Ordering number : EN7232B

# LB1940T LB1940U



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# Monolithic Digital IC 2-ch H-Bridge Constant Current Driver

#### Overview

The LB1940T and LB1940U are 2-phase exciter type bipolar stepper motor driver ICs that feature low-voltage, (supporting 3V battery) and low current operation with low saturation voltage. These ICs enable constant-current control of actuators, and are optimal for driving the actuators of PC peripherals such as USB compatible scanners, FDDs, and printers, as well as for controlling the shutter, iris, and AF of a digital still camera.

#### **Features**

• Low-voltage driving

2-power source type:  $VS = 1.6 \text{ to } 7.5 \text{V}, V_{DD} = 1.9 \text{ to } 6.5 \text{V}$ 

Single power source type:  $VS = V_DD = 1.9$  to 7.5V

• Low saturation output:  $V_O(sat) = 0.3V$  at IO of 200mA

• Constant-current control

• Built-in reference voltage (Vref = 0.9V)

• Small-sized, low-profile package (LB1940T: TSSOP20; 225mil; thickness (t) = 1.2mm max.)

(LB1940U: MSOP20; thickness (t) = 0.85mm max.)

#### **Specifications**

#### **Absolute Maximum Ratings** at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	VB max	VS1, VS2, V <sub>DD</sub>	-0.3 to +10.5	V
Output applied voltage	V <sub>OUT</sub> max	OUT1, OUT2, OUT3, OUT4	-0.3 to +10.5	٧
Output Current	I <sub>O</sub> max		400	mA
Input applied voltage	V <sub>IN</sub> max	ENA1, ENA2, IN1, IN2, VC	-0.3 to +10.5	>
Allowable power dissipation	Pd max	Mounted on a specified board *	800	mW
Operating temperature	Topr		-20 to +85	°C
Storage temperature	Tstg		-55 to +150	°C

<sup>\*</sup> Mounted on a Specified board: 114.3mm×76.1mm×1.6mm, glass epoxy

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

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#### Allowable Operating Range at Ta = 25°C

Parameter	Symbol	Conditions	Ratings			unit
Parameter		Conditions	min	typ	max	unit
Function-guaranteed voltage range	VOPR1 V <sub>DD</sub> system, VS = 2.0V		1.9		6.5	V
	VOPR2	VS system, V <sub>DD</sub> = 5.0V	1.6		7.5	
Low level input threshold voltage	V <sub>IL</sub>	ENA1, ENA2, IN1, IN2	-0.3		1.0	V
High level input threshold voltage	V <sub>IH</sub>	ENA1, ENA2, IN1, IN2	2.0		6.0	V
VC input voltage	VC		0.19		1.0	V

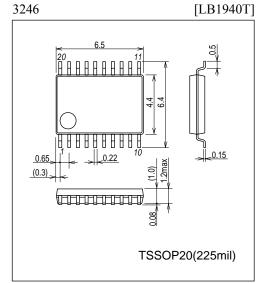
# Electrical Characteristics at Ta = 25°C, VS = 3V, $V_{DD} = 5V$

