

Please note that Cypress is an Infineon Technologies Company.

The document following this cover page is marked as "Cypress" document as this is the company that originally developed the product. Please note that Infineon will continue to offer the product to new and existing customers as part of the Infineon product portfolio.

Continuity of document content

The fact that Infineon offers the following product as part of the Infineon product portfolio does not lead to any changes to this document. Future revisions will occur when appropriate, and any changes will be set out on the document history page.

Continuity of ordering part numbers

Infineon continues to support existing part numbers. Please continue to use the ordering part numbers listed in the datasheet for ordering.

www.infineon.com



4-Mbit (256K × 16) F-RAM

Features

- 4-Mbit ferroelectric random access memory (F-RAM) logically organized as 256K × 16
 - □ Configurable as 512K × 8 using UB and LB
 - ☐ High-endurance 100 trillion (10¹⁴) read/writes
 - □ 151-year data retention (see Data Retention and Endurance on page 10)
 - □ NoDelay™ writes
 - ☐ Page mode operation to 25 ns cycle time
 - □ Advanced high-reliability ferroelectric process
- SRAM compatible
 - □ Industry-standard 256K × 16 SRAM pinout
 - □ 55 ns access time, 110 ns cycle time
- Advanced features
 - □ Software-programmable block write-protect
- Superior to battery-backed SRAM modules
 - □ No battery concerns
 - Monolithic reliability
 - ☐ True surface mount solution, no rework steps
 - □ Superior for moisture, shock, and vibration
- Low power consumption
 - □ Active current 8 mA (typ)
 - Standby current 90 μA (typ)
- Low-voltage operation: V_{DD} = 2.7 V to 3.6 V
- Industrial temperature: -40 °C to +85 °C
- 48-ball fine-pitch ball grid array (FBGA) package
- Restriction of hazardous substances (RoHS) compliant

Functional Description

The FM22LD16 is a 256K × 16 nonvolatile memory that reads and writes similar to a standard SRAM. A ferroelectric random access memory or F-RAM is nonvolatile, which means that data is retained after power is removed. It provides data retention for over 151 years while eliminating the reliability concerns, functional disadvantages, and system design complexities of battery-backed SRAM (BBSRAM). Fast write timing and high write endurance make the F-RAM superior to other types of memory.

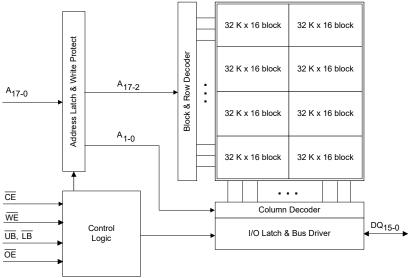
The FM22LD16 operation is similar to that of other RAM devices and therefore, it can be used as a drop-in replacement for a standard SRAM in a system. Read and write cycles may be triggered by $\overline{\text{CE}}$ or simply by changing the address. The F-RAM memory is nonvolatile due to its unique ferroelectric memory process. These features make the FM22LD16 ideal for nonvolatile memory applications requiring frequent or rapid writes.

The FM22LD16 includes a low voltage monitor that blocks access to the memory array when V_{DD} drops below V_{DD} min. The memory is protected against an inadvertent access and data corruption under this condition. The device also features software-controlled write protection. The memory array is divided into 8 uniform blocks, each of which can be individually write protected.

The device is available in a 48-ball FBGA package. Device specifications are guaranteed over the industrial temperature range $-40~^{\circ}\text{C}$ to +85 $^{\circ}\text{C}$.

For a complete list of related documentation, click here.







Contents

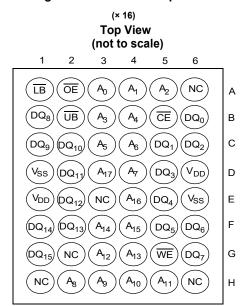
Pinout	3
Pin Definitions	3
Device Operation	4
Memory Operation	4
Read Operation	4
Write Operation	4
Page Mode Operation	4
Pre-charge Operation	4
Software Write Protect	4
Software Write-Protect Timing	7
SRAM Drop-In Replacement	8
Maximum Ratings	
Operating Range	9
DC Electrical Characteristics	9
Data Retention and Endurance	
Capacitance	10
Thermal Resistance	10
AC Test Conditions	10

AC Switching Characteristics	11
SRAM Read Cycle	11
SRAM Write Cycle	12
Power Cycle and Sleep Mode Timing	16
Functional Truth Table	
Ordering Information	18
Ordering Code Definitions	18
Package Diagram	19
Acronyms	
Document Conventions	20
Units of Measure	20
Document History Page	21
Sales, Solutions, and Legal Information	22
Worldwide Sales and Design Support	
Products	22
PSoC® Solutions	22
Cypress Developer Community	22
Tochnical Support	22



