

## Enhanced Product

## AD8421-EP

### FEATURES

Specified from  $-55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$

0.9  $\mu\text{V}/^{\circ}\text{C}$  maximum input offset voltage drift

5 ppm/ $^{\circ}\text{C}$  maximum gain drift ( $G = 1$ )

Low power

2.3 mA maximum supply current

Low noise

3.2 nV/ $\sqrt{\text{Hz}}$  maximum input voltage noise at 1 kHz

200 fA/ $\sqrt{\text{Hz}}$  current noise at 1 kHz

Excellent ac specifications

2 MHz bandwidth ( $G = 100$ )

0.6  $\mu\text{s}$  settling time to 0.001% ( $G = 10$ )

80 dB minimum CMRR at 20 kHz ( $G = 1$ )

High precision dc performance

84 dB CMRR minimum ( $G = 1$ )

2 nA maximum input bias current

Inputs protected to 40 V from opposite supply

Gain set with a single resistor ( $G = 1$  to 10,000)

### ENHANCED PRODUCT FEATURES

Supports defense and aerospace applications (AQEC standard)

Military temperature range ( $-55^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ )

Controlled manufacturing baseline

One assembly/test site

One fabrication site

Enhanced product change notification

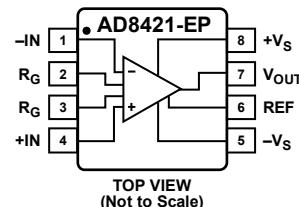
Qualification data available on request

### GENERAL DESCRIPTION

The AD8421-EP is a low cost, low power, extremely low noise, ultralow bias current, high speed instrumentation amplifier that is ideally suited for a broad spectrum of signal conditioning and data acquisition applications. This product features extremely high CMRR, allowing it to extract low level signals in the presence of high frequency common-mode noise over a wide temperature range.

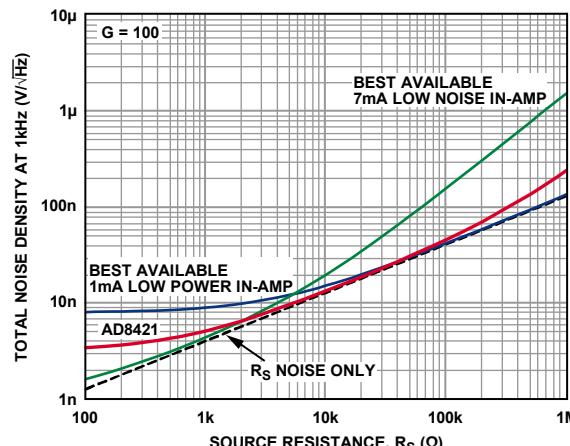
The 10 MHz bandwidth, 35 V/ $\mu\text{s}$  slew rate, and 0.6  $\mu\text{s}$  settling time to 0.001% ( $G = 10$ ) allow the AD8421-EP to amplify high speed signals and excel in applications that require high channel count, multiplexed systems. Even at higher gains, the current feedback architecture maintains high performance; for example, at  $G = 100$ , the bandwidth is 2 MHz and the settling time is 0.8  $\mu\text{s}$ . The AD8421-EP has excellent distortion performance, making it suitable for use in demanding applications such as vibration analysis.

### PIN CONNECTION DIAGRAM



11139-001

Figure 1.



11139-078

Figure 2. Noise Density vs. Source Resistance

The AD8421-EP delivers 3 nV/ $\sqrt{\text{Hz}}$  input voltage noise and 200 fA/ $\sqrt{\text{Hz}}$  current noise with only 2 mA quiescent current, making it an ideal choice for measuring low level signals. For applications with high source impedance, the AD8421-EP employs innovative process technology and design techniques to provide noise performance that is limited only by the sensor.

The AD8421-EP uses unique protection methods to ensure robust inputs while still maintaining very low noise. This protection allows input voltages up to 40 V from the opposite supply rail without damage to the part.

A single resistor sets the gain from 1 to 10,000. The reference pin can be used to apply a precise offset to the output voltage.

The AD8421-EP is specified over the military temperature range of  $-55^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ . It is available in an 8-lead MSOP package.

Additional application and technical information can be found in the AD8421 data sheet.

Rev. 0

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Document Feedback

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## REVISION HISTORY

5/13—Revision 0: Initial Version

## SPECIFICATIONS

$V_S = \pm 15$  V,  $V_{REF} = 0$  V,  $T_A = 25^\circ\text{C}$ ,  $G = 1$ ,  $R_L = 2$  k $\Omega$ , unless otherwise noted.

Table 1.

Parameter	Test Conditions/ Comments	Min	Typ	Max	Unit
COMMON-MODE REJECTION RATIO (CMRR)					
CMRR DC to 60 Hz with 1 k $\Omega$ Source Imbalance	$V_{CM} = -10$ V to +10 V	84			dB
G = 1		104			dB
G = 10		124			dB
G = 100		134			dB
G = 1000					dB
Over Temperature, G = 1	$T_A = -55^\circ\text{C}$ to +125°C	80			dB
CMRR at 20 kHz	$V_{CM} = -10$ V to +10 V	80			dB
G = 1		90			dB
G = 10		100			dB
G = 100		100			dB
G = 1000					dB
NOISE					
Voltage Noise, 1 kHz <sup>1</sup>	$V_{IN+}, V_{IN-} = 0$ V		3	3.2	nV/ $\sqrt{\text{Hz}}$
Input Voltage Noise, $e_{ni}$				60	nV/ $\sqrt{\text{Hz}}$
Output Voltage Noise, $e_{no}$					
Peak to Peak, RTI	$f = 0.1$ Hz to 10 Hz	2			$\mu\text{V p-p}$
G = 1		0.5			$\mu\text{V p-p}$
G = 10		0.07			$\mu\text{V p-p}$
G = 100 to 1000					
Current Noise					
Spectral Density	$f = 1$ kHz	200			fA/ $\sqrt{\text{Hz}}$
Peak to Peak, RTI	$f = 0.1$ Hz to 10 Hz	18			pA p-p
VOLTAGE OFFSET <sup>2</sup>					
Input Offset Voltage, $V_{OSI}$	$V_S = \pm 5$ V to $\pm 15$ V		70		$\mu\text{V}$
Over Temperature	$T_A = -55^\circ\text{C}$ to +125°C		160		$\mu\text{V}$
Average TC			0.9		$\mu\text{V}/^\circ\text{C}$
Output Offset Voltage, $V_{OSO}$			600		$\mu\text{V}$
Over Temperature	$T_A = -55^\circ\text{C}$ to +125°C		1.5		mV
Average TC			9		$\mu\text{V}/^\circ\text{C}$
Offset RTI vs. Supply (PSR)	$V_S = \pm 2.5$ V to $\pm 18$ V				
G = 1		90	120		dB
G = 10		110	120		dB
G = 100		124	130		dB
G = 1000		130	140		dB
INPUT CURRENT					
Input Bias Current		1	2		nA
Over Temperature	$T_A = -55^\circ\text{C}$ to +125°C		8		nA
Average TC		50			pA/ $^\circ\text{C}$
Input Offset Current		0.5	2		nA
Over Temperature	$T_A = -55^\circ\text{C}$ to +125°C		3		nA
Average TC		1			pA/ $^\circ\text{C}$

