K4A4G165WD

Preliminary

4Gb D-die DDR4 SDRAM x16 only

96FBGA with Lead-Free & Halogen-Free (RoHS compliant)



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datasheet

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Revision History

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1. Ordering Information

[Table 1] Samsung 4Gb DDR4 D-die ordering information table

Organization	DDR4-2133 (15-15-15)	DDR4-2400 (17-17-17) ²	Package
256Mx16	K4A4G165WD-BCPB	K4A4G165WD-BCRC	96FBGA

NOTE :

1. Speed bin is in order of CL-tRCD-tRP.

2. Backward compatible to DDR4-2133(15-15-15)

2. Key Features

[Table 2] 4Gb DDR4 D-die Speed bins

Speed	DDR4-1600	DDR4-1866	DDR4-2133	DDR4-2400	Unit
Speed	11-11-11	13-13-13	15-15-15	17-17-17	Unit
tCK(min)	1.25	1.071	0.938	0.833	ns
CAS Latency	11	13	15	17	nCK
tRCD(min)	13.75	13.92	14.06	14.16	ns
tRP(min)	13.75	13.92	14.06	14.16	ns
tRAS(min)	35	34	33	32	ns
tRC(min)	48.75	47.92	47.06	46.16	ns

- JEDEC standard 1.2V (1.14V~1.26V)
- V_{DDQ} = 1.2V (1.14V~1.26V)
- V_{PP} = 2.5V (2.375V~2.75V)
- 800 MHz f_{CK} for 1600Mb/sec/pin,933 MHz f_{CK} for 1866Mb/sec/pin, 1067MHz f_{CK} for 2133Mb/sec/pin, 1200MHz f_{CK} for2400Mb/sec/pin
- 8 Banks (2 Bank Groups)
- Programmable CAS Latency(posted CAS): 10,11,12,13,14,15,16,17,18
- Programmable Additive Latency: 0, CL-2 or CL-1 clock
- Programmable CAS Write Latency (CWL) = 9,11 (DDR4-1600), 10,12 (DDR4-1866) ,11,14 (DDR4-2133) and 12,16 (DDR4-2400)
- 8-bit pre-fetch
- Burst Length: 8 (Interleave without any limit, sequential with starting address "000" only), 4 with tCCD = 4 which does not allow seamless read or write [either On the fly using A12 or MRS]
- Bi-directional Differential Data-Strobe
- Internal(self) calibration : Internal self calibration through ZQ pin (RZQ : 240 ohm ± 1%)
- On Die Termination using ODT pin
- Average Refresh Period 7.8us at lower than $T_{CASE}\,85^{\circ}C,\,3.9us$ at $85^{\circ}C$ < T_{CASE} \leq 95 $^{\circ}C$
- Asynchronous Reset
- Package : 96 balls FBGA x16
- · All of Lead-Free products are compliant for RoHS
- All of products are Halogen-free
- · CRC(Cyclic Redundancy Check) for Read/Write data security
- · Command address parity check
- DBI(Data Bus Inversion)
- Gear down mode
- · POD (Pseudo Open Drain) interface for data input/output
- Internal VREF for data inputs
- External VPP for DRAM Activating Power

NOTE : 1. This data sheet is an abstract of full DDR4 specification and does not cover the common features which are described in "DDR4 SDRAM Device Operation & Timing Diagram".

2. The functionality described and the timing specifications included in this data sheet are for the DLL Enabled mode of operation.

The 4Gb DDR4 SDRAM D-die is organized as a 32Mbit x 16 I/Os x 8banks device. This synchronous device achieves high speed double-data-rate transfer rates of up to 2400Mb/sec/pin (DDR4-2400) for general applications.

The chip is designed to comply with the following key DDR4 SDRAM features such as posted CAS, Programmable CWL, Internal (Self) Calibration, On Die Termination using ODT pin and Asynchronous Reset.

All of the control and address inputs are synchronized with a pair of externally supplied differential clocks. Inputs are latched at the crosspoint of differential clocks (CK rising and \overline{CK} falling). All I/Os are synchronized with a pair of bidirectional strobes (DQS and \overline{DQS}) in a source synchronous fashion. The address bus is used to convey row, column, and bank address information in a $\overline{RAS}/\overline{CAS}$ multiplexing style. The DDR4 device operates with a single 1.2V (1.14V~1.26V) power supply, 1.2V(1.14V~1.26V) V_{DDQ} and 2.5V (2.375V~2.75V) V_{PP}.

The 4Gb DDR4 D-die device is available in 96ball FBGAs(x16).



3. Package pinout/Mechanical Dimension & Addressing

3.1 x16 Package Pinout (Top view) : 96ball FBGA Package

	1	2	3
A	VDDQ	VSSQ	DQU0
в	VPP	VSS	VDD
С	VDDQ	DQU4	DQU2
D	VDD	VSSQ	DQU6
Е	VSS	DMU_n/ DBIU_n	VSSQ
F	VSSQ	VDDQ	DQSL_c
G	VDDQ	DQL0	DQSL_t
Н	VSSQ	DQL4	DQL2
J	VDD	VDDQ	DQL6
к	VSS	CKE	ODT
L	VDD	WE_n/ A14	ACT_n
М	VREFCA	BG0	A10/AP
Ν	VSS	BA0	A4
Ρ	RESET_n	A6	A0
R	VDD	A8	A2
Т	VSS	A11	PAR

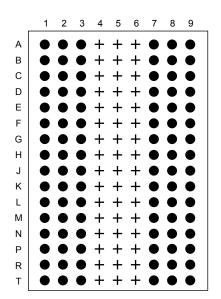
4	4 5 6		7	8	9	
			DQSU_c	VSSQ	VDDQ	Α
			DQSU_t	DQU1	VDD	в
			DQU3	DQU5	VSSQ	С
			DQU7	VSSQ	VDDQ	D
			DML_n DBIL_n	VSSQ	VSS	Е
			DQL1	VDDQ	ZQ	F
			VDD	VSS	VDDQ	G
			DQL3	DQL5	VSSQ	Н
			DQL7	VDDQ	VDD	J
			CK_t	CK_c	VSS	к
			CS_n	RAS_n	VDD	L
			A12/BC_n	CAS_n	VSS	М
			A3	BA1	TEN	Ν
			A1	A5	ALERT_n	Ρ
			A9	A7	VPP	R
			NC	A13	VDD	Т

Ball Locations (x16)

Populated ball

+ Ball not populated

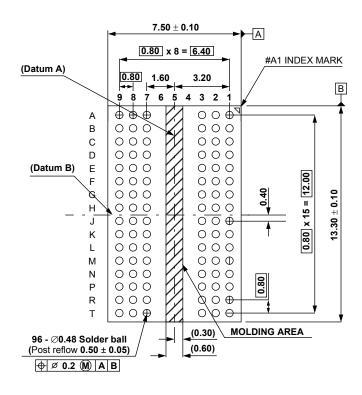
Top view (See the balls through the package)



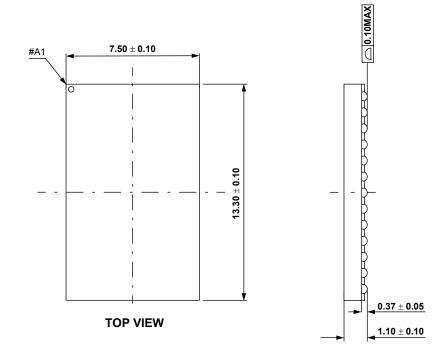


3.2 FBGA Package Dimension (x16)

Units : Millimeters



BOTTOM VIEW





4. Input/Output Functional Description

[Table 3] Input/Output function description

Symbol	Туре	Function
CK_t, CK_c	Input	Clock: CK_t and CK_c are differential clock inputs. All address and control input signals are sampled on the crossing of the positive edge of CK_t and negative edge of CK_c.
CKE	Input	Clock Enable: CKE HIGH activates, and CKE Low deactivates, internal clock signals and device input buffers and output drivers. Taking CKE Low provides Precharge Power-Down and Self-Refresh operation (all banks idle), or Active Power-Down (row Active in any bank). CKE is synchronous for Self-Refresh exit. After VREFCA and Internal DQ Vref have become stable during the power on and initialization sequence, they must be maintained during all operations (including Self-Refresh). CKE must be maintained high throughout read and write accesses. Input buffers, excluding CK_t,CK_c, ODT and CKE are disabled during power-down. Input buffers, excluding CKE, are disabled during Self-Refresh.
CS_n	Input	Chip Select: All commands are masked when CS_n is registered HIGH. CS_n provides for external Rank selection on systems with multiple Ranks. CS_n is considered part of the command code.
ODT	Input	On Die Termination: ODT (registered HIGH) enables RTT_NOM termination resistance internal to the DDR4 SDRAM. When enabled, ODT is only applied to each DQ, DQS_t, DQS_c and DM_n/DBI_n/ TDQS_t, NU/TDQS_c (When TDQS is enabled via Mode Register A11=1 in MR1) signal for x8 configurations. For x16 configuration ODT is applied to each DQ, DQSU_t, DQSU_c, DQSL_t, DQSL_c, DMU_n, and DML_n signal. The ODT pin will be ignored if MR1 is programmed to disable RTT_NOM. Activation Command Input : ACT_n defines the Activation command being entered along with CS_n. The
ACT_n	Input	input into RAS_n, CAS_n/A15 and WE_n/A14 will be considered as Row Address A15, A14
RAS_n, CAS_n/A15, WE_n/A14	Input	Command Inputs: RAS_n, CAS_n/A15 and WE_n/A14 (along with CS_n) define the command being entered. Those pins have multi function. For example, for activation with ACT_n Low, those are Addressing like A15, A14 but for non-activation command with ACT_n High, those are Command pins for Read, Write and other command defined in command truth table
DM_n/DBI_n/TDQS_t, (DMU_n/DBIU_n), (DML_n/DBIL_n)	Input/Output	Input Data Mask and Data Bus Inversion: DM_n is an input mask signal for write data. Input data is masked when DM_n is sampled LOW coincident with that input data during a Write access. DM_n is sampled on both edges of DQS. DM is muxed with DBI function by Mode Register A10,A11,A12 setting in MR5. For x8 device, the function of DM or TDQS is enabled by Mode Register A11 setting in MR1. DBI_n is an input/output identifing whether to store/output the true or inverted data. If DBI_n is LOW, the data will be stored/output after inversion inside the DDR4 SDRAM and not inverted if DBI_n is HIGH. TDQS is only supported in X8
BG0 - BG1	Input	Bank Group Inputs : BG0 - BG1 define to which bank group an Active, Read, Write or Precharge command is being applied. BG0 also determines which mode register is to be accessed during a MRS cycle. X4/8 have BG0 and BG1 but x16 has only BG0
BA0 - BA1	Input	Bank Address Inputs: BA0 - BA1 define to which bank an Active, Read, Write or Precharge command is being applied. Bank address also determines which mode register is to be accessed during a MRS cycle.
A0 - A15	Input	Address Inputs: Provide the row address for ACTIVATE Commands and the column address for Read/ Write commands to select one location out of the memory array in the respective bank. (A10/AP, A12/ BC_n, RAS_n, CAS_n/A15 and WE_n/A14 have additional functions, see other rows.The address inputs also provide the op-code during Mode Register Set commands.
A10 / AP	Input	Auto-precharge: A10 is sampled during Read/Write commands to determine whether Autoprecharge should be performed to the accessed bank after the Read/Write operation. (HIGH: Autoprecharge; LOW: no Autoprecharge).A10 is sampled during a Precharge command to determine whether the Precharge applies to one bank (A10 LOW) or all banks (A10 HIGH). If only one bank is to be precharged, the bank is selected by bank addresses.
A12 / BC_n	Input	Burst Chop: A12 / BC_n is sampled during Read and Write commands to determine if burst chop (on-the-fly) will be performed. (HIGH, no burst chop; LOW: burst chopped). See command truth table for details.
RESET_n	Input	Active Low Asynchronous Reset: Reset is active when RESET_n is LOW, and inactive when RESET_n is HIGH. RESET_n must be HIGH during normal operation. RESET_n is a CMOS rail to rail signal with DC high and low at 80% and 20% of V_{DD} .
DQ	Input / Output	Data Input/ Output: Bi-directional data bus. If CRC is enabled via Mode register then CRC code is added at the end of Data Burst. Any DQ from DQ0~DQ3 may indicate the internal Vref level during test via Mode Register Setting MR4 A4=High. During this mode, RTT value should be set to Hi-Z. Refer to vendor specific datasheets to determine which DQ is used.
DQS_t, DQS_c, DQSU_t, DQSU_c, DQSL_t, DQSL_c	Input / Output	Data Strobe: output with read data, input with write data. Edge-aligned with read data, centered in write data. For the x16, DQSL corresponds to the data on DQL0-DQL7; DQSU corresponds to the data on DQU0-DQU7. The data strobe DQS_t, DQSL_t and DQSU_t are paired with differential signals DQS_c, DQSL_c and DQSU_c, respectively, to provide differential pair signaling to the system during reads and writes. DDR4 SDRAM supports differential data strobe only and does not support single-ended.