Pinout

Figure 1. 48-ball FBGA pinout



Pin Definitions

Pin Name	I/O Type	Description
A ₁₇ A ₀	Input	Address inputs : The 18 address lines select one of 262,144 words in the F-RAM array. The lowest two address lines A_1 – A_0 may be used for page mode read and write operations.
DQ ₁₅ -DQ ₀	Input/Output	Data I/O Lines: 16-bit bidirectional data bus for accessing the F-RAM array.
WE	Input	Write Enable : A write cycle begins when $\overline{\text{WE}}$ is asserted. The rising edge causes the FM22LD16 to write the data on the DQ bus to the F-RAM array. The falling edge of WE latches a new column address for page mode write cycles.
CE	Input	Chip Enable : The device is selected and a new memory access begins on the falling edge of $\overline{\text{CE}}$. The entire address is latched internally at this point. Subsequent changes to the A_1 – A_0 address inputs allow page mode operation.
ŌE	Input	Output Enable: When OE is LOW, the FM22LD16 drives the data bus when the valid read data is available. Deasserting OE HIGH tristates the DQ pins.
UB	Input	Upper Byte Select : Enables DQ_{15} – DQ_8 pins during reads and writes. These pins are HI-Z if $\overline{\text{UB}}$ is HIGH. If the user does not perform byte writes and the device is not configured as a 512K × 8, the $\overline{\text{UB}}$ and $\overline{\text{LB}}$ pins may be tied to ground.
LB	Input	Lower Byte Select : Enables DQ_7 – DQ_0 pins during reads and writes. These pins are HI-Z if \overline{LB} is HIGH. If the user does not perform byte writes and the device is not configured as a 512K × 8, the \overline{UB} and \overline{LB} pins may be tied to ground.
V _{SS}	Ground	Ground for the device. Must be connected to the ground of the system.
V_{DD}	Power supply	Power supply input to the device.
NC	No connect	No connect. This pin is not connected to the die.

Document Number: 001-86190 Rev. *H Page 3 of 22



Device Operation

The FM22LD16 is a word wide F-RAM memory logically organized as 262,144 × 16 and accessed using an industry-standard parallel interface. All data written to the part is immediately nonvolatile with no delay. The device offers page mode operation, which provides high-speed access to addresses within a page (row). Access to a different page requires that either CE transitions LOW or the upper address (A₁₇–A₂) changes. See the Functional Truth Table on page 17 for a complete description of read and write modes.

Memory Operation

Users access 262,144 memory locations, each with 16 data bits through a parallel interface. The F-RAM array is organized as eight blocks, each having 8192 rows. Each row has four column locations, which allow fast access in page mode operation. When an initial address is latched by the falling edge of $\overline{\text{CE}}$, subsequent column locations may be accessed without the need to toggle $\overline{\text{CE}}$. When $\overline{\text{CE}}$ is deasserted HIGH, a pre-charge operation begins. Writes occur immediately at the end of the access with no delay. The $\overline{\text{WE}}$ pin must be toggled for each write operation. The write data is stored in the nonvolatile memory array immediately, which is a feature unique to F-RAM called NoDelay writes.

Read Operation

A read operation begins on the falling edge of $\overline{\text{CE}}$. The falling edge of $\overline{\text{CE}}$ causes the address to be latched and starts a memory read cycle if $\overline{\text{WE}}$ is HIGH. Data becomes available on the bus after the access time is met. When the address is latched and the access completed, a new access to a random location (different row) may begin while $\overline{\text{CE}}$ is still LOW. The minimum cycle time for random addresses is t_{RC} . Note that unlike SRAMs, the FM22LD16's $\overline{\text{CE}}$ -initiated access time is faster than the address access time.

The FM22LD16 will drive the data bus when \overline{OE} and at least one of the byte enables $\overline{(UB,LB)}$ is asserted LOW. The upper data byte is driven when \overline{UB} is LOW, and the lower data byte is driven when \overline{LB} is LOW. If \overline{OE} is asserted after the memory access time is met, the data bus will be driven with valid data. If \overline{OE} is asserted before completing the memory access, the data bus will not be driven until valid data is available. This feature minimizes supply current in the system by eliminating transients caused by invalid data being driven to the bus. When \overline{OE} is deasserted HIGH, the data bus will remain in a HI-Z state.

Write Operation

In the FM22LD16, writes o<u>ccur</u> in th<u>e same</u> interval as reads. The FM22LD16 supports both \overline{CE} and \overline{WE} controlled write cycles. In both cases, the address A_{17} – A_2 is latched on the falling edge of \overline{CE} .

In a $\overline{\text{CE}}$ -controlled write, the $\overline{\text{WE}}$ signal is asserted before beginning the memory cycle. That is, $\overline{\text{WE}}$ is LOW when $\overline{\text{CE}}$ falls. In this case, the device begins the memory cycle as a write. The FM22LD16 will not drive the data bus regardless of the state of $\overline{\text{OE}}$ as long as $\overline{\text{WE}}$ is LOW. Input data must be valid when $\overline{\text{CE}}$ is

deasserted HIGH. In a $\overline{\text{WE}}$ -controlled write, the memory cycle begins on the falling edge of $\overline{\text{CE}}$. The $\overline{\text{WE}}$ signal falls some time later. Therefore, the memory cycle begins as a read. The data bus will be driven if $\overline{\text{OE}}$ is LOW; however, it will be HI-Z when $\overline{\text{WE}}$ is asserted LOW. The $\overline{\text{CE}}$ - and $\overline{\text{WE}}$ -controlled write timing cases are shown in the Figure 11 on page 14.

