

Getting started with the X-NUCLEO-IKS01A3 motion MEMS and environmental sensor expansion board for STM32 Nucleo

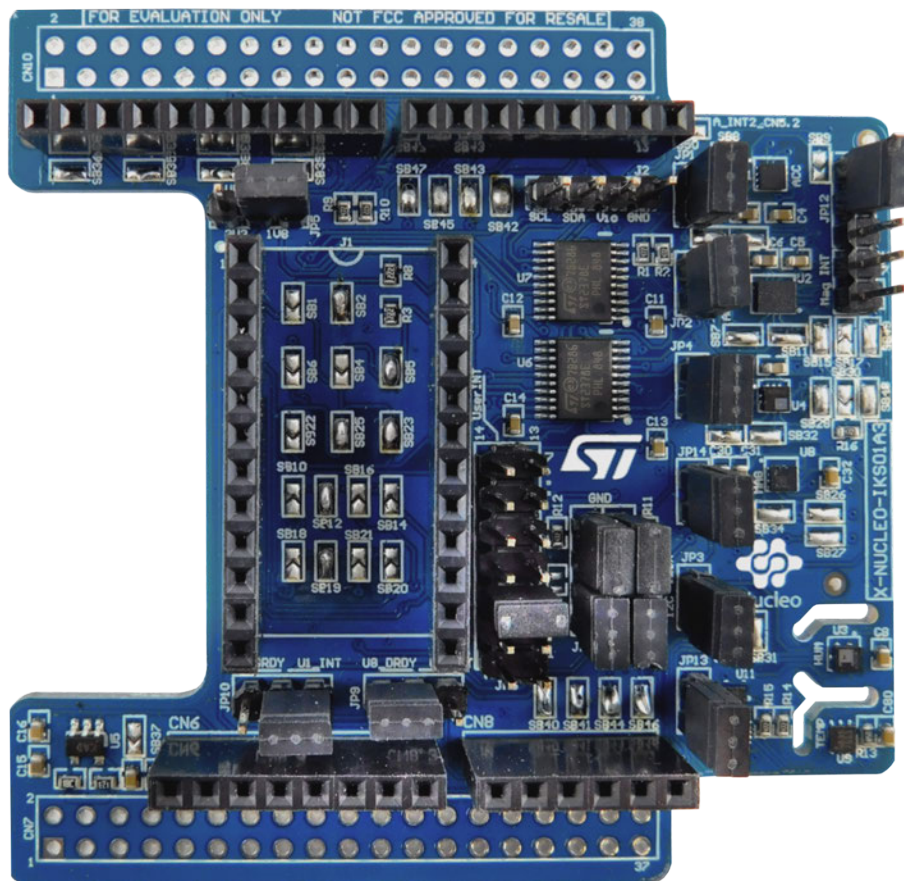
Introduction

The X-NUCLEO-IKS01A3 is a motion MEMS and environmental sensor evaluation board system.

It is compatible with the Arduino UNO R3 connector layout and features the [LSM6DSO](#) 3-axis accelerometer + 3-axis gyroscope, the [LIS2MDL](#) 3-axis magnetometer, the [LIS2DW12](#) 3-axis accelerometer, the [HTS221](#) humidity and temperature sensor, the [LPS22HH](#) pressure sensor, and the [STTS751](#) temperature sensor.

The X-NUCLEO-IKS01A3 interfaces with the STM32 microcontroller via the I²C pin, and it is possible to change the default I²C port.

