, can be configured as INT1 input
P5.1/TDI	Input port 5.1, configured as JTAG port by default

P5.2/TMS Input port 5.2, configured as JTAG port by default

#### Analog Output Interface

P2.7/AOPWM1 Input/output, can be configured as 8-bit PWM output 1 with programmable carrier frequency  
 P3.1/AOPWM2 Input/output, can be configured as 8-bit PWM output 2 with programmable carrier frequency

#### Crystal Interface

XTAL0 Input, connected to crystal  
 XTAL1 Output, connected to crystal

#### Reset Interface

RESET Input and Output, system reset, doesn't require external RC time constant

#### I<sup>2</sup>C Interface

SCL/SO-SI Output, I<sup>2</sup>C clock output, or SPI data  
 SDA/CS0 Input/output, I<sup>2</sup>C Data line or SPI chip select 0

#### I<sup>2</sup>C/SPI Interface

SCL/SO-SI Output, I<sup>2</sup>C clock output, or SPI data  
 SDA/CS0 Input/output, I<sup>2</sup>C data line or SPI chip select 0  
 P1.3/SYNC/SCK Input/output port 1.3, can be configured as SYNC output or SPI clock output  
 P3.0/INT2/CS1 Input/output port 3.0, can be configured as INT2 input or SPI chip select 1

## 4.2 Motion Peripheral Interface Group

### PWM

PWMUH Output, PWM phase U high side gate signal, internally pulled down by 58k $\Omega$ , configured high true at a power up  
 PWMUL Output, PWM phase U low side gate signal, internally pulled down by 58k $\Omega$ , configured high true at a power up  
 PWMVH Output, PWM phase V high side gate signal, internally pulled down by 58k $\Omega$ , configured high true at a power up  
 PWMVL Output, PWM phase V low side gate signal, internally pulled down by 58k $\Omega$ , configured high true at a power up  
 PWMWH Output, PWM phase W high side gate signal, internally pulled down by 58k $\Omega$ , configured high true at a power up  
 PWMWL Output, PWM phase W low side gate signal, internally pulled down by 58k $\Omega$ , configured high true at a power up  
 PFCPWM Output, PFCPWM output signal, internally pulled up by 70k $\Omega$ , configured low true at a power up

### Fault

GATEKILL Input, upon assertion this negates all six PWM signals, active low, internally pulled up by 70k $\Omega$

## 4.3 Analog Interface Group

AVSS Analog power return, (analog internal 1.8V power is shared with VDDCAP)  
 AREF 0.6V buffered output  
 CMEXT Unbuffered 0.6V, input to the AREF buffer, capacitor needs to be connected.  
 IFB+ Input, Operational amplifier positive input for shunt resistor current sensing

IFB-	Input, Operational amplifier negative input for shunt resistor current sensing
IFBO	Output, Operational amplifier output for shunt resistor current sensing
AIN0	Input, Analog input channel 0 (0 – 1.2 V), typically configured for DC bus voltage input
AIN1	Input, Analog input channel 1 (0 – 1.2 V), needs to be pulled down to AVSS if unused
AIN2	Input, Analog input channel 2 (0 – 1.2 V), needs to be pulled down to AVSS if unused
AIN3	Input, Analog input channel 3 (0 – 1.2 V), needs to be pulled down to AVSS if unused
AIN4	Input, Analog input channel 4 (0 – 1.2 V), needs to be pulled down to AVSS if unused
AIN5+	Input, Operational amplifier positive input for shunt resistor current sensing
AIN5-	Input, Operational amplifier negative input for shunt resistor current sensing
AIN5O	Output, Operational amplifier output for AIN5 output, there is a single sample/hold circuit on the output

#### 4.4 Power Interface Group

VDD1	Digital power (3.3V)
VDDCAP	Internal 1.8V output, requires capacitors to the pin. Shared with analog power pad internally <b>Note:</b> The internal 1.8V supply is not designed to power any external circuits or devices. Only capacitors should be connected to this pin.
VSS	Digital common

#### 4.5 Test Interface Group

P5.2/TMS	JTAG test mode input or input digital port
TDO	JTAG data output
P5.1/TDI	JTAG data input, or input digital port
TCK	JTAG test clock

## 5 DC Characteristics

### 5.1 Absolute Maximum Ratings

Symbol	Parameter	Min	Typ	Max	Condition
V <sub>DD1</sub>	Supply Voltage	-0.3 V	-	3.6 V	Respect to VSS
V <sub>IA</sub>	Analog Input Voltage	-0.3 V	-	1.98 V	Respect to AVSS
V <sub>ID</sub>	Digital Input Voltage	-0.3 V	-	6.0 V	Respect to VSS
T <sub>A</sub>	Ambient Temperature	-40 °C	-	125 °C	
T <sub>S</sub>	Storage Temperature	-65 °C	-	150 °C	

**Table 1. Absolute Maximum Ratings**

**Caution:** Stresses beyond those listed in “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only and function of the device at these or any other conditions beyond those indicated in the operational sections of the specifications are not implied.

### 5.2 System Clock Frequency and Power Consumption

C<sub>CAREF</sub> = 1nF, C<sub>CMEXT</sub> = 100nF. VDD1=3.3V, Unless specified, Ta = 25°C.

Symbol	Parameter	Min	Typ	Max	Unit
SYSCCLK	System Clock	32	-	120	MHz
P <sub>D</sub>	Power consumption		100 <sup>1)</sup>	-	mW

**Table 2. System Clock Frequency**

Note 1) The value is based on the condition of MCE clock=120MHz, 8051 clock 30MHz with a actual motor running by a typical MCE application program and 8051 code.

### 5.3 Digital I/O DC Characteristics

Symbol	Parameter	Min	Typ	Max	Condition
$V_{DD1}$	Supply Voltage	3.0 V	3.3 V	3.6 V	Recommended
$V_{IL}$	Input Low Voltage	-0.3 V	-	0.8 V	Recommended
$V_{IH}$	Input High Voltage	2.0 V		3.6 V	Recommended
$C_{IN}$	Input capacitance	-	3.6 pF	-	<sup>(1)</sup>
$I_L$	Input leakage current		$\pm 10$ nA	$\pm 1$ $\mu$ A	$V_O = 3.3$ V or 0 V
$I_{OL1}^{(2)}$	Low level output current	8.9 mA	13.2 mA	15.2 mA	$V_{OL} = 0.4$ V <sup>(1)</sup>
$I_{OH1}^{(2)}$	High level output current	12.4 mA	24.8 mA	38 mA	$V_{OH} = 2.4$ V <sup>(1)</sup>
$I_{OL2}^{(3)}$	Low level output current	17.9 mA	26.3 mA	33.4 mA	$V_{OL} = 0.4$ V <sup>(1)</sup>
$I_{OH2}^{(3)}$	High level output current	24.6 mA	49.5 mA	81 mA	$V_{OH} = 2.4$ V <sup>(1)</sup>

**Table 3. Digital I/O DC Characteristics**

Note:

- (1) Data guaranteed by design.
- (2) Applied to SCL/SO-SI, SDA/CS0 pins.
- (3) Applied to all digital I/O pins except SCL/SO-SI and SDA/CS0 pins.