Symbol	Туре	Function
TDQS_t, TDQS_c	Output	Termination Data Strobe: TDQS_t/TDQS_c is applicable for x8 DRAMs only. When enabled via Mode Register A11 = 1 in MR1, the DRAM will enable the same termination resistance function on TDQS_t/TDQS_c that is applied to DQS_t/DQS_c. When disabled via mode register A11 = 0 in MR1, DM/DBI/TDQS will provide the data mask function or Data Bus Inversion depending on MR5; A11,12,10and TDQS_c is not used. x4/x16 DRAMs must disable the TDQS function via mode register A11 = 0 in MR1.
PAR	Input	Command and Address Parity Input : DDR4 Supports Even Parity check in DRAMs with MR setting. Once it's enabled via Register in MR5, then DRAM calculates Parity with ACT_n,RAS_n,CAS_n/A15,WE_n/A14,BG0-BG1,BA0-BA1,A15-A0. Input parity should maintain at the rising edge of the clock and at the same time with command & address with CS_n LOW
ALERT_n	Input/Output	Alert : It has multi functions such as CRC error flag , Command and Address Parity error flag as Output signal . If there is error in CRC, then Alert_n goes LOW for the period time interval and goes back HIGH. If there is error in Command Address Parity Check, then Alert_n goes LOW for relatively long period until on going DRAM internal recovery transaction to complete. During Connectivity Test mode, this pin works as input. Using this signal or not is dependent on system. In case of not connected as Signal, ALERT_n Pin must be bounded to VDD on board.
TEN	Input	Connectivity Test Mode Enable : Required on x16 devices and optional input on x4/x8 with densities equal to or greater than 8Gb. HIGH in this pin will enable Connectivity Test Mode operation along with other pins. It is a CMOS rail to rail signal with AC high and low at 80% and 20% of VDD. Using this signal or not is dependent on System. This pin may be DRAM internally pulled low through a weak pull-down resistor to VSS.
NC		No Connect: No internal electrical connection is present.
VDDQ	Supply	DQ Power Supply: 1.2 V +/- 0.06 V
VSSQ	Supply	DQ Ground
VDD	Supply	Power Supply: 1.2 V +/- 0.06 V
VSS	Supply	Ground
VPP	Supply	DRAM Activating Power Supply: 2.5V (2.375V min , 2.75V max)
VREFCA	Supply	Reference voltage for CA
ZQ	Supply	Reference Pin for ZQ calibration

5. DDR4 SDRAM Addressing

2 Gb Addressing Table

Configuration		512 Mb x4	256 Mb x8	128 Mb x16
	# of Bank Groups	4	4	2
Bank Address	BG Address	BG0~BG1	BG0~BG1	BG0
	Bank Address in a BG	BA0~BA1	BA0~BA1	BA0~BA1
Row Address		A0~A14	A0~A13	A0~A13
Column Address		A0~A9	A0~A9	A0~A9
Page size		512B	1KB	2KB

4 Gb Addressing Table

Configuration		1 Gb x4	512 Mb x8	256 Mb x16
	# of Bank Groups	4	4	2
Bank Address	BG Address	BG0~BG1	BG0~BG1	BG0
	Bank Address in a BG	BA0~BA1	BA0~BA1	BA0~BA1
R	ow Address	A0~A15	A0~A14	A0~A14
Column Address		A0~A9	A0~A9	A0~A9
Page size		512B	1KB	2KB

8 Gb Addressing Table

Configuration		2 Gb x4	1 Gb x8	512 Mb x16
	# of Bank Groups	4	4	2
Bank Address	BG Address	BG0~BG1	BG0~BG1	BG0
	Bank Address in a BG	BA0~BA1	BA0~BA1	BA0~BA1
R	ow Address	A0~A16	A0~A15	A0~A15
Column Address		A0~A9	A0~A9	A0~A9
	Page size	512B	1KB	2KB

16 Gb Addressing Table

Configuration		4 Gb x4	2 Gb x8	1 Gb x16
	# of Bank Groups	4	4	2
Bank Address	BG Address	BG0~BG1	BG0~BG1	BG0
	Bank Address in a BG	BA0~BA1	BA0~BA1	BA0~BA1
Row Address		A0~A17	A0~A16	A0~A16
Column Address		A0~A9	A0~A9	A0~A9
	Page size	512B	1KB	2KB

NOTE 1 : Page size is the number of bytes of data delivered from the array to the internal sense amplifiers when an ACTIVE command is registered.

Page size is per bank, calculated as follows: page size = $2^{\text{COLBITS} * \text{ORG}+8}$ where, COLBITS = the number of column address bits, ORG = the number of I/O (DQ) bits



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6. Absolute Maximum Ratings

[Table 4] Absolute Maximum DC Ratings

Symbol	Parameter	Rating	Units	NOTE
VDD	Voltage on VDD pin relative to Vss	-0.3 ~ 1.5	V	1,3
VDDQ	Voltage on VDDQ pin relative to Vss	-0.3 ~ 1.5	V	1,3
VPP	Voltage on VPP pin relative to Vss	-0.3 ~ 3.0	V	4
V _{IN,} V _{OUT}	Voltage on any pin except VREFCA relative to Vss	-0.3 ~ 1.5	V	1,3,5
T _{STG}	Storage Temperature	-55 to +100	°C	1,2

NOTE :

1. Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability

2. Storage Temperature is the case surface temperature on the center/top side of the DRAM. For the measurement conditions, please refer to JESD51-2 standard.

3. VDD and VDDQ must be within 300 mV of each other at all times; and VREFCA must be not greater than 0.6 x VDDQ, When VDD and VDDQ are less than 500 mV; VREFCA may be equal to or less than 300 mV

4. VPP must be equal or greater than VDD/VDDQ at all times.

5. Overshoot area above 1.5 V is specified in section 8.3.4 , 8.3.5 and 8.3.6.

7. AC & DC Operating Conditions

[Table 5] Recommended DC Operating Conditions

Symbol	Parameter	Rating		Unit	NOTE	
Symbol	Falameter	Min.	Тур.	Max.		NOTE
VDD	Supply Voltage	1.14	1.2	1.26	V	1,2,3
VDDQ	Supply Voltage for Output	1.14	1.2	1.26	V	1,2,3
VPP		2.375	2.5	2.75	V	3

NOTE :

1. Under all conditions VDDQ must be less than or equal to VDD.

2. VDDQ tracks with VDD. AC parameters are measured with VDD and VDDQ tied together.

3. DC bandwidth is limited to 20MHz.



8. AC & DC Input Measurement Levels

8.1 AC & DC Logic input levels for single-ended signals

[Table 6] Single-ended AC & DC input levels for Command and Address

Symbol	Parameter	DDR4-1600/18	Unit	NOTE	
Symbol	Farameter	Min.	Max.		NOTE
VIH.CA(DC75)	DC input logic high	VREFCA+ 0.075	Vdd	V	
VIL.CA(DC75)	DC input logic low	Vss	VREFCA-0.075	V	
VIH.CA(AC100)	AC input logic high	Vref + 0.1	Note 2	V	1
VIL.CA(AC100)	AC input logic low	Note 2	Vref - 0.1	V	1
VREFCA(DC)	Reference Voltage for ADD, CMD inputs	0.49*Vdd	0.51*Vdd	V	2,3

NOTE :

1. See "Overshoot and Undershoot Specifications" .

2. The AC peak noise on VREFCA may not allow VREFCA to deviate from VREFCA(DC) by more than ± 1% VDD (for reference : approx. ± 12mV)

3. For reference : approx. VDD/2 ± 12mV

8.2 V_{REF} Tolerances

The dc-tolerance limits and ac-noise limits for the reference voltages V_{REFCA} is illustrated in Figure 1. It shows a valid reference voltage $V_{REF}(t)$ as a function of time. (V_{REF} stands for V_{REFCA} and V_{REFDQ} likewise).

 $V_{REF}(DC)$ is the linear average of $V_{REF}(t)$ over a very long period of time (e.g. 1 sec). This average has to meet the min/max requirement in Table 6 on page 12. Furthermore $V_{REF}(t)$ may temporarily deviate from $V_{REF}(DC)$ by no more than ± 1% V_{DD} .

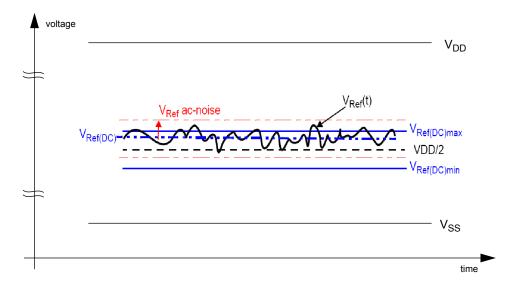


Figure 1. Illustration of $V_{REF}(DC)$ tolerance and VREF ac-noise limits

The voltage levels for setup and hold time measurements $V_{IH}(AC)$, $V_{IH}(DC)$, $V_{IL}(AC)$ and $V_{IL}(DC)$ are dependent on V_{REF} .

"V_{REF}" shall be understood as $V_{REF}(DC),$ as defined in Figure 1 .

This clarifies, that dc-variations of V_{REF} affect the absolute voltage a signal has to reach to achieve a valid high or low level and therefore the time to which setup and hold is measured. System timing and voltage budgets need to account for $V_{REF}(DC)$ deviations from the optimum position within the data-eye of the input signals.

This also clarifies that the DRAM setup/hold specification and derating values need to include time and voltage associated with V_{REF} ac-noise. Timing and voltage effects due to ac-noise on V_{REF} up to the specified limit (+/-1% of V_{DD}) are included in DRAM timings and their associated deratings.



8.3 AC & DC Logic Input Levels for Differential Signals

8.3.1 Differential signals definition

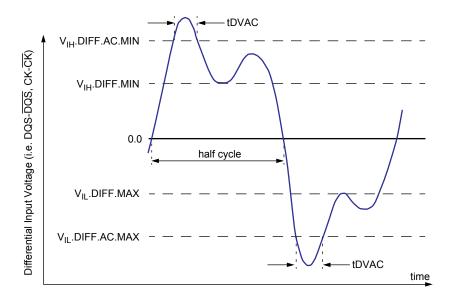


Figure 2. Definition of differential ac-swing and "time above ac level" tDVAC

NOTE :

1. Differential signal rising edge from VIL.DIFF.MAX to VIH.DIFF.MIN must be monotonic slope.

2. Differential signal falling edge from VIH.DIFF.MIN to VIL.DIFF.MAX must be monotonic slope.

8.3.2 Differential swing requirement for clock (CK_t - CK_c)

[Table 7] Differential AC & DC Input Levels

Symbol	Parameter	DDR4 -1600	DDR4	-2400	unit	NOTE	
Symbol	Farameter	min	max	min	max	um	NOTE
V _{IHdiff}	differential input high	+0.150	NOTE 3	TBD	NOTE 3	V	1
V _{ILdiff}	differential input low	NOTE 3	-0.150	NOTE 3	TBD	V	1
V _{IHdiff} (AC)	differential input high ac	2 x (V _{IH} (AC) - V _{REF})	NOTE 3	2 x (V _{IH} (AC) - V _{REF})	NOTE 3	V	2
V _{ILdiff} (AC)	differential input low ac	NOTE 3	$2 \times (V_{IL}(AC) - V_{REF})$	NOTE 3	$2 \times (V_{IL}(AC) - V_{REF})$	V	2

NOTE:

1. Used to define a differential signal slew-rate.

2. for CK_t - CK_c use $V_{IHCA}\!/\!V_{ILCA}(AC)$ of ADD/CMD and $V_{REFCA};$

3. These values are not defined; however, the differential signals CK_t - CK_c, need to be within the respective limits (V_{IHCA}(DC) max, V_{ILCA}(DC)min) for single-ended signals as well as the limitations for overshoot and undershoot.

[Table 8] Allowed time before ringback (tDVAC) for CK_t - CK_c

Slew Rate [V/ns]	tDVAC [ps] @ V _{IF}	_{l/Ldiff} (AC) = 200mV	tDVAC [ps] @ V _{IH/Ldiff} (AC) = TBDmV		
Siew Rate [V/IIS]	min	max	min	max	
> 4.0	120	-	TBD	-	
4.0	115	-	TBD	-	
3.0	110	-	TBD	-	
2.0	105	-	TBD	-	
1.8	100	-	TBD	-	
1.6	95	-	TBD	-	
1.4	90	-	TBD	-	
1.2	85	-	TBD	-	
1.0	80	-	TBD	-	
< 1.0	80	-	TBD	-	



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8.3.3 Single-ended requirements for differential signals

Each individual component of a differential signal (CK_t, CK_c) has also to comply with certain requirements for single-ended signals.

CK_t and CK _c have to approximately reach V_{SEL}min / V_{SEL}max [approximately equal to the ac-levels { V_{IH.CA}(AC) / V_{IL.CA}(AC)} for ADD/CMD signals] in every half-cycle.

Note that the applicable ac-levels for ADD/CMD might be different per speed-bin etc. E.g. if Different value than V_{IH.CA}(AC100)/V_{IL.CA}(AC100) is used for ADD/CMD signals, then these ac-levels apply also for the single-ended signals CK_t and CK_c.

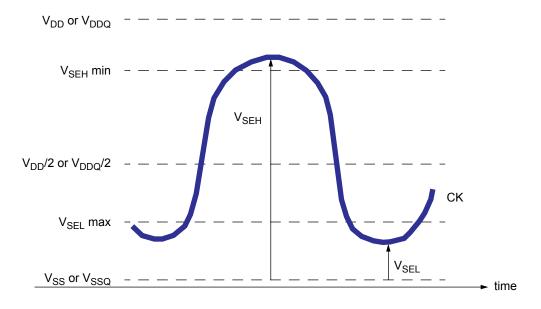


Figure 3. Single-ended requirement for differential signals

Note that while ADD/CMD signal requirements are with respect to V_{REFCA} , the single-ended components of differential signals have a requirement with respect to $V_{DD}/2$; this is nominally the same. The transition of single-ended signals through the ac-levels is used to measure setup time. For single-ended components of differential signals the requirement to reach $V_{SEL}max$, $V_{SEH}min$ has no bearing on timing, but adds a restriction on the common mode characteristics of these signals.