Figure 1. X-NUCLEO-IKS01A3 expansion board

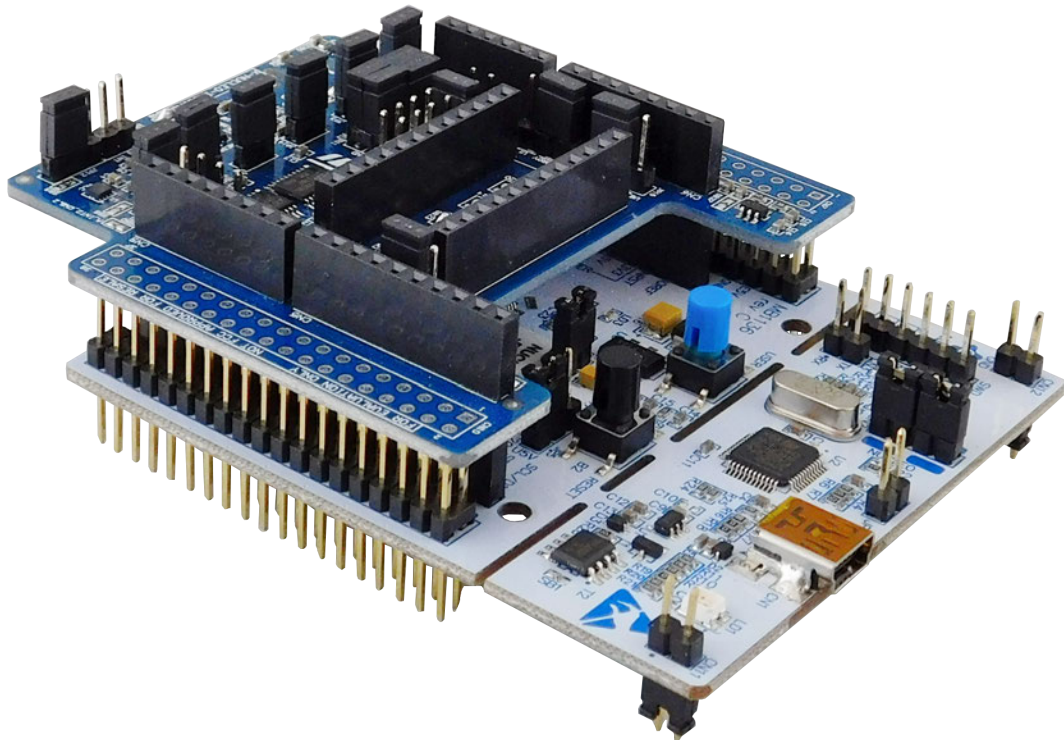


1 Getting started

1.1 Hardware requirements

The X-NUCLEO-IKS01A3 is designed to be used with STM32 Nucleo boards (visit www.st.com for further information).

Figure 2. X-NUCLEO-IKS01A3 plugged on an STM32 Nucleo board



The X-NUCLEO-IKS01A3 must be connected on the matching pins of any STM32 Nucleo board with the Arduino UNO R3 connector.

Note: X-NUCLEO-IKS01A3 components are ESD sensitive and, as the board has male/female pass-through connectors, it is important to handle it with care to avoid bending or damaging the pins.

RELATED LINKS

[See the X-CUBE-MEMS1 product page for firmware and related documentation](#)

2 System requirements

To complete the system setup, you need:

- a Windows® (7, 8, 10) PC
- a USB type A to mini-B USB cable to connect the STM32 Nucleo to the PC
- board firmware and software package (X-CUBE-MEMS1) installed on the user PC

3 Hardware description

The board lets you test the functionality of the motion MEMS accelerometer, gyroscope and magnetometer, and environmental humidity, temperature and pressure sensors, via the I²C communication bus.

It also allows all [LSM6DSO](#) sensor hub function testing.