### 5.4 Analog I/O DC Characteristics

- OP amps for current sensing (IFB+,IFB-,IFBO, AIN5+,AIN5-,AIN5O)

$C_{AREF} = 1\text{nF}$ ,  $C_{MEXT} = 100\text{nF}$ .  $V_{DD1} = 3.3\text{V}$ , Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Condition
$V_{\text{OFFSET}}$	Input Offset Voltage	-	-	26 mV	$V_{\text{AVDD}} = 1.8\text{ V}$
$V_{\text{I}}$	Input Voltage Range	0 V		1.2 V	Recommended
$V_{\text{OUTSW}}$	OP amp output operating range	50 mV <sup>(1)</sup>	-	1.2 V	$V_{\text{AVDD}} = 1.8\text{ V}$
$C_{\text{IN}}$	Input capacitance	-	3.6 pF	-	(1)
$R_{\text{FDBK}}$	OP amp feedback resistor	5 k $\Omega$	-	20 k $\Omega$	Requested between IFBO and IFB-
OP $G_{\text{AINCL}}$	Operating Close loop Gain	80 db	-	-	(1)
CMRR	Common Mode Rejection Ratio	-	80 db	-	(1)
$I_{\text{SRC}}$	Op amp output source current	-	1 mA	-	$V_{\text{OUT}} = 0.6\text{ V}$ (1)
$I_{\text{SNK}}$	Op amp output sink current	-	100 $\mu\text{A}$	-	$V_{\text{OUT}} = 0.6\text{ V}$ (1)

**Table 4. Analog I/O DC Characteristics**

Note:

(1) Data guaranteed by design.

### 5.5 Under Voltage Lockout DC characteristics

Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Condition
$UV_{CC+}$	UVcc positive going Threshold	2.78 V	3.04 V	3.23 V	(1)
$UV_{CC-}$	UVcc negative going Threshold	2.78 V	2.97 V	3.23 V	
$UV_{CCH}$	UVcc Hysteresys	-	73 mV	-	(1)

**Table 5. UVcc DC Characteristics**

Note:

(1) Data guaranteed by design.

### 5.6 Itrip comparator DC characteristics

Unless specified,  $V_{DD1}=3.3\text{V}$ ,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Condition
$Itrip_+$	Itrip positive going Threshold	-	1.22V	-	$V_{DD1} = 3.3\text{ V}$
$Itrip_-$	Itrip negative going Threshold	-	1.10V	-	$V_{DD1} = 3.3\text{ V}$
$ItripH$	Itrip Hysteresys	-	120mV	-	

**Table 6. Itrip DC Characteristics**

### 5.7 CMEXT and AREF Characteristics

$C_{AREF} = 1\text{nF}$ ,  $C_{MEXT} = 100\text{nF}$ . Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Condition
$V_{CM}$	CMEXT voltage	495 mV	600 mV	700 mV	$V_{VDD1} = 3.3\text{ V}$
$V_{AREF}$	Buffer Output Voltage	495 mV	600 mV	700 mV	$V_{VDD1} = 3.3\text{ V}$
$\Delta V_o$	Load regulation ( $V_{DC}-0.6$ )	-	1 mV	-	(1)
PSRR	Power Supply Rejection Ratio	-	75 db	-	(1)

**Table 7. CMEXT and AREF DC Characteristics**

Note:

(1) Data guaranteed by design.



## 6 AC Characteristics

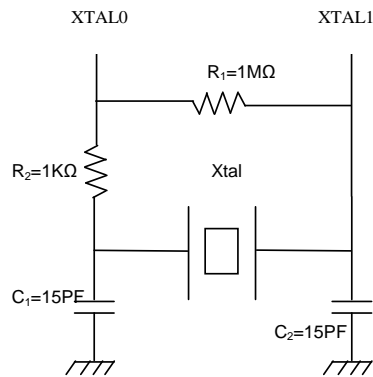
### 6.1 Digital PLL AC Characteristics

Symbol	Parameter	Min	Typ	Max	Condition
$F_{CLKIN}$	Crystal input frequency	3.2 MHz	4 MHz	60 MHz	<sup>(1)</sup> (see figure below)
$F_{PLL}$	Internal clock frequency	32 MHz	50 MHz	128 MHz	<sup>(1)</sup>
$F_{LWPPW}$	Sleep mode output frequency	$F_{CLKIN} \div 256$	-	-	<sup>(1)</sup>
$J_S$	Short time jitter	-	200 psec	-	<sup>(1)</sup>
$D$	Duty cycle	-	50 %	-	<sup>(1)</sup>
$T_{LOCK}$	PLL lock time	-	-	500 $\mu$ sec	<sup>(1)</sup>

**Table 8. PLL AC Characteristics**

Note:

(1) Data guaranteed by design.



**Figure 6. Crystal circuit example**

## 6.2 Analog to Digital Converter AC Characteristics

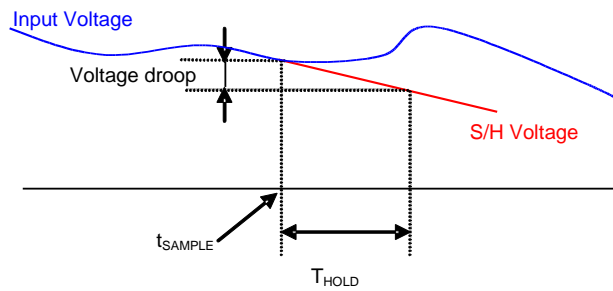
Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Condition
$T_{\text{CONV}}$	Conversion time	-	-	2.05 $\mu\text{sec}$	(1)
$T_{\text{HOLD}}$	Sample/Hold maximum hold time	-	-	10 $\mu\text{sec}$	Voltage droop $\leq 15$ LSB (see figure below)

**Table 9 . A/D Converter AC Characteristics**

Note:

(1) Data guaranteed by design.