[Table 9] Single-ended levels for CK_t, CK_c

Symbol	Paramotor	DDR4-1600/1866/2133		DDR4-2400			NOTE
Symbol	Symbol Parameter		Max	Min	Max	Unit	NOTE
V _{SEH}	Single-ended high-level for CK_t , CK_c	(VDD/2)+0.100	NOTE3	TBD	NOTE3	V	1, 2
V _{SEL}	Single-ended low-level for CK_t, CK_c	NOTE3	(VDD/2)-0.100	NOTE3	TBD	V	1, 2

NOTE :

1. For $CK_t - CK_c$ use $V_{IH.CA}/V_{IL.CA}(AC)$ of ADD/CMD;

2. V_{IH}(AC)/V_{IL}(AC) for ADD/CMD is based on V_{REFCA};

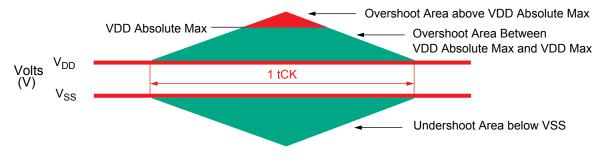
3. These values are not defined, however the single-ended signals CK_t - CK_c need to be within the respective limits (V_{IH.CA}(DC) max, V_{IL.CA}(DC)min) for single-ended signals as well as the limitations for overshoot and undershoot.



8.3.4 Address, Command and Control Overshoot and Undershoot specifications

[Table 10] AC overshoot/undershoot specification for Address, Command and Control pins

Parameter		Unit			
		DDR4-1866	DDR4-2133	DDR4-2400	Unit
Maximum peak amplitude above VDD Absolute Max allowed for overshoot area	0.06	0.06	0.06	0.06	V
Delta value between VDD Absolute Max and VDD Max allowed for overshoot area	0.24	0.24	0.24	0.24	V
Maximum peak amplitude allowed for undershoot area	0.3	0.3	0.3	0.3	V-ns
Maximum overshoot area per 1tCK Above Absolute Max	0.0083	0.0071	0.0062	0.0055	V-ns
Maximum overshoot area per 1tCK Between Absolute Max and VDD Max	0.2550	0.2185	0.1914	0.1699	V-ns
Maximum undershoot area per 1tCK Below VSS	0.2644	0.2265	0.1984	0.1762	V-ns
(A0-A13,BG0-BG1,BA0-BA1,ACT_n,RAS_n,CAS_n/A1	5,WE_n/A14,C	S_n,CKE,OD	T,C2-C0)		





8.3.5 Clock Overshoot and Undershoot Specifications

[Table 11] AC overshoot/undershoot specification for Clock

Parameter		Specification				
	DDR4-1600	DDR4-1866	DDR4-2133	DDR4-2400	Unit	
Maximum peak amplitude above VDD Absolute Max allowed for overshoot area	0.06	0.06	0.06	0.06	V	
Delta value between VDD Absolute Max and VDD Max allowed for overshoot area	0.24	0.24	0.24	0.24	V	
Maximum peak amplitude allowed for undershoot area	0.3	0.3	0.3	0.3	V	
Maximum overshoot area per 1UI Above Absolute Max	0.0038	0.0032	0.0028	0.0025	V-ns	
Maximum overshoot area per 1UI Between Absolute Max and VDD Max	0.1125	0.0964	0.0844	0.0750	V-ns	
Maximum undershoot area per 1UI Below VSS		0.0980	0.0858	0.0762	V-ns	
(CK t. CK c)	•		•			

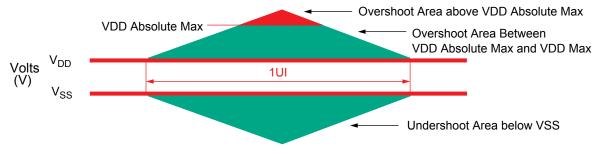


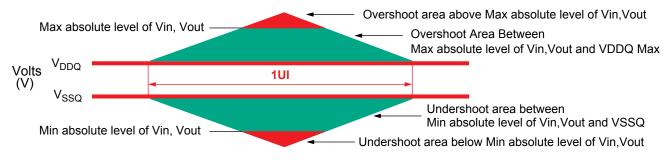
Figure 5. Clock Overshoot and Undershoot Definition

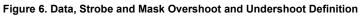
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8.3.6 Data, Strobe and Mask Overshoot and Undershoot Specifications

[Table 12] AC overshoot/undershoot specification for Data, Strobe and Mask

Parameter		Specif	ication		Unit
		DDR4-1866	DDR4-2133	DDR4-2400	Unit
Maximum peak amplitude above Max absolute level of Vin, Vout	0.16	0.16	0.16	0.16	V
Overshoot area Between Max Absolute level of Vin, Vout and VDDQ Max	0.24	0.24	0.24	0.24	V
Undershoot area Between Min absolute level of Vin, Vout and VSSQ	0.30	0.30	0.30	0.30	V
Maximum peak amplitude below Min absolute level of Vin, Vout	0.10	0.10	0.10	0.10	V
Maximum overshoot area per 1UI Above Max absolute level of Vin, Vout	0.0150	0.0129	0.0113	0.0100	V-ns
Maximum overshoot area per 1UI Between Max absolute level of Vin,Vout and VDDQ Max	0.1050	0.0900	0.0788	0.0700	V-ns
Maximum undershoot area per 1UI Between Min absolute level of Vin,Vout and VSSQ	0.1050	0.0900	0.0788	0.0700	V-ns
Maximum undershoot area per 1UI Below Min absolute level of Vin,Vout	0.0150	0.0129	0.0113	0.0100	V-ns
(DQ, DQS_t, DQS_c, DM_n, DBI_n, TI	DQS_t, TDQS	_c)			







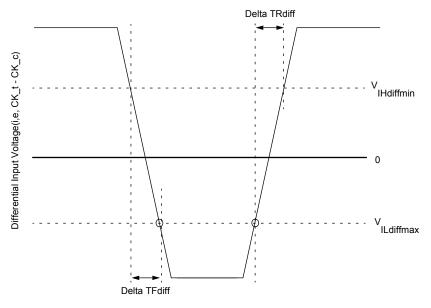
8.4 Slew rate definitions for Differential Input Signals (CK) Input slew rate for differential signals (CK_t, CK_c) are defined and measured as shown in Table 13 and Figure 7.

[Table 13] Differential input slew rate definition

Description	Meas	ured	Defined by
Description	From	То	Denned by
Differential input slew rate for rising edge(CK_t - CK_c)	V ILdiffmax	V IHdiffmin	[^V IHdiffmin - ^V ILdiffmax] / DeltaTRdiff
Differential input slew rate for falling edge(CK_t - CK_c)	V IHdiffmin	V ILdiffmax	^{[V} IHdiffmin - ^V ILdiffmax] / ^{Delta} TFdiff

NOTE :

The differential signal (i.e. CK - CK and DQS - DQS) must be linear between these thresholds.



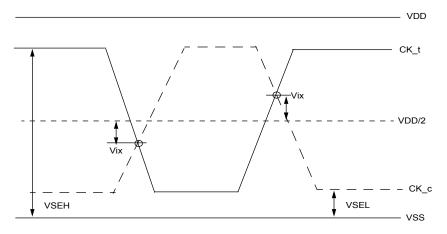




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8.5 Differential Input Cross Point Voltage

To guarantee tight setup and hold times as well as output skew parameters with respect to clock, each cross point voltage of differential input signals (CK_t, CK_c) must meet the requirements in Table 15. The differential input cross point voltage VIX is measured from the actual cross point of true and complement signals to the midlevel between of VDD and VSS.





[Table 14] Cross point voltage for differential input signals (CK)

Symbol	Parameter	DDR4-1600/1866/2133				
Symbol		m	in	max		
-	Area of VSEH, VSEL	VSEL =< VDD/2 - 145mV	VDD/2 - 145mV =< VSEL =< VDD/2 - 100mV	VDD/2 + 100mV =< VSEH =< VDD/2 + 145mV	VDD/2 + 145mV =< VSEH	
VIX(CK)	Differential Input Cross Point Voltage relative to VDD/2 for CK_t, CK_c	-120mV	-(VDD/2 - VSEL) + 25mV	(VSEH - VDD/2) - 25mV	120mV	

Symbol	Parameter		DDR4-2	400	
Symbol	Falametei	min		max	
-	Area of VSEH, VSEL	TBD	TBD	TBD	TBD
VIX(CK)	Differential Input Cross Point Voltage relative to VDD/2 for CK_t, CK_c	TBD	TBD	TBD	TBD



8.6 CMOS rail to rail Input Levels

8.6.1 CMOS rail to rail Input Levels for RESET_n

[Table 15] CMOS rail to rail Input Levels for RESET_n

Parameter	Symbol	Min	Мах	Unit	NOTE
AC Input High Voltage	VIH(AC)_RESET	0.8*VDD	VDD	V	6
DC Input High Voltage	VIH(DC)_RESET	0.7*VDD	VDD	V	2
DC Input Low Voltage	VIL(DC)_RESET	VSS	0.3*VDD	V	1
AC Input Low Voltage	VIL(AC)_RESET	VSS	0.2*VDD	V	7
Rising time	TR_RESET	-	1.0	us	4
RESET pulse width	tPW_RESET	1.0	-	us	3,5

NOTE :

 After RESET_n is registered LOW, RESET_n level shall be maintained below VIL(DC)_RESET during tPW_RESET, otherwise, SDRAM may not be reset.
 Once RESET_n is registered HIGH, RESET_n level must be maintained above VIH(DC)_RESET, otherwise, SDRAM operation will not be guaranteed until it is reset asserting RESET_n signal LOW.

3. RESET is destructive to data contents.

4. No slope reversal(ringback) requirement during its level transition from Low to High.

5. This definition is applied only "Reset Procedure at Power Stable".

- Overshoot might occur. It should be limited by the Absolute Maximum DC Ratings.
 Undershoot might occur. It should be limited by Absolute Maximum DC Ratings

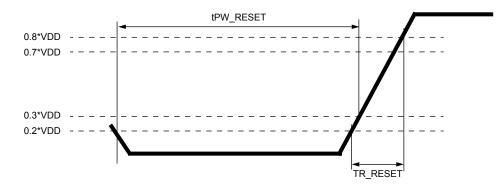


Figure 9. RESET_n Input Slew Rate Definition



8.7 AC and DC Logic Input Levels for DQS Signals

8.7.1 Differential signal definition

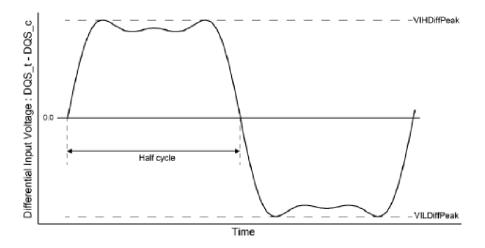


Figure 10. Definition of differential DQS Signal AC-swing Level

8.7.2 Differential swing requirements for DQS (DQS_t - DQS_c)

[Table 16] Differential AC and DC Input Levels for DQS

Symbol	Parameter	DDR4-1600, 1866, 2133		DDR4-2400		Unit	Note
Cymbol	i didificici	Min	Max	Min	Max		11010
VIHDiffPeak	VIH.DIFF.Peak Voltage	186	Note2	TBD	TBD	mV	1
VILDiffPeak	VIL.DIFF.Peak Voltage	Note2	-186	TBD	TBD	mV	1

NOTE :

1.Used to define a differential signal slew-rate.

2. These values are not defined; however, the differential signals DQS_t - DQS_c, need to be within the respective limits Overshoot, Undershoot Specification for single-ended signals.

8.7.3 Peak voltage calculation method

The peak voltage of Differential DQS signals are calculated in a following equation.