The board features:

- Operating range: 3.3 V, 250 mA
- LSM6DSO: MEMS 3D accelerometer ($\pm 2/\pm 4/\pm 8/\pm 16$ g) + 3D gyroscope ($\pm 125/\pm 250/\pm 500/\pm 1000/\pm 2000$ dps)
- LIS2MDL: MEMS 3D magnetometer (± 50 gauss)
- LIS2DW12: MEMS 3D accelerometer ($\pm 2/\pm 4/\pm 8/\pm 16$ g)
- LPS22HH: MEMS pressure sensor, 260-1260 hPa absolute digital output barometer
- HTS221: capacitive digital relative humidity and temperature
- STTS751: Temperature sensor (-40 °C to $+125$ °C)
- DIL 24-pin socket available for additional MEMS adapters and other sensors
- Free comprehensive development firmware library and example for all sensors compatible with STM32Cube firmware
- I²C sensor hub features on LSM6DSO available
- Compatible with STM32 Nucleo boards
- Equipped with Arduino UNO R3 connector
- RoHS compliant
- WEEE compliant

Each device has a separate power supply to allow power consumption measurement of every sensor.

The expansion board is power supply compatible with STM32 Nucleo boards: it mounts an LDO to generate 1.8 V for all the MEMS sensors except for the [STTS751](#), which is supplied by a separate LDO generating 2.5 V.

All signals between the sensors and the main board are translated by a level shifter.

3.1 Default solder bridge configuration

The user can configure several aspects of the X-NUCLEO-IKS01A3 through several solder bridges which can be left open (not mounted) or closed (mounted) to configure different hardware settings.

Table 1. Default solder bridge default configuration (device to I²C bus connection)

| Device | BUS | Solder bridge (default) | Solder bridge (not mounted) |
|----------------|-------------------|-------------------------|---|
| LIS2DW12 | I ² C2 | SB3, SB13 | - |
| LSM6DSO | I ² C2 | SB7, SB11 | - |
| HTS221 | I ² C1 | SB24, SB31 | - |
| LPS22HH | I ² C1 | SB29, SB32 | - |
| STTS751 | I ² C1 | SB26, SB27 | - |
| LIS2MDL | I ² C1 | SB33, SB34 | - |
| STM32 Nucleo | I ² C2 | SB35, SB36 | - |
| DIL24 Adapter | I ² C1 | SB12, SB19 | SB1, SB4, SB6, SB10, SB14, SB16, SB18, SB20, SB21, SB22 |
| *DIL24 Adapter | I ² C2 | SB16, SB21 | SB1, SB4, SB6, SB10, SB14, SB12, SB18, SB20, SB19, SB22 |
| *DIL24 Adapter | I ² Cx | SB14, SB20 | SB1, SB4, SB6, SB10, SB12, SB16, SB18, SB19, SB21, SB22 |

Table 2. Device I²C address

| Device | Solder bridge (non default) | I ² C address default |
|----------|-----------------------------|----------------------------------|
| LIS2DW12 | SB8 | 32h |
| LIS2DW12 | SB9 ⁽¹⁾ | 30h |
| LSM6DSO | SB15 | D6h |
| LSM6DSO | SB17 ⁽¹⁾ | D4h |
| LIS2MDL | - | 3C |
| STTS751 | - | 94h |
| LPS22HB | SB13 | BAh |
| LPS22HB | SB14 | B8h |
| HTS221 | - | BEh |

1. not mounted by default

Note: Other SBs mounted by default are SB40 to SB49 (STM32 Nucleo GPIO INT), SB23, SB25, SB39
 Other SBs not mounted by default are SB38, SB37, SB50

3.2 Block diagram

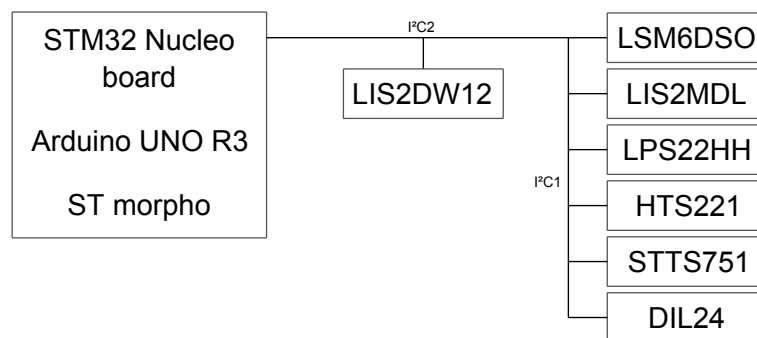
The LSM6DSO has an I²C sensor hub which allows it to behave as the I²C master for other slave devices connected via an I²C_{aux} bus. Various configurations are possible for different I²C bus connections with or without the LSM6DSO sensor hub.

