

# RoboClockII<sup>™</sup> Junior, CY7B9930V, CY7B9940V

# High Speed Multifrequency PLL Clock Buffer

#### **Features**

- 12-100 MHz (CY7B9930V), or 24-200 MHz (CY7B9940V) input/output operation
- Matched pair output skew < 200 ps
- Zero input-to-output delay
- 10 LVTTL 50% duty-cycle outputs capable of driving 50ω terminated lines
- Commercial temperature range with eight outputs at 200 MHz
- Industrial temperature range with eight outputs at 200 MHz
- 3.3V LVTTL/LV differential (LVPECL), fault-tolerant and hot insertable reference inputs
- Multiply ratios of (1–6, 8, 10, 12)
- Operation up to 12x input frequency
- Individual output bank disable for aggressive power management and EMI reduction
- Output high impedance option for testing purposes
- Fully integrated PLL with lock indicator
- Low cycle-to-cycle jitter (<100 ps peak-peak)

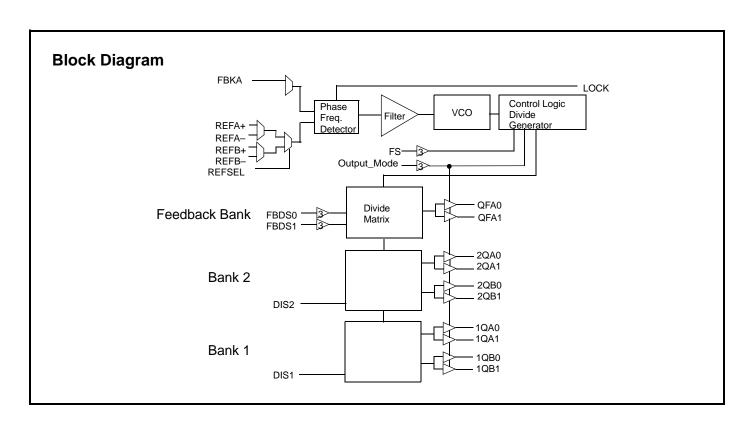
- Single 3.3V ± 10% supply
- 44-pin TQFP package

#### **Functional Description**

The CY7B9930V and CY7B9940V High-Speed Multifrequency PLL Clock Buffers offer user-selectable control over system clock functions. This multiple output clock driver provides the system integrator with functions necessary to optimize the timing of high performance computer or communication systems.

Ten configurable outputs can each drive terminated transmission lines with impedances as low as  $50\Omega$  while delivering minimal and specified output skews at LVTTL levels. The outputs are arranged in three banks. The FB feedback bank consists of two outputs, which allows divide-by functionality from 1 to 12. Any one of these ten outputs can be connected to the feedback input as well as driving other inputs.

Selectable reference input is a fault tolerance feature that allows smooth change over to secondary clock source, when the primary clock source is not in operation. The reference inputs are configurable to accommodate both LVTTL or differential (LVPECL) inputs. The completely integrated PLL reduces jitter and simplifies board layout.



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## Block Diagram Description Phase Frequency Detector and Filter

These two blocks accept signals from the REF inputs (REFA+, REFA-, REFB+ or REFB-) and the FB input (FBKA). Correction information is then generated to control the frequency of the Voltage Controlled Oscillator (VCO). These two blocks, along with the VCO, form a Phase-Locked Loop (PLL) that tracks the incoming REF signal.

The RoboClockII™ Junior has a flexible REF input scheme. These inputs allow the use of either differential LVPECL or single ended LVTTL inputs. To configure as single ended LVTTL inputs, leave the complementary pin to 1.5V), then use the other input pin as an LVTTL input. The REF inputs are also tolerant to hot insertion.

The REF inputs can be changed dynamically. When changing from one reference input to the other reference input of the same frequency, the PLL is optimized to ensure that the clock outputs period is not less than the calculated system budget ( $t_{MIN} = t_{REF}$  (nominal reference clock period) –  $t_{CCJ}$  (cycle-to-cycle jitter) –  $t_{PDEV}$  (max. period deviation)) while reacquiring lock.