VIH.DIFF.Peak Voltage = Max(f(t))

VIL.DIFF.Peak Voltage = Min(f(t))

f(t) = VDQS_t - VDQS_c

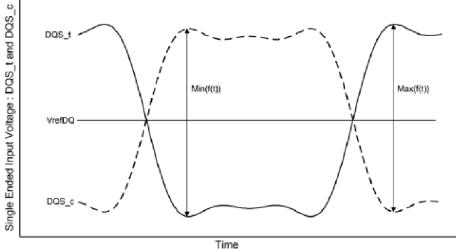
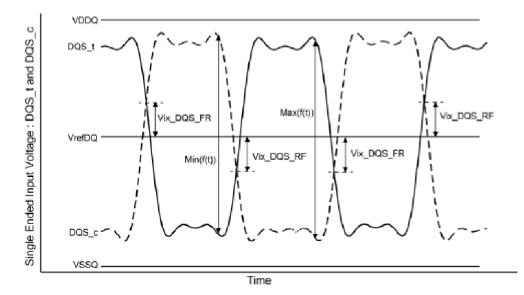


Figure 11. Definition of differential DQS Peak Voltage



8.7.4 Differential Input Cross Point Voltage

To guarantee tight setup and hold times as well as output skew parameters with respect to strobe, the cross point voltage of differential input signals (DQS_t, DQS_c) must meet the requirements in Table 17. The differential input cross point voltage VIX is measured from the actual cross point of true and complement signals to the mid level that is VrefDQ.Vix Definition (DQS)



[Table 17] Cross point voltage for differential input signals (DQS)

Symbol	Symbol Parameter	DDR4-1600	, 1866, 2133	DDR4	-2400	Unit	Note
Cymbol	i didiliotoi	Min	Max	Min	Max		11010
Vix_DQS_ratio	DQS Differential input crosspoint voltage ratio	-	25	-	25	%	1, 2, 3

NOTE :

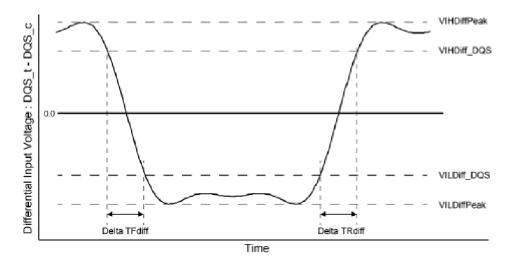
1. The base level of Vix_DQS_FR/RF is VrefDQ that is DDR4 SDRAM internal setting value by Vref Training.

2. Vix_DQS_FR is defined by this equation : Vix_DQS_FR = |Min(f(t)) x Vix_DQS_Ratio|

3. Vix_DQS_RF is defined by this equation : Vix_DQS_RF = Max(f(t)) x Vix_DQS_Ratio

8.7.5 Differential Input Slew Rate Definition

Input slew rate for differential signals (DQS_t, DQS_c) are defined and measured as shown in are DD and Table CC.



NOTE :

1. Differential signal rising edge from VILDiff_DQS to VIHDiff_DQS must be monotonic slope.

2. Differential signal falling edge from VIHDiff_DQS to VILDiff_DQS must be monotonic slope.

Figure 12. Differential Input Slew Rate Definition for DQS_t, DQS_c



[Table 18] Differential Input Slew Rate Definition for DQS_t, DQS_c

Description			Defined by
2000.19.00.	From	То	200025
Differential input slew rate for rising edge(DQS_t - DQS_c)	VILDiff_DQS	VIHDiff_DQS	VILDiff_DQS - VIHDiff_DQS /DeltaTRdiff
Differential input slew rate for falling edge(DQS_t - DQS_c)	VIHDiff_DQS	VILDiff_DQS	VILDiff_DQS - VIHDiff_DQS /DeltaTFdiff

[Table 19] Differential Input Level for DQS_t, DQS_c

Symbol	Symbol Parameter	DDR4-1600	, 1866, 2133	DDR4	-2400	Unit	NOTE
Cymbol		Min	Max	Min	Max		NOTE
VIHDiff_DQS	Differntial Input High	136	-	TBD	TBD	mV	
VILDiff_DQS	Differntial Input Low	-	-136	TBD	TBD	mV	

[Table 20] Differential Input Slew Rate for DQS_t, DQS_c

Symbol	Symbol Parameter	DDR4-1600	, 1866, 2133	DDR4-2400		Unit	NOTE
Cymbol		Min	Max	Min	Max		NOTE
SRIdiff	Differential Intput Slew Rate	TBD	18	TBD	TBD	V/ns	



9. AC and DC output Measurement levels

9.1 Output Driver DC Electrical Characteristics

The DDR4 driver supports two different Ron values. These Ron values are referred as strong(low Ron) and weak mode(high Ron). A functional representation of the output buffer is shown in the figure below. Output driver impedance RON is defined as follows:

The individual pull-up and pull-down resistors (RON_{Pu} and RON_{Pd}) are defined as follows:

 $RON_{Pu} = \frac{VDDQ - Vout}{|I out|}$ $RON_{Pd} = \frac{Vout}{|I out|}$

t_____ t____ under the

under the condition that RONPu is off

under the condition that RONPd is off

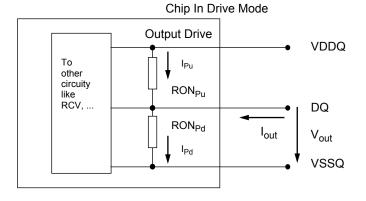


Figure 13. Output driver



[Table 21] Output Driver DC Electrical Characteristics, assuming RZQ=240ohm; entire operating temperature range; after proper ZQ calibration

RON _{NOM}	Resistor	Vout	Min	Nom	Max	Unit	NOTE
		VOLdc= 0.5*VDDQ	0.8	1	1.1	Unit RZQ/7 RZQ/5 RZQ/5 RZQ/5 RZQ/5 RZQ/5 RZQ/5 % % %	1,2
	RON34Pd	VOMdc= 0.8* VDDQ	0.9	1	1.1	RZQ/7	1,2
34Ω		VOHdc= 1.1* VDDQ	0.9	1	1.25	RZQ/7	1,2
3412		VOLdc= 0.5* VDDQ	0.9	1	1.25	RZQ/7	1,2
	RON34Pu	VOMdc= 0.8* VDDQ	0.9	1	1.1	RZQ/7	1,2
		VOHdc= 1.1* VDDQ	0.8	1	1.1	RZQ/7	1,2
		VOLdc= 0.5*VDDQ	0.8	1	1.1	RZQ/5	1,2
	RON48Pd	VOMdc= 0.8* VDDQ	0.9	1	1.1	RZQ/5	1,2
48Ω	RON48Pd	VOHdc= 1.1* VDDQ	0.9	1	1.25	RZQ/5	1,2
4012		VOLdc= 0.5* VDDQ	0.9	1	1.25	RZQ/5	1,2
	RON48Pu	VOMdc= 0.8* VDDQ	0.9	1	1.1	RZQ/5	1,2
		VOHdc= 1.1* VDDQ	0.8	1	1.1	RZQ/5	1,2
	veen pull-up and n, MMPuPd	VOMdc= 0.8* VDDQ	-10	-	10	%	1,2,3,4
	Q within byte vari- ıp, MMPudd	VOMdc= 0.8* VDDQ	-	-	10	%	1,2,4
	Q within byte vari- dn, MMPddd	VOMdc= 0.8* VDDQ	-	-	10	%	1,2,4

NOTE :

1. The tolerance limits are specified after calibration with stable voltage and temperature. For the behavior of the tolerance limits if temperature or voltage changes after calibration, see following section on voltage and temperature sensitivity(TBD).

2. Pull-up and pull-dn output driver impedances are recommended to be calibrated at 0.8 * VDDQ. Other calibration schemes may be used to achieve the linearity spec shown above, e.g. calibration at 0.5 * VDDQ and 1.1 * VDDQ.

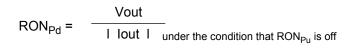
3. Measurement definition for mismatch between pull-up and pull-down, MMPuPd : Measure RONPu and RONPD both at 0.8*VDD separately; Ronnom is the nominal Ron value

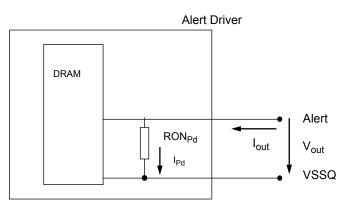
	RONPu -RONPd
MMF	PuPd = *100
4. RON variance range ratio to RON Nominal value in a g	iven component, including DQS_t and DQS_c.
	RONPuMax -RONPuMin
MMF	Pudd =*100
	RONPdMax -RONPdMin
MMF	Pddd = *100
5. This parameter of x16 device is specified for Uper byte	and Lower byte.



9.1.1 Alert_n output Drive Characteristic

A functional representation of the output buffer is shown in the figure below. Output driver impedance RON is defined as follows:





RON _{NOM}	Resistor	Vout	Min	Nom	Мах	Unit	NOTE
		VOLdc= 0.1* VDDQ	0.6	1	1.2	34Ω	1
34Ω	RON _{34Pd}	V _{OMdc} = 0.8* VDDQ	0.8	1	1.2	34Ω	1
		V _{OHdc} = 1.1* VDDQ	0.8	1	1.4	34Ω	1

NOTE :

1. VDDQ voltage is at VDDQ DC. VDDQ DC definition is TBD.

9.1.2 Output Driver Characteristic of Connectivity Test (CT) Mode

Following Output driver impedance RON will be applied Test Output Pin during Connectivity Test (CT) Mode. The individual pull-up and pull-down resistors (RONPu_CT and RONPd_CT) are defined as follows:

 $RON_{Pu_CT} = \frac{V_{DDQ} V_{OUT}}{I \text{ lout I}}$ $RON_{Pd_CT} = \frac{V_{OUT}}{I \text{ lout I}}$

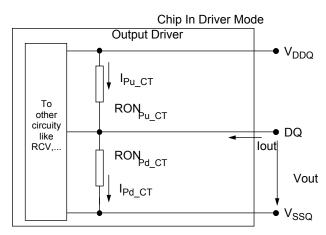


Figure 14. Output Driver



RON _{NOM_CT}	Resistor	Vout	Max	Units	NOTE
		$VOB_{dc} = 0.2 \times V_{DDQ}$	1.9	34Ω	1
	PON	$VOL_{dc} = 0.5 \times V_{DDQ}$	1.1	34Ω	1
	RON _{Pd_CT}	$VOM_{dc} = 0.8 \times V_{DDQ}$	2.2	34Ω	1
34Ω		VOH _{dc} = 1.1 x V _{DDQ}	2.5	34Ω	1
3412		$VOB_{dc} = 0.2 \times V_{DDQ}$	2.5	34Ω	1
	RON	$VOL_{dc} = 0.5 \times V_{DDQ}$	2.2	34Ω	1
	RON _{Pu_CT} -	$VOM_{dc} = 0.8 \times V_{DDQ}$	2.0	34Ω	1
		VOH _{dc} = 1.1 x V _{DDQ}	1.9	34Ω	1

NOTE :

1. Connectivity test mode uses un-calibrated drivers, showing the full range over PVT. No mismatch between pull up and pull down is defined.

9.2 Single-ended AC & DC Output Levels

[Table 22] Single-ended AC & DC output levels

Symbol	Parameter	DDR4-1600/1866/2133/2400	Units	NOTE
V _{OH} (DC)	DC output high measurement level (for IV curve linearity)	1.1 x V _{DDQ}	V	
V _{OM} (DC)	DC output mid measurement level (for IV curve linearity)	0.8 x V _{DDQ}	V	
V _{OL} (DC)	DC output low measurement level (for IV curve linearity)	0.5 x V _{DDQ}	V	
V _{OH} (AC)	AC output high measurement level (for output SR)	(0.7 + 0.15) x V _{DDQ}	V	1
V _{OL} (AC)	AC output low measurement level (for output SR)	(0.7 - 0.15) x V _{DDQ}	V	1

NOTE :

1. The swing of \pm 0.15 × V_{DDQ} is based on approximately 50% of the static single-ended output peak-to-peak swing with a driver impedance of RZQ/7 Ω and an effective test load of 50 Ω to V_{TT} = V_{DDQ}.

9.3 Differential AC & DC Output Levels

[Table 23] Differential AC & DC output levels

Symbol	Parameter	DDR4-1600/1866/2133/2400	Units	NOTE
V _{OHdiff} (AC)	AC differential output high measurement level (for output SR)	+0.3 x V _{DDQ}	V	1
V _{OLdiff} (AC)	AC differential output low measurement level (for output SR)	-0.3 x V _{DDQ}	V	1

NOTE :

1. The swing of ± 0.3 × V_{DDQ} is based on approximately 50% of the static differential output peak-to-peak swing with a driver impedance of RZQ/7 Ω and an effective test load of 50 Ω to V_{TT} = V_{DDQ} at each of the differential outputs.



9.4 Single-ended Output Slew Rate

With the reference load for timing measurements, output slew rate for falling and rising edges is defined and measured between V_{OL(AC)} and V_{OH(AC)} for single ended signals as shown in Table 24 and Figure 15.

[Table 24] Single-ended output slew rate definition

Description	Meas	ured	Defined by
Description	From	То	Defined by
Single ended output slew rate for rising edge	V _{OL} (AC)	V _{OH} (AC)	[V _{OH} (AC)-V _{OL} (AC)] / Delta TRse
Single ended output slew rate for falling edge	V _{OH} (AC)	V _{OL} (AC)	[V _{OH} (AC)-V _{OL} (AC)] / Delta TFse

NOTE :

1. Output slew rate is verified by design and characterization, and may not be subject to production test.

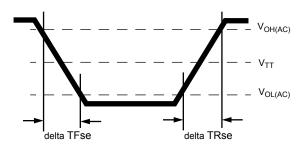


Figure 15. Single-ended Output Slew Rate Definition

[Table 25] Single-ended output slew rate

Parameter	Symbol	DDR4	-1600	DDR4	-1866	DDR4	-2133	DDR4	-2400	Units
	Symbol	Min	Мах	Min	Мах	Min	Мах	Min	Мах	Units
Single ended output slew rate	SRQse	4	9	4	9	4	9	4	9	V/ns

Description: SR: Slew Rate

Q: Query Output (like in DQ, which stands for Data-in, Query-Output)

se: Single-ended Signals

For Ron = RZQ/7 setting

NOTE :

-Case 1 is defined for a single DQ signal within a byte lane which is switching into a certain direction (either from high to low or low to high) while all remaining DQ signals in the same byte lane are static (i.e. they stay at either high or low).