Write access to the array begins on the falling edge of $\overline{\text{WE}}$ after the memory cycle is initiated. The write access terminates on the rising edge of $\overline{\text{WE}}$ or $\overline{\text{CE}}$, whichever comes first. A valid write operation requires the user to meet the access time specification before deasserting $\overline{\text{WE}}$ or $\overline{\text{CE}}$. The data setup time indicates the interval during which data cannot change before the end of the write access (rising edge of $\overline{\text{WE}}$ or $\overline{\text{CE}}$).

Unlike other nonvolatile memory technologies, there is no write delay with F-RAM. Because the read and write access times of the underlying memory are the same, the user experiences no delay through the bus. The entire memory operation occurs in a single bus cycle. Data polling, a technique used with EEPROMs to determine if a write is complete, is unnecessary.

Page Mode Operation

The F-RAM array is organized as eight blocks, each having 8192 rows. Each row has four column-address locations. Address inputs A_1 – A_0 define the column address to be accessed. An access can start on any column address, and other column locations may be accessed without the need to toggle the \overline{CE} pin. For fast access reads, after the first data byte is driven to the bus, the column address inputs A_1 – A_0 may be changed to a new value. A new data byte is then driven to the DQ pins no later than t_{AAP} , which is less than half the initial read access time. For fast access writes, the first write pulse defines the first write access. While \overline{CE} is LOW, a subsequent write pulse along with a new column address provides a page mode write access.

Pre-charge Operation

The pre-charge operation is an internal condition in which the memory state is prepared for a new access. Pre-charge is user-initiated by driving the $\overline{\text{CE}}$ signal HIGH. It must remain HIGH for at least the minimum pre-charge time, t_{PC} .

Pre-charge is also activated by changing the upper addresses, A_{17} – A_2 . The current row is first closed before accessing the new row. The device automatically detects an upper order address change, which starts a pre-charge operation. The new address is latched and the new read data is valid within the t_{AA} address access time; see Figure 8 on page 13. A similar sequence occurs for write cycles; see Figure 13 on page 14. The rate at which random addresses can be issued is t_{RC} and t_{WC} , respectively.

Software Write Protect

The $256K \times 16$ address space is divided into eight sectors (blocks) of $32K \times 16$ each. Each sector can be individually software write-protected and the settings are nonvolatile. A unique address and command sequence invokes the write-protect mode.

To modify write protection, the system host must issue six read commands, three write commands, and a final read command.



The specific sequence of read addresses must be provided to access the write-protect mode. Following the read address sequence, the host must write a data byte that specifies the desired protection state of each sector. For confirmation, the system must then write the complement of the protection byte immediately after the protection byte. Any error that occurs including read addresses in the wrong order, issuing a seventh read address, or failing to complement the protection value will leave the write protection unchanged.

The write-protect state machine monitors all addresses, taking no action until this particular read/write sequence occurs. During the address sequence, each read will occur as a valid operation and data from the corresponding addresses will be driven to the data bus. Any address that occurs out of sequence will cause the software protection state machine to start over. After the address sequence is completed, the next operation must be a write cycle. The lower data byte contains the write-protect settings. This value will not be written to the memory array, so the address is a don't-care. Rather it will be held pending the next cycle, which must be a write of the data complement to the protection settings. If the complement is correct, the write-protect settings will be adjusted. Otherwise, the process is aborted and the address sequence starts over. The data value written after the correct six addresses will not be entered into the memory.

The protection data byte consists of eight bits, each associated with the write-protect state of a sector. The data byte must be driven to the lower eight bits of the data bus, DQ₇–DQ₀. Setting a bit to '1' write-protects the corresponding sector; a '0' enables writes for that sector. The following table shows the write-protect sectors with the corresponding bit that controls the write-protect setting.

Table 1. Write Protect Sectors - 32K × 16 Blocks

Sectors	Blocks
Sector 7	3FFFFh-38000h
Sector 6	37FFFh-30000h
Sector 5	2FFFFh-28000h
Sector 4	27FFFh-20000h
Sector 3	1FFFFh-18000h
Sector 2	17FFFh-10000h
Sector 1	0FFFFh-08000h
Sector 0	07FFFh-00000h

The write-protect address sequence follows:

- 1. Read address 24555h
- 2. Read address 3AAAAh
- 3. Read address 02333h
- 4. Read address 1CCCCh
- 5. Read address 000FFh
- 6. Read address 3EF00h
- 7. Write address 3AAAAh
- 8. Write address 1CCCCh
- 9. Write address 0FF00h

10.Read address 00000h

Note If \overline{CE} is LOw entering the sequence, then an address of 00000h must precede 24555h.

The address sequence provides a secure way of modifying the protection. The write-protect sequence has a one in 3×10^{32} chance of randomly accessing exactly the first six addresses. The odds are further reduced by requiring three more write cycles, one that requires an exact inversion of the data byte. Figure 2 on page 6 shows a flow chart of the entire write-protect operation. The write-protect settings are nonvolatile. The factory default: all blocks are unprotected.