#### VCO, Control Logic, and Divide Generator

The VCO accepts analog control inputs from the PLL filter block. The FS control pin setting determines the nominal operational frequency range of the divide by one output ( $f_{NOM}$ ) of the device.  $f_{NOM}$  is directly related to the VCO frequency. There are two versions of the RoboClockII Junior, a low speed device (CY7B9930V) where  $f_{NOM}$  ranges from 12 MHz to 100 MHz, and a high speed device (CY7B9940V), which ranges from 24 MHz to 200 MHz. The FS setting for each device is shown in Table 1. The  $f_{NOM}$  frequency is seen on "divide-by-one" outputs.

Table 1. Frequency Range Select

	CY7B	9930V	CY7B9940V			
FS <sup>[1]</sup>	f <sub>NOM</sub>	f <sub>NOM</sub> (MHz)		(MHz)		
	Min.	Max.	Min.	Max.		
LOW	12	26	24	52		
MID	24	52	48	100		
HIGH	48	100	96	200 <sup>[2]</sup>		

#### **Divide Matrix**

The Divide Matrix is comprised of three independent banks: two banks of clock outputs and one bank for feedback. Each clock output bank has two pairs of low-skew, high fanout output buffers ([1:2]Q[A:B][0:1]), and an output disable (DIS[1:2]).

The feedback bank has one pair of low-skew, high fanout output buffers (QFA[0:1]). One of these outputs may connect to the selected feedback input (FBKA+). This feedback bank also has two divider function selects FBDS[0:1].

The divide capabilities for each bank are shown in Table 2.

**Table 2. Output Divider Function** 

	ction ects	Output	t Divider Fu	unction
FBDS1 FBDS0		Bank 1	Bank 2	Feedback Bank
LOW	LOW	/1	/1	/1
LOW	MID	/1	/1	/2
LOW	HIGH	/1	/1	/3
MID	LOW	/1	/1	/4
MID	MID	/1	/1	/5
MID	HIGH	/1	/1	/6
HIGH	LOW	/1	/1	/8
HIGH	MID	/1	/1	/10
HIGH	HIGH	/1	/1	/12

#### **Output Disable Description**

The outputs of Bank 1 and Bank 2 can be independently put into a HOLD OFF or high impedance state. The combination of the Output\_Mode and DIS[1:2] inputs determines the clock outputs' state for each bank. When the DIS[1:2] is LOW, the outputs of the corresponding bank are enabled. When the DIS[1:2] is HIGH, the outputs for that bank are disabled to a high impedance (HI-Z) or HOLD OFF state depending on the Output\_Mode input. Table 3 defines the disabled output functions.

#### Notes

2. The maximum output frequency is 200 MHz.

The level to be set on FS is determined by the "nominal" operating frequency (f<sub>NOM</sub>) of the V<sub>CO</sub>. f<sub>NOM</sub> always appears on an output when the output is operating in the undivided mode. The REF and FB are at f<sub>NOM</sub> when the output connected to FB is undivided.



The HOLD OFF state is designed as a power saving feature. An output bank is disabled to the HOLD OFF state in a maximum of six output clock cycles from the time when the disable input (DIS[1:2]) is HIGH. When disabled to the HOLD OFF state, outputs are driven to a logic LOW state on its falling edge. This ensures the output clocks are stopped without glitch. When a bank of outputs is disabled to HI-Z state, the respective bank of outputs go HI-Z immediately.

Table 3. DIS[1:2] Pin Functionality

OUTPUT_MODE	DIS[1:2]/FBDIS	Output Mode
HIGH/LOW	LOW	ENABLED
HIGH	HIGH	HI-Z
LOW	HIGH	HOLD-OFF
MID	Х	FACTORY TEST

#### **Lock Detect Output Description**

The LOCK detect output indicates the lock condition of the integrated PLL. Lock detection is accomplished by comparing the phase difference between the reference and feedback inputs. Phase error is declared when the phase difference between the two inputs is greater than the specified device propagation delay limit ( $t_{PD}$ ).

When in the locked state, after four or more consecutive feedback clock cycles with phase errors, the LOCK output is forced LOW to indicate out-of-lock state.

When in the out-of-lock state, 32 consecutive phase errorless feedback clock cycles are required to allow the LOCK output to indicate lock condition (LOCK = HIGH).

If the feedback clock is removed after LOCK has gone HIGH, a Watchdog circuit is implemented to indicate the out-of-lock condition after a timeout period by deasserting LOCK LOW. This timeout period is based upon a divided down reference clock.