-Case 2 is defined for a single DQ signal within a byte lane which is switching into a certain direction (either from high to low or low to high) while all remaining DQ signals in the same byte lane are switching into the opposite direction (i.e. from low to high or high to low respectively). For the remaining DQ signal switching into the opposite direction, the regular maximum limit of 9 V/ns applies



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9.5 Differential Output Slew Rate

With the reference load for timing measurements, output slew rate for falling and rising edges is defined and measured between VOLdiff(AC) and VOHdiff(AC) for differential signals as shown in Table 26 and Figure 16.

[Table 26] Differential output slew rate definition

Description	Meas	ured	Defined by
Description	From	То	Defined by
Differential output slew rate for rising edge	V _{OLdiff} (AC)	V _{OHdiff} (AC)	[V _{OHdiff} (AC)-V _{OLdiff} (AC)] / Delta TRdiff
Differential output slew rate for falling edge	V _{OHdiff} (AC)	V _{OLdiff} (AC)	[V _{OHdiff} (AC)-V _{OLdiff} (AC)] /Delta TFdiff

NOTE :

1. Output slew rate is verified by design and characterization, and may not be subject to production test.

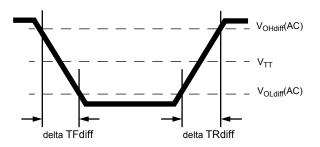


Figure 16. Differential Output Slew Rate Definition

[Table 27] Differential output slew rate

Parameter	Symbol	DDR4	-1600	DDR4	-1866	DDR4	-2133	DDR4	-2400	Units
	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Units
Differential output slew rate	SRQdiff	8	18	8	18	8	18	8	18	V/ns

Description: SR: Slew Rate

Q: Query Output (like in DQ, which stands for Data-in, Query-Output) diff: Differential Signals

For Ron = RZQ/7 setting



9.6 Single-ended AC & DC Output Levels of Connectivity Test Mode

Following output parameters will be applied for DDR4 SDRAM Output Signal during Connectivity Test Mode.

[Table 28] Single-ended AC & DC output levels of Connectivity Test Mode

Symbol	Parameter	DDR4-1600/1866/2133 /2400	Unit	Notes
V _{OH(DC)}	DC output high measurement level (for IV curve linearity)	1.1 x VDDQ	V	
V _{OM(DC)}	DC output mid measurement level (for IV curve linearity)	0.8 x VDDQ	V	
V _{OL(DC)}	DC output low measurement level (for IV curve linearity)	0.5 x VDDQ	V	
V _{OB(DC)}	DC output below measurement level (for IV curve linearity)	0.2 x VDDQ	V	
V _{OH(AC)}	AC output high measurement level (for output SR)	VTT + (0.1 x VDDQ)	V	1
V _{OL(AC)}	AC output below measurement level (for output SR)	VTT - (0.1 x VDDQ)	V	1

NOTE

1. The effective test load is 50Ω terminated by VTT = 0.5 * VDDQ.

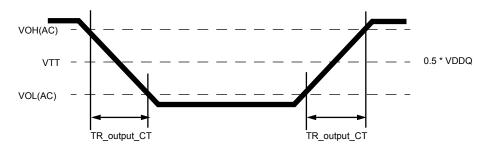


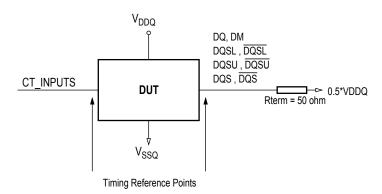
Figure 17. Output Slew Rate Definition of Connectivity Test Mode

[Table 29] Single-ended output slew rate of Connectivity Test Mode

Parameter	Symbol	DDR4-1600/18	366/2133/2400	Unit	Notes
	Symbol	Min	Мах	Unit	Notes
Output signal Falling time	TF_output_CT	-	10	ns/V	
Output signal Rising time	TR_output_CT	-	10	ns/V	

9.7 Test Load for Connectivity Test Mode Timing

The reference load for ODT timings is defined in Figure 18.







10. Speed Bin

[Table 30] DDR4-1600 Speed Bins and Operations

	Spe	ed Bin		DDR4	-1600		
	CL-nR	CD-nRP		11-11-11			NOTE
	Parameter			min	max		
Inte	rnal read command to f	first data	tAA	13.75	18.00	ns	10
Internal read co	ommand to first data wit	h read DBI enabled	tAA_DBI	tAA(min) + 2nCK	tAA(max) +2nCK	ns	10
ACT t	o internal read or write	delay time	tRCD	13.75	-	ns	10
	PRE command perio	od	tRP	13.75	-	ns	10
ACT to PRE command period		tRAS	35	9 x tREFI	ns	10	
ACT	to ACT or REF comma	nd period	tRC	48.75	-	ns	10
	Normal	Read DBI		•	•		
CWL = 9	CL = 9	CL = 11	tCK(AVG)	Rese	rved	ns	1,2,3,4,9
CVVL - 9	CL = 10	CL = 12	tCK(AVG)	1.5	1.6	ns	1,2,3,4,9
	CL = 10	CL = 12	tCK(AVG)	Rese	rved	ns	1,2,3,4
CWL = 9,11	CL = 11	CL = 13	tCK(AVG)	1.25	<1.5	ns	1,2,3,4
	CL = 12	CL = 14	tCK(AVG)	1.25	<1.5	ns	1,2,3
Supported CL Settings				10,11,12		nCK	11
	Supported CL Se	ttings with read DBI		12,13	12,13,14		11
	Supported	CWL Settings		9,1	1	nCK	

[Table 31] DDR4-1866 Speed Bins and Operations

	Spee	ed Bin		DDR4-	1866		
	CL-nR	CD-nRP	13-13-13			Unit	NOTE
	Parameter		Symbol	min	min max		
Interna	Internal read command to first data		tAA	13.92	18.00	ns	10
Internal read comm	nand to first data wit	h read DBI enabled	tAA_DBI	tAA(min) + 2nCK	tAA(max) +2nCK	ns	10
ACT to in	ternal read or write	delay time	tRCD	13.92	-	ns	10
F	PRE command peric	od	tRP	13.92	-	ns	10
ACT	to PRE command p	period	tRAS	34	9 x tREFI	ns	10
ACT to A	ACT to ACT or REF command period		tRC	47.92 -		ns	10
	Normal	Read DBI				•	•
CWL = 9	CL = 9	CL = 11	tCK(AVG)	Reserved		ns	1,2,3,4,9
CWL - 9	CL = 10	CL = 12	tCK(AVG)	1.5	1.6	ns	1,2,3,4,9
	CL = 10	CL = 12	tCK(AVG)	Reser	ved	ns	4
CWL = 9,11	CL = 11	CL = 13	tCK(AVG)	1.25	<1.5	ns	1,2,3,4,6
	CL = 12	CL = 14	tCK(AVG)	1.25	<1.5	ns	1,2,3,6
	CL = 12	CL = 14	tCK(AVG)	Reser	ved	ns	1,2,3,4
CWL = 10,12	CL = 13	CL = 15	tCK(AVG)	1.071	<1.25	ns	1,2,3,4
	CL = 14	CL = 16	tCK(AVG)	1.071	<1.25	ns	1,2,3
Supported CL Settings				10,11,12,13,14,15,16		nCK	11
	Supported CL Set	ttings with read DBI		12,13,14,15	nCK	11	
	Supported (CWL Settings		9,10,1	1,12	nCK	



[Table 32] DDR4-2133 Speed Bins and Operations

	Spee	d Bin		DDR4	-2133		
	CL-nR0	CD-nRP		15-15-15			NOTE
	Parameter		Symbol	min	max		
Internal read command to first data		tAA	14.06 (13.75) ⁵	18.00	ns	10	
Internal read command to first data with read DBI enabled		tAA_DBI	tAA(min) + 3nCK	tAA(max) + 3nCK	ns	10	
ACT to inter	rnal read or write	e delay time	tRCD	14.06 (13.75) ⁵	-	ns	10
PR	E command per	iod	tRP	14.06 (13.75) ⁵	-	ns	10
ACT to	ACT to PRE command period		tRAS 33 9 x tREFI		ns	10	
ACT to ACT or REF command period		and period	tRC	47.06 (46.75) ⁵	-	ns	10
	Normal	Read DBI					
CWL = 9	CL = 9	CL = 11	tCK(AVG)	Rese	rved	ns	1,2,3,4,9
CVVL = 9	CL = 10	CL = 12	tCK(AVG)	1.5	1.6	ns	1,2,3,9
CWL = 9,11	CL = 11	CL = 13	tCK(AVG)	1.25	<1.5	ns	1,2,3,4,7
CVVL = 9,11	CL = 12	CL = 14	tCK(AVG)	1.25	<1.5	ns	1,2,3,7
CWL = 10,12	CL = 13	CL = 15	tCK(AVG)	1.071	<1.25	ns	1,2,3,4,7
CVVL = 10,12	CL = 14	CL = 16	tCK(AVG)	1.071	<1.25	ns	1,2,3,7
	CL = 14	CL = 17	tCK(AVG)	Rese	rved	ns	1,2,3,4
CWL = 11,14	CL = 15	CL = 18	tCK(AVG)	0.938	<1.071	ns	1,2,3,4
Ī	CL = 16	CL = 19	tCK(AVG)	0.938	<1.071	ns	1,2,3
ļ	Supported	CL Settings		10,11.12,13,14,15,16			11
Sı	pported CL Sett	tings with read DB	I	12,13,14,15,16,18,19		nCK	
	Supported C	WL Settings		9,10,11	,12,14	nCK	



[Table 33] DDR4-2400 Speed Bins and Operations

	Spee	ed Bin		DDR4-	2400		NOTE
	CL-nR	CD-nRP		17-17	-17	Unit	
	Parameter		Symbol	min	max		
Internal re	ead command to	o first data	tAA	14.16 (13.75) ⁵ 18.00		ns	10
Internal read command to first data with read DBI enabled		tAA_DBI	tAA(min) + 3nCK	tAA(max) + 3nCK	ns	10	
ACT to inte	rnal read or write	e delay time	tRCD	14.16 (13.75) ⁵	-	ns	10
PR	E command per	riod	tRP	14.16 (13.75) ⁵	-	ns	10
ACT to	PRE command	l period	tRAS	32	9 x tREFI	ns	10
ACT to ACT or REF command period		tRC	46.16 (45.75) ⁵	-	ns	10	
	Normal	Read DBI	L. L				
CWL = 9	CL = 9	CL = 11	tCK(AVG)	Reserved		ns	1,2,3,4,9
CVVL = 9	CL = 10	CL = 12	tCK(AVG)	1.5	1.6	ns	1,2,3,4,9
	CL = 10	CL = 12	tCK(AVG)	Reser	ved	ns	4
CWL = 9,11	CL = 11	CL = 13	tCK(AVG)	1.25	<1.5	ns	1,2,3,4,8
	CL = 12	CL = 14	tCK(AVG)	1.25	<1.5	ns	1,2,3,8
	CL = 12	CL = 14	tCK(AVG)	Reser	ved	ns	4
CWL = 10,12	CL = 13	CL = 15	tCK(AVG)	1.071	<1.25	ns	1,2,3,4,8
	CL = 14	CL = 16	tCK(AVG)	1.071	<1.25	ns	1,2,3,8
	CL = 14	CL = 17	tCK(AVG)	Reser	ved	ns	4
CWL = 11,14	CL = 15	CL = 18	tCK(AVG)	0.938	<1.071	ns	1,2,3,4,8
	CL = 16	CL = 19	tCK(AVG)	0.938	<1.071	ns	1,2,3,8
	CL = 15	CL = 18	tCK(AVG)	Reser	ved	ns	1,2,3,4
CWL = 12,16	CL = 16	CL = 19	tCK(AVG)	Reser	ved	ns	1,2,3,4
UVVL - 12,10	CL = 17	CL = 20	tCK(AVG)	0.833	<0.938		
Ī	CL = 18	CL = 21	tCK(AVG)	0.833	<0.938	ns	1,2,3
·	Supported	CL Settings		10,11,12,13,14,15,16,17,18		nCK	11
Su	upported CL Set	tings with read DB	1	12,13,14,15,16,18,19,20,21		nCK	
	Supported 0	CWL Settings		9,10,11,12,14,16			



10.1 Speed Bin Table Note

Absolute Specification

- VDDQ = VDD = 1.20V +/- 0.06 V
- VPP = 2.5V +0.25/-0.125 V
- The values defined with above-mentioned table are DLL ON case.
- DDR4-1600, 1866, 2133 and 2400 Speed Bin Tables are valid only when Geardown Mode is disabled.
- 1. The CL setting and CWL setting result in tCK(avg).MIN and tCK(avg).MAX requirements. When making a selection of tCK(avg), both need to be fulfilled: Requirements from
- CL setting as well as requirements from CWL setting.
 tCK(avg).MIN limits: Since CAS Latency is not purely analog data and strobe output are synchronized by the DLL all possible intermediate frequencies may not be guaranteed. An application should use the next smaller JEDEC standard tCK(avg) value (1.5, 1.25, 1.071, 0.938 or 0.833 ns) when calculating CL [nCK] = tAA [ns] / tCK(avg).Ins], rounding up to the next 'Supported CL', where tAA = 12.5ns and tCK(avg) = 1.3 ns should only be used for CL = 10 calculation.
 CK(avg).MAX limits: Calculate tCK(avg) = tAA.MAX / CL SELECTED and round the resulting tCK(avg) down to the next valid speed bin (i.e. 1.5ns or 1.25ns or 1.071 ns or 1
- 0.938 ns or 0.833 ns). This result is tCK(avg).MAX corresponding to CL SELECTED.
- 4. 'Reserved' settings are not allowed. User must program a different value.
 5. Programmed 13.75ns on the DIMM SPD to be backward compatible to the lower frequency. The system operates clock cycle is calculated by dividing tAA, tRCD, tRP(in ns) by tCK(in ns) and rounding up to the next integer. tRC = 13.75ns + tRAS
- 6. Any DDR4-1866 speed bin also supports functional operation at lower frequencies as shown in the table which are not subject to Production Tests but verified by Design/ Characterization.
- 7. Any DDR4-2133 speed bin also supports functional operation at lower frequencies as shown in the table which are not subject to Production Tests but verified by Design/ Characterization
- 8. Any DDR4-2400 speed bin also supports functional operation at lower frequencies as shown in the table which are not subject to Production Tests but verified by Design/ Characterization.
- 9. DDR4-1600 AC timing apply if DRAM operates at lower than 1600 MT/s data rate. 10. Parameters apply from tCK(avg)min to tCK(avg)max at all standard JEDEC clock period values as stated in the Speed Bin Tables.
- 11. CL number in parentheses, it means that these numbers are optional.