Mode 1: standard I²C bus connection (all sensors)

In standard I²C mode, all devices are connected to an external main board via the same I²C bus.

The board configuration is:

- JP7: 1-2, 3-4 (I²C1 = I²C2, I²Cx=GND)
- JP8: 1-2, 3-4 (I²C1 = I²C2, I²Cx=GND)

Figure 3. X-NUCLEO-IKS01A3 standard I²C


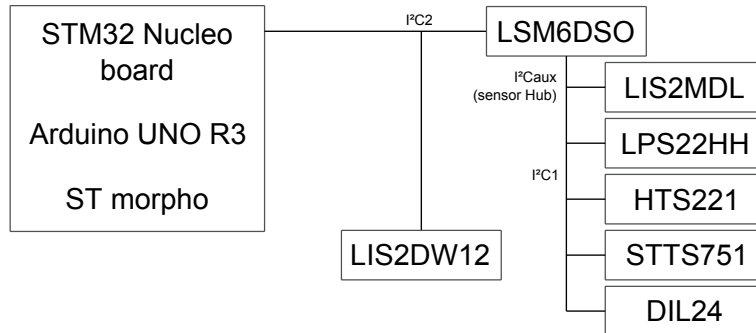
Mode 2: LSM6DSO I²C sensor hub (all sensors)

In this sensor hub I²C mode, the LSM6DSO is connected to an external main board by an I²C bus; all other devices except LIS2DW12 are slaves connected to LSM6DSO via I²C_{aux}.

The board configuration is:

- JP7: 2-3 (I²C1 = I²Cx)
- JP8: 2-3 (I²C1 = I²Cx)

Figure 4. X-NUCLEO-IKS01A3 LSM6DSO I²C sensor hub



Mode 3: DIL24 plus LSM6DSO I²C sensor hub (all sensors, not DIL24)

In this sensor hub I²C mode, the LSM6DSO and the DIL24 adapter are connected to an external main board by an I²C bus; all other devices except LIS2DW12 are slaves of the LSM6DSO via I²C_{aux}.

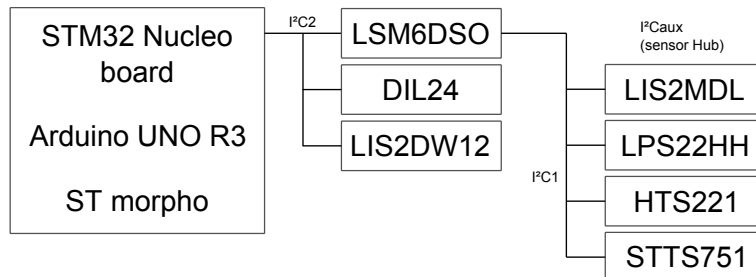
The board configuration is:

- JP7: 2-3 (I²C1 = I²Cx)
- JP8: 2-3 (I²C1 = I²Cx)

DIL24 adapter (to I²C2): SB16, SB21

Not mounted: SB6, SB10, SB12, SB14, SB18, SB19, SB20, SB22

Figure 5. X-NUCLEO-IKS01A3 DIL24, LSM6DSO I²C sensor hub (all sensors)



Mode 4: LSM6DSO plus DIL24 I²C sensor hub (all sensors)

In this sensor hub I²C mode, the LSM6DSO and the DIL24 adapter are connected to an external main board by an I²C bus; all other devices except LIS2DW12 are slaves of the DIL24 adapter via I²C_{aux}.