Parameter	Test Conditions/ Comments	Min	Typ	Max	Unit
DYNAMIC RESPONSE					
Small Signal Bandwidth	–3 dB				
G = 1		10			MHz
G = 10		10			MHz
G = 100		2			MHz
G = 1000		0.2			MHz
Settling Time 0.01%	10 V step				
G = 1		0.7			μs
G = 10		0.4			μs
G = 100		0.6			μs
G = 1000		5			μs
Settling Time 0.001%	10 V step				
G = 1		1			μs
G = 10		0.6			μs
G = 100		0.8			μs
G = 1000		6			μs
Slew Rate					
G = 1 to 100		35			V/μs
GAIN <sup>3</sup>	G = 1 + (9.9 kΩ/R <sub>G</sub> )				
Gain Range		1		10,000	V/V
Gain Error	V <sub>OUT</sub> = ±10 V				
G = 1			0.05		%
G = 10 to 1000			0.3		%
Gain Nonlinearity	V <sub>OUT</sub> = –10 V to +10 V				
G = 1	R <sub>L</sub> ≥ 2 kΩ			1	ppm
	R <sub>L</sub> = 600 Ω		1	3	ppm
G = 10 to 1000	R <sub>L</sub> ≥ 600 Ω	30	50		ppm
	V <sub>OUT</sub> = –5 V to +5 V	5	10		ppm
Gain vs. Temperature <sup>3</sup>					
G = 1			5		ppm/°C
G > 1			–80		ppm/°C
INPUT					
Input Impedance					
Differential		30  3			GΩ  pF
Common Mode		30  3			GΩ  pF
Input Operating Voltage Range <sup>4</sup>	V <sub>S</sub> = ±2.5 V to ±18 V	–V <sub>S</sub> + 2.3		+V <sub>S</sub> – 1.8	V
Over Temperature	T <sub>A</sub> = –55°C	–V <sub>S</sub> + 2.5		+V <sub>S</sub> – 2.0	V
	T <sub>A</sub> = +125°C	–V <sub>S</sub> + 2.1		+V <sub>S</sub> – 1.8	V
OUTPUT	R <sub>L</sub> = 2 kΩ				
Output Swing	V <sub>S</sub> = ±2.5 V to ±18 V	–V <sub>S</sub> + 1.2		+V <sub>S</sub> – 1.7	V
Over Temperature	T <sub>A</sub> = –55°C to +125°C	–V <sub>S</sub> + 1.4		+V <sub>S</sub> – 1.9	V
Short-Circuit Current			65		mA
REFERENCE INPUT					
R <sub>IN</sub>		20			kΩ
I <sub>IN</sub>		20	24		μA
Voltage Range	V <sub>IN+</sub> , V <sub>IN–</sub> = 0 V	–V <sub>S</sub>		+V <sub>S</sub>	V
Reference Gain to Output			1 ± 0.0001		V/V

Parameter	Test Conditions/ Comments	Min	Typ	Max	Unit
POWER SUPPLY					
Operating Range	Dual supply Single supply	$\pm 2.5$ 5	$\pm 18$ 36 2	2.3 2.8	V V mA
Quiescent Current Over Temperature	$T_A = -55^{\circ}\text{C}$ to $+125^{\circ}\text{C}$				mA
TEMPERATURE RANGE					
For Specified Performance		-55	+125		$^{\circ}\text{C}$

<sup>1</sup> Total voltage noise =  $\sqrt{(e_{\text{n}})^2 + (e_{\text{no}}/G)^2 + e_{\text{RG}}^2}$ . See the AD8421 data sheet for more information.

<sup>2</sup> Total RTI  $V_{\text{OS}} = (V_{\text{OSI}}) + (V_{\text{OSO}}/G)$ .

<sup>3</sup> These specifications do not include the tolerance of the external gain setting resistor,  $R_G$ . For  $G > 1$ , add  $R_G$  errors to the specifications given in this table.

<sup>4</sup> Input voltage range of the AD8421-EP input stage only. The input range can depend on the common-mode voltage, differential voltage, gain, and reference voltage. See the Typical Performance Characteristics section for more information.

## ABSOLUTE MAXIMUM RATINGS

Table 2.

Parameter	Rating
Supply Voltage	$\pm 18\text{ V}$
Output Short-Circuit Current Duration	Indefinite
Maximum Voltage at $-\text{IN}$ or $+\text{IN}^1$	$-\text{V}_S + 40\text{ V}$
Minimum Voltage at $-\text{IN}$ or $+\text{IN}$	$+\text{V}_S - 40\text{ V}$
Maximum Voltage at REF <sup>2</sup>	$+\text{V}_S + 0.3\text{ V}$
Minimum Voltage at REF	$-\text{V}_S - 0.3\text{ V}$
Storage Temperature Range	$-65^\circ\text{C}$ to $+150^\circ\text{C}$
Operating Temperature Range	$-55^\circ\text{C}$ to $+125^\circ\text{C}$
Maximum Junction Temperature	$150^\circ\text{C}$
ESD	
Human Body Model	2 kV
Charged Device Model	1.25 kV
Machine Model	0.2 kV

<sup>1</sup> For voltages beyond these limits, use input protection resistors. See the AD8421 data sheet for more information.

<sup>2</sup> There are ESD protection diodes from the reference input to each supply, so REF cannot be driven beyond the supplies in the same way that  $+\text{IN}$  and  $-\text{IN}$  can. See the AD8421 data sheet for more information.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## THERMAL RESISTANCE

$\theta_{JA}$  is specified for a device in free air using a 4-layer JEDEC printed circuit board (PCB).

Table 3.

Package	$\theta_{JA}$	Unit
8-Lead MSOP	138.6	$^\circ\text{C}/\text{W}$

## ESD CAUTION



### ESD (electrostatic discharge) sensitive device.

Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

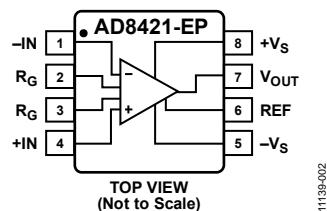


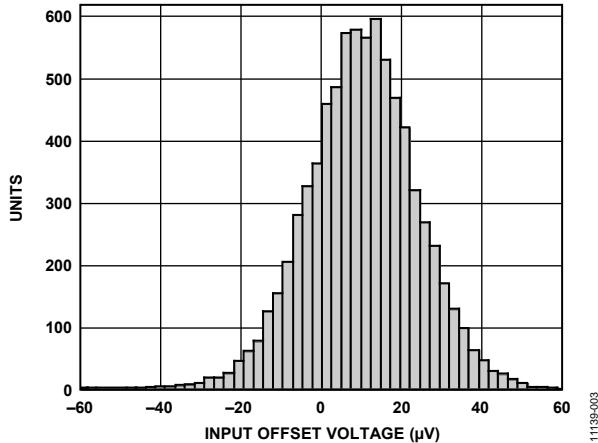
Figure 3. Pin Configuration

Table 4. Pin Function Descriptions

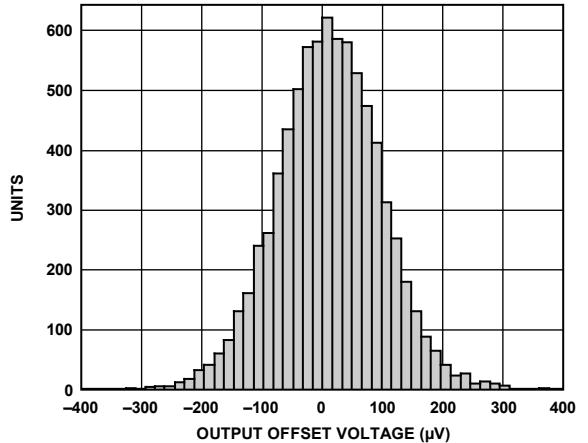
Pin No.	Mnemonic	Description
1	-IN	Negative Input Terminal.
2, 3	R <sub>G</sub>	Gain Setting Terminals. Place resistor across the R <sub>G</sub> pins to set the gain. G = 1 + (9.9 kΩ/R <sub>G</sub> ).
4	+IN	Positive Input Terminal.
5	-V <sub>S</sub>	Negative Power Supply Terminal.
6	REF	Reference Voltage Terminal. Drive this terminal with a low impedance voltage source to level shift the output.
7	V <sub>OUT</sub>	Output Terminal.
8	+V <sub>S</sub>	Positive Power Supply Terminal.

## TYPICAL PERFORMANCE CHARACTERISTICS

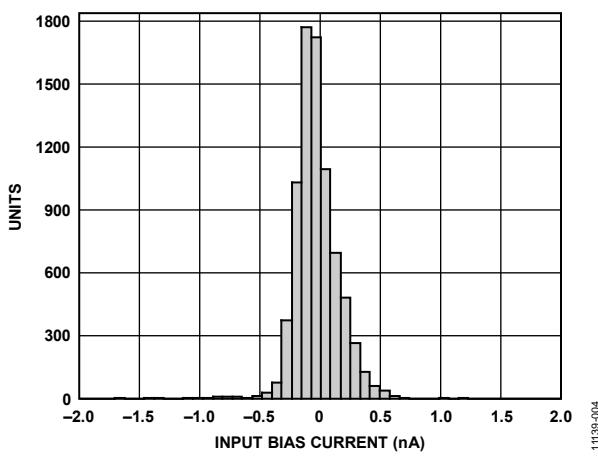
$T_A = 25^\circ\text{C}$ ,  $V_S = \pm 15 \text{ V}$ ,  $V_{\text{REF}} = 0 \text{ V}$ ,  $R_L = 2 \text{ k}\Omega$ , unless otherwise noted.