11. IDD and IDDQ Specification Parameters and Test conditions

11.1 IDD, IPP and IDDQ Measurement Conditions

In this chapter, IDD, IPP and IDDQ measurement conditions such as test load and patterns are defined. Figure 19 shows the setup and test load for IDD, IPP and IDDQ measurements.

- I IDD currents (such as IDD0, IDD0A, IDD1, IDD1A, IDD2N, IDD2NA, IDD2NL, IDD2NT, IDD2P, IDD2Q, IDD3N, IDD3NA, IDD3P, IDD4R, IDD4RA, IDD4W, IDD4WA, IDD5B, IDD5F2, IDD5F4, IDD6N, IDD6E, IDD6R, IDD6A, IDD7 and IDD8) are measured as time-averaged currents with all VDD balls of the DDR4 SDRAM under test tied together. Any IPP or IDDQ current is not included in IDD currents.
- I IPP currents have the same definition as IDD except that the current on the VPP supply is measured.
- I IDDQ currents (such as IDDQ2NT and IDDQ4R) are measured as time-averaged currents with all VDDQ balls of the DDR4 SDRAM under test tied together. Any IDD current is not included in IDDQ currents.

Attention: IDDQ values cannot be directly used to calculate IO power of the DDR4 SDRAM. They can be used to support correlation of simulated IO power to actual IO power as outlined in Figure 20. In DRAM module application, IDDQ cannot be measured separately since VDD and VDDQ are using one merged-power layer in Module PCB.

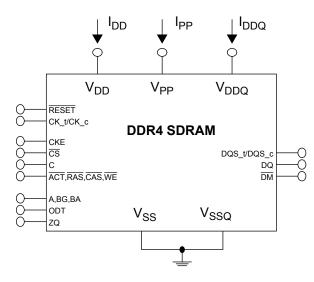
For IDD, IPP and IDDQ measurements, the following definitions apply:

- I "0" and "LOW" is defined as VIN <= VILAC(max).
- I "1" and "HIGH" is defined as VIN >= VIHAC(min).
- "MID-LEVEL" is defined as inputs are VREF = VDD / 2.
- I Timings used for IDD, IPP and IDDQ Measurement-Loop Patterns are provided in Table 34.
- I Basic IDD, IPP and IDDQ Measurement Conditions are described in Table 35.
- I Detailed IDD, IPP and IDDQ Measurement-Loop Patterns are described in Table 36 through Table 44.
- I IDD Measurements are done after properly initializing the DDR4 SDRAM. This includes but is not limited to setting

RON = RZQ/7 (34 Ohm in MR1); RTT_NOM = RZQ/6 (40 Ohm in MR1); RTT_WR = RZQ/2 (120 Ohm in MR2); RTT_PARK = Disable; Qoff = 0_B (Output Buffer enabled) in MR1; TDQS_t disabled in MR1; CRC disabled in MR2; CA parity feature disabled in MR5; Gear down mode disabled in MR3 Read/Write DBI disabled in MR5; DM disabled in MR5

- Attention: The IDD, IPP and IDDQ Measurement-Loop Patterns need to be executed at least one time before actual IDD or IDDQ measurement is started.
- I Define D = {CS_n, ACT_n, RAS_n, CAS_n, WE_n } := {HIGH, LOW, LOW, LOW, LOW}
- I Define D# = {CS_n, ACT_n, RAS_n, CAS_n, WE_n } := {HIGH, HIGH, HIGH, HIGH, HIGH,





NOTE:

1. DIMM level Output test load condition may be different from above

Figure 19. Measurement Setup and Test Load for IDD, IPP and IDDQ Measurements

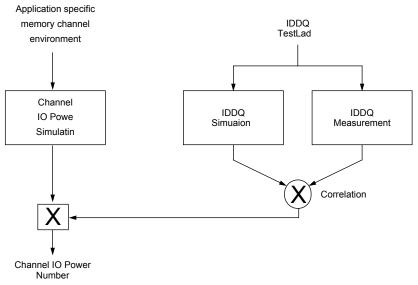


Figure 20. Correlation from simulated Channel IO Power to actual Channel IO Power supported by IDDQ Measurement.



[Table 34] Timings used for IDD, IPP and IDDQ Measurement-Loop Patterns

Symbol		DDR4-1600	DDR4-1866	DDR4-2133	DDR4-2400	Unit
Symbol		11-11-11	13-13-13	15-15-15	17-17-17	Unit
tCK		1.25	1.071	0.938	0.833	ns
CL		11	13	15	17	nCK
CWL		11	12	14	16	nCK
nRCD		11	13	15	17	nCK
nRC		39	45	51	56	nCK
nRAS		28	32	36	39	nCK
nRP		11	13	15	17	nCK
	x4	16	16	16	16	nCK
nFAW	x8	20	22	23	26	nCK
	x16	28	28	32	36	nCK
	x4	4	4	4	4	nCK
nRRDS	x8	4	4	4	4	nCK
	x16	5	5	6	7	nCK
	x4	5	5	6	6	nCK
nRRDL	x8	5	5	6	6	nCK
	x16	6	6	7	8	nCK
tCCD_S		4	4	4	4	nCK
tCCD_L		5	5	6	6	nCK
tWTR_S		2	3	3	3	nCK
tWTR_L		6	7	8	9	nCK
nRFC 2Gb		128	150	171	193	nCK
nRFC 4Gb		208	243	278	313	nCK
nRFC 8Gb		280	327	374	421	nCK
nRFC 16Gb		TBD	TBD	TBD	TBD	nCK
TBD						nCK



[Table 35] Basic IDD, IPP and IDDQ Measurement Conditions

Symbol	Description
	Operating One Bank Active-Precharge Current (AL=0)
IDD0	CKE: High; External clock: On; tCK, nRC, nRAS, CL : see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: High between ACT and PRE; Command, Address, Bank Group Address, Bank Address Inputs: partially toggling according to Table 36 on page 40; Data IO: VDDQ; DM_n: stable at 1; Bank Activity: Cycling with one bank active at a time: 0,0,1,1,2,2, (see Table 36 on page 40); Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0; Pattern Details: see Table 36 on page 40
IDD0A	Operating One Bank Active-Precharge Current (AL=CL-1) AL = CL-1, Other conditions: see IDD0
IPP0	Operating One Bank Active-Precharge IPP Current Same condition with IDD0
IDD1	Operating One Bank Active-Read-Precharge Current (AL=0) CKE: High; External clock: On; tCK, nRC, nRAS, nRCD, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: High between ACT, RD and PRE; Command, Address, Bank Group Address, Bank Address Inputs, Data IO: partially toggling according to Table 37 on page 41; DM_n: stable at 1; Bank Activity: Cycling with one bank active at a time: 0,0,1,1,2,2, (see Table 37 on page 41); Output Buf- fer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0; Pattern Details: see Table 37 on page 41
IDD1A	Operating One Bank Active-Read-Precharge Current (AL=CL-1) AL = CL-1, Other conditions: see IDD1
IPP1	Operating One Bank Active-Read-Precharge IPP Current Same condition with IDD1
IDD2N	Precharge Standby Current (AL=0) CKE: High; External clock: On; tCK, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: stable at 1; Command, Address, Bank Group Address, Bank Address Inputs: partially toggling according to Table 38 on page 42; Data IO: VDDQ; DM_n: stable at 1; Bank Activity: all banks closed; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0; Pattern Details: see Table 38 on page 42
IDD2NA	Precharge Standby Current (AL=CL-1) AL = CL-1, Other conditions: see IDD2N
IPP2N	Precharge Standby IPP Current Same condition with IDD2N
IDD2NT	Precharge Standby ODT Current CKE: High; External clock: On; tCK, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: stable at 1; Command, Address, Bank Group Address, Bank Address Inputs: partially toggling according to Table 39 on page 43; Data IO: VSSQ; DM_n: stable at 1; Bank Activity: all banks closed; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: toggling according to Table 39 on page 43; Pattern Details: see Table 39 on page 43
IDDQ2NT (Optional)	Precharge Standby ODT IDDQ Current Same definition like for IDD2NT, however measuring IDDQ current instead of IDD current
IDD2NL	Precharge Standby Current with CAL enabled Same definition like for IDD2N, CAL enabled ³
IDD2NG	Precharge Standby Current with Gear Down mode enabled Same definition like for IDD2N, Gear Down mode enabled ³
	Precharge Standby Current with DLL disabled
IDD2ND	Same definition like for IDD2N, DLL disabled ³
IDD2N_par	Precharge Standby Current with CA parity enabled Same definition like for IDD2N, CA parity enabled ³
IDD2P	Precharge Power-Down Current CKE: Low; External clock: On; tCK, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: stable at 1; Command, Address, Bank Group Address, Bank Address Inputs: stable at 0; Data IO: VDDQ; DM_n: stable at 1; Bank Activity: all banks closed; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0
IPP2P	Precharge Power-Down IPP Current Same condition with IDD2P
IDD2Q	Precharge Quiet Standby Current CKE: High; External clock: On; tCK, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: stable at 1; Command, Address, Bank Group Address, Bank Address Inputs: stable at 0; Data IO: VDDQ; DM_n: stable at 1;Bank Activity: all banks closed; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0
IDD3N	Active Standby Current CKE: High; External clock: On; tCK, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: stable at 1; Command, Address, Bank Group Address, Bank Address Inputs: partially toggling according to Table 38 on page 42; Data IO: VDDQ; DM_n: stable at 1;Bank Activity: all banks open; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0; Pattern Details: see Table 38 on page 42



Symbol	Description
IDD3NA	Active Standby Current (AL=CL-1) AL = CL-1, Other conditions: see IDD3N
IPP3N	Active Standby IPP Current Same condition with IDD3N
IDD3P	Active Power-Down Current CKE: Low; External clock: On; tCK, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: stable at 1; Command, Address, Bank Group Address, Bank Address Inputs: stable at 0; Data IO: VDDQ; DM_n: stable at 1; Bank Activity: all banks open; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0
IPP3P	Active Power-Down IPP Current Same condition with IDD3P
IDD4R	Operating Burst Read Current CKE: High; External clock: On; tCK, CL: see Table 34 on page 36; BL: 8 ² ; AL: 0; CS_n: High between RD; Command, Address, Bank Group Address, Bank Address Inputs: partially toggling according to Table 40 on page 44; Data IO: seamless read data burst with different data between one burst and the next one according to Table 40 on page 44; DM_n: stable at 1; Bank Activity: all banks open, RD commands cycling through banks: 0,0,1,1,2,2, (see Table 40 on page 44); Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0; Pattern Details: see Table 40 on page 44
IDD4RA	Operating Burst Read Current (AL=CL-1) AL = CL-1, Other conditions: see IDD4R
IDD4RB	Operating Burst Read Current with Read DBI Read DBI enabled ³ , Other conditions: see IDD4R
IPP4R	Operating Burst Read IPP Current Same condition with IDD4R
IDDQ4R (Optional)	Operating Burst Read IDDQ Current Same definition like for IDD4R, however measuring IDDQ current instead of IDD current
IDDQ4RB (Optional)	Operating Burst Read IDDQ Current with Read DBI Same definition like for IDD4RB, however measuring IDDQ current instead of IDD current
IDD4W	Operating Burst Write Current CKE: High; External clock: On; tCK, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: High between WR; Command, Address, Bank Group Address, Bank Address Inputs: partially toggling according to Table 41 on page 45; Data IO: seamless write data burst with different data between one burst and the next one according to Table 41 on page 45; DM_n: stable at 1; Bank Activity: all banks open, WR commands cycling through banks: 0,0,1,1,2,2, (see Table 41 on page 45); Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at <u>HIGH</u> ; Pattern Details: see Table 41 on page 45
IDD4WA	Operating Burst Write Current (AL=CL-1) AL = CL-1, Other conditions: see IDD4W
IDD4WB	Operating Burst Write Current with Write DBI Write DBI enabled ³ , Other conditions: see IDD4W
IDD4WC	Operating Burst Write Current with Write CRC Write CRC enabled ³ , Other conditions: see IDD4W
IDD4W_par	Operating Burst Write Current with CA Parity CA Parity enabled ³ , Other conditions: see IDD4W
IPP4W	Operating Burst Write IPP Current Same condition with IDD4W
IDD5B	Burst Refresh Current (1X REF) CKE: High; External clock: On; tCK, CL, nRFC: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n: High between REF; Command, Address, Bank Group Address, Bank Address Inputs: partially toggling according to Table 43 on page 47; Data IO: VDDQ; DM_n: stable at 1; Bank Activity: REF command every nRFC (see Table 43 on page 47); Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0; Pattern Details: see Table 43 on page 47
IPP5B	Burst Refresh Write IPP Current (1X REF) Same condition with IDD5B
IDD5F2	Burst Refresh Current (2X REF) tRFC=tRFC_x2, Other conditions: see IDD5B
IPP5F2	Burst Refresh Write IPP Current (2X REF) Same condition with IDD5F2
IDD5F4	Burst Refresh Current (4X REF) tRFC=tRFC_x4, Other conditions: see IDD5B
IPP5F4	Burst Refresh Write IPP Current (4X REF) Same condition with IDD5F4