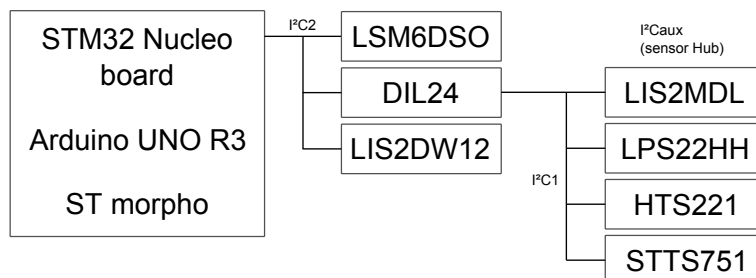
The board configuration is:

- JP7: 2-3 (I²C1 = I²Cx)
- JP8: 2-3 (I²C1 = I²Cx)

DIL24 adapter (to I²C2): SB16 SB21

Not mounted: SB6, SB10, SB12, SB14, SB18, SB19, SB20, SB22

Figure 6. X-NUCLEO-IKS01A3 LSM6DSO, DIL24, I²C sensor hub (all sensors)



Mode 5: LSM6DSO plus I²C sensor hub DIL24

In this sensor hub I²C mode, the LSM6DSO and other sensors are connected to an external main board via an I²C bus; the DIL24 adapter is a slave of the LSM6DSO via I²C_{aux}.

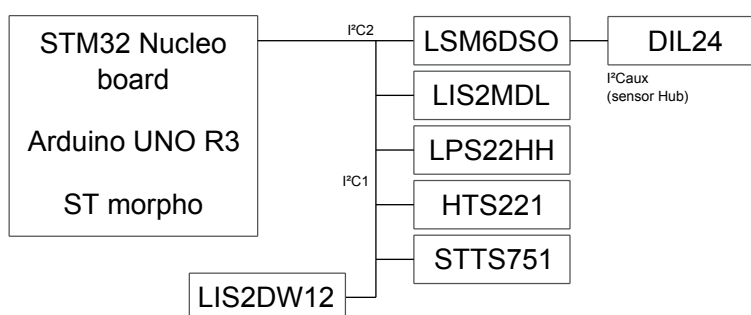
The board configuration is:

- JP7: 1-2 (I²C1 = I²Cx)
- JP8: 1-2 (I²C1 = I²Cx)

DIL24 adapter (to I²Cx): SB14, SB20

Not mounted: SB6, SB10, SB12, SB16, SB18, SB19, SB21, SB22

Figure 7. X-NUCLEO-IKS01A3 LSM6DSO plus sensor hub DIL24



3.3 Sensor I²C address selection

Most sensors allow I²C address LSB selection by pulling the SD0 pin low or high. The board has solder bridges to control SD0 level.

Table 3. Solder bridges for SD0 level control and I²C address

| Sensor | SD0 high | SD0 low |
|--------------------|--------------|--------------|
| STTS751 (U9) | ADD= 94h | |
| LIS2DW12(U1) | SB8 ADD=32h | SB9 ADD=30h |
| LSM6DSO (U2) | SB15 ADD=D6h | SB17 ADD=D4h |
| LPS22HH (U4) | SB28 ADD=BAh | SB30 ADD=B8h |
| LIS2MDL (U8) | ADD =3Ch | ADD =3Ch |
| HTS221 (U3) | ADD= BEh | ADD= BEh |
| DIL24 Adapter (J1) | SB1/SB2 | SB4/SB5 |

3.4 Sensor current consumption measurement

The X-NUCLEO-IKS01A3 expansion board is equipped with jumpers which allow separate current consumption measurement for each sensor.

To measure current consumption, connect an ammeter to the appropriate jumper.

Note: As the sensors have very low current consumption, you should set a suitable range and use an ammeter with low burden voltage.