For example, the following sequence write-protects addresses from 18000h to 27FFFh (sectors 3 and 4):

	Address	Data
Read	24555h	-
Read	3AAAAh	_
Read	02333h	_
Read	1CCCCh	-
Read	000FFh	-
Read	3EF00h	_
Write	3AAAAh	18h; bits 3 and 4 = 1
Write	1CCCCh	E7h; complement of 18h
Write	0FF00h	Don't care
Read	00000h	

Document Number: 001-86190 Rev. *H Page 5 of 22

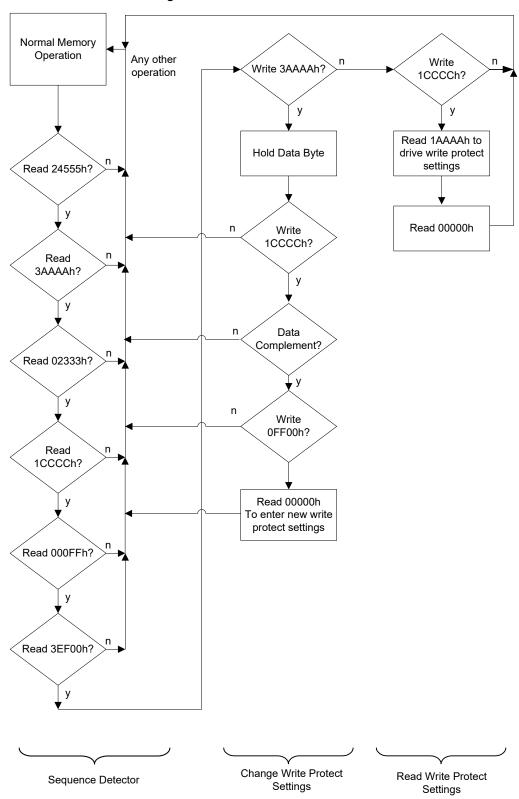


Figure 2. Write-Protect State Machine



Software Write-Protect Timing

Figure 3. Sequence to Set Write-Protect Blocks [1]

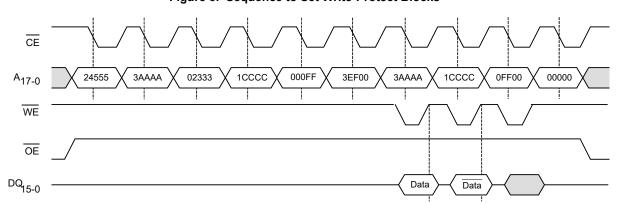
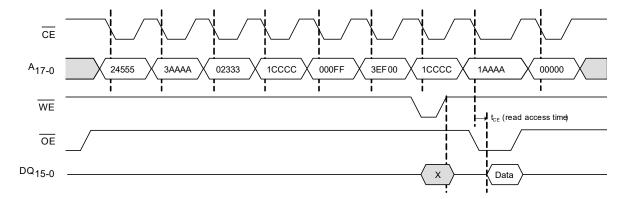


Figure 4. Sequence to Read Write-Protect Settings $^{[1]}$



Note 1. This sequence requires $t_{AS} \ge 10$ ns and address must be stable while \overline{CE} is LOW.

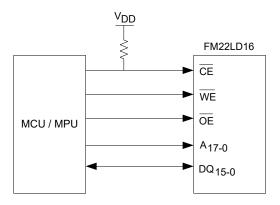


SRAM Drop-In Replacement

The FM22LD16 is designed to be a drop-in replacement for standard asynchronous SRAMs. The device does not require $\overline{\text{CE}}$ to toggle for each new address. $\overline{\text{CE}}$ may remain LOW indefinitely. While $\overline{\text{CE}}$ is LOW, the device automatically detects address changes and a new access begins. This functionality allows $\overline{\text{CE}}$ to be grounded as you might with an SRAM. It also allows page mode operation at speeds up to 40 MHz.

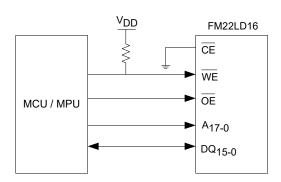
Figure 5 shows a pull-up resistor on \overline{CE} , which will keep the pin HIGH during power cycles, assuming the MCU / MPU pin tristates during the reset condition. The pull-up resistor value should be chosen to ensure the \overline{CE} pin tracks V_{DD} to a high enough value, so that the current drawn when \overline{CE} is LOW is not an issue. A 10-k Ω resistor draws 330 μ A when \overline{CE} is LOW and V_{DD} = 3.3 V.

Figure 5. Use of Pull-up Resistor on CE



Note that if \overline{CE} is tied to ground, the user \overline{must} be \overline{sure} \overline{WE} is not LOW at power-up or power-down events. If \overline{CE} and \overline{WE} are both LOW during power cycles, data will be corrupted. Figure 6 shows a pull-up resistor on \overline{WE} , which will keep the pin HIGH during power cycles, assuming the MCU / MPU pin tristates during the reset condition. The pull-up resistor value should be chosen to ensure the \overline{WE} pin tracks $\overline{V_{DD}}$ to a high enough value, so that the current drawn when \overline{WE} is LOW is not an issue. A 10-k Ω resistor draws 330 μ A when \overline{WE} is LOW and $\overline{V_{DD}}$ = 3.3 V.

Figure 6. Use of Pull-up Resistor on WE

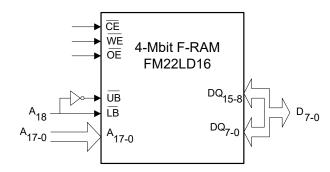


Note If \overline{CE} is tied to ground, the user gives up the ability to perform the software write-protect sequence.