Symbol	Description
IDD6N	Self Refresh Current: Normal Temperature Range <i>T</i> _{CASE} : 0 - 85°C; Low Power Array Self Refresh (LP ASR) : Normal ⁴ ; CKE: Low; External clock: Off; CK_t and CK_c#: LOW; CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n#, Command, Address, Bank Group Address, Bank Address, Data IO: High; DM_n: stable at 1; Bank Activity: Self-Refresh operation; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: MID-LEVEL
IPP6N	Self Refresh IPP Current: Normal Temperature Range Same condition with IDD6N
IDD6E	Self-Refresh Current: Extended Temperature Range ⁾ <i>T</i> _{CASE} : 0 - 95°C; Low Power Array Self Refresh (LP ASR) : Extended ⁴ ; CKE: Low; External clock: Off; CK_t and CK_c: LOW; CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n, Command, Address, Bank Group Address, Bank Address, Data IO: High; DM_n:stable at 1; Bank Activity: Extended Temperature Self-Refresh operation; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: MID- LEVEL
IPP6E	Self Refresh IPP Current: Extended Temperature Range Same condition with IDD6E
IDD6R	Self-Refresh Current: Reduced Temperature Range <i>T</i> _{CASE} : 0 - TBD (~35-45)°C; Low Power Array Self Refresh (LP ASR) : Reduced ⁴ ; CKE: Low; External clock: Off; CK_t and CK_c#: LOW; CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n#, Command, Address, Bank Group Address, Bank Address, Data IO: High; DM_n:stable at 1; Bank Activity: Extended Temperature Self-Refresh operation; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: MID-LEVEL
IPP6R	Self Refresh IPP Current: Reduced Temperature Range Same condition with IDD6R
IDD6A	Auto Self-Refresh Current <i>T</i> _{CASE} : 0 - 95°C; Low Power Array Self Refresh (LP ASR) : Auto ⁴ ;CKE: Low; External clock: Off; CK_t and CK_c#: LOW; CL: see Table 34 on page 36; BL: 8 ¹ ; AL: 0; CS_n#, Command, Address, Bank Group Address, Bank Address, Data IO: High; DM_n:stable at 1; Bank Activity: Auto Self-Refresh operation; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: MID-LEVEL
IPP6A	Auto Self-Refresh IPP Current Same condition with IDD6A
IDD7	Operating Bank Interleave Read Current CKE: High; External clock: On; tCK, nRC, nRAS, nRCD, nRRD, nFAW, CL: see Table 34 on page 36; BL: 8 ¹ ; AL: CL-1; CS_n: High between ACT and RDA; Command, Address, Bank Group Address, Bank Address Inputs: partially toggling according to Table 44 on page 48; Data IO: read data bursts with different data between one burst and the next one according to Table 44 on page 48; DM_n: stable at 1; Bank Activity: two times interleaved cycling through banks (0, 1,7) with different addressing, see Table 44 on page 48; Output Buffer and RTT: Enabled in Mode Registers ² ; ODT Signal: stable at 0; Pattern Details: see Table 44 on page 48
IPP7	Operating Bank Interleave Read IPP Current Same condition with IDD7
IDD8	Maximum Power Down Current TBD
IPP8	Maximum Power Down IPP Current Same condition with IDD8

NOTE :

- Burst Length: BL8 fixed by MRS: set MR0 [A1:0=00].
 Output Buffer Enable
- set MR1 [A12 = 0] : Qoff = Output buffer enabled set MR1 [A2:1 = 0] : Output Driver Impedance Control = RZQ/7
- RTT_Nom enable
- set MR1 [A10:8 = 011] : RTT_NOM = RZQ/6 RTT_WR enable set MR2 [A10:9 = 01] : RTT_WR = RZQ/2 RTT_PARK disable
- set MR5 [A8:6 = 000]
- 3. CAL enabled : set MR4 [A8:6 = 001] : 1600MT/s 010] : 1866MT/s, 2133MT/s 011] : 2400MT/s

- Gear Down mode enabled :set MR3 [A3 = 1] : 1/4 Rate DLL disabled : set MR1 [A0 = 0] CA parity enabled :set MR5 [A2:0 = 001] : 1600MT/s,1866MT/s, 2133MT/s 010] : 2400MT/s

- CA parity enables ... Read DBI enabled : set MR5 [A12 = 1] Write DBI enabled : set :MR5 [A11 = 1] 4. Low Power Array Self Refresh (LP ASR) : set MR2 [A7:6 = 00] : Normal 01] : Reduced Temperature range 10] : Extended Temperature range 10] : Extended Temperature range 11] · Auto Self Refresh

5. IDD2NG should be measured after sync pulse(NOP) input.



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[Table 36] IDD0, IDD0A and IPP0 Measurement-Loop Pattern¹

		- 1	DU, IDDUA and IF																	
CK_t/CK_c	CKE	Sub-Loop	Cycle Number	Command	cs_n	ACT_n	RAS_n	CAS_n/ A15	WE_n/ A14	ОDТ	C[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
			0	ACT	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			1,2	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
		0	3,4	D_#, D_#	1	1	1	1	1	0	0	3 2	3	0	0	0	7	F	0	-
				repeat patte	ern 1	.4 unti	nRAS	5 - 1, tr	uncat	e if neo	cessar	у								
			nRAS	PRE	0	1	0	1	0	0	0	0	0	0	0	0	0	0	0	-
				repeat patte	ern 1	.4 unti	nRC	- 1, tru	ncate	if nece	essary									
		1	1*nRC	repeat Sub	-Loop	0, use	BG[1	:0] ² =	1, BA	[1:0] =	1 inst	ead								
		2	2*nRC	repeat Sub-	-Loop	0, use	BG[1	:0] ² =	0, BA	[1:0] =	2 inst	ead								
		3	3*nRC	repeat Sub	-Loop	0, use	BG[1	:0] ² =	1, BA	[1:0] =	3 inst	ead								
	Ę	4	4*nRC	repeat Sub	-Loop	0, use	BG[1	:0] ² =	0, BA	[1:0] =	1 inst	ead								
toggling	Static High	5	5*nRC	repeat Sub-	-Loop	0, use	BG[1	:0] ² =	1, BA	[1:0] =	2 inst	ead								
tog	Stati	6	6*nRC	repeat Sub-	-Loop	0, use	BG[1	:0] ² =	0, BA	[1:0] =	3 inst	ead								
		7	7*nRC	repeat Sub-	-Loop	0, use	BG[1	:0] ² =	1, BA	[1:0] =	0 inst	ead								
		8	8*nRC	repeat Sub	-Loop	0, use	BG[1	:0] ² = :	2, BA	[1:0] =	0 inst	ead								
		9	9*nRC	repeat Sub	-Loop	0, use	BG[1	:0] ² = :	3, BA	[1:0] =	1 inst	ead								
		10	10*nRC	repeat Sub	-Loop	0, use	BG[1	:0] ² = :	2, BA	[1:0] =	2 inst	ead								
		11	11*nRC	repeat Sub	-Loop	0, use	BG[1	:0] ² = :	3, BA	[1:0] =	3 inst	ead								For x4 and
		12	12*nRC	repeat Sub	-Loop	0, use	BG[1	:0] ² = 2	2, BA	[1:0] =	1 inst	ead								x8 only
		13	13*nRC	repeat Sub-	-Loop	0, use	BG[1	:0] ² = :	3, BA	[1:0] =	2 inst	ead								
		14	14*nRC	repeat Sub-	-Loop	0, use	BG[1	:0] ² = :	2, BA	[1:0] =	3 inst	ead								
		15	15*nRC	repeat Sub-	-Loop	0, use	BG[1	:0] ² = :	3, BA	[1:0] =	0 inst	ead								

NOTE :

DQS_t, DQS_c are VDDQ.
 BG1 is don't care for x16 device
 C[2:0] are used only for 3DS device

4. DQ signals are VDDQ.



[Table 37] IDD1, IDD1A and IPP1 Measurement-Loop Pattern¹

		1.55	1, IDD1A and IPP1 N	lououronion	00	φ													-	
CK_t, CK_c	CKE	Sub-Loop	Cycle Number	Command	u_cs_n	ACT_n	RAS_n	CAS_n/A15	WE_n/A14	тао	c[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
			0	ACT	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			1, 2	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			3, 4	D#, D#	1	1	1	1	1	0	0	3 ^b	3	0	0	0	7	F	0	-
				repeat patte	rn 1	.4 un	til nR	CD - /	AL - 1	, trun	cate i	f nec	essai	y						
		0	nRCD -AL	RD	0	1	1	0	1	0	0	0	0	0	0	0	0	0	0	D0=00, D1=FF D2=FF, D3=00 D4=FF, D5=00 D6=00, D7=FF
				repeat patte	rn 1	.4 un	til nR	AS - '	1, trur	cate	if nec	essa	ry					i	i	
			nRAS	PRE	0	1	0	1	0	0	0	0	0	0	0	0	0	0	0	-
				repeat patte	1			C - 1,	trunc			ssary								1
			1*nRC + 0	ACT	0	0	0	1	1	0	0	1	1	0	0	0	0	0	0	-
			1*nRC + 1, 2	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			1*nRC + 3, 4	D#, D#	1	1	1	1	1	0	0	3 ^b	3	0	0	0	7	F	0	-
				repeat patte	rn nR	C + 1	l4 ι	until 1	*nRC	+ nR	AS - '	1, tru	ncate	if neo	cessa	ary				
DL DL	ligh	1	1*nRC + nRCD - AL		0	1	1	0	1	0	0	1	1	0	0	0	0	0	0	D0=FF, D1=00 D2=00, D3=FF D4=00, D5=FF D6=FF, D7=00
toggling	Static High			repeat patte				-			-		-							
\$	Sta		1*nRC + nRAS	PRE	0	1	0	1	0	0	0	0	0	0	0	0	0	0	0	-
				repeat nRC									-							
		2	2*nRC	repeat Sub-						_	-									
		3	3*nRC	repeat Sub-	Loop	1, us	e BG	[1:0]	² = 1,	BA[1	:0] =	3 inst	tead							
		4	4*nRC	repeat Sub-	Loop	0, us	e BG	[1:0] ²	² = 0,	BA[1	:0] =	1 inst	tead							
		5	5*nRC	repeat Sub-	Loop	1, us	e BG	[1:0]	² = 1,	BA[1	:0] =	2 inst	tead							
		6	6*nRC	repeat Sub-	Loop	0, us	e BG	[1:0] ²	² = 0,	BA[1	:0] =	3 inst	tead							
		8	7*nRC	repeat Sub-	Loop	1, us	e BG	[1:0] ²	² = 1,	BA[1	:0] =	0 inst	tead							
		9	9*nRC	repeat Sub-	Loop	1, us	e BG	[1:0]	² = 2,	BA[1	:0] =	0 inst	tead							
		10	10*nRC	repeat Sub-	Loop	0, us	e BG	[1:0] ²	² = 3,	BA[1	:0] =	1 inst	tead							
		11	11*nRC	repeat Sub-	Loop	1, us	e BG	[1:0]	² = 2,	BA[1	:0] =	2 inst	tead							
		12	12*nRC	repeat Sub-							-									
		13	13*nRC	repeat Sub-	Loop	1, us	e BG	[1:0] ²	² = 2,	BA[1	:0] =	1 inst	tead							For x4 and x8 only
		14	14*nRC	repeat Sub-																
		15	15*nRC	repeat Sub-							-									
		16	16*nRC	repeat Sub-	-															
L		• •	-		Loop	J, UJ		r]	σ,	241	- 10-	5 113	Juu							

NOTE :