Table 4. Jumpers for current consumption measurement

| Sensor | Jumper |
|--------------------|--------|
| LIS2MDL (U8) | JP14 |
| LSM6DSO (U2) | JP11 |
| HTS221 (U3) | JP3 |
| LPS22HH (U4) | JP4 |
| STTS751 (U9) | JP13 |
| LIS2DW12 (U1) | JP1 |
| DIL24 Adapter (J1) | JP5 |

3.5 Sensor disconnection

To disconnect a sensor, you should disconnect the I²C bus as well as the power supply. See the table below for the relevant jumpers and solder bridges.

Table 5. Link between sensors, jumpers and I²C solder bridges

| Sensor | Power | SDA | SCL |
|---------------|-------|------------|------------|
| LIS2MDL (U8) | JP14 | SB34 | SB33 |
| LSM6DSO (U2) | JP11 | SB11 | SB7 |
| HTS221 (U3) | JP3 | SB24 | SB31 |
| LIS2DW12 (U1) | JP1 | SB3 | SB13 |
| STTS751 (U9) | JP13 | SB26 | SB27 |
| LPS22HH (U4) | JP4 | SB32 | SB29 |
| DIL24 adapter | JP5 | SB12,14,16 | SB19,20,21 |

3.6 Adapter board for DIL24 socket

An additional sensor can be connected as an adapter board to J1 DIL24 socket.

As there are a few different interrupt signal assignments for DIL24 pins, the appropriate pin can be selected using the JP6 header.

RELATED LINKS

Please visit the [ST website](#) to find other available sensors

3.7 Connectors

Table 6. Arduino R3 UNO connectors

| Connector | Pin ⁽¹⁾ | Signal |
|-----------|--------------------|----------------------|
| CN5 | 7 | GND |
| | 9 | I ² C SDA |
| | 10 | I ² C SCL |
| CN6 | 2 | 3.3 V |
| | 4 | 3.3 V |
| | 6 | GND |
| | 7 | GND |
| | 8 | N.C.[FT1] |
| CN8 | 3 | LIS2MDL DRDY |
| | 4 | LIS2DW12 INT |
| | 5 | STTS751 INT |
| | 6 | INT1 (DIL24) |
| CN9 | 3 | USER INT |
| | 5 | LSM6DSO INT1 |
| | 6 | LSM6DSO INT2 |
| | 7 | LPS22HH INT1 |

1. *unlisted pins are not connected.*

Table 7. ST morpho connectors

| Connector | Pin ⁽¹⁾ | Signal |
|-----------|--------------------|----------------------|
| CN7 | 12 | 3.3 V |
| | 16 | 3.3 V |
| | 20 | GND |
| | 22 | GND |
| | 32 | LIS2MDL DRDY |
| | 34 | LIS2MDL DRDY |
| | 36 | STTS751 INT |
| | 38 | INT1 (DIL24) |
| CN10 | 3 | I ² C SCL |
| | 5 | I ² C SDA |
| | 25 | LPS22HH INT1 |
| | 27 | LSM6DSO INT2 |
| | 29 | LSM6DSO INT1 |
| | 33 | USER INT |