Danasatas	0	Con disions	Ratings			unit		
Parameter	Symbol	Conditions	min	typ	max	urnit		
Standby current dissipation	ISTB	VS = V <sub>DD</sub> = 6.5V		0.1	1.0	μΑ		
Regulator output circuit								
VREF output voltage	VREF	I <sub>OL</sub> = 0 to 1mA	0.85	0.9	0.95	<b>V</b>		
SVDD output voltage	VSVDD	I <sub>OL</sub> = 10mA	4.70	4.85		٧		
H bridge output circuit								
OUT output saturation voltage (at saturation control)	V <sub>O</sub> (sat)1	V <sub>DD</sub> = 5.0V, VS = 2.0V I <sub>O</sub> = 200mA (PNP side)		0.20	0.30	>		
	V <sub>O</sub> (sat)2	V <sub>DD</sub> = 5.0V, VS = 2.0V I <sub>O</sub> = 200mA (NPN side)		0.10	0.15	٧		
OUT output current (at constant current control)	I <sub>OUT</sub> 1	$V_{DD}$ = 6.0V, VC = 0.2V, VS = 3.5V $R_L$ = 5 $\Omega$ (between OUT-OUT), RFB = 2 $\Omega$	94	100	106	mA		
	I <sub>OUT</sub> 2	$VC = \frac{Rb}{Ra + Rb} VREF (Ra = 70k\Omega, Rb = 20k\Omega) *$ $V_{DD} = 6.0V, VS = 2.0V$ $R_{I} = 5\Omega \text{ (between OUT-OUT), RFB} = 1\Omega$	180	200	220	mA		
VS system operating current consumption	IS1	$VC = \frac{Rb}{Ra + Rb} VREF (Ra = 70k\Omega, Rb = 20k\Omega) *$		1.5	3	mA		
V <sub>DD</sub> system operating current dissipation	I <sub>DD</sub> 1	$VC = \frac{Rb}{Ra + Rb} VREF (Ra = 70k\Omega, Rb = 20k\Omega) *$ $ENA1 = 2V$		4	7	mA		
VC input current	IVC	V <sub>DD</sub> = 6.0V, VS = 2.0V, VC = 1.9V	0		-1	μΑ		
Control input circuit								
Control pin maximum input current	lіН	V <sub>IH</sub> = 5.5V		80	100	μΑ		
	I <sub>IL</sub>	V <sub>IL</sub> = GND	-1		0			

 $<sup>^{\</sup>star}$  For Ra and Rb, refer to Application Circuit Diagram.

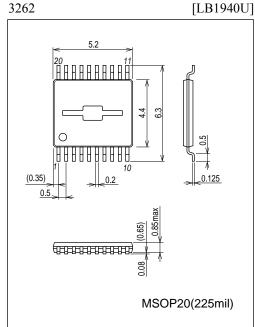
# **Package Dimensions**

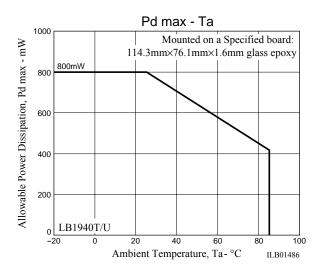
unit: mm (typ)



# **Package Dimensions**

unit: mm (typ)



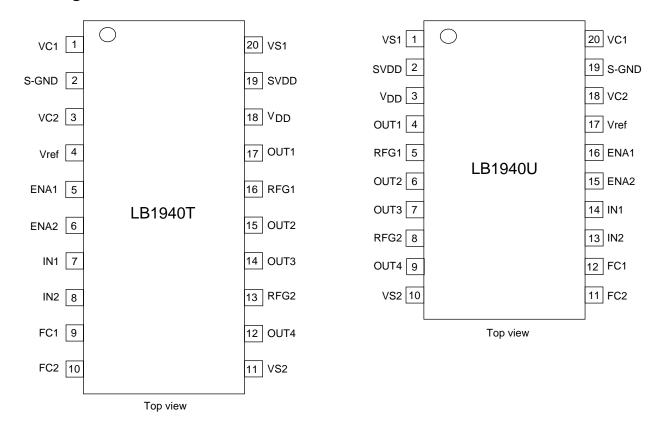


#### **True Table**

Input			Output							
ENA		II	IN		OUT				Mode	
1	2	1	2	1	2	3	4	SVDD		
L	L								Standby (current dissipation zero)	
		Н		L	Н			on	Reverse rotation	
Н	L		Н	L			on	Forward rotation		
н		Η			L	Н	on	Reverse rotation		
		L			Н	L	on	Forward rotation		
A blank means "don't care".		A blank means "off".								