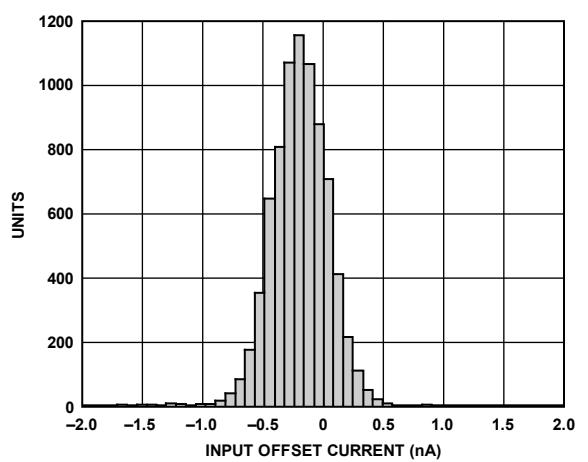
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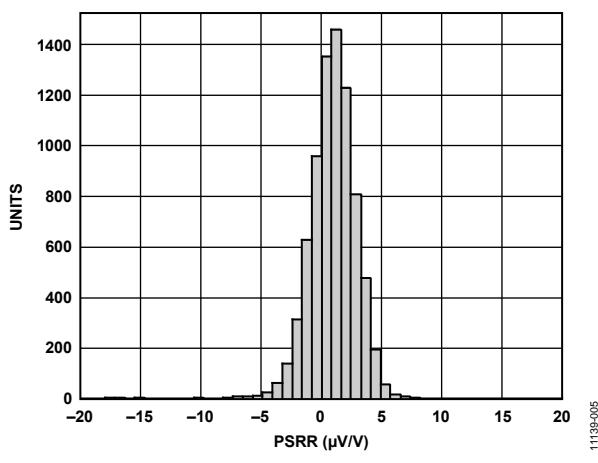
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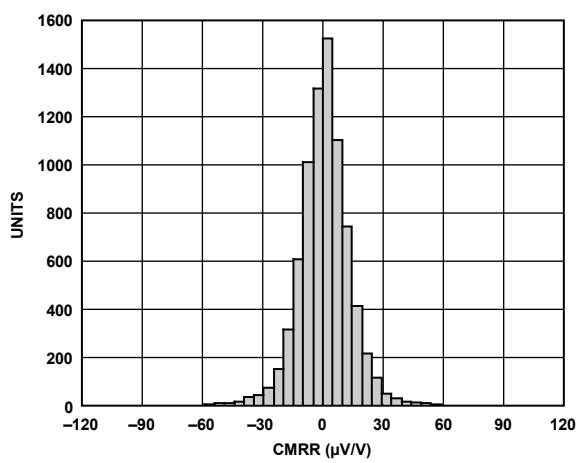
11139-004



11139-007



11139-005



11139-008

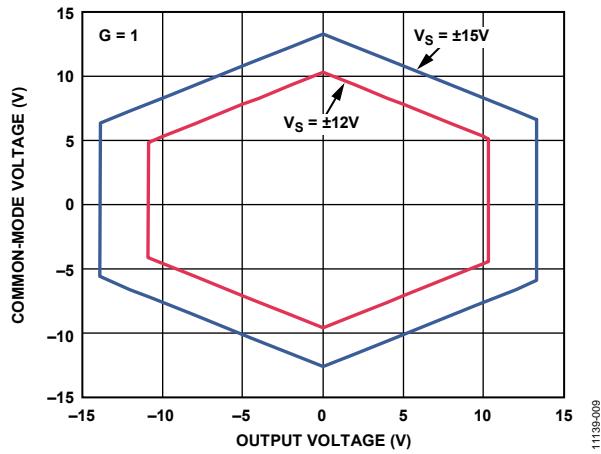


Figure 10. Input Common-Mode Voltage vs. Output Voltage;  
 $V_S = \pm 12\text{ V}$  and  $\pm 15\text{ V}$  ( $G = 1$ )

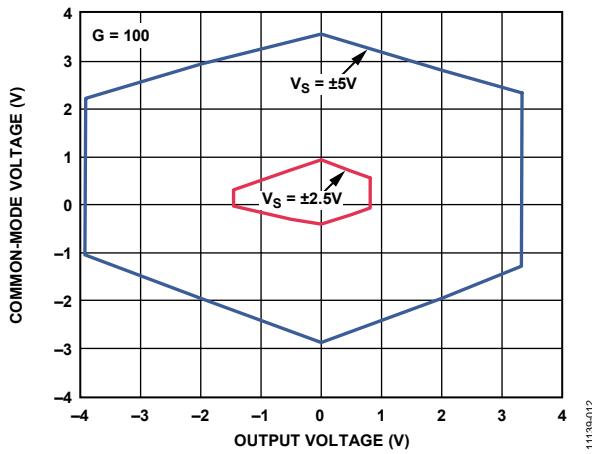


Figure 13. Input Common-Mode Voltage vs. Output Voltage;  
 $V_S = \pm 2.5\text{ V}$  and  $\pm 5\text{ V}$  ( $G = 100$ )

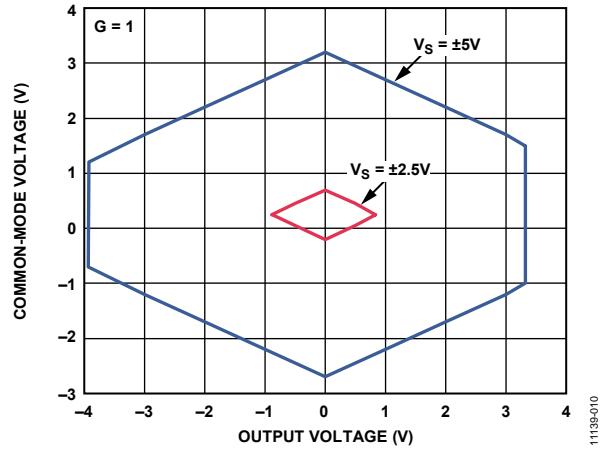


Figure 11. Input Common-Mode Voltage vs. Output Voltage;  
 $V_S = \pm 2.5\text{ V}$  and  $\pm 5\text{ V}$  ( $G = 1$ )

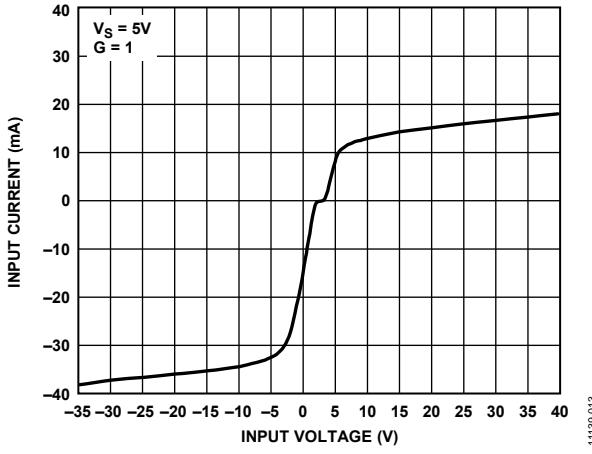


Figure 14. Input Overvoltage Performance;  $G = 1$ ,  $+V_S = 5\text{ V}$ ,  $-V_S = 0\text{ V}$

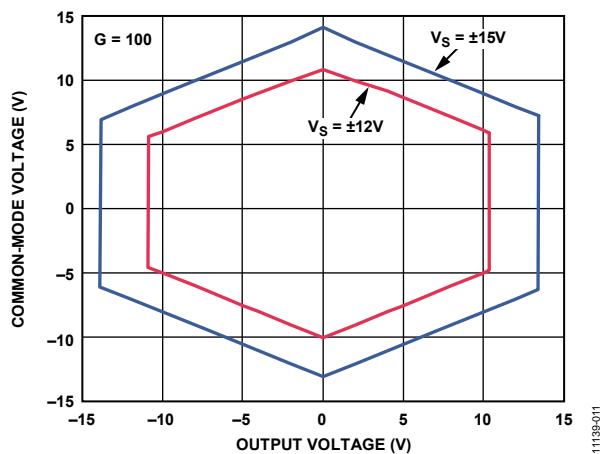


Figure 12. Input Common-Mode Voltage vs. Output Voltage;  
 $V_S = \pm 12\text{ V}$  and  $\pm 15\text{ V}$  ( $G = 100$ )