1. *The unlisted pins are not connected.*

4 Bill of materials

Table 8. X-NUCLEO-IKS01A3 bill of materials

| Item | Quantity | Reference | Part / value | Description | Manufacturer | Part number |
|------|----------|---|---------------------|--------------------------------------|--------------------|--------------------------|
| 1 | 4 | C3, C6, C15, C31 | 10µF | CAP CER 0603 6.3 V X5R ±20% | MULTICOMP | MC0603X106M6R3CT |
| 2 | 12 | C4, C5, C8, C9, C11, C12, C13, C14, C16, C17, C30, C80 | 100nF | CAP CER 0603 25 V X7R ±10% | MULTICOMP | MC0603B104K250CT |
| 3 | 1 | C18 | 2.2µF | CAP CER 0603 25 V X5R ±10% | MULTICOMP | MC0603X225K100CT |
| 4 | 1 | C32 | 220nF | CAP CER 0603 25 V X7R 10% | KEMET | C0603X224K4RACTU |
| 5 | 4 | CN5, CN6, CN8, CN9 | 10x1, 8x1, 6x1, 8x1 | Headers | 4UCON | - |
| 6 | 1 | J1 | - | DIL24 Socket | MULTICOMP | 2212S-12SG-85 |
| 7 | 7 | JP1, JP2, JP3, JP4, JP11, JP13, JP14 | 2x1 | Header + Shunt | HARWIN | M20-9990246 |
| 8 | 4 | JP5, JP9, JP10, JP12 | - | Header + Shunt | Generic Components | 2211S-03G |
| 9 | 1 | JP6 | 2x7 | Header | Generic Components | 61301421121 |
| 10 | 2 | JP7, JP8 | - | Header + 2 shunts | Generic Components | 2211S-04G |
| 11 | 10 | R1, R2, R9, R10, R11, R12, R14, R15, R16, R17 | 4k7 | RES 0603 ±1% 1/16 W | MULTICOMP | MC0063W060314K7 |
| 12 | 2 | R3, R8 | 2k2 | RES 0603 ±1% 1/16 W | MULTICOMP | MC0063W060312K2 |
| 13 | 1 | R6 | 12k | RES 0603 ±1% 1/16 W | MULTICOMP | MC0063W0603512K |
| 14 | 1 | R7 | 15k | RES 0603 ±1% 1/16 W | MULTICOMP | MC0063W0603515K |
| 15 | 1 | R13 | 7K5 | RES 0603 ±0.5% 1/16 W | SUSUMU | RR0816P-752-D |
| 16 | 34 | SB2, SB3, SB5, SB7, SB8, SB11, SB12, SB13, SB15, SB19, SB23, SB24, SB25, SB26, SB27, SB28, SB29, SB31, SB32, SB33, SB34, SB35, SB36, SB39, SB40, SB41, SB42, SB43, SB44, SB45, SB46, SB47, SB48, SB49 | - | Solder Bridge | - | - |
| 17 | 1 | U1 | LIS2DW12 | 3-axis MEMS accelerometer | ST | LIS2DW12 |
| 18 | 1 | U2 | LSM6DSO | iNEMO 6DoF inertial measurement unit | ST | LSM6DSO |

| Item | Quantity | Reference | Part / value | Description | Manufacturer | Part number |
|------|----------|-----------|--------------|--|--------------|-----------------------------|
| 19 | 1 | U3 | HTS221 | Digital sensor for relative humidity and temperature | ST | HTS221 |
| 20 | 1 | U4 | LPS22HH | MEMS nano pressure sensor | ST | LPS22HH |
| 21 | 1 | U5 | LDK130M-R | 300 mA low quiescent current very low noise LDO | ST | LDK130M-R |
| 22 | 2 | U6, U7 | ST2378E | 8-Bit Level Translator with 15kV ESD Protection | ST | ST2378E |
| 23 | 1 | U8 | LIS2MDL | Magnetic sensor digital output 50 gauss | ST | LIS2MDL |
| 24 | 1 | U9 | STTS751 | 2.25 V low-voltage local digital temperature sensor | ST | STTS751 |
| 25 | 1 | U10 | NTS0104GU12 | IC TXRX TRANSLATING 2BIT 8XSON | NXP | NTS0104GU12 |
| 26 | 1 | U11 | LDK120PU25 | 200 mA low quiescent current very low noise LDO | ST | LDK120PU25R |

Revision history

Table 9. Document revision history

| Date | Version | Changes |
|-------------|---------|---|
| 18-Feb-2019 | 1 | Initial release. |
| 07-Jul-2020 | 2 | Updated Section 3.2 Block diagram. |
| 09-Sep-2020 | 3 | Updated Section 3 Hardware description. |

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