# LB1940T, LB1940U

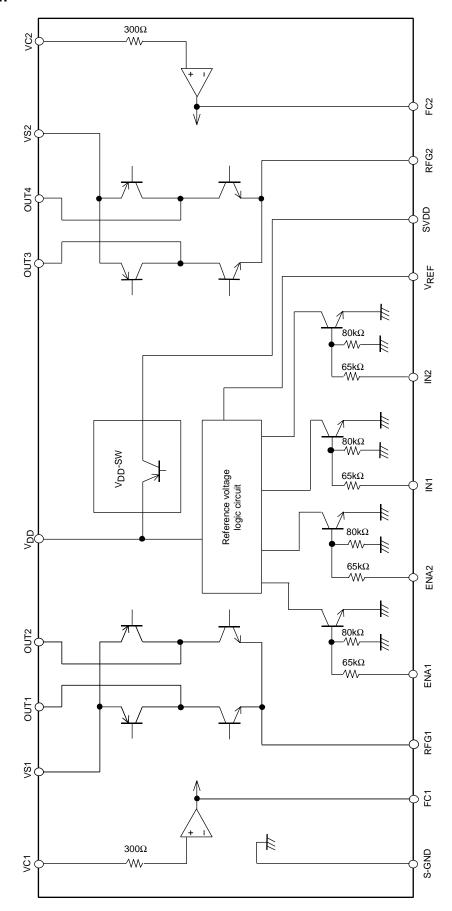
# **Pin Assignment**



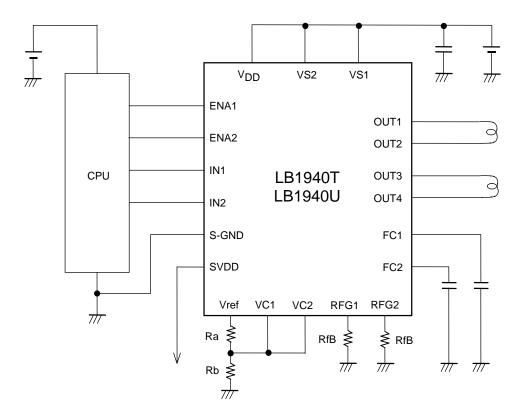
### **Pin Description**

Pin No.		Pin	D i e	Pin No.		Pin	December 1
LB1940T	LB1940U	Name	Description	LB1940T	LB1940U	Name	Description
1	20	VC1	Reference voltage input for 1ch control	11	10	VS2	Motor power supply (+)
2	19	S-GND	GND for control system	12	9	OUT4	Motor drive output 4
3	18	VC2	Reference voltage input for 2ch control	13	8	RFG2	Constant-current detection pin
4	17	Vref	Reference voltage output	14	7	OUT3	Motor drive output 3
5	16	ENA1	Signal input for 1ch control	15	6	OUT2	Motor drive output 2
6	15	ENA2	Signal input for 2ch control	16	5	RFG1	Constant-current detection pin 1
7	14	IN1	Signal input for 1ch control	17	4	OUT1	Motor drive output 1
8	13	IN2	Signal input for 2ch control	18	3	$V_{DD}$	Control system power supply (+)
9	12	FC1	C connection pin for 1ch phase compensation	19	2	SVDD	Control system power output
10	11	FC2	C connection pin for 2ch phase compensation	20	1	VS1	Motor power supply (+)

# **Block Diagram**



#### **Application Circuit Diagram**



At constant-current control: The OUT current is controlled so that the RFG pin voltage is equal to the VC input pin voltage.

For example,  $I_{OUT} = 200 \text{mA}$  (= 0.2V/1 $\Omega$ ) when VC = 0.2V and RFB = 1 $\Omega$ .

\*: There is no priority relationship between respective input voltages (ENA, IN) and respective supply voltages (V<sub>DD</sub>, VS). For example, operation with  $V_{IN} = 5V$ ,  $V_{DD} = 3V$ , VS = 2V is possible.

Note: The input voltage range to the reference voltage input pin VC for constant-current setting is from 0.19V to 1.0V.

#### **Constant current setting**

The composition of the constant-control circuit of this IC is as shown in the figure below.

The voltage entered in the VC pin is entered as a reference to the "+" side input of the constant-current control amplifier.