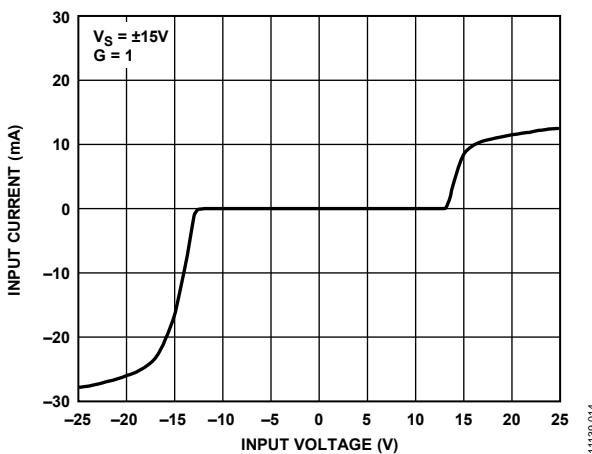


Figure 15. Input Overvoltage Performance;  $G = 1$ ,  $V_S = \pm 15\text{ V}$

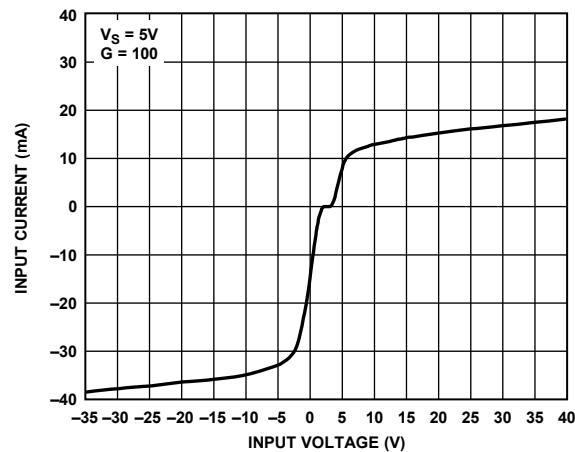
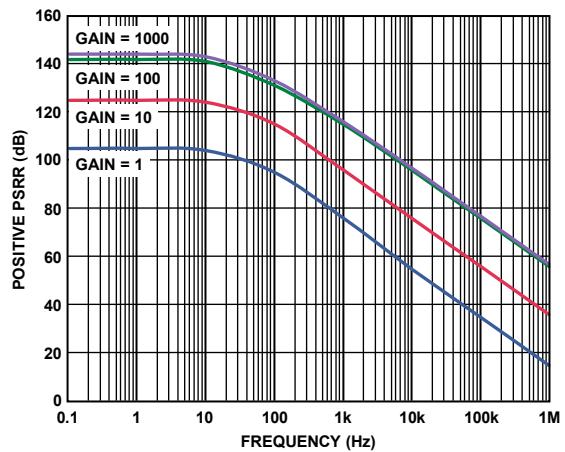
Figure 16. Input Overvoltage Performance;  $+V_S = 5\text{ V}$ ,  $-V_S = 0\text{ V}$ ,  $G = 100$ 

Figure 19. Positive PSRR vs. Frequency

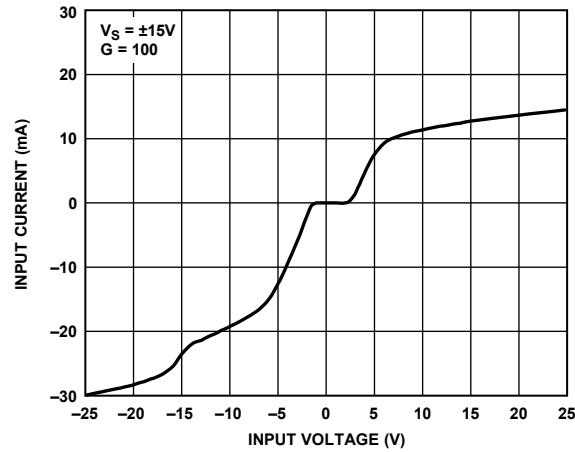
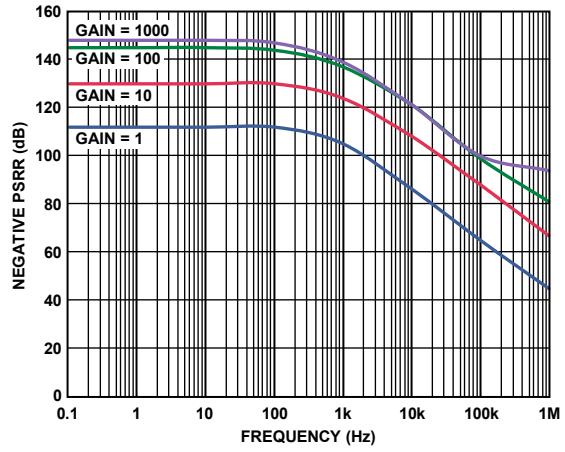
Figure 17. Input Overvoltage Performance;  $V_S = \pm 15\text{ V}$ ,  $G = 100$ 

Figure 20. Negative PSRR vs. Frequency

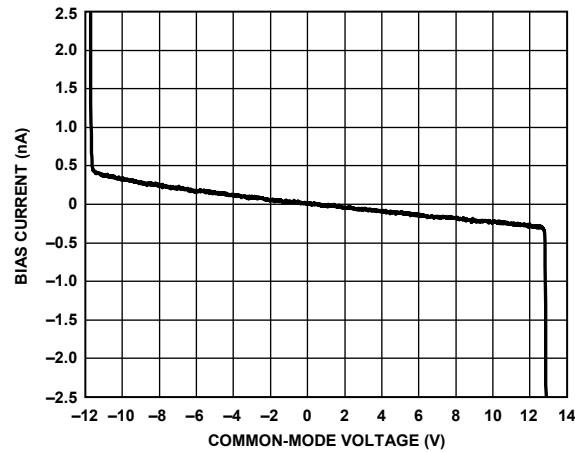


Figure 18. Input Bias Current vs. Common-Mode Voltage

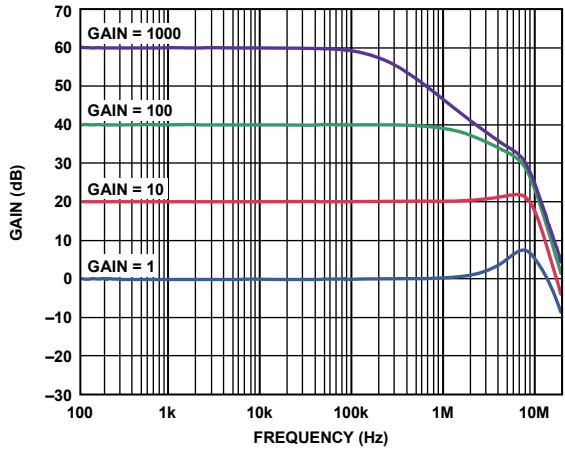


Figure 21. Gain vs. Frequency

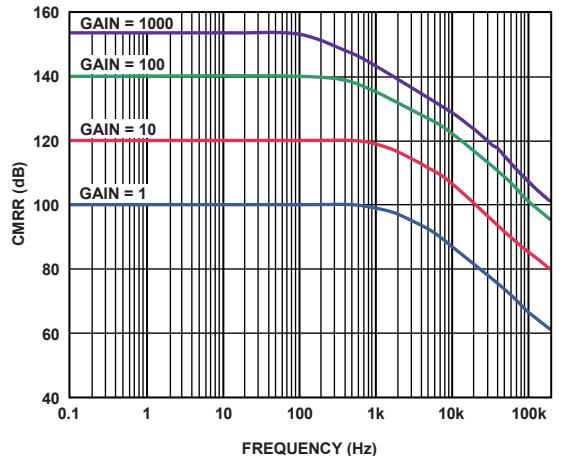


Figure 22. CMRR vs. Frequency

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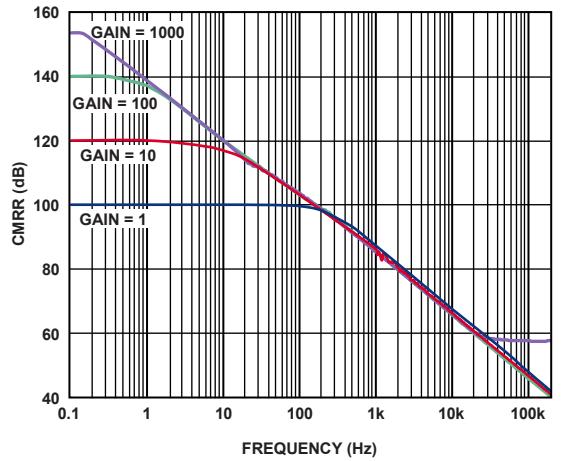
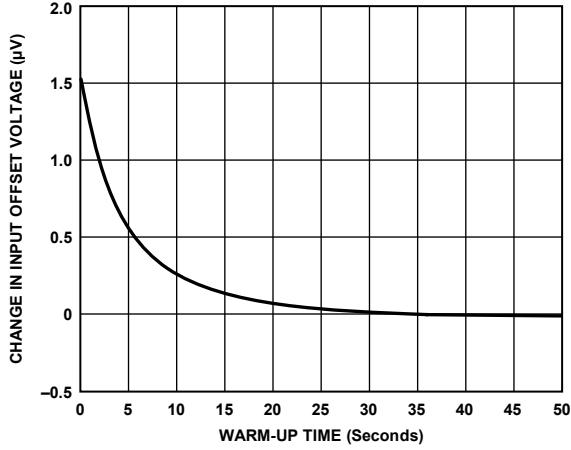