This assumes that there is activity on the selected REF input. If there is no activity on the selected REF input then the LOCK detect pin may not accurately reflect the state of the internal PLL.

#### **Factory Test Mode Description**

The device enters factory test mode when the OUTPUT\_MODE is driven to MID. In factory test mode, the device operates with its internal PLL disconnected; the input level supplied to the reference input is used in place of the PLL output. In TEST mode the selected FB input must be tied LOW. All functions of the device remain operational in factory test mode except the internal PLL and output bank disables. The OUTPUT\_MODE input is designed as a static input. Dynamically toggling this input from LOW to HIGH may temporarily cause the device to go into factory test mode (when passing through the MID state).

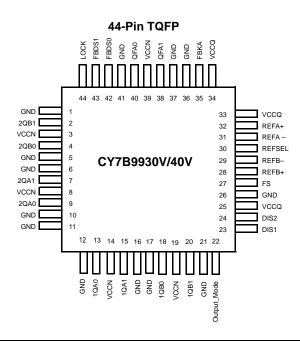
#### Factory Test Reset

When in factory test mode (OUTPUT\_MODE = MID), the device is reset to a deterministic state by driving the DIS2 input HIGH. When the DIS2 input is driven HIGH in factory test mode, all clock outputs go to HI-Z; after the selected reference clock pin has five positive transitions, all the internal finite state machines (FSM) are set to a deterministic state. The deterministic state of the state machines depends on the configurations of the divide selects and frequency select input. All clock outputs stay in high impedance mode and all FSMs stay in the deterministic state until DIS2 is deasserted. When DIS2 is deasserted (with OUTPUT\_MODE still at MID), the device reenters factory test mode.

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#### **Pin Definitions**



Name	I/O	Type	Description
FBKA	Input	LVTTL	Feedback Input.
REFA+, REFA- REFB+, REFB-	Input	LVTTL/ LVDIFF	<b>Reference Inputs</b> : These inputs operate as either differential PECL or single ended TTL reference inputs to the PLL. When operating as a single ended LVTTL input, leave the complementary input must be left open.
REFSEL	Input	LVTTL	<b>Reference Select Input</b> : The REFSEL input controls reference input configuration. When LOW, it uses the REFA pair as the reference input. When HIGH, it uses the REFB pair as the reference input. This input has an internal pull down.
FS <sup>[3]</sup>	Input	3 Level Input	<b>Frequency Select</b> : Set this input according to the nominal frequency (f <sub>NOM</sub> ). See Table 1.
FBDS[0:1] <sup>[3]</sup>	Input	3 Level Input	<b>Feedback Divider Function Select</b> . These inputs determine the function of the QFA0 and QFA1 outputs. See Table 2.
DIS[1:2]	Input	LVTTL	<b>Output Disable</b> : Each input controls the state of the respective output bank. When HIGH, the output bank is disabled to the "HOLD OFF" or "HI-Z" state; the disable state is determined by OUTPUT_MODE. When LOW, the [1:4]Q[A:B][0:1] is enabled. See Table 3. These inputs each have an internal pull down.
LOCK	Output	LVTTL	PLL Lock Indicator: When HIGH, this output indicates that the internal PLL is locked to the reference signal. When LOW, the PLL is attempting to acquire lock.
Output_Mode <sup>[3]</sup>	Input	3 Level Input	<b>Output Mode</b> : This pin determines the clock outputs' disable state. When this input is HIGH, the clock outputs disable to high impedance (HI-Z). When this input is LOW, the clock outputs disables to "HOLD OFF" mode. When in MID, the device enters factory test mode.
QFA[0:1]	Output	LVTTL	<b>Clock Feedback Output</b> : This pair of clock outputs connects to the FB input. These outputs have numerous divide options. The function is determined by the setting of the FBDS[0:1] pins.
[1:2]Q[A:B][0:1]	Output	LVTTL	Clock Output.
VCCN		PWR	Output Buffer Power: Power supply for each output pair.
VCCQ		PWR	Internal Power: Power supply for the internal circuitry.
GND		PWR	Device Ground.

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Note
3. For all tri-state inputs, HIGH indicates a connection to V<sub>CC</sub>, LOW indicates a connection to GND, and MID indicates an open connection. Internal termination circuitry holds an unconnected input to V<sub>CC</sub>/2.



