

### **Features**

- 3.3 and 5 VDC voltage supply option
- PWM Absolute Position
- Bushing or servo mount
- Non-contacting magnetic technology
- Small size
- CMOS and TTL compatible

- Resolution: 1024 states
- Long life
- High operating speed
- Highly repeatable
- Sealed option
- Magnetic technology

# **EMS22P - Non-Contacting PWM Encoder**

<b>Electrical Characteristics</b>	
Resolution	
Insulation Resistance (500 VDC)	1,000 megohms
, ,	
	5.0 VDC ±10 %, 3.3 VDC ±10 %
11,7	
Output Voltage	
	Vss+0.4 V maximum
·	Vdd-0.5 V minimum
Output Current	Vac 0.0 V IIIIIIIIIIIIII
	4 mA maximum
11,7	2 mA maximum
. ,	
	10,000 rpm maximum
=	
Accuracy	270 1 11
	±0.7 ° or better
	±1.4°
Jutput Transition Noise	
Environmental Characteristics	
Operating Temperature Range	40 °C to +125 °C (-40 °F to +257 °F)
	55 °C to +125 °C (-67 °F to +257 °F)
	MIL-STD-202, Method 103B, Condition B
,	15 G
	50 G
Rotational Life	
• · · · · · · · · · · · · · · · · · · ·	
•	
Mechanical Characteristics	000 0 0 11
S .	360 ° Continuous
Torque	
•	
Running	
Mounting Torque	
Shaft End Play	
Shaft Radial Play	
Weight	
Terminals	
Soldering Condition	.,
Mariaal Coldoning	370 °C (700 °F) max. for 3 seconds
Wave Soldering	96.5Sn/3.0Ag/0.5Cu solder with no-clean flux
wave coluening	260 °C (500 °F) max. for 10 seconds
Wash processes	260 °C (500 °F) max. for 10 seconds
•	
HardwareOne lockwasher	and one mounting nut supplied with each encoder, except on servo mount versions.

#### **Pin Configuration**

Output Type	Pin 1	Pin 2	Pin 3	Pin 4	Pin 5	Pin 6
PWM	PWM Signal	GND	GND	GND	VCC*	CS**

- \* Can be 5 or 3.3 VDC depending on the version.
- \*\* Active low chip select pin; if not used connect pin 6 to GND.



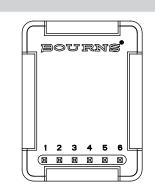
### WARNING Cancer and Reproductive Harm - www.P65Warnings.ca.gov

\*RoHS Directive 2002/95/EC Jan. 27, 2003 including annex and RoHS Recast 2011/65/EU June 8, 2011.

Specifications are subject to change without notice.
Users should verify actual device performance in their specific applications.

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### **Applications**

- Material handling equipment
- Brushless DC motor commutation
- Robotics
- Automotive
- Industrial automation
- Petroleum refinery

- Medical (low/medium risk)\*
- Office equipment
- Audio and broadcast equipment

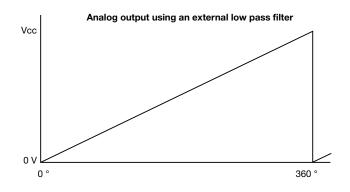
## **EMS22P - Non-Contacting PWM Encoder**

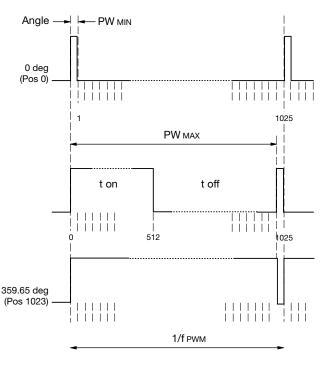
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#### **Output Type Waveform and Variant Table**

#### **PWM Output**

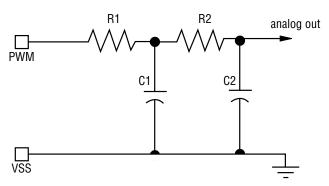
	Parameter	Symbol	Туре	Unit	Note
	PWM frequency	fPWM	0.9756	KHz	Signal period: 1025 μs
	MIN pulse with	PWMIN	1	μS	Position 0 Angle 0 °
ſ	MAX pulse with	PWMAX	1024	μS	Position 1023 Angle 359.65 °





Position = t on \* 1025/(t on + t off) - 1

#### Recommended Filter



Simple Passive 2nd Order Low Pass Filter

R1, R2 ≥ 4.7K Ohms

C1, C2  $\geq$  1  $\mu$ F / 6 V

R1 should be  $\geq$  4.7K ohms to avoid loading of the PWM output. Larger values of Rx and Cx will provide better filtering and less ripple, but will also slow down the response time.