 $\overline{\text{CE}}$ applications that require the lowest power consumption, the $\overline{\text{CE}}$ signal should be active (LOW) only during memory accesses. The FM22LD16 draws supply current while $\overline{\text{CE}}$ is LOW, even if addresses and control signals are static. While $\overline{\text{CE}}$ is HIGH, the device draws no more than the maximum standby current, I_{SB} . $\overline{\text{CE}}$ toggling LOW on every address access is perfectly acceptable in FM22LD16.

The $\overline{\text{UB}}$ and $\overline{\text{LB}}$ byte select pins are active for both read and write cycles. They may be used to allow the device to be wired as a 512K × 8 memory. The upper and lower data bytes can be tied together and controlled with the byte selects. Individual byte enables or the next higher address line A_{18} may be available from the system processor.

Figure 7. FM22LD16 Wired as 512K × 8





Maximum Ratings

Package power dissipation capability
(T _A = 25 °C)
Surface mount Pb soldering temperature
(3 seconds)+260 °C
DC output current
(1 output at a time, 1s duration)15 mA
Static discharge voltage
Human Body Model (JEDEC Std JESD22-A114-D) 2.5 kV
Charged Device Model (JEDEC Std JESD22-C101-C) 1.5 kV
Machine Model (JEDEC Std JESD22-A115-A)150 V
Latch-up current > 100 mA

Operating Range

Range	Ambient Temperature (T _A)	V_{DD}
Industrial	–40 °C to +85 °C	2.7 V to 3.6 V

DC Electrical Characteristics

Over the Operating Range

Parameter	Description	Test Conditions	Min	Typ [2]	Max	Unit
V_{DD}	Power supply voltage		2.7	3.3	3.6	V
I _{DD}	V _{DD} supply current	V_{DD} = 3.6 V, \overline{CE} cycling at min. cycle time. All inputs toggling at CMOS levels (0.2 V or V_{DD} – 0.2 V), all DQ pins unloaded.	1	8	12	mA
I _{SB}	Standby current	$V_{DD} = 3.6 \text{ V}, \overline{\text{CE}} \text{ at } V_{DD}, T_A = 25 ^{\circ}\text{C}$	-	90	150	μΑ
		All other pins are static and at CMOS levels $(0.2 \text{ V or V}_{DD} - 0.2 \text{ V})$	_	-	270	μА
I _{LI}	Input leakage current	V_{IN} between V_{DD} and V_{SS}	-	_	<u>+</u> 1	μΑ
I _{LO}	Output leakage current	V _{OUT} between V _{DD} and V _{SS}	_	_	<u>+</u> 1	μΑ
V _{IH}	Input HIGH voltage		2.2	-	V _{DD} + 0.3	V
V _{IL}	Input LOW voltage		-0.3	-	0.6	V
V _{OH1}	Output HIGH voltage	I _{OH} = -1.0 mA	2.4	_	-	V
V _{OH2}	Output HIGH voltage	I _{OH} = -100 μA	V _{DD} – 0.2	-	-	V
V _{OL1}	Output LOW voltage	I _{OL} = 2.1 mA	_	_	0.4	V
V _{OL2}	Output LOW voltage	I _{OL} = 100 μA	_	_	0.2	V

Note

Document Number: 001-86190 Rev. *H Page 9 of 22

^{2.} Typical values are at 25 °C, V_{DD} = V_{DD} (typ). Not 100% tested.



Data Retention and Endurance

Parameter	Description	Test condition	Min	Max	Unit
T _{DR}	Data retention	T _A = 85 °C	10	_	Years
		T _A = 75 °C	38	_	
		T _A = 65 °C	151	_	
NV _C	Endurance	Over operating temperature	10 ¹⁴	_	Cycles

Capacitance

Parameter	Description	Test Conditions	Max	Unit
C _{I/O}	Input/Output capacitance (DQ)	$T_A = 25 ^{\circ}\text{C}, f = 1 \text{MHz}, V_{DD} = V_{DD}(\text{Typ})$	8	pF
C _{IN}	Input capacitance		6	pF

Thermal Resistance

Parameter	Description	Test Conditions	48-ball FBGA	Unit
Θ_{JA}	,	Test conditions follow standard test methods and procedures for measuring thermal impedance, in		°C/W
$\Theta_{\sf JC}$	Thermal resistance (junction to case)	accordance with EIA/JESD51.	10	°C/W

AC Test Conditions

Input pulse levels	0 V to 3 V
Input rise and fall times (10%–90%)	<u><</u> 3 ns
Input and output timing reference levels	1.5 V
Output load capacitance	30 pF