**Figure 7. Voltage droop and S/H hold time**

### 6.3 Op amp AC Characteristics

Unless specified,  $T_a = 25^\circ\text{C}$ .

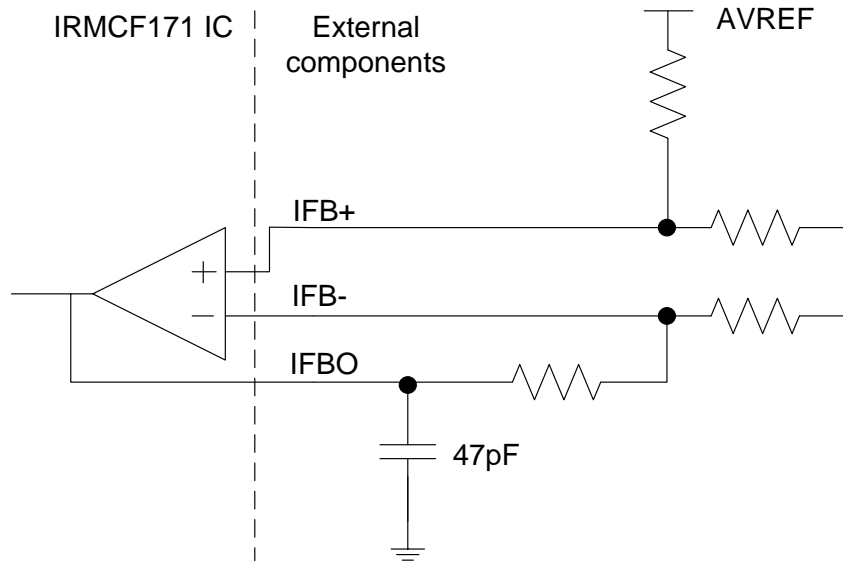
Symbol	Parameter	Min	Typ	Max	Condition
$OP_{SR}$	OP amp slew rate	-	10 V/ $\mu\text{sec}$	-	$V_{DD1} = 3.3\text{ V}$ , $CL = 33\text{ pF}$ <sup>(1)</sup>
$OP_{IMP}$	OP input impedance	-	$10^8\ \Omega$	-	<sup>(1)</sup> <sup>(2)</sup>
$T_{SET}$	Settling time	-	400 ns	-	$V_{DD1} = 3.3\text{ V}$ , $CL = 33\text{ pF}$ <sup>(1)</sup>

**Table 10 Current Sensing OP Amp AC Characteristics**

Note:

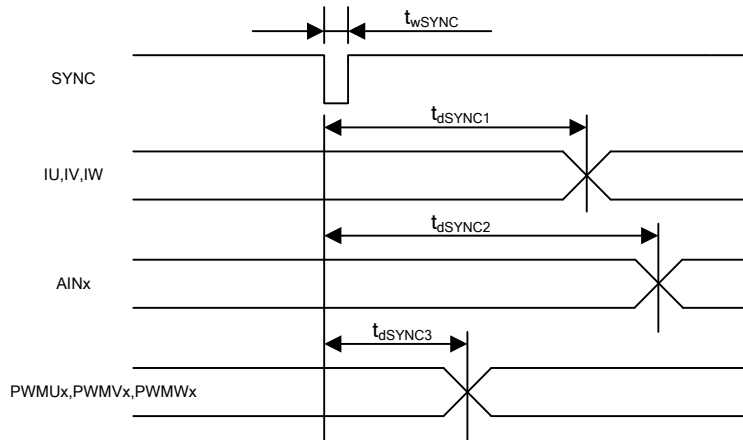
(1) Data guaranteed by design.

(2) To guarantee stability of the operational amplifier, it is recommended to load the output pin by a capacitor of 47pF, see Figure 8. Here only the single shunt current amplifier is shown but all op amp outputs should be loaded with this capacitor value.



**Figure 8 Op amp output capacitor**

### 6.4 SYNC to SVPWM and A/D Conversion AC Timing



**Figure 9. SYNC timing**

Unless specified, Ta = 25°C.

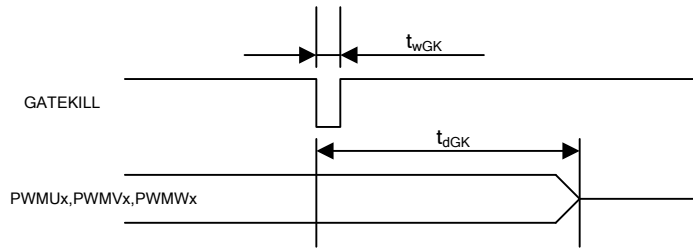
Symbol	Parameter	Min	Typ	Max	Unit
$t_{wSYNC}$	SYNC pulse width	-	32	-	SYSCLK
$t_{dSYNC1}$	SYNC to current feedback conversion time	-	-	100	SYSCLK
$t_{dSYNC2}$	SYNC to AIN0-4, ADCH, ADCL analog input conversion time	-	-	200	SYSCLK <sup>(1)</sup>
$t_{dSYNC3}$	SYNC to PWM output delay time	-	-	2	SYSCLK

**Table 11. SYNC AC Characteristics**

Note:

(1) AIN1 – AIN5 channels are converted once every 5 SYNC events

### 6.5 GATEKILL to SVPWM AC Timing



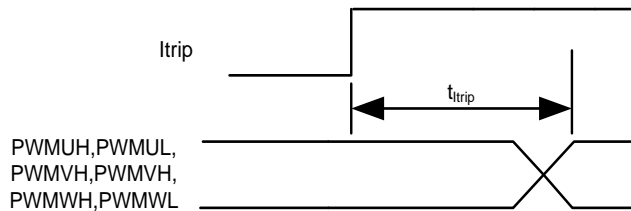
**Figure 10. Gatekill timing**

Unless specified, Ta = 25°C.