Figure 23. CMRR vs. Frequency, 1 kΩ Source Imbalance

11139-022

Figure 24. Change in Input Offset Voltage ( $V_{os}$ ) vs. Warm-Up Time

11139-123

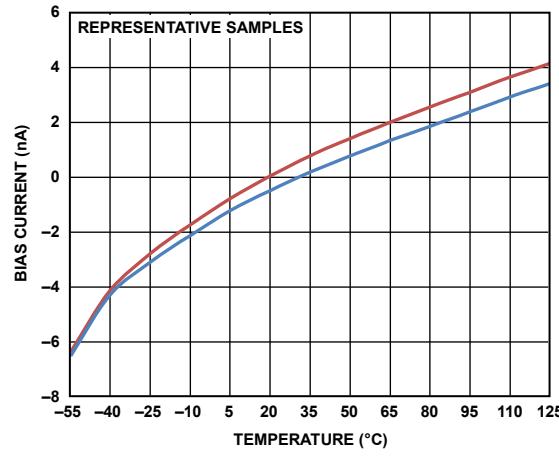
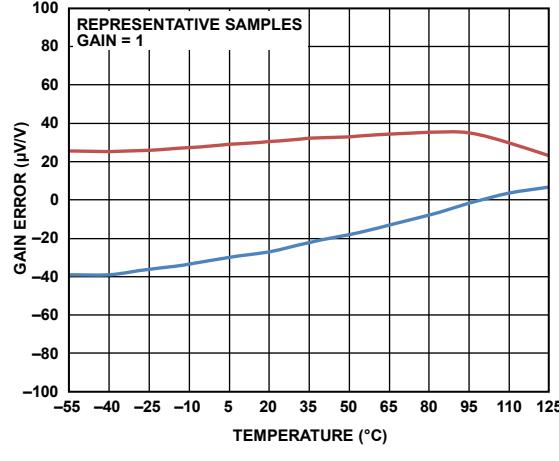
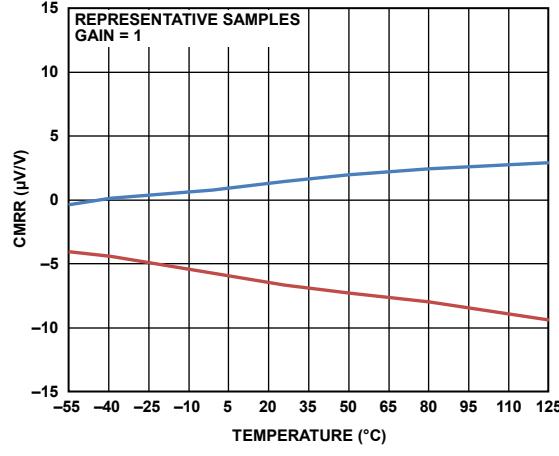


Figure 25. Input Bias Current vs. Temperature

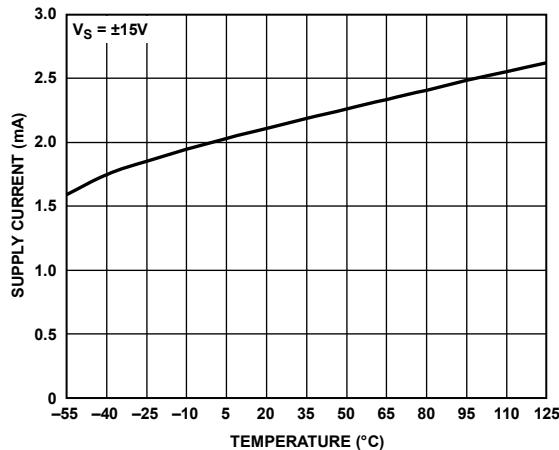
11139-125

Figure 26. Gain vs. Temperature ( $G = 1$ )

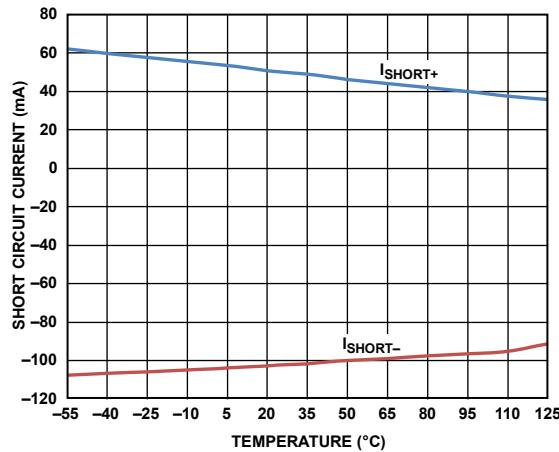
11139-126

Figure 27. CMRR vs. Temperature ( $G = 1$ )

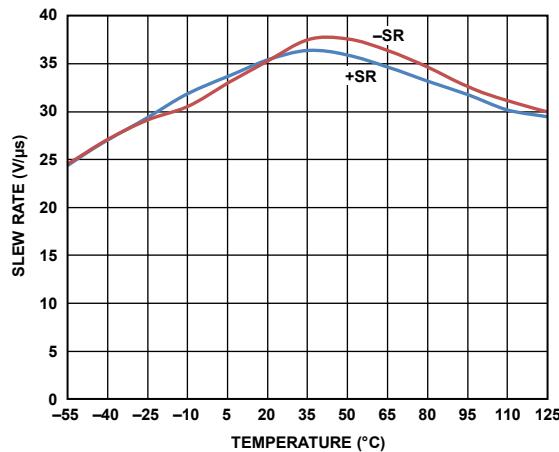
11139-127

Figure 28. Supply Current vs. Temperature ( $G = 1$ )

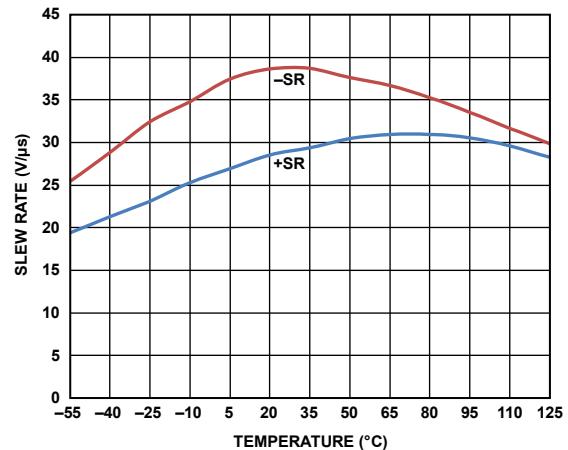
11139-128

Figure 29. Short-Circuit Current vs. Temperature ( $G = 1$ )

11139-129

Figure 30. Slew Rate vs. Temperature,  $V_S = \pm 15 V$  ( $G = 1$ )

11139-130

Figure 31. Slew Rate vs. Temperature,  $V_S = \pm 5 V$  ( $G = 1$ )

