

#### **Features**

- 3.3 and 5 VDC voltage supply option
- Absolute
- Bushing or servo mount
- Non-contacting magnetic technology
- Small size
- CMOS and TTL compatible

- Resolution: 1024 positions
- Long life
- High operating speed
- Highly repeatable
- Sealed option
- Magnetic technology

# **EMS22A - Non-Contacting Absolute Encoder**

Electrical Characteristics	
Resolution	
	1,000 megohms
Electrical Travel	
	5.0 VDC ±10 %, 3.3 VDC ±10 %
11,	
Output Voltage	
·	Vdd-0.5 V minimum
Output Current	Turk of the state
	4 mA maximum
11,7	2 mA maximum
,	
Accuracy	0.7.0
	±0.7 ° or bette
	±1.4 °
Output Transition Noise	
<b>Environmental Characteristics</b>	
Pperating Temperature Range	40 °C to +125 °C (-40 °F to +257 °F
	55 °C to +125 °C (-67 °F to +257 °F
	MIL-STD-202, Method 103B, Condition E
•	15 G
	50 G
Rotational Life	
• • • • • • • • • • • • • • • • • • • •	
Mechanical Characteristics	
orque	
Starting	
Running	
· ·	
•	
9	Axial, radial or ribbon cable
Soldering Condition	Axiai, radiai of ribbott cabic
iviariuai Suideririy	
Move Coldering	370 °C (700 °F) max. for 3 seconds
wave soldering	
W. I	260 °C (500 °F) max. for 10 seconds
•	Not recommended
	Manufacturer's trademark, name, part number, and date code
⊣ardwareOne lockwasher and	one mounting nut supplied with each encoder, except on servo mount versions.

#### **Pin Configuration**

Output Type	Pin 1 (DI) (1)	Pin 2 (CLK)	Pin 3	Pin 4 (DO)	Pin 5	Pin 6
Absolute	Digital Input	Clock	GND	Digital Output	VCC (2)	CS

 $<sup>^{(1)}</sup>$  Pin 1 (DI) should be grounded when in a single sensor configuration.

<sup>(2)</sup> Can be 5 or 3.3 VDC depending on the version.



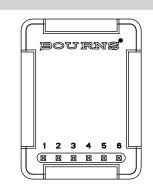
### WARNING Cancer and Reproductive Harm - $\underline{www.P65Warnings.ca.gov}$

\*RoHS Directive 2002/95/EC Jan. 27, 2003 including annex and RoHS Recast 2011/65/EU June 8, 2011.

Specifications are subject to change without notice.
Users should verify actual device performance in their specific applications.

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### **Applications**

- Material handling equipment
- Brushless DC motor commutation
- Robotics
- Automotive
- Industrial automation
- Petroleum refinery

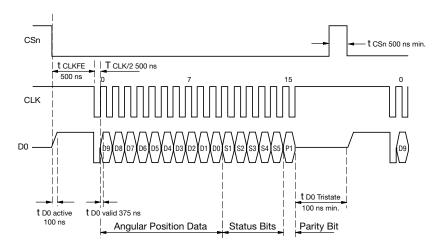
- Medical (low/medium risk)\*
- Office equipment
- Audio and broadcast equipment

## **EMS22A - Non-Contacting Absolute Encoder**

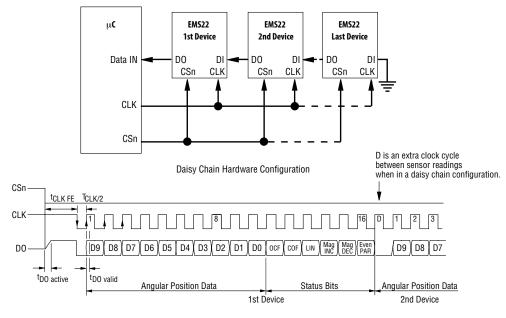
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#### **Output Type Waveform and Variant Table**

#### **Absolute Output**



Data Content	Description	
D9:D0	Absolute angular position data	
S1	End of offset compensation algorithm	
S2	Cordic overflow indicating an error in cordic part	
S3	Linearity alarm	
S4	Increase in magnetic magnitude	
S5	Decrease in magnetic magnitude	
P1	Even parity for detecting bits 1-15 transmission error	



Daisy Chain Mode Data Transfer

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Consult factory for options not shown, including:

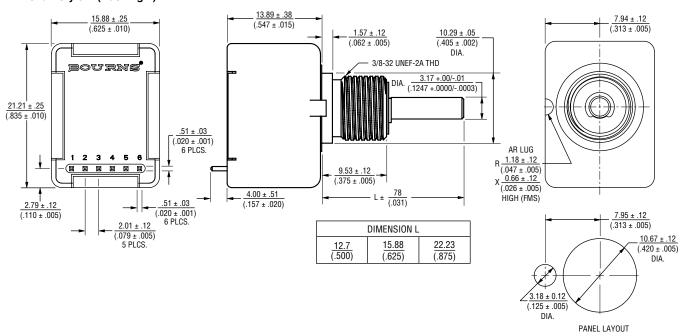
- Wire lead or cable options · Special shaft/bushing sizes and features
- Connectors
- · Special performance characteristics
- · Non-standard resolutions
- · PCB mounting bracket

## **EMS22A - Non-Contacting Absolute Encoder**

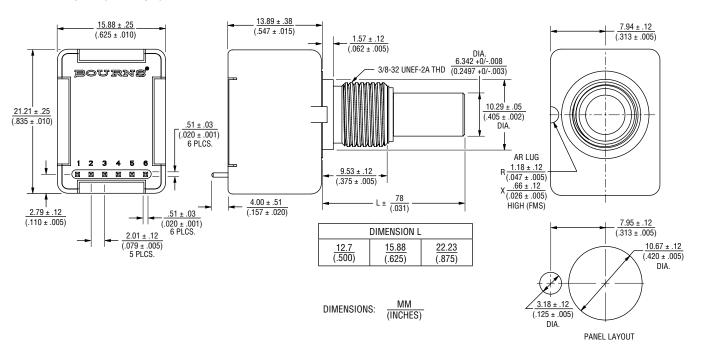
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### **Product Dimensions**

#### Shaft Style D (Bushing T)



### Shaft Style B (Bushing S)



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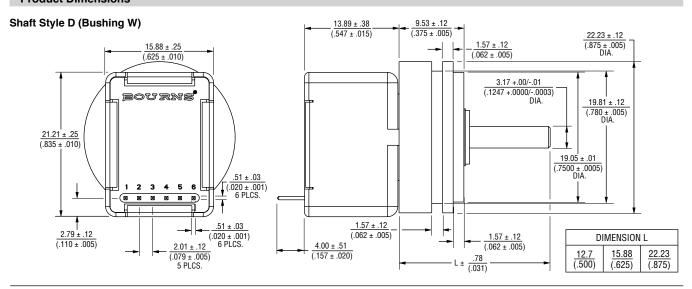
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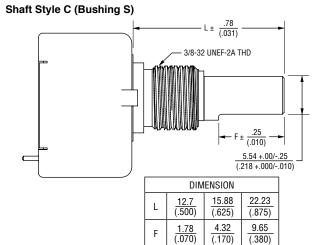
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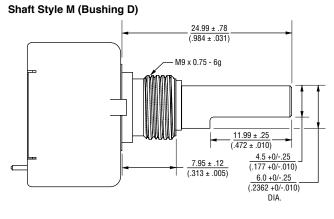
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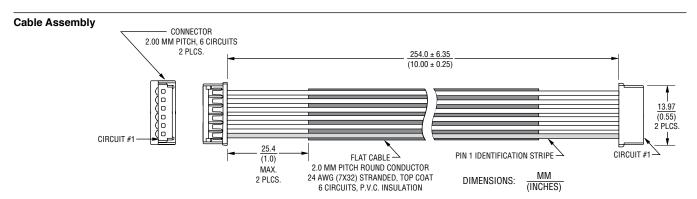
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#### **Product Dimensions**









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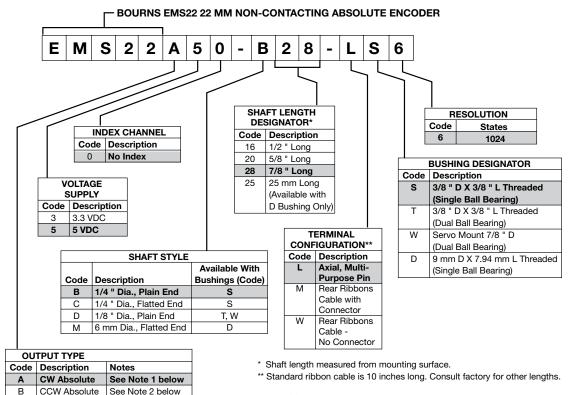
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### **EMS22A - Non-Contacting Absolute Encoder**

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#### **How To Order**



Note 1: (A) positions increase from 0 to 1024 with CW rotation of the shaft. Note 2: (B) positions increase from 0 to 1024 with CCW rotation of the shaft.

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