1. DQS_t, DQS_c are used according to RD Commands, otherwise VDDQ

2. BG1 is don't care for x16 device

3. C[2:0] are used only for 3DS device

4. Burst Sequence driven on each DQ signal by Read Command. Outside burst operation, DQ signals are VDDQ.



CK_t, CK_c	CKE	Sub-Loop	Cycle Number	Command	CS_n	ACT_n	RAS_n	CAS_n/A15	WE_n/A14	ODT	C[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
			0	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
		•	1	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
		0	2	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	0
			3	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	0
		1	4-7	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 1,	BA[1	:0] =	1 inste	ead							
		2	8-11	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 0,	BA[1	:0] = :	2 inste	ead							
		3	12-15	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 1,	BA[1	:0] = :	3 inste	ead							
		4	16-19	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 0,	BA[1	:0] =	1 inst	ead							
0	gh	5	20-23	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 1,	BA[1	:0] = :	2 inste	ead							
toggling	Static High	6	24-27	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 0,	BA[1	:0] =	3 inst	ead							
ţ	Stat	7	28-31	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 1,	BA[1	:0] =	0 inst	ead							
		8	32-35	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 2 ,	BA[1	:0] =	0 inst	ead							
		9	36-39	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 3,	BA[1	:0] =	1 inst	ead							
		10	40-43	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 2 ,	BA[1	:0] = :	2 inste	ead							
		11	44-47	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 3 ,	BA[1	:0] =	3 inst	ead							
		12	48-51	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 2 ,	BA[1	:0] =	1 inste	ead							
		13	52-55	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 3 ,	BA[1	:0] =	2 inst	ead							
		14	56-59	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 2 ,	BA[1	:0] =	3 inst	ead							
		15	60-63	repeat Su	b-Loo	p 0, u	se BC	G[1:0]	² = 3,	BA[1	:0] =	0 inst	ead							

[Table 38] IDD2N, IDD2NA, IDD2NL, IDD2NG, IDD2ND, IDD2N_par, IPP2, IDD3N, IDD3NA and IDD3P Measurement-Loop Pattern¹

NOTE :

1. DQS_t, DQS_c are VDDQ.

2. BG1 is don't care for x16 device

3. C[2:0] are used only for 3DS device

4. DQ signals are VDDQ.



[Table 39] IDD2NT and IDDQ2NT Measurement-Loop Pattern¹

-		_			-															
CK_t, CK_c	CKE	Sub-Loop	Cycle Number	Command	cs_n	ACT_n	RAS_n	CAS_n/A15	WE_n/A14	ODT	C[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
			0	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
		•	1	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
		0	2	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
			3	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
		1	4-7	repeat Sub-L	oop 0	, but (ODT =	1 and	BG[1	: 0] ² =	: 1, B/	A [1:0]	= 1 ir	stead						
		2	8-11	repeat Sub-L	.oop 0	, but (DDT =	0 and	BG[1	:0] ² =	• 0, B/	A[1:0]	= 2 ir	stead						
		3	12-15	repeat Sub-L	.oop 0	, but (DDT =	1 and	BG[1	: 0] ² =	= 1, B/	A[1:0]	= 3 ir	stead						
		4	16-19	repeat Sub-L	.oop 0	, but (DDT =	0 and	BG[1	:0] ² =	= 0, B/	4[1:0]	= 1 ir	stead						
5	igh	5	20-23	repeat Sub-L	.oop 0	, but (DDT =	1 and	BG[1	: 0] ² =	= 1, B/	A[1:0]	= 2 ir	stead						
toggling	Static High	6	24-27	repeat Sub-L	oop 0	, but (DDT =	: 0 and	BG[1	:0] ² =	: 0, B/	4[1:0]	= 3 ir	stead						
ğ	Stat	7	28-31	repeat Sub-L	.oop 0	, but (DDT =	1 and	BG[1	: 0] ² =	= 1, B/	4[1:0]	= 0 ir	stead						
		8	32-35	repeat Sub-L	.oop 0	, but (DDT =	0 and	BG[1	:0] ² =	= 2, B/	4[1:0]	= 0 ir	stead						
		9	36-39	repeat Sub-L	.oop 0	, but (ODT =	1 and	BG[1	:0] ² =	= 3, B/	4[1:0]	= 1 ir	stead						
		10	40-43	repeat Sub-L	.oop 0	, but (DDT =	0 and	BG[1	: 0] ² =	= 2, B/	4[1:0]	= 2 ir	stead						
		11	44-47	repeat Sub-L	.oop 0	, but (DDT =	1 and	BG[1	:0] ² =	= 3, B/	4[1:0]	= 3 ir	stead						For x4 and x8
		12	48-51	repeat Sub-L	oop 0	, but (ODT =	0 and	BG[1	:0] ² =	= 2, B/	A[1:0]	= 1 ir	stead						only
		13	52-55	repeat Sub-L	oop 0	, but (DT =	1 and	BG[1	:0] ² =	: 3, B/	A[1:0]	= 2 ir	stead						
		14	56-59	repeat Sub-L	oop 0	, but (ODT =	0 and	BG[1	:0] ² =	= 2, B/	A [1:0]	= 3 ir	stead						
		15	60-63	repeat Sub-L	oop 0	, but (ODT =	1 and	BG[1	:0] ² =	: 3, B/	A[1:0]	= 0 ir	stead						

NOTE : 1. DQS_t, DQS_c are VDDQ. 2. BG1 is don't care for x16 device

C[2:0] are used only for 3DS device
 DQ signals are VDDQ.



0				_				10			-									
CK_t, CK_c	СКЕ	Sub-Loop	Cycle Number	Command	cs_n	ACT_n	RAS_n	CAS_n/A15	WE_n/A14	ОDT	C[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
		0	0	RD	0	1	1	0	1	0	0	0	0	0	0	0	0	0	0	D0=00, D1=FF D2=FF, D3=00 D4=FF, D5=00 D6=00, D7=FF
			1	D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			2,3	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
		1	4	RD	0	1	1	0	1	0	0	1	1	0	0	0	7	F	0	D0=FF, D1=00 D2=00, D3=FF D4=00, D5=FF D6=FF, D7=00
			5	D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			6,7	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
		2	8-11	repeat Sub-L	oop C	, use	BG[1	:0] ² =	= 0, B	A[1:0] = 2	inste	ad							
bu	High	3	12-15	repeat Sub-L	oop 1	, use	BG[1	:0] ² =	= 1, B	A[1:0] = 3	inste	ad							
toggling	Static High	4	16-19	repeat Sub-L	oop C	, use	BG[1	: 0] ² =	= 0, B	A[1:0] = 1	inste	ad							
Ĕ	Sta	5	20-23	repeat Sub-L	oop 1	, use	BG[1	:0] ² =	= 1, B	A[1:0] = 2	inste	ad							
		6	24-27	repeat Sub-L	oop C	, use	BG[1	:0] ² =	= 0, B	A[1:0] = 3	inste	ad							
		7	28-31	repeat Sub-L	oop 1	, use	BG[1	:0] ² =	= 1, B	A[1:0] = 0	inste	ad							
		8	32-35	repeat Sub-L	oop C	, use	BG[1	:0] ² =	= 2, B	A[1:0] = 0	inste	ad							
		9	36-39	repeat Sub-L	oop 1	, use	BG[1	:0] ² =	= 3, B	A[1:0] = 1	inste	ad							
		10	40-43	repeat Sub-L	oop C	, use	BG[1	:0] ² =	= 2, B	A[1:0] = 2	inste	ad							
		11	44-47	repeat Sub-L																
		12	48-51	repeat Sub-L	oop C	, use	BG[1	: 0] ² =	= 2, B	A[1:0] = 1	inste	ad							For x4 and x8 only
		13	52-55	repeat Sub-L	oop 1	, use	BG[1	:0] ² =	= 3, B	A[1:0] = 2	inste	ad							
		14	56-59	repeat Sub-L	oop C	, use	BG[1	:0] ² =	= 2, B	A[1:0] = 3	inste	ad							
		15	60-63	repeat Sub-L	oop 1	, use	BG[1	:0] ² =	= 3, B	A[1:0] = 0	instea	ad							

[Table 40] IDD4R, IDDR4RA, IDD4RB and IDDQ4R Measurement-Loop Pattern¹

NOTE : 1. DQS_t, DQS_c are used according to RD Commands, otherwise VDDQ. 2. BG1 is don't care for x16 device

3. C[2:0] are used only for 3DS device

4. Burst Sequence driven on each DQ signal by Read Command.



[Table 41] IDD4W, IDD4WA, IDD4WB and IDD4W_par Measurement-Loop Pattern¹

CK_t, CK_c	CKE	Sub-Loop	Cycle Number	Command	cs_n	ACT_n	RAS_n	CAS_n/A15	WE_n/A14	ОDT	C[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
		0	0	WR	0	1	1	0	1	0	0	0	0	0	0	0	0	0	0	D0=00, D1=FF D2=FF, D3=00 D4=FF, D5=00 D6=00, D7=FF
			1	D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			2,3	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
		1	4	WR	0	1	1	0	1	0	0	1	1	0	0	0	7	F	0	D0=FF, D1=00 D2=00, D3=FF D4=00, D5=FF D6=FF, D7=00
			5	D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			6,7	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
		2	8-11	repeat Sub-Lo	oop 0	, use	BG[1	:0] ² =	: 0, B	A[1:0] = 2	instea	ad							
bu	High	3	12-15	repeat Sub-Lo	oop 1	, use	BG[1	:0] ² =	: 1, B	A[1:0] = 3	instea	ad							
toggling	Static High	4	16-19	repeat Sub-Lo	oop 0	, use	BG[1	:0] ² =	• 0, B	A[1:0] = 1	instea	ad							
t t	ŝ	5	20-23	repeat Sub-Lo	oop 1	, use	BG[1	:0] ² =	: 1, B	A[1:0] = 2	instea	ad							
		6	24-27	repeat Sub-Lo	oop 0	, use	BG[1	:0] ² =	: 0, B	A[1:0)] = 3	instea	ad							
		7	28-31	repeat Sub-Lo	oop 1	, use	BG[1	:0] ² =	: 1, B	A[1:0) = 0	instea	ad							
		8	32-35	repeat Sub-Lo	oop 0	, use	BG[1	:0] ² =	2, B	A[1:0) = 0	instea	ad							
		9	36-39	repeat Sub-Lo	oop 1	, use	BG[1	:0] ² =	: 3, B	A[1:0)] = 1	instea	ad							
		10	40-43	repeat Sub-Lo	oop 0	, use	BG[1	:0] ² =	: 2, B	A[1:0] = 2	instea	ad							
		11	44-47	repeat Sub-Lo	oop 1	, use	BG[1	:0] ² =	: 3, B	A[1:0)] = 3	instea	ad							For v4 and v9 anti-
		12	48-51	repeat Sub-Lo	oop 0	, use	BG[1	:0] ² =	: 2, B	A[1:0)] = 1	instea	ad							For x4 and x8 only
		13	52-55	repeat Sub-Lo	oop 1	, use	BG[1	:0] ² =	: 3, B	A[1:0] = 2	instea	ad							
		14	56-59	repeat Sub-Lo	oop 0	, use	BG[1	:0] ² =	: 2, B	A[1:0] = 3	instea	ad							
		15	60-63	repeat Sub-Lo	oop 1	, use	BG[1	:0] ² =	3, B	A[1:0] = 0	instea	ad							

NOTE : 1. DQS_t, DQS_c are used according to WR Commands, otherwise VDDQ. 2. BG1 is don't care for x16 device

3. C[2:0] are used only for 3DS device

4. Burst Sequence driven on each DQ signal by Write Command.



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[Table 42] IDD4WC Measurement-Loop Pattern¹

CK_t, CK_c	СКЕ	Sub-Loop	Cycle Number	Command	CS_n	ACT_n	RAS_n	CAS_n/A15	WE_n/A14	орт	C[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
			0	WR	0	1	1	0	1	0	0	0	0	0	0	0	0	0	0	D0=00, D1=FF D2=FF, D3=00 D4=FF, D5=00 D6=00, D7=FF D8=CRC
			1,2	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
		0	3,4	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
		0	5	WR	0	1	1	0	1	0	0	1	1	0	0	0	7	F	0	D0=FF, D1=00 D2=00, D3=FF D4=00, D5=FF D6=FF, D7=00 D8=CRC
			6,7	D, D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			8,9	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
g	igh	2	10-14	repeat Sub-	Loop	0, us	se BG	i[1:0]	² = 0,	BA[′	1:0] =	2 ins	stead							
toggling	Static High	3	15-19	repeat Sub-	Loop	1, us	se BG	i[1:0]	² = 1,	BA[′	1:0] =	3 ins	stead							
to	Stat	4	20-24	repeat Sub-	Loop	0, us	se BG	i[1:0]	² = 0,	BA[′	1:0] =	• 1 ins	stead							
		5	25-29	repeat Sub-	Loop	1, us	se BG	i[1:0]	² = 1,	BA[′	1:0] =	2 ins	stead							
		6	30-34	repeat Sub-	Loop	0, us	se BG	i[1:0]	² = 0,	BA[′	1:0] =	3 ins	stead							
		7	35-39	repeat Sub-	Loop	1, us	se BG	i[1:0]	² = 1,	BA[′	1:0] =	• 0 ins	stead							
		8	40-44	repeat Sub-	Loop	0, us	se BG	i[1:0]	² = 2 ,	BA[′	1:0] =	• 0 ins	stead							
		9	45-49	repeat Sub-	Loop	1, us	se BG	i[1:0]	² = 3 ,	BA[′	1:0] =	1 ins	stead							
		10	50-54	repeat Sub-	Loop	0, us	se BG	i[1:0]	² = 2 ,	BA[′	1:0] =	2 ins	stead							
		11	55-59	repeat Sub-	Loop	1, us	se BG	i[1:0]	² = 3 ,	BA[′	1:0] =	3 ins	stead							For v4 and v9 ask
		12	60-64	repeat Sub-	Loop	0, us	se BG	i[1:0]	² = 2 ,	BA[′	1:0] =	• 1 ins	stead							For x4 and x8 only
	ĺ	13	65-69	repeat Sub-	Loop	1, us	e BG	[1:0]	² = 3,	BA[