#### **Absolute Maximum Conditions**

Static discharge voltage	. >2000V
MIL-STD-883, Method 3015)	
Latch up current>	±200 mA

#### **Operating Range**

Range	Ambient Temperature	V <sub>CC</sub>
Commercial	0°C to +70°C	3.3V ±10%
Industrial	–40°C to +85°C	3.3V ±10%

#### **Electrical Characteristics** Over the Operating Range

Parameter	Description		Test Conditions	Min.	Max.	Unit
LVTTL Comp	oatible Output Pins (C	FA[0:1], [1:4]Q[A:B][0:1], L	OCK)			
V <sub>OH</sub>	LVTTL HIGH voltage	QFA[0:1], [1:2]Q[A:B][0:1]	$V_{CC} = Min., I_{OH} = -30 \text{ mA}$	2.4	_	V
		LOCK	$I_{OH} = -2 \text{ mA}, V_{CC} = \text{Min}.$	2.4	_	V
V <sub>OL</sub>	LVTTL LOW voltage	QFA[0:1], [1:2]Q[A:B][0:1]	$V_{CC} = Min., I_{OL} = 30 \text{ mA}$	-	0.5	V
		LOCK	$I_{OL}$ = 2 mA, $V_{CC}$ = Min.	-	0.5	V
loz	High impedance state	leakage current		-100	100	μΑ
LVTTL Comp	patible Input Pins (FB	KA, REFA±, REFB±, REFSE	L, DIS[1:2])			
V <sub>IH</sub>	LVTTL Input HIGH	FBKA+, REF[A:B]±	Min. ≤ V <sub>CC</sub> ≤ Max.	2.0	V <sub>CC</sub> +0.3	V
		REFSEL, DIS[1:2]		2.0	V <sub>CC</sub> +0.3	V
V <sub>IL</sub>	LVTTL Input LOW	FBKA+, REF[A:B]±	Min. <u>&lt;</u> V <sub>CC</sub> <u>&lt;</u> Max.	-0.3	0.8	V
		REFSEL, DIS[1:2]		-0.3	0.8	V
ı	LVTTL V <sub>IN</sub> >V <sub>CC</sub>	FBKA+, REF[A:B]±	$V_{CC} = GND, V_{IN} = 3.63V$	_	100	μΑ
I <sub>IH</sub> LVTTL Input HIGH Current	LVTTL Input HIGH	FBKA+, REF[A:B]±	$V_{CC} = Max., V_{IN} = V_{CC}$	_	500	μΑ
	Current	REFSEL, DIS[1:2]	$V_{IN} = V_{CC}$	_	500	μΑ
I <sub>IL</sub> LVTTL Input LOW		FBKA+, REF[A:B]±	$V_{CC} = Max., V_{IN} = GND$	-500	-	μΑ
	Current	REFSEL, DIS[1:2]		-500	-	μΑ
3-Level Inpu	t Pins (FBDS[0:1], FS	, Output_Mode)				
V <sub>IHH</sub>	Three level input HIG	H <sup>[4]</sup>	Min. ≤ V <sub>CC</sub> ≤ Max.	0.87*V <sub>CC</sub>	-	V
V <sub>IMM</sub>	Three level input MID	[4]	Min. ≤ V <sub>CC</sub> ≤ Max.	0.47*V <sub>CC</sub>	0.53*V <sub>CC</sub>	V
V <sub>ILL</sub>	Three level input LOV	V <sup>[4]</sup>	Min. ≤ V <sub>CC</sub> ≤ Max.		0.13*V <sub>CC</sub>	V
Інн	Three level input HIGH current	Three level input pins	$V_{IN} = V_{CC}$	-	200	μΑ
IMM	Three level input MID current	Three level input pins	$V_{IN} = V_{CC}/2$	<b>–</b> 50	50	μΑ
ILL	Three level input LOW current	Three level input pins	V <sub>IN</sub> = GND	-200	-	μΑ
LVDIFF Inpu	t Pins (REF[A:B]±)					
V <sub>DIFF</sub>	Input differential volta	ge		400	V <sub>CC</sub>	mV
V <sub>IHHP</sub>	Highest input HIGH ve	oltage		1.0	V <sub>CC</sub>	V
V <sub>ILLP</sub>	Lowest input LOW vo	Itage		GND	V <sub>CC</sub> - 0.4	V
V <sub>COM</sub>	Common mode range	(crossing voltage)		0.8	V <sub>CC</sub>	V

#### Note

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<sup>1.</sup> These inputs are normally wired to V<sub>CC</sub>, GND, or left unconnected (actual threshold voltages vary as a percentage of V<sub>CC</sub>). Internal termination resistors hold the unconnected inputs at V<sub>CC</sub>/2. If these inputs are switched, the function and timing of the outputs may glitch and the PLL may require an additional t<sub>LOCK</sub> time before all data sheet limits are achieved.