11139-131

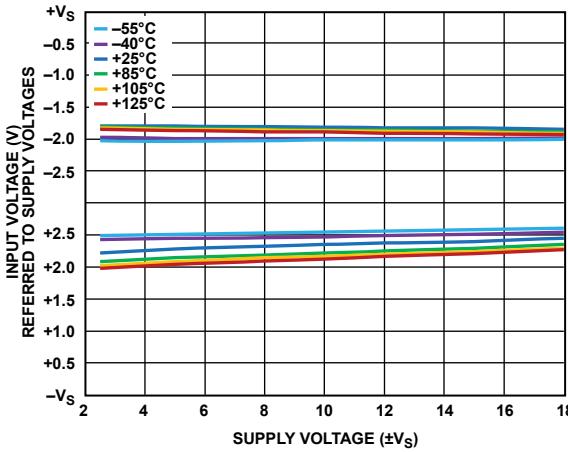


Figure 32. Input Voltage Limit vs. Supply Voltage

11139-132

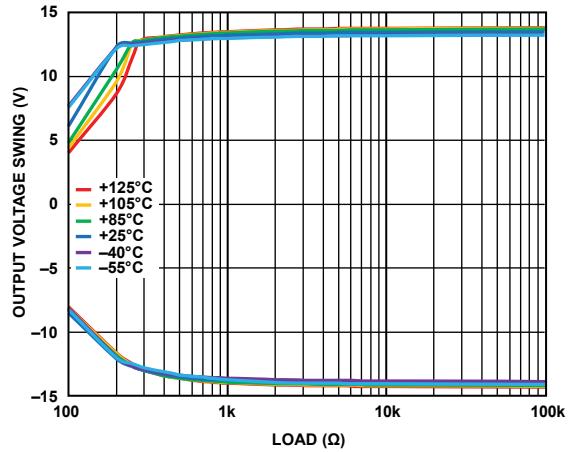


Figure 33. Output Voltage Swing vs. Load Resistance

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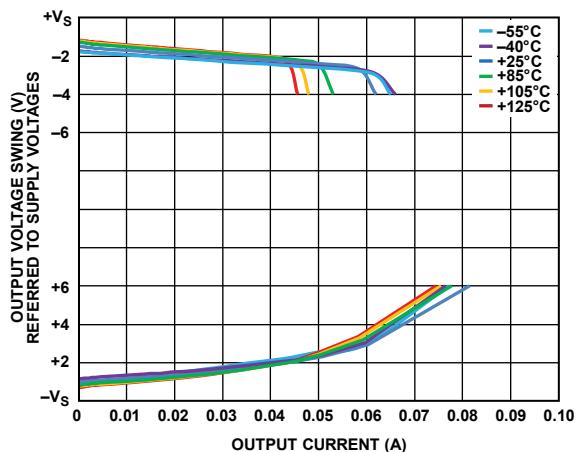


Figure 34. Output Voltage Swing vs. Output Current

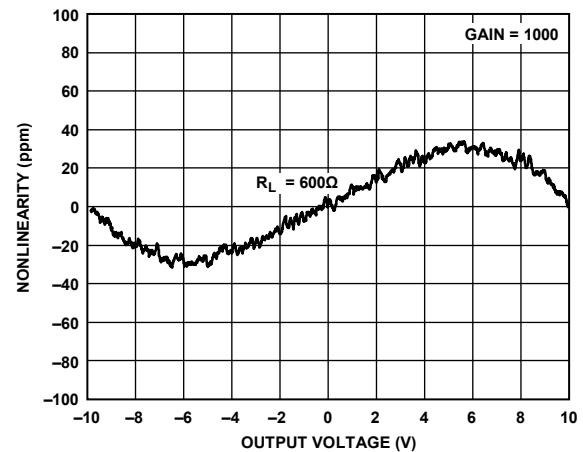
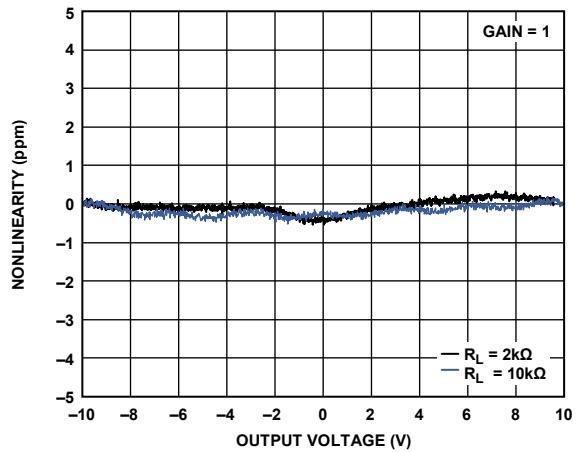
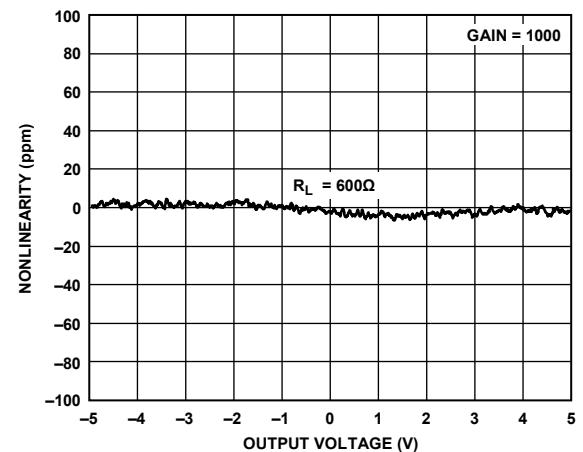
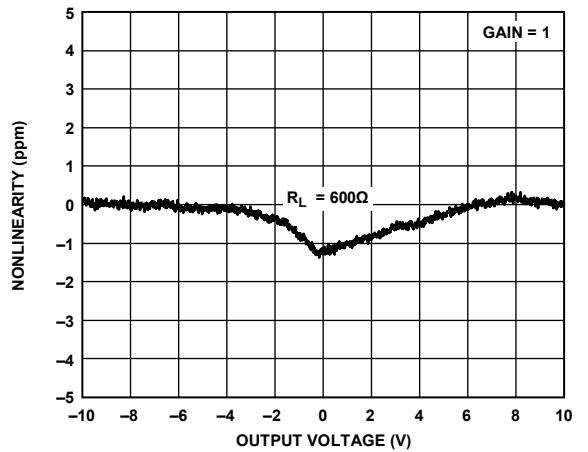
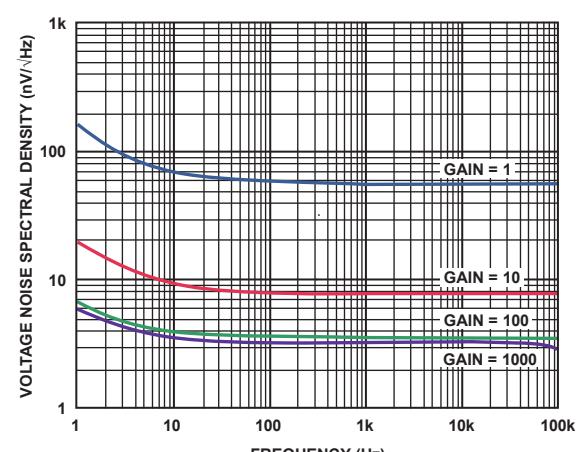
Figure 37. Gain Nonlinearity ( $G = 1000$ ),  $R_L = 600\Omega$ ,  $V_{OUT} = \pm 10\text{ V}$ Figure 35. Gain Nonlinearity ( $G = 1$ ),  $R_L = 10\text{k}\Omega$ ,  $2\text{k}\Omega$ Figure 38. Gain Nonlinearity ( $G = 1000$ ),  $R_L = 600\Omega$ ,  $V_{OUT} = \pm 5\text{ V}$ Figure 36. Gain Nonlinearity ( $G = 1$ ),  $R_L = 600\Omega$ 

Figure 39. RTI Voltage Noise Spectral Density vs. Frequency

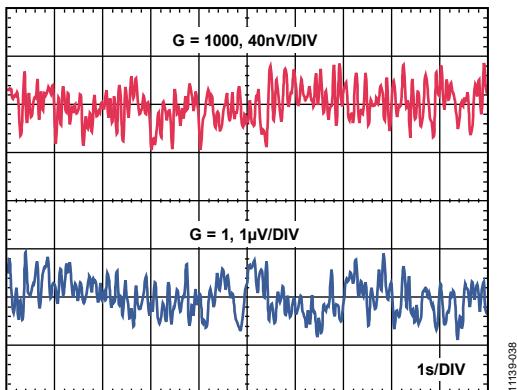
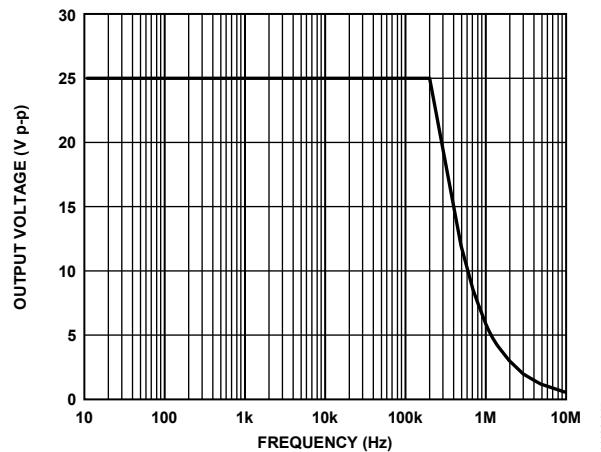
Figure 40. 0.1 Hz to 10 Hz RTI Voltage Noise ( $G = 1$ ,  $G = 1000$ )