Symbol	Parameter	Min	Typ	Max	Unit
t <sub>wGK</sub>	GATEKILL pulse width	32	-	-	SYCLK
t <sub>dGK</sub>	GATEKILL to PWM output delay	-	-	100	SYCLK

**Table 12. GATEKILL to SVPWM AC Timing**

### 6.6 Itrip AC Timing



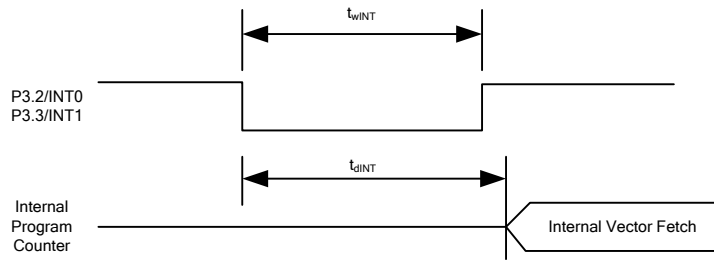
**Figure 11. ITRIP timing**

Unless specified, Ta = 25°C.

Symbol	Parameter	Min	Typ	Max	Unit
t <sub>TRIP</sub>	Itrip propagation delay	-	-	100(sysclk)+1.0usec	SYCLK+usec

**Table 13. Itrip AC Timing**

### 6.7 Interrupt AC Timing



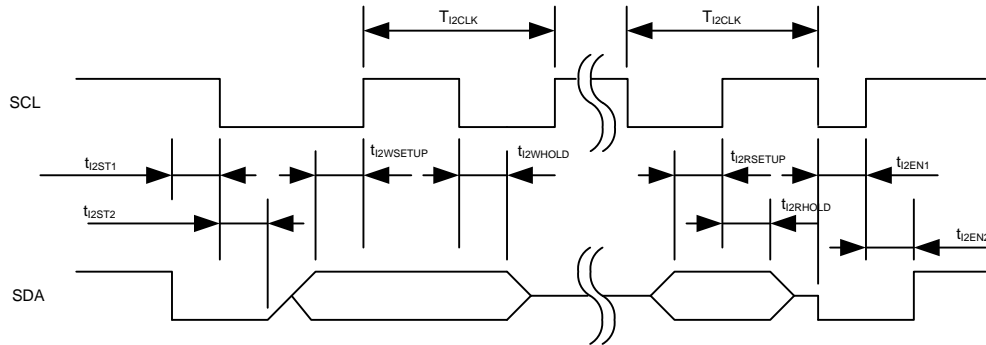
**Figure 12. Interrupt timing**

Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Unit
$t_{wINT}$	INT0, INT1 Interrupt Assertion Time	4	-	-	SYSClk
$t_{dINT}$	INT0, INT1 latency	-	-	4	SYSClk

**Table 14. Interrupt AC Timing**

## 6.8 I<sup>2</sup>C AC Timing



**Figure 13. I<sup>2</sup>C Timing**

Unless specified, Ta = 25°C.

Symbol	Parameter	Min	Typ	Max	Unit
T <sub>I2CLK</sub>	I <sup>2</sup> C clock period	10	-	8192	SYSCLK
t <sub>12ST1</sub>	I <sup>2</sup> C SDA start time	0.25	-	-	T <sub>I2CLK</sub>
t <sub>12ST2</sub>	I <sup>2</sup> C SCL start time	0.25	-	-	T <sub>I2CLK</sub>
t <sub>12WSETUP</sub>	I <sup>2</sup> C write setup time	0.25	-	-	T <sub>I2CLK</sub>
t <sub>12WHOLD</sub>	I <sup>2</sup> C write hold time	0.25	-	-	T <sub>I2CLK</sub>
t <sub>12RSETUP</sub>	I <sup>2</sup> C read setup time	I <sup>2</sup> C filter time <sup>(1)</sup>	-	-	SYSCLK
t <sub>12RHOLD</sub>	I <sup>2</sup> C read hold time	1	-	-	SYSCLK

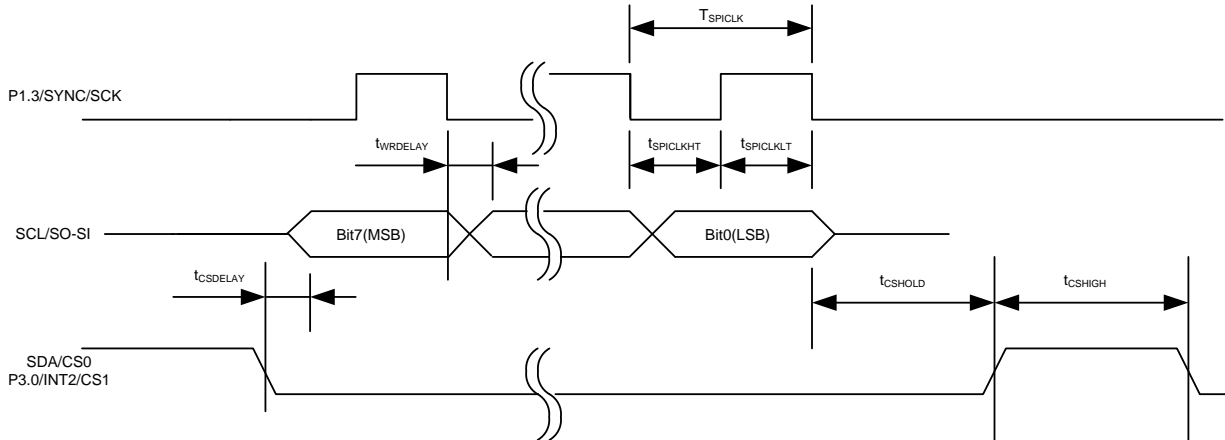
**Table 15. I<sup>2</sup>C AC Timing**

Note:

(1) I<sup>2</sup>C read setup time is determined by the programmable filter time applied to I<sup>2</sup>C communication.