#### **Electrical Characteristics** Over the Operating Range (continued)

Parameter	Description		Test Conditions	Min.	Max.	Unit	
Operating Current							
I <sub>CCI</sub>	Internal operating	CY7B9930V	$V_{CC} = Max., f_{MAX}^{[5]}$	_	200	mA	
	current	CY7B9940V		_	200	mA	
I <sub>CCN</sub>	Output current	CY7B9930V	V <sub>CC</sub> = Max.,	_	40	mA	
	dissipation/pair <sup>[6]</sup>	CY7B9940V	$V_{CC} = Max.,$ $C_{LOAD} = 25 \text{ pF},$ $R_{LOAD} = 50\Omega \text{ at } V_{CC}/2,$ $f_{MAX}$	-	50	mA	
			MAX				

#### Capacitance

Parameter	Description	Test Conditions	Min.	Max.	Unit
C <sub>IN</sub>	Input capacitance	$T_A = 25^{\circ}C$ , $f = 1$ MHz, $V_{CC} = 3.3V$	_	5	pF

#### **Switching Characteristics**

Over the Operating Range<sup>[7, 8, 9, 10, 11]</sup>

Davamatav	Description		CY7B9930/40V-2		CY7B9930/40V-5		I I and t
Parameter	Description		Min.	Max.	Min.	Max.	Unit
f <sub>in</sub>	Clock input frequency	CY7B9930V	12	100	12	100	MHz
		CY7B9940V	24	200	24	200	MHz
f <sub>out</sub>	Clock input frequency	CY7B9930V	12	100	12	100	MHz
		CY7B9940V	24	200	24	200	MHz
t <sub>SKEWPR</sub>	Matched pair skew <sup>[12, 13]</sup>		_	185	_	185	ps
t <sub>SKEWBNK</sub>	Intrabank skew <sup>[12, 13]</sup>		_	200	-	250	ps
t <sub>SKEW0</sub>	Output-Output skew (same frequency and phase, rise to rise, fall to fall) <sup>[12, 13]</sup>		_	250	_	550	ps
t <sub>SKEW1</sub>	Output-Output skew (same frequency and phase, other banks at different frequency, rise to rise, fall to fall) <sup>[12, 13]</sup>		-	250	-	650	ps
t <sub>CCJ1-3</sub>	Cycle-to-cycle jitter (divide by 1 output frequency, FB = divide by 1, 2, 3)		-	150	-	150	ps Peak- Peak
t <sub>CCJ4-12</sub>	Cycle-to-cycle jitter (divide by 1 output frequency, FB = divide by 4, 5, 6, 8, 10, 12)		-	100	-	100	ps Peak- Peak
t <sub>PD</sub>	Propagation delay, REF to FB Rise		-250	250	-500	500	ps
t <sub>PDDELTA</sub>	Propagation delay difference between two devices <sup>[14]</sup>		_	200		200	ps
t <sub>REFpwh</sub>	REF input (pulse width HIGH) <sup>[15]</sup>		2.0	_	2.0	_	ns
t <sub>REFpwl</sub>	REF input (pulse width LOW) <sup>[15]</sup>		2.0	_	2.0	_	ns
t <sub>r</sub> /t <sub>f</sub>	Output rise/fall time <sup>[16]</sup>		0.15	2.0	0.15	2.0	ns