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Consult factory for options not shown, including:

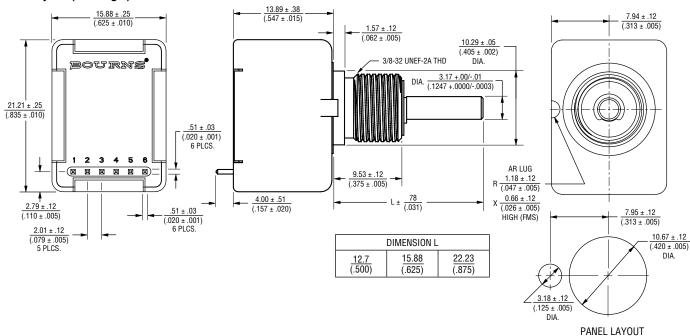
- Wire lead or cable options Special shaft/bushing sizes and features
- Connectors Special performance characteristics
- PCB mounting bracket Non-standard resolutions

# **EMS22P - Non-Contacting PWM Encoder**

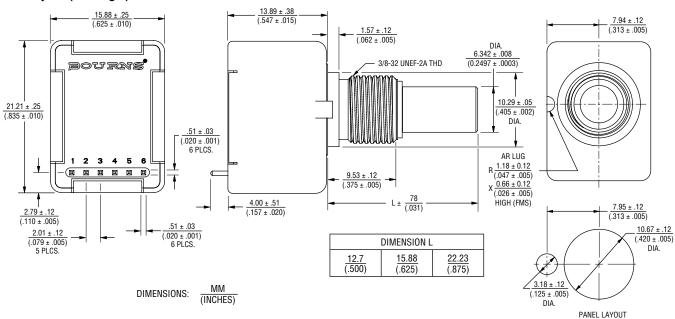
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#### **Product Dimensions**

### Shaft Style D (Bushing T)



#### Shaft Style B (Bushing S)



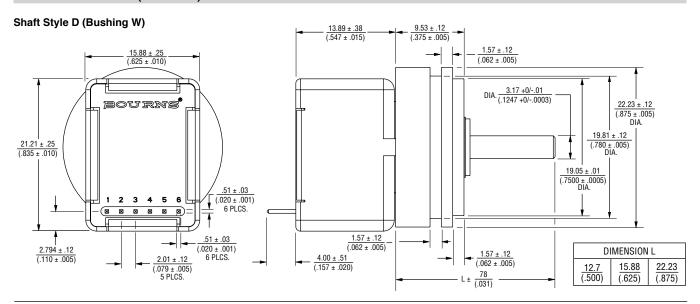
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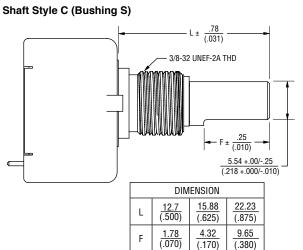
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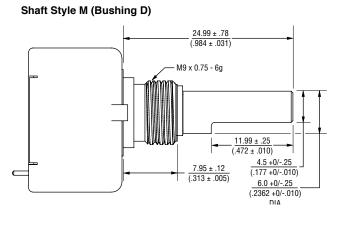
# **EMS22P - Non-Contacting PWM Encoder**

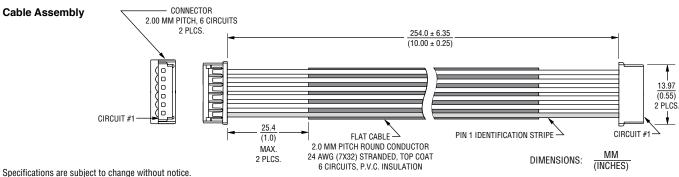
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#### **Product Dimensions (Continued)**









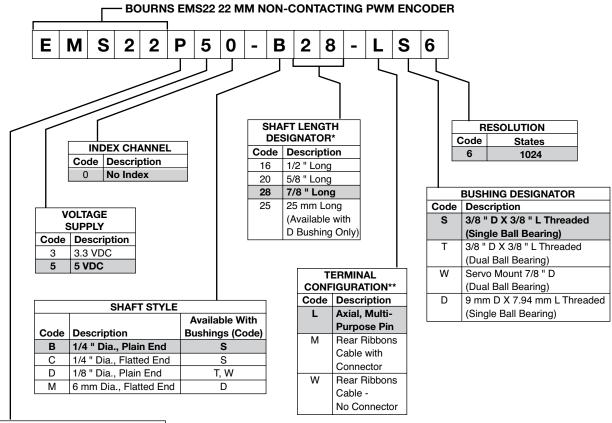
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# **EMS22P - Non-Contacting PWM Encoder**

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#### **How To Order**



OUTPUT TYPE

 Code
 Description
 Notes

 P
 CW PWM
 See Note 1

 R
 CCW PWM
 See Note 2

Note 1: (P) t on increases from 1 to 1025 with CW rotation of the shaft.

Note 2: (R) t on increases from 1 to 1025 with CCW rotation of the shaft.

<sup>\*</sup> Shaft length measured from mounting surface.

<sup>\*\*</sup> Standard ribbon cable is 10 inches long. Consult factory for other lengths.

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