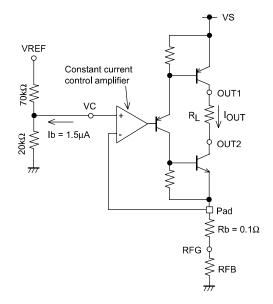
The "-" side of this constant-current control amplifier is connected to the RFG pin via the wire bonded resistor Rb (=  $0.1\Omega$ ).

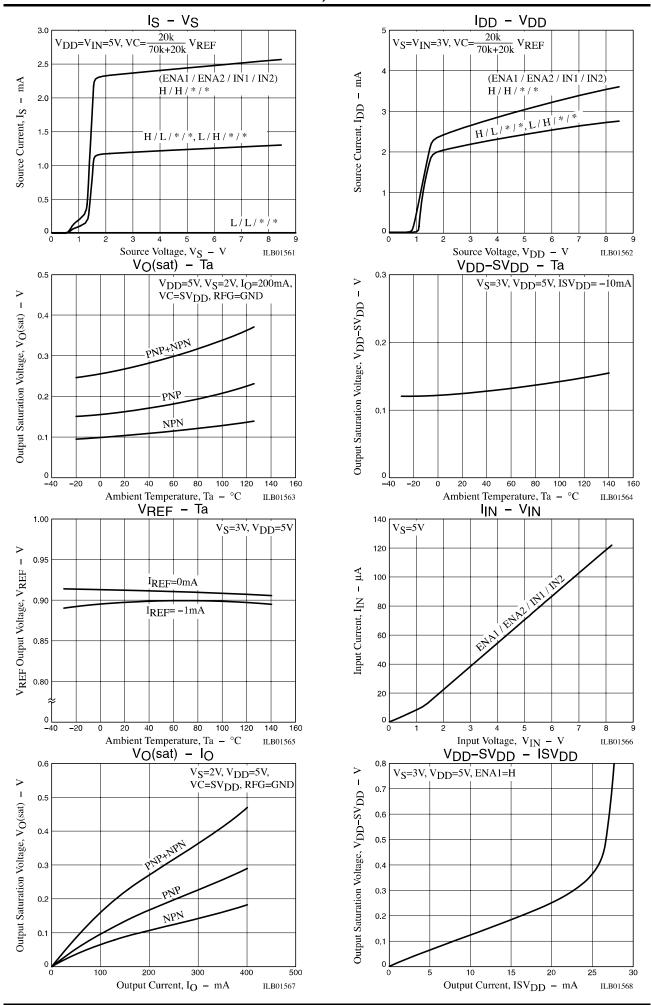
The constant-current control circuit consists of comparison of the voltage generated at the external current detection resistor with the above reference voltage.

In addition, since the bias current Ib (=  $1.5\mu A$ ) flows out of the positive (+) input of the constant current control amplifier during the constant current control, if the voltage is input to the VC pin by dividing the VREF voltage by 4.5 according to the dividing resistance ( $70k\Omega$  and  $20k\Omega$ ) as shown in the figure, the formula for calculating the VC voltage is as follows :

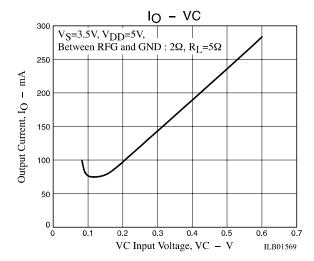
$$VC = VREF/4.5 + Ib \times 20k\Omega = VREF/4.5 + 0.03$$

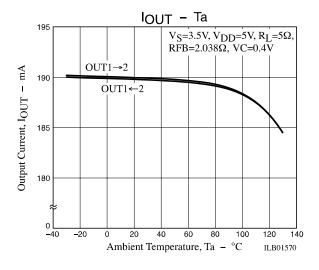
Therefore, the theoretical equation to set the constant current  $I_{OUT}$  is as follows:  $I_{OUT} = VC/(RFB+Rb) = (VREF/4.5+0.03)/(RFB+Rb)$ 





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