## 6.9 SPI AC Timing

### 6.9.1.1 SPI Write AC timing



**Figure 14. SPI write timing**

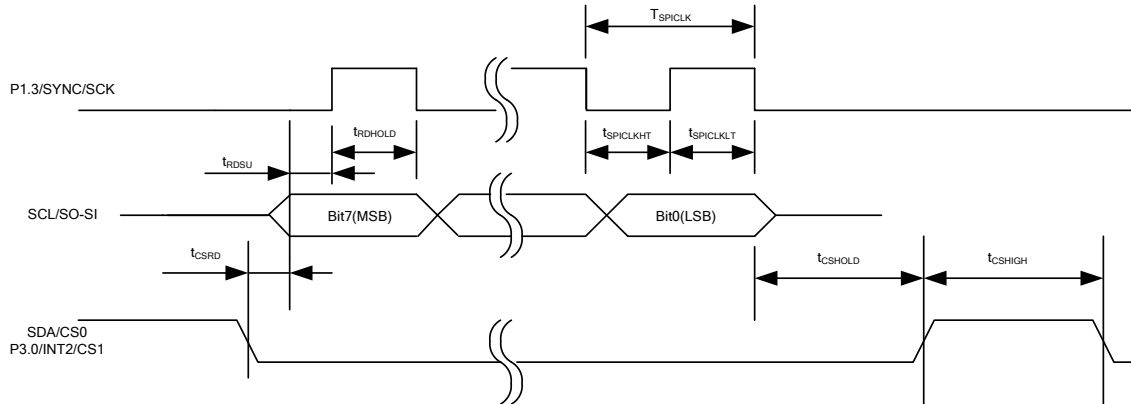
Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Unit
$T_{\text{SPICLK}}$	SPI clock period	4	-	-	SYSCLK
$t_{\text{SPICLKHT}}$	SPI clock high time	-	1/2	-	$T_{\text{SPICLK}}$
$t_{\text{SPICLKLT}}$	SPI clock low time	-	1/2	-	$T_{\text{SPICLK}}$
$t_{\text{CSDELAY}}$	CS to data delay time	-	-	10	nsec
$t_{\text{WRDELAY}}$	CLK falling edge to data delay time	-	-	10	nsec
$t_{\text{CSHIGH}}$	CS high time between two consecutive byte transfer	1	-	-	$T_{\text{SPICLK}}$
$t_{\text{CSHOLD}}$	CS hold time	-	1	-	$T_{\text{SPICLK}}$

**Table 16. SPI Write AC Timing**



### 6.9.1.2 SPI Read AC Timing



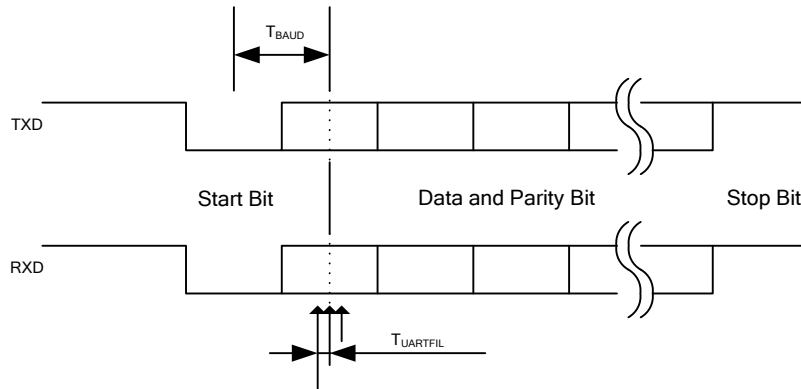
**Figure 15. SPI read timing**

Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Unit
$T_{\text{SPICLK}}$	SPI clock period	4	-	-	SYSCLK
$t_{\text{SPICLKHT}}$	SPI clock high time	-	1/2	-	$T_{\text{SPICLK}}$
$t_{\text{SPICLKLT}}$	SPI clock low time	-	1/2	-	$T_{\text{SPICLK}}$
$t_{\text{CSRD}}$	CS to data delay time	-	-	10	nsec
$t_{\text{RDSU}}$	SPI read data setup time	10	-	-	nsec
$t_{\text{RDHOLD}}$	SPI read data hold time	10	-	-	nsec
$t_{\text{CSHIGH}}$	CS high time between two consecutive byte transfer	1	-	-	$T_{\text{SPICLK}}$
$t_{\text{CSHOLD}}$	CS hold time	-	1	-	$T_{\text{SPICLK}}$

**Table 17. SPI Read AC Timing**

### 6.10 UART AC Timing



**Figure 16. UART timing**

Unless specified,  $T_a = 25^\circ\text{C}$ .

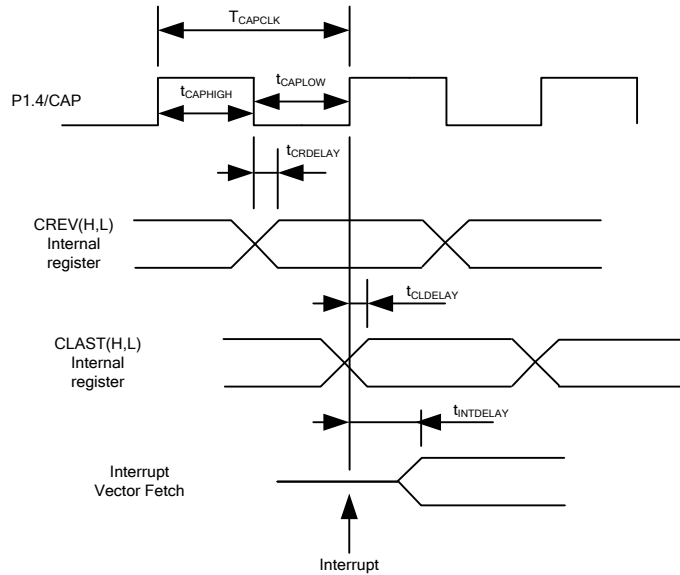
Symbol	Parameter	Min	Typ	Max	Unit
$T_{\text{BAUD}}$	Baud Rate Period	-	57600	-	bit/sec
$T_{\text{UARTFIL}}$	UART sampling filter period <sup>(1)</sup>	-	1/16	-	$T_{\text{BAUD}}$

**Table 18. UART AC Timing**

Note:

- (1) Each bit including start and stop bit is sampled three times at center of a bit at an interval of  $1/16 T_{\text{BAUD}}$ . If three sampled values do not agree, then UART noise error is generated.