#### Notes

- I<sub>CCI</sub> measurement is performed with Bank1 and FB Bank configured to run at maximum frequency (f<sub>NOM</sub> = 100 MHz for CY7B9930V, f<sub>NOM</sub> = 200 MHz for CY7B9940V), and all other clock output banks to run at half the maximum frequency. FS and OUTPUT\_MODE are asserted to the HIGH state.
- 6. This is dependent upon frequency and number of outputs of a bank being loaded. The value indicates maximum I<sub>CCN</sub> at maximum frequency and maximum load of 25 pF terminated to 50Ω at V<sub>CC</sub>/2.
   7. This is for non-three level inputs.
- Assumes 25 pF Max. Load Capacitance up to 185 Mhz. At 200 MHz the max load is 10 pF.
- 9. Both outputs of pair must be terminated, even if only one is being used.
- 10. Each package must be properly decoupled.
- 11. AC parameters are measured at 1.5V, unless otherwise indicated.
- 12. Test Load  $C_L$ = 25 pF, terminated to  $V_{CC}/2$  with  $50\Omega$ .
- SKEW is defined as the time between the earliest and the latest output transition among all outputs for which the same phase delay has been selected when all outputs are loaded with 25 pF and properly terminated up to 185 MHz. At 200 MHz the max load is 10 pF.
   Guaranteed by statistical correlation. Tested initially and after any design or process changes that may affect these parameters.
- 15. Tested initially and after any design or process changes that may affect these parameters.

  16. Rise and fall times are measured between 2.0V and 0.8V.

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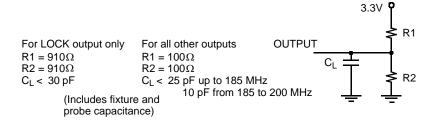
#### **Switching Characteristics**

Over the Operating Range<sup>[7, 8, 9, 10, 11]</sup> (continued)

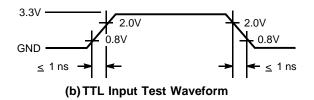
Doromotor	Description		30/40V-2	CY7B99	Unit	
Parameter			Max.	Min.	Max.	Unit
t <sub>LOCK</sub>	PLL lock time from power up	_	10	_	10	ms
t <sub>RELOCK1</sub>	PLL relock time (from same frequency, different phase) with stable power supply	_	500	_	500	μS
t <sub>RELOCK2</sub>	PLL Relock Time (from different frequency, different phase) with Stable Power Supply <sup>[17]</sup>	-	1000	-	1000	μS
t <sub>ODCV</sub>	Output duty cycle deviation from 50% <sup>[11]</sup>	-1.0	1.0	-1.0	1.0	ns
t <sub>PWH</sub>	Output HIGH time deviation from 50% <sup>[18]</sup>	_	1.5	_	1.5	ns
t <sub>PWL</sub>	Output LOW time deviation from 50% <sup>[18]</sup>	_	2.0	_	2.0	ns
t <sub>PDEV</sub>	Period deviation when changing from reference to reference <sup>[19]</sup>	_	0.025	_	0.025	UI
t <sub>OAZ</sub>	DIS[1:2] HIGH to output high impedance from ACTIVE <sup>[12, 20]</sup>	1.0	10	1.0	10	ns
t <sub>OZA</sub>	DIS[1:2] LOW to output ACTIVE from output is high impedance <sup>[20, 21]</sup>	0.5	14	0.5	14	ns

#### **AC Test Loads and Waveform**

See note. [22]



#### (a) LVTTL AC Test Load

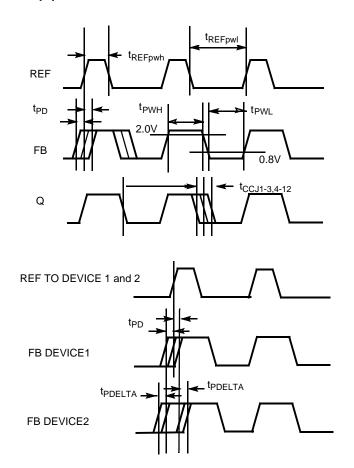


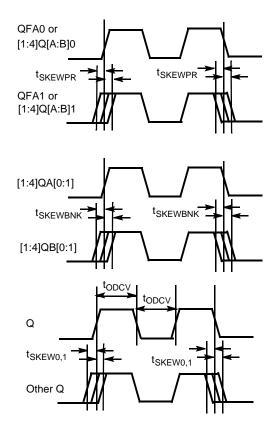
- 17.  $f_{\mbox{\scriptsize NOM}}$  must be within the frequency range defined by the same FS state.
- 18. t<sub>PWH</sub> is measured at 2.0V. t<sub>PWL</sub> is measured at 0.8V.
  19. UI = Unit Interval. Examples: 1 UI is a full period. 0.1 UI is 10% of period.
  20. Measured at 0.5V deviation from starting voltage.
- 21. For  $f_{OZA}$  minimum,  $C_L = 0$  pF. For  $f_{OZA}$  maximum,  $C_L = 25$  pF to 18 MHz, 10 pF from 185 to 200 MHz. 22. These figures are for illustration only. The actual ATE loads may vary.