Figure 43. Large Signal Frequency Response

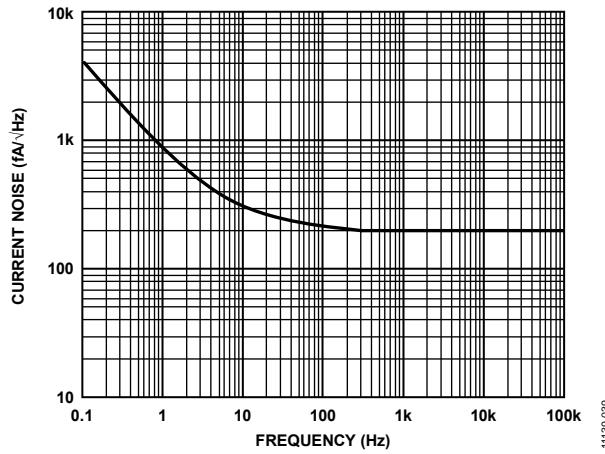


Figure 41. Current Noise Spectral Density vs. Frequency

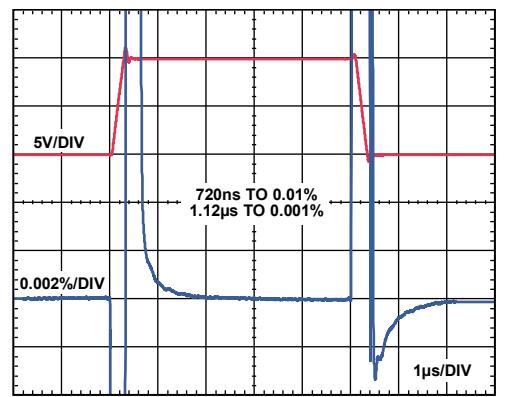
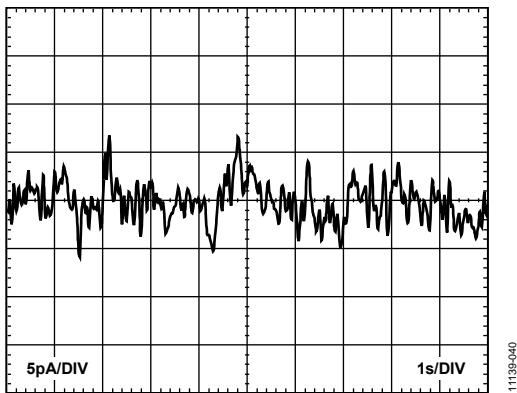
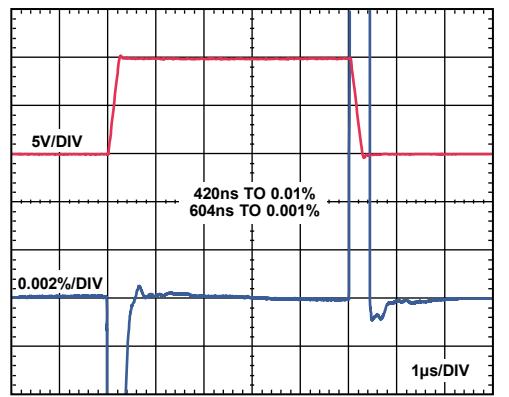
Figure 44. Large Signal Pulse Response and Settling Time ( $G = 1$ ),  
10 V Step,  $V_S = \pm 15$  V,  $R_L = 2$  kΩ,  $C_L = 100$  pF

Figure 42. 0.1 Hz to 10 Hz Current Noise

Figure 45. Large Signal Pulse Response and Settling Time ( $G = 10$ ),  
10 V Step,  $V_S = \pm 15$  V,  $R_L = 2$  kΩ,  $C_L = 100$  pF

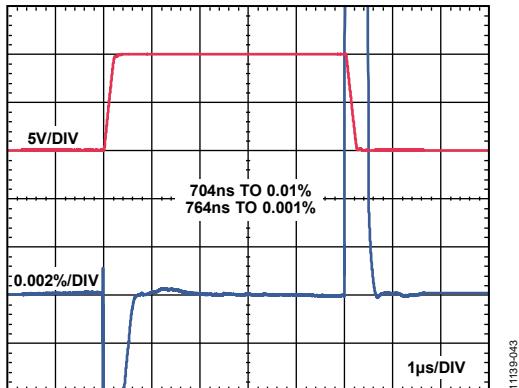


Figure 46. Large Signal Pulse Response and Settling Time ( $G = 100$ ),  
10 V Step,  $V_S = \pm 15 V$ ,  $R_L = 2 k\Omega$ ,  $C_L = 100 pF$

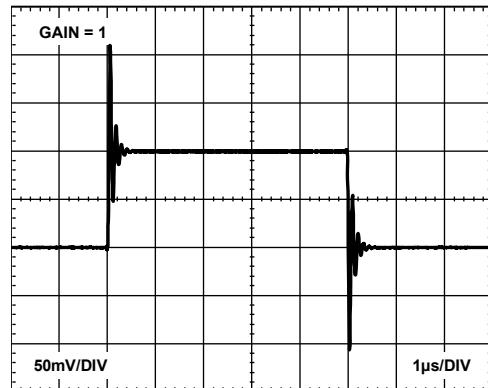


Figure 49. Small Signal Pulse Response ( $G = 1$ ),  $R_L = 600 \Omega$ ,  $C_L = 100 pF$

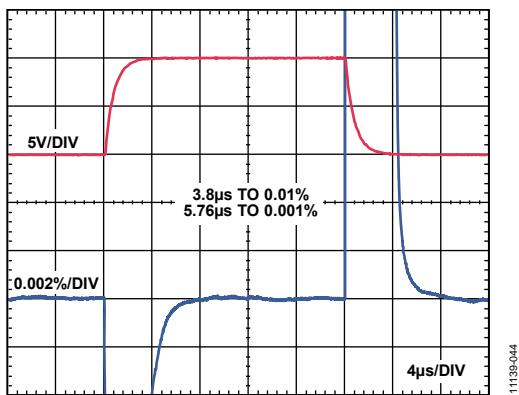


Figure 47. Large Signal Pulse Response and Settling Time ( $G = 1000$ ),  
10 V Step,  $V_S = \pm 15 V$ ,  $R_L = 2 k\Omega$ ,  $C_L = 100 pF$

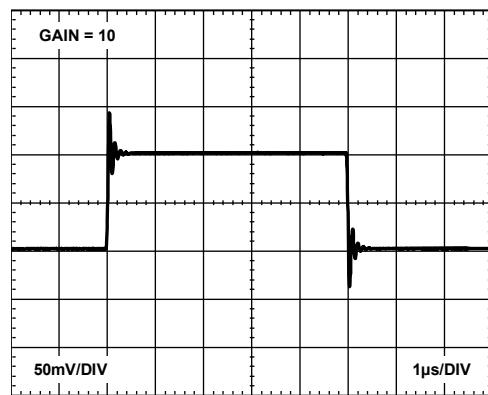


Figure 50. Small Signal Pulse Response ( $G = 10$ ),  $R_L = 600 \Omega$ ,  $C_L = 100 pF$

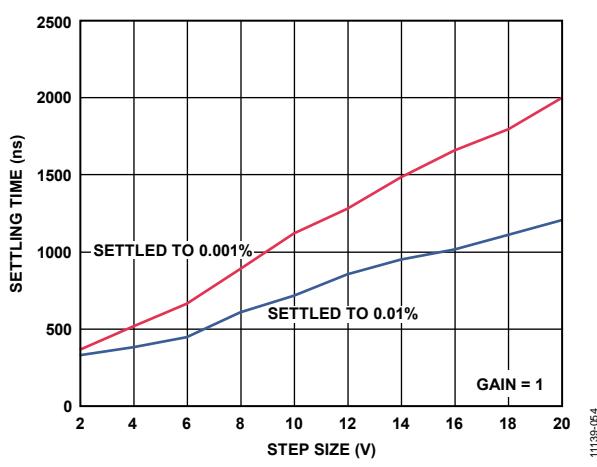


Figure 48. Settling Time vs. Step Size ( $G = 1$ ),  $R_L = 2 k\Omega$ ,  $C_L = 100 pF$