### 6.11 CAPTURE Input AC Timing

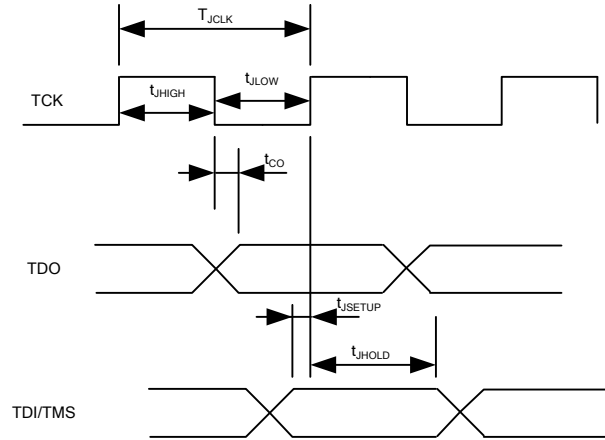


**Figure 17. CAPTURE timing**

Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Unit
$T_{CAPCLK}$	CAPTURE input period	8	-	-	SYSCCLK
$t_{CAPHIGH}$	CAPTURE input high time	4	-	-	SYSCCLK
$t_{CAPLOW}$	CAPTURE input low time	4	-	-	SYSCCLK
$t_{CRDELAY}$	CAPTURE falling edge to capture register latch time	-	-	4	SYSCCLK
$t_{CLDELAY}$	CAPTURE rising edge to capture register latch time	-	-	4	SYSCCLK
$t_{INTDELAY}$	CAPTURE input interrupt latency time	-	-	4	SYSCCLK

**Table 19. CAPTURE AC Timing**

**6.12 JTAG AC Timing**

**Figure 18. JTAG timing**

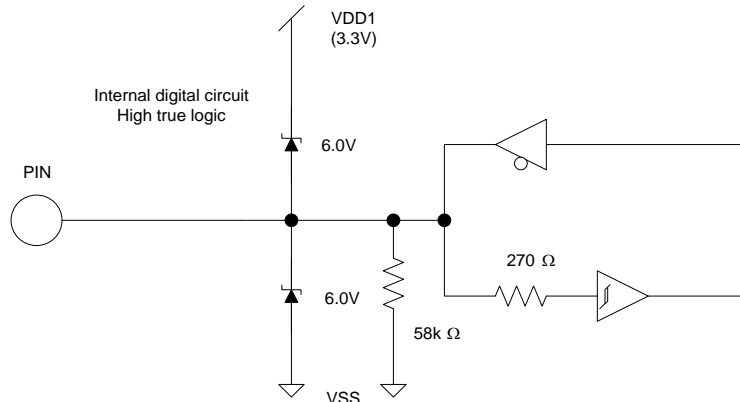
 Unless specified,  $T_a = 25^\circ\text{C}$ .

Symbol	Parameter	Min	Typ	Max	Unit
$T_{JCLK}$	TCK Period	-	-	50	MHz
$t_{JHIGH}$	TCK High Period	10	-	-	nsec
$t_{JLOW}$	TCK Low Period	10	-	-	nsec
$t_{CO}$	TCK to TDO propagation delay time	0	-	5	nsec
$t_{JSETUP}$	TDI/TMS setup time	4	-	-	nsec
$t_{JHOLD}$	TDI/TMS hold time	0	-	-	nsec

**Table 20. JTAG AC Timing**

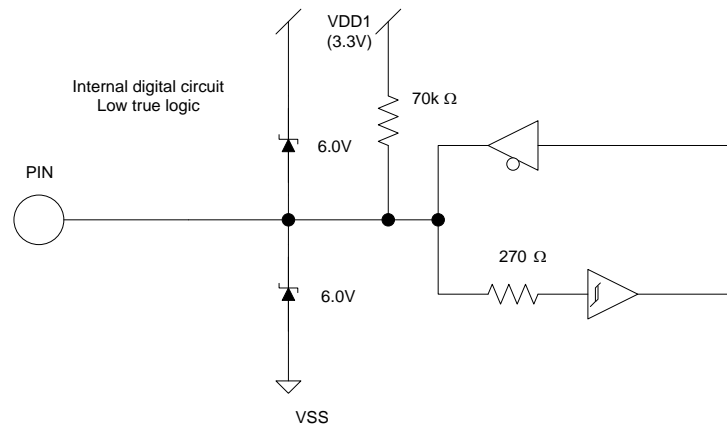
## 7 I/O Structure

The following figure shows the motor PWM output (PWMUH/PWMUL/PWMVH/PWMVL/PWMWH/PWMWL)



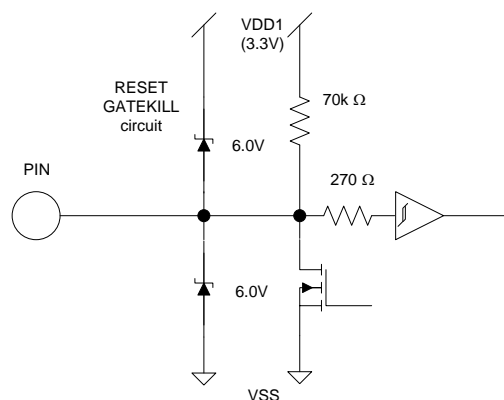
**Figure 19. PWMUL/PWMUH/PWMVL/PWMVH/PWMWL/PWMWH output**

The following figure shows the digital I/O structure except the motor PWM output



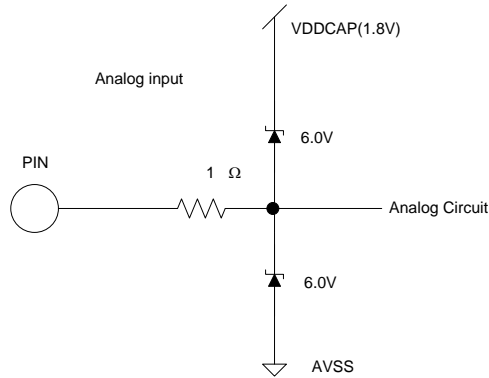
**Figure 20. All digital I/O except motor PWM output**

The following figure shows RESET and GATEKILL I/O structure.



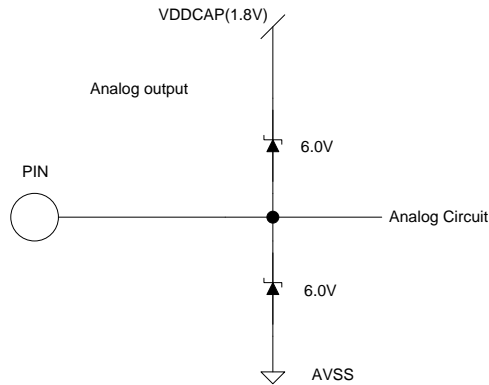
**Figure 21. RESET, GATEKILL I/O**

The following figure shows the analog input structure.



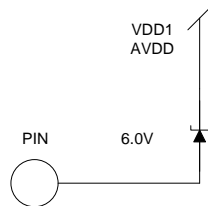
**Figure 22. Analog input**

The following figure shows all analog operational amplifier output pins and AREF pin I/O structure.