AC Switching Characteristics

Over the Operating Range

Parameters [3]						
Cypress Parameter	Alt Parameter	Description	Min	Max	Unit	
SRAM Read	Cycle					
t _{CE}	t _{ACE}	Chip enable access time	_	55	ns	
t _{RC}	_	Read cycle time	110	-	ns	
t _{AA}	_	Address access time	_	110	ns	
t _{OH}	t _{OHA}	Output hold time	20	-	ns	
t _{AAP}	_	Page mode address access time	_	25	ns	
t _{OHP}	_	Page mode output hold time	5	_	ns	
t _{CA}	_	Chip enable active time	55	_	ns	
t _{PC}	_	Pre-charge time	55	-	ns	
t _{BA}	t _{BW}	UB, LB access time	_	20	ns	
t _{AS}	t _{SA}	Address setup time (to CE LOW)	0	-	ns	
t _{AH}	t _{HA}	Address hold time (CE Controlled)	55	-	ns	
t _{OE}	t _{DOE}	Output enable access time	_	15	ns	
t _{HZ} [4, 5]	t _{HZCE}	Chip Enable to output HI-Z	_	10	ns	
t _{OHZ} [4, 5]	t _{HZOE}	Output enable HIGH to output HI-Z	_	10	ns	
t _{BHZ} [4, 5]	t _{HZBE}	UB, LB HIGHHIGH to output HI-Z	_	10	ns	

Notes

^{3.} Test conditions assume a signal transition time of 3 ns or less, timing reference levels of 0.5 × V_{DD}, input pulse levels of 0 to 3 V, output loading of the specified I_{OL}/I_{OH} and load capacitance shown in AC Test Conditions on page 10.

t_{HZ}, t_{OHZ} and t_{BHZ} are specified with a load capacitance of 5 pF. Transition is measured when the outputs enter a high impedance state.
 This parameter is characterized but not 100% tested.



AC Switching Characteristics (continued)

Over the Operating Range

Parameters [3]					
Cypress Parameter	Alt Parameter	Description	Min	Max	Unit
SRAM Write	Cycle			•	
t _{WC}	t _{WC}	Write cycle time	110	_	ns
t _{CA}	-	Chip enable active time	55	_	ns
t _{CW}	t _{SCE}	Chip enable to write enable HIGH	55	_	ns
t _{PC}	_	Pre-charge time	55	_	ns
t _{PWC}	_	Page mode write enable cycle time	25	_	ns
t _{WP}	t _{PWE}	Write enable pulse width	16	_	ns
t _{AS}	t _{SA}	Address setup time (to CE LOW)	0	_	ns
t _{ASP}	_	Page mode address setup time (to WE LOW)	8	_	ns
t _{AHP}	-	Page mode address hold time (to WE LOW)	15	_	ns
t _{WLC}	t _{PWE}	Write enable LOW to chip disabled	25	_	ns
t _{BLC}	t _{BW}	UB, LB LOW to chip disabled	25	_	ns
t _{WLA}	-	Write enable LOW to A _{17–2} change	25	_	ns
t _{AWH}	-	A ₁₇₋₂ change to write enable HIGH	110	_	ns
t _{BS}		UB, LB setup time (to CE LOW)	2	_	ns
t _{BH}		UB, LB hold time (to CE HIGH)	0	_	ns
t _{DS}	t _{SD}	Data input setup time	14	_	ns
t _{DH}	t _{HD}	Data input hold time	0	_	ns
t _{WZ} [6, 7]	t _{HZWE}	Write enable LOW to output HI-Z	_	10	ns
t _{WX} ^[7]	_	Write enable HIGH to output driven 10			
t _{WS} ^[8]	_	Write enable to CE LOW setup time 0			
t _{WH} ^[8]	_	Write enable to CE HIGH hold time	0	_	ns

t_{WZ} is specified with a load capacitance of 5 pF. Transition is measured when the outputs enter a high impedance state.
 This parameter is characterized but not 100% tested.
 The relationship between CE and WE determines if a CE- or WE-controlled write occurs. The parameters t_{WS} and t_{WH} are not tested.



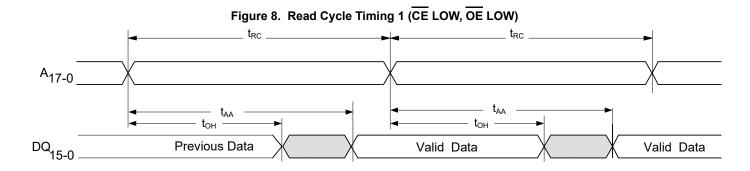


Figure 9. Read Cycle Timing 2 (CE Controlled)

CE

A17-0

OE

Tober

Tob

CE

A₁₇₋₂

A₁₋₀

Col 0

Col 1

Col 2

Data 0

Data 1

Data 2

Figure 10. Page Mode Read Cycle Timing [9]

^{9.} Although sequential column addressing is shown, it is not required.

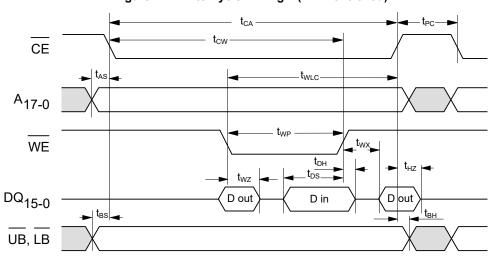


Figure 11. Write Cycle Timing 1 (WE Controlled) [10]

Figure 12. Write Cycle Timing 2 (CE Controlled)

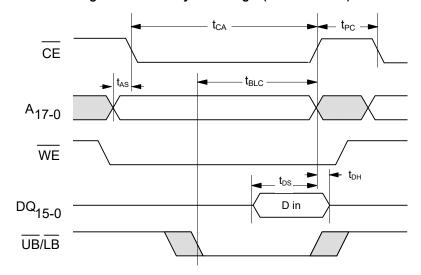
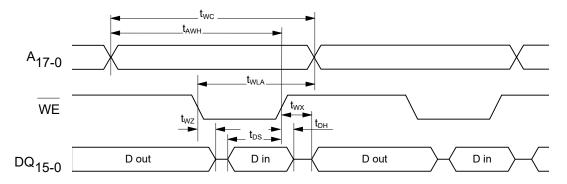


Figure 13. Write Cycle Timing 3 (CE LOW) [10]



Note 10. $\overline{\text{OE}}$ (not shown) is LOW only to show the effect of $\overline{\text{WE}}$ on DQ pins.