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## AC Timing Diagrams See note. [11]







## **Ordering Information**

Propagation Delay (ps) Max. Speed (MHz) Ordering Code		Ordering Code	Package Type	Operating Range
500	100	CY7B9930V-5AC [23]	44-Lead Thin Quad Flat Pack	Commercial
500	100	CY7B9930V-5AI [23]	44-Lead Thin Quad Flat Pack	Industrial
500	200	CY7B9940V-5AC	44-Lead Thin Quad Flat Pack	Commercial
500	200	CY7B9940V-5AI [23]	44-Lead Thin Quad Flat Pack	Industrial
250	100	CY7B9930V-2AC [23]	44-Lead Thin Quad Flat Pack	— Commercial
250	200	CY7B9940V-2AC	44-Lead Thin Quad Flat Pack	Commercial
250	100	CY7B9930V-2AI [23]	44-Lead Thin Quad Flat Pack	— Industrial
250	200	CY7B9940V-2AI [23]	44-Lead Thin Quad Flat Pack	Industrial
Pb-free				
500	100	CY7B9930V-5AXC	44-Lead Thin Quad Flat Pack	Commercial
500	100	CY7B9930V-5AXCT	44-Lead Thin Quad Flat Pack-Tape and Reel	Commercial
500	200	CY7B9940V-5AXC	44-Lead Thin Quad Flat Pack	Commercial
500	200	CY7B9940V-5AXCT	44-Lead Thin Quad Flat Pack-Tape and Reel	
500	200	CY7B9940V-5AXI	44-Lead Thin Quad Flat Pack	Industrial
500	200	CY7B9940V-5AXIT	44-Lead Thin Quad Flat Pack-Tape and Reel	
250	250 200 CY7B9940V-2AXC 44-Lead Thin Quad Flat Pack		Commercial	
250	200	CY7B9940V-2AXCT	44-Lead Thin Quad Flat Pack-Tape and Reel	
250	250 200 CY7B9940V-2AXI 44-Lead Thin Quad Flat Pack		Industrial	
250	200	CY7B9940V-2AXIT	44-Lead Thin Quad Flat Pack-Tape and Reel	

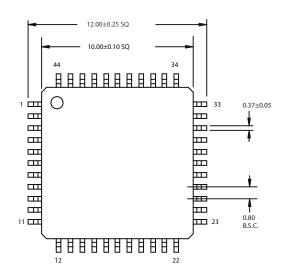
**Note** 23. It is a obsolete device.

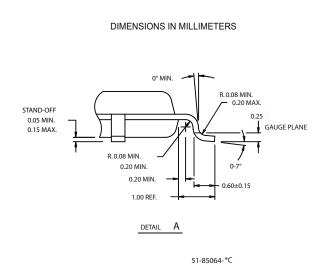
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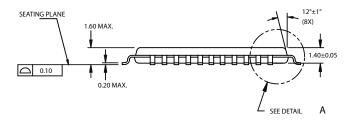


## **Package Diagrams**

### 44 Lead Thin Plastic Quad Flatpack 10 X 10 X 1.4mm







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#### **Document History Page**

Document Title: RoboClockII™ Junior, CY7B9930V, CY7B9940V High Speed Multifrequency PLL Clock Buffer Document Number: 38-07271				
REV.	ECN NO.	Issue Date	Orig. of Change	Description of Change
**	110536	12/02/01	SZV	Change from Spec number: 38-01141
*A	115109	7/03/02	HWT	Add 44TQFP package for both CY7B9930/40V – Industrial Operating Range
*B	128463	7/29/03	RGL	Added clock input frequency $(f_{in})$ specifications in the switching characteristics table. Added Min. values for the clock output frequency $(f_{out})$ in the switching characteristics table.
*C	1346903	8/8/07	WWZ/VED/ ARI	Update the ordering info to reflect the current status and Pb-free part numbers. Implemented new template. Updated the package diagram.

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