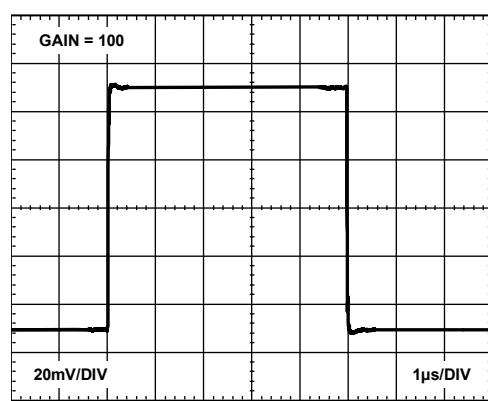


Figure 51. Small Signal Pulse Response ( $G = 100$ ),  $R_L = 600 \Omega$ ,  $C_L = 100 pF$

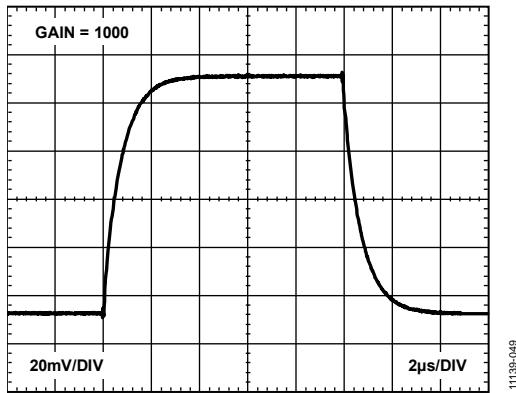


Figure 52. Small Signal Pulse Response ( $G = 1000$ ),  $R_L = 600\Omega$ ,  $C_L = 100\text{ pF}$

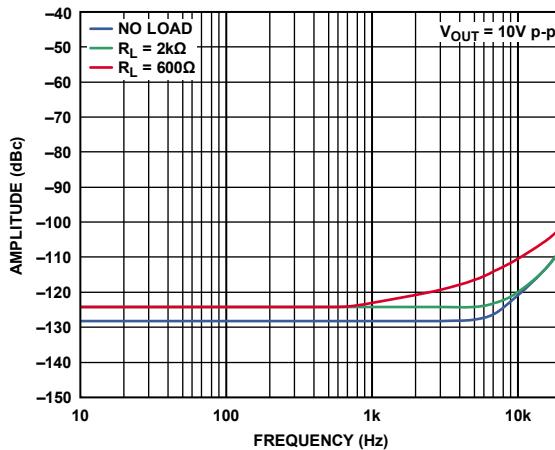


Figure 55. Third Harmonic Distortion vs. Frequency ( $G = 1$ )

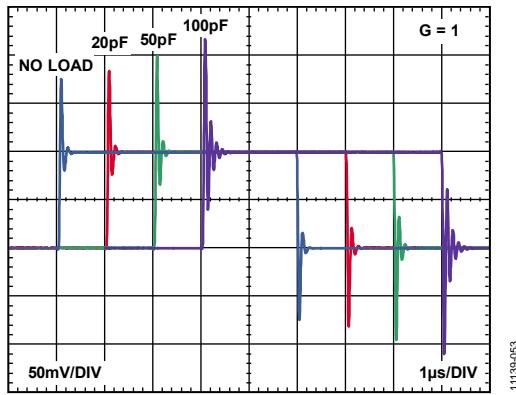


Figure 53. Small Signal Response with Various Capacitive Loads ( $G = 1$ ),  
 $R_L = \text{Infinity}$

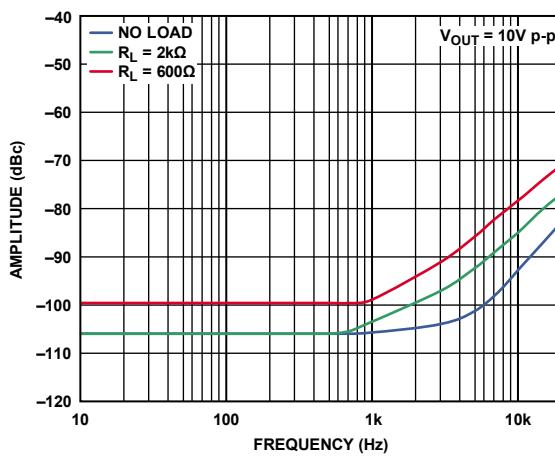


Figure 56. Second Harmonic Distortion vs. Frequency ( $G = 1000$ )

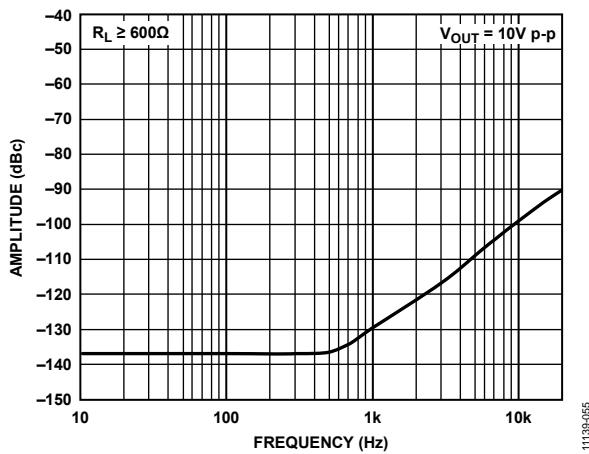


Figure 54. Second Harmonic Distortion vs. Frequency ( $G = 1$ )

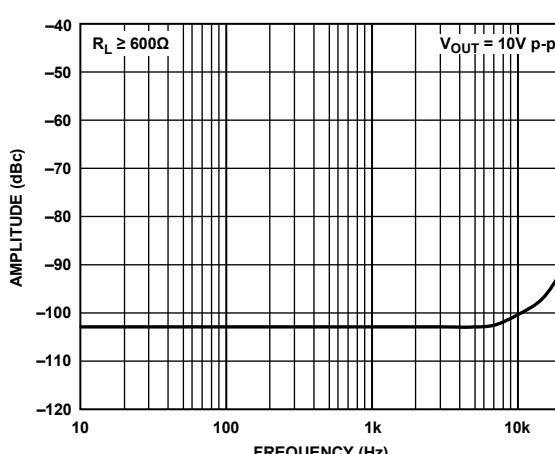


Figure 57. Third Harmonic Distortion vs. Frequency ( $G = 1000$ )

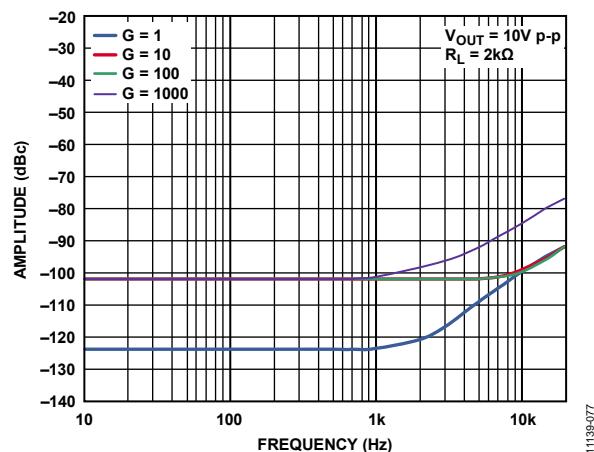
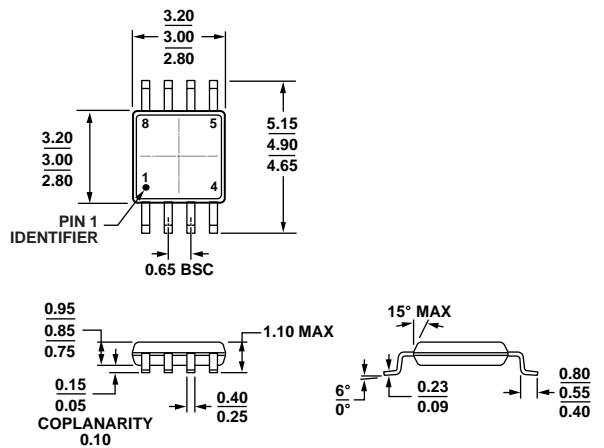


Figure 58. THD vs. Frequency

11139-077

## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-187-AA

Figure 59. 8-Lead Mini Small Outline Package [MSOP]  
(RM-8)

Dimensions shown in millimeters

10-07-2009-B

## ORDERING GUIDE

Model <sup>1</sup>	Temperature Range	Package Description	Package Option	Branding
AD8421TRMZ-EP	-55°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	Y4T
AD8421TRMZ-EP-R7	-55°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	Y4T

<sup>1</sup> Z = RoHS Compliant Part.

## NOTES

## **NOTES**

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D11139-0-5/12(0)



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