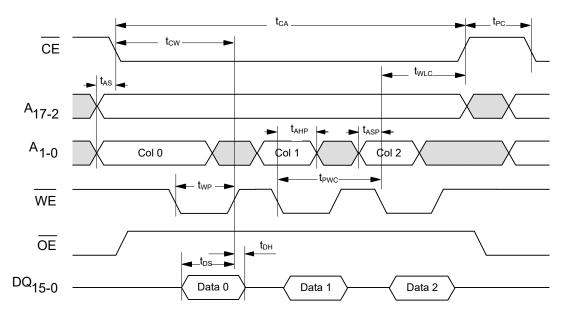


Figure 14. Page Mode Write Cycle Timing

Note 11. UB and LB to show byte enable and byte masking cases.

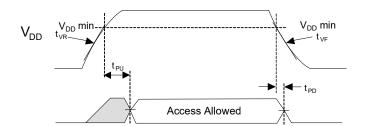


Power Cycle and Sleep Mode Timing

Over the Operating Range

Parameter	Description	Min	Max	Unit
t _{PU}	Power-up (after V _{DD} min. is reached) to first access time	450	-	μs
t _{PD}	Last write (WE HIGH) to power down time	0	-	μs
t _{VR} ^[12, 13]	V _{DD} power-up ramp rate	50	-	μs/V
t _{VF} ^[12, 13]	V _{DD} power-down ramp rate	100	_	μs/V

Figure 15. Power Cycle and Sleep Mode Timing



Note

Document Number: 001-86190 Rev. *H Page 16 of 22

^{12.} Slope measured at any point on the $V_{\mbox{\scriptsize DD}}$ waveform.

^{13.} Cypress cannot test or characterize all V_{DD} power ramp profiles. The behavior of the internal circuits is difficult to predict when V_{DD} is below the level of a transistor threshold voltage. Cypress strongly recommends that V_{DD} power up faster than 100 ms through the range of 0.4 V to 1.0 V.



Functional Truth Table

CE	WE	A ₁₇₋₂	A ₁₋₀	Operation [14, 15]
Н	Х	Х	Х	Standby/Idle
Ļ	H H	V V	V V	Read
L	Н	No Change	Change	Page Mode Read
L	Н	Change	V	Random Read
Ļ	L L	V V	V V	CE-Controlled Write ^[15]
L	\downarrow	V	V	WE-Controlled Write [15, 16]
L	↓	No Change	V	Page Mode Write [17]
↑ L	X X	X X	X X	Starts pre-charge

^{14.} H = Logic HIGH, L = Logic LOW, V = Valid Data, X = Don't Care, ↓ = toggle LOW, ↑ = toggle HIGH.

15. For write cycles, data-in is latched on the rising edge of CE or WE, whichever comes first.

16. WE-controlled write cycle begins as a Read cycle and then A₁₇₋₂ is latched.

^{17.} Addresses A₁₋₀ must remain stable for at least 10 ns during page mode operation.

18. The UB and LB pins may be grounded if 1) the system does not perform byte writes and 2) the device is not configured as a 512K x 8.

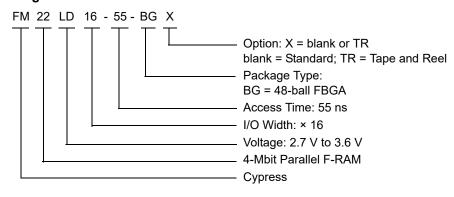


Ordering Information

Access Time (ns)	Ordering Code	Package Diagram	Package Type	Operating Range
55	FM22LD16-55-BG	001-91158	48-ball FBGA	Industrial
	FM22LD16-55-BGTR			

All the above parts are Pb-free.