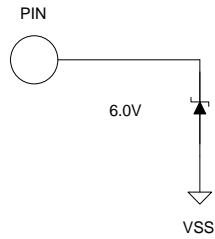
**Figure 23 Analog operational amplifier output and AREF I/O structure**

The following figure shows the VSS,AVSS pin I/O structure



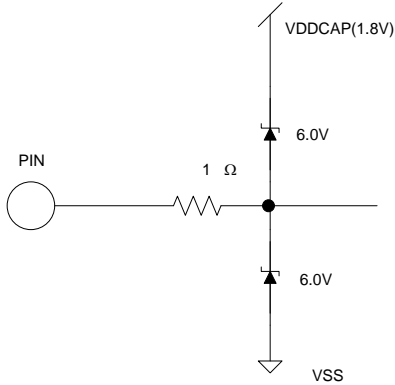
**Figure 24. VSS,AVSS pin I/O structure**

The following figure shows the VDD1,VDDCAP pin I/O structure



**Figure 25. VDD1,VDDCAP pin I/O structure**

The following figure shows the XTAL0 and XTAL1 pins structure



**Figure 26. XTAL0/XTAL1 pins structure**

## 8 Pin List

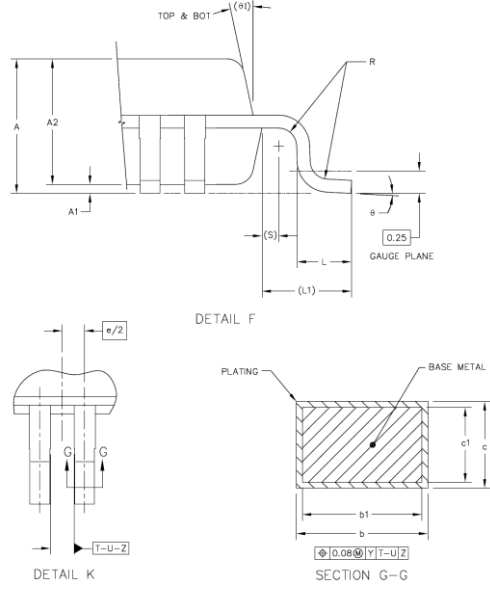
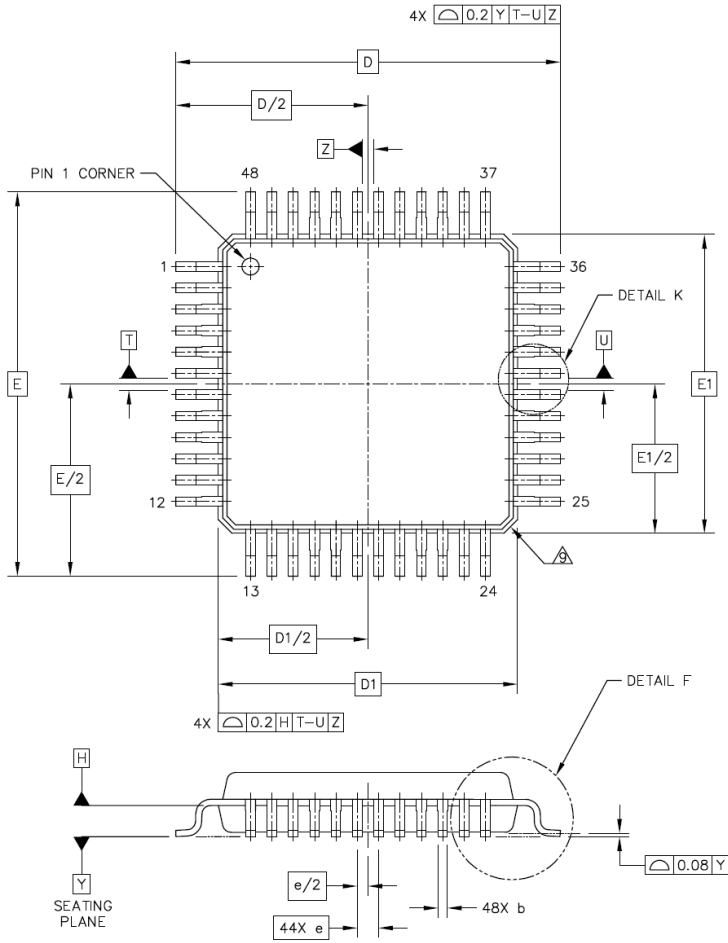
Pin Number	Pin Name	Internal Pull-up /Pull-down	Pin Type	Description
1	XTAL0		I	Crystal input
2	XTAL1		O	Crystal output
3	P1.0/T2		I/O	Discrete programmable I/O or Timer/Counter 2 input
4	SCL/SO-SI		I/O	I <sup>2</sup> C clock output (open drain, need pull up) or SPI data
5	SDA/CS0		I/O	I <sup>2</sup> C data (open drain, need pull up) or SPI Chip Select 0
6	P1.3/SYNC/SCK		I/O	Discrete programmable I/O or SYNC output or SPI clock output
7	P1.4/CAP		I/O	Discrete programmable I/O or Capture timer input
8	VDD1		P	3.3V digital power
9	VSS		P	Digital common
10	VDDCAP		P	Internal 1.8V output, Capacitor(s) to be connected
11	P2.0/NMI		I/O	Discrete programmable I/O or Non-maskable Interrupt input
12	P3.2/INT0		I/O	Discrete programmable I/O or Interrupt 0 input
13	P2.7/AOPWM1		I/O	Discrete programmable I/O or PWM 1 digital output
14	AIN0		I	Analog input channel 0, 0-1.2V range, needs to be pulled down to AVSS if unused
15	AIN1		I	Analog input channel 1, 0-1.2V range, needs to be pulled down to AVSS if unused
16	AIN2		I	Analog input channel 2, 0-1.2V range, needs to be pulled down to AVSS if unused
17	AIN3		I	Analog input channel 3, 0-1.2V range, needs to be pulled down to AVSS if unused
18	AIN4		I	Analog input channel 4, 0-1.2V range, needs to be pulled down to AVSS if unused
19	IFB-		I	Single shunt current sensing OP amp input (-)
20	IFB+		I	Single shunt current sensing OP amp input (+)
21	IFBO		O	Single shunt current sensing OP amp output
22	CMEXT		O	Unbuffered 0.6V output. Capacitor needs to be connected.
23	AREF		O	Analog reference voltage output (0.6V)
24	AIN5-		I	Analog input channel 5, 0-1.2V range, needs to be pulled down to AVSS if unused
25	AIN5+		I	Analog input channel 5, 0-1.2V range, needs to be pulled down to AVSS if unused
26	AIN5O		O	Analog output 5, 0-1.2V range,
27	AVSS		P	Analog common
28	VDDCAP		P	Internal 1.8V output, Capacitor(s) to be connected
29	VDD1		P	3.3V digital power
30	VSS		P	Digital common
31	P3.1/AOPWM2		I/O	Discrete programmable I/O or PWM 2 digital output
32	PWMWL	58 k $\Omega$ Pull down	O	PWM gate drive for phase W low side, configurable either high or low true.
33	PWMVL	58 k $\Omega$ Pull down	O	PWM gate drive for phase V low side, configurable either high or low true