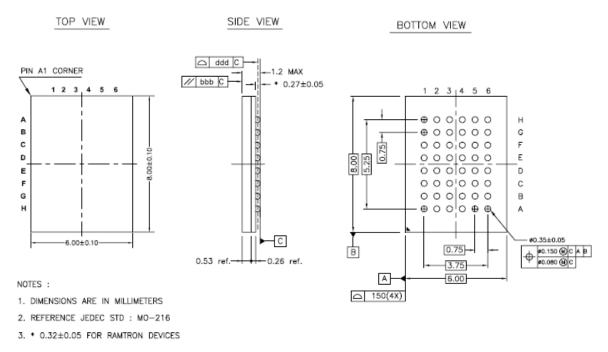
Ordering Code Definitions





Package Diagram

Figure 16. 48-ball FBGA (6 × 8 × 1.2 mm) Package Outline, 001-91158



001-91158 **



Acronyms

Acronym	Description
CPU	Central Processing Unit
CMOS	Complementary Metal Oxide Semiconductor
EIA	Electronic Industries Alliance
F-RAM	Ferroelectric Random Access Memory
I/O	Input/Output
MCU	Microcontroller Unit
MPU	Microprocessor Unit
RoHS	Restriction of Hazardous Substances
R/W	Read and Write
SRAM	Static Random Access Memory
TSOP	Thin Small Outline Package

Document Conventions

Units of Measure

Symbol	Unit of Measure
°C	degree Celsius
Hz	hertz
kHz	kilohertz
kΩ	kilohm
MHz	megahertz
μΑ	microampere
μF	microfarad
μS	microsecond
mA	milliampere
ms	millisecond
MΩ	megaohm
ns	nanosecond
Ω	ohm
%	percent
pF	picofarad
V	volt
W	watt

Document Number: 001-86190 Rev. *H Page 20 of 22



Document History Page

Rev.	ECN No.	Submission Date	Description of Change
**	3912933	02/25/2013	New spec.
*A	4191807	11/14/2013	Added watermark "Not recommended for new designs" across the document.
*B	4274811	03/11/2014	Removed watermark "Not recommended for new designs" across the document. Updated Maximum Ratings: Added "Maximum Junction Temperature" and its corresponding details. Added "DC voltage applied to outputs in High-Z state" and its corresponding details. Added "Transient voltage (< 20 ns) on any pin to ground potential" and its corresponding details. Added "Package power dissipation capability (T _A = 25 °C)" and its corresponding details. Added "DC output current (1 output at a time, 1s duration)" and its corresponding details. Added "Latch-up Current" and its corresponding details. Removed "Package Moisture Sensitivity Level" and its corresponding details. Updated Data Retention and Endurance: Removed existing details of T _{DR} parameter. Added details of T _{DR} parameter corresponding to "T _A = 85 °C", "T _A = 75 °C" and "T _A = 65 °C' Added NV _C parameter and its corresponding details. Added Thermal Resistance. Updated Package Diagram: Removed "Ramtron Revision History". Updated to Cypress template. Completing Sunset Review.
*C	4566147	11/10/2014	Updated Functional Description: Added "For a complete list of related documentation, click here." at the end.
*D	4879990	08/11/2015	Updated Maximum Ratings: Removed "Maximum junction temperature" and its corresponding details. Added "Maximum accumulated storage time" and its corresponding details. Added "Ambient temperature with power applied" and its corresponding details. Updated to new template.
*E	5110110	01/27/2016	Updated Maximum Ratings: Changed value of "Latch-up current" from "> 140 mA" to "> 100 mA". Completing Sunset Review.
*F	5962083	11/09/2017	Updated Cypress Logo and Copyright.
*G	6390500	11/21/2018	Updated Maximum Ratings: Replaced "–55 °C to +125 °C" with "–65 °C to +125 °C" in ratings corresponding to "Storage temperature". Updated to new template.
*H	6735005	11/20/2019	Updated Device Operation: Updated Software Write-Protect Timing: Updated Figure 4. Updated to new template.

Document Number: 001-86190 Rev. *H Page 21 of 22



Sales, Solutions, and Legal Information

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at Cypress Locations.

cypress.com/touch

cypress.com/wireless

cypress.com/usb

Products

Touch Sensing

USB Controllers

Wireless Connectivity

Arm® Cortex® Microcontrollers cypress.com/arm Automotive cypress.com/automotive Clocks & Buffers cypress.com/clocks Interface cypress.com/interface Internet of Things cypress.com/iot Memory cypress.com/memory Microcontrollers cypress.com/mcu **PSoC** cypress.com/psoc Power Management ICs cypress.com/pmic

PSoC® Solutions

PSoC 1 | PSoC 3 | PSoC 4 | PSoC 5LP | PSoC 6 MCU

Cypress Developer Community

Community | Projects | Video | Blogs | Training | Components

Technical Support

cypress.com/support

© Cypress Semiconductor Corporation, 2013–2019. This document is the property of Cypress Semiconductor Corporation and its subsidiaries ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. No computing device can be absolutely secure. Therefore, despite security measures implemented in Cypress hardware or software products, Cypress shall have no liability arising out of any security breach, such as unauthorized access to or use of a Cypress product. CYPRESS DOES NOT REPRESENT, WARRANT, OR GUARANTEE THAT CYPRESS PRODUCTS, OR SYSTEMS CREATED USING CYPRESS PRODUCTS, WILL BE FREE FROM CORRUPTION, ATTACK, VIRUSES, INTERFERENCE, HACKING, DATA LOSS OR THEFT, OR OTHER SECURITY INTRUSION (collectively, "Security Breach"). Cypress disclaims any liability relating to any Security Breach, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from any Security Breach. In addition, the products described in these materials may contain design defects or errors known as errata which may cause the product to deviate from published specifications. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. "High-Risk Device" means any device or system whose failure could cause personal injury, death, or property damage. Examples of High-Risk Devices are weapons, nuclear installations, surgical implants, and other medical devices. "Critical Component" means any component o

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.