Pin Number	Pin Name	Internal Pull-up /Pull-down	Pin Type	Description
34	PWMUL	58 kΩ Pull down	O	PWM gate drive for phase U low side, configurable either high or low true
35	PWMWH	58 kΩ Pull down	O	PWM gate drive for phase W high side, configurable either high or low true
36	PWMVH	58 kΩ Pull down	O	PWM gate drive for phase V high side, configurable either high or low true
37	PWMUH	58 kΩ Pull down	O	PWM gate drive for phase U high side, configurable either high or low true
38	P1.5		I/O	Discrete programmable I/O.
39	GATEKILL	70 kΩ Pull up	I	PWM shutdown input, configurable digital filter, active low input.
40	P3.0/INT2/CS1	70 kΩ Pull up	I/O	Discrete programmable I/O or external interrupt 2 input or SPI Chip Select 1
41	P5.2/TMS		I	JTAG test mode input or input digital port
42	TDO		O	JTAG test data output
43	P5.1/TDI		I	JTAG test data input or input digital port
44	TCK		I	JTAG test clock
45	RESET		I	Reset, low true, Schmitt trigger input
46	P1.1/RXD		I/O	UART receiver input or Discrete programmable I/O
47	P1.2/RXD		I/O	UART transmitter output or Discrete programmable I/O
48	P3.3/INT1		I/O	Interrupt 1 input or Discrete I/O

**Table 21. Pin List**

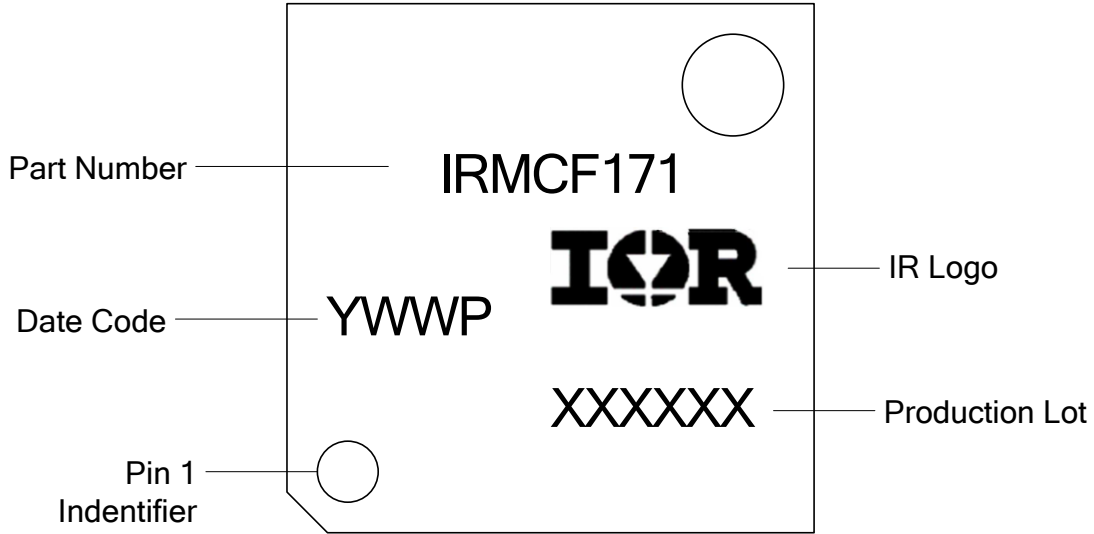
## 9 Package Dimensions



- NOTES:
1. DIMENSIONS ARE IN MILLIMETERS.
  2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5M-1994.
  3. DATUM PLANE H IS LOCATED AT BOTTOM OF LEAD AND IS COINCIDENT WITH THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY AT THE BOTTOM OF THE PARTING LINE.
  4. DATUM T, U AND Z TO BE DETERMINED AT DATUM PLANE H.
  5. DIMENSIONS D AND E TO BE DETERMINED AT SEATING PLANE Y.
  6. DIMENSIONS D1 AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25 PER SIDE. DIMENSIONS D1 AND E1 DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE H.
  7. DIMENSION b DOES NOT INCLUDE DAM BAR PROTRUSION. DAM BAR PROTRUSION SHALL NOT CAUSE THE b DIMENSION TO EXCEED 0.35.
  8. MINIMUM SOLDER PLATE THICKNESS SHALL BE 0.0076.
- EXACT SHAPE OF EACH CORNER IS OPTIONAL.

DIM	MIN	MAX	DIM	MIN	MAX	DIM	MIN	MAX
A	1.4	1.6	L1		1 REF			
A1	0.05	0.15	R	0.15	0.25			
A2	1.35	1.45	S		0.2 REF			
b	0.17	0.27	θ	1°	5°			
b1	0.17	0.23	θ1		12° REF			
c	0.09	0.2						
c1	0.09	0.16						
D		9 BSC						
D1		7 BSC						
e		0.5 BSC						
E		9 BSC						
E1		7 BSC						
L	0.5	0.7						

**10 Part Marking Information**



**11 Qualification Information**

<b>Qualification Level</b>		Industrial <sup>††</sup> (per JEDEC JESD 47E)
<b>Moisture Sensitivity Level</b>		MSL3 <sup>†††</sup> (per IPC/JEDEC J-STD-020C)
<b>ESD</b>	<b>Machine Model</b>	Class B (per JEDEC standard JESD22-A114D)
	<b>Human Body Model</b>	Class 2 (per EIA/JEDEC standard EIA/JESD22-A115-A)
<b>RoHS Compliant</b>		Yes

† Qualification standards can be found at International Rectifier’s web site <http://www.irf.com/>

†† Higher qualification ratings may be available should the user have such requirements. Please contact your International Rectifier sales representative for further information.

††† Higher MSL ratings may be available for the specific package types listed here. Please contact your International Rectifier sales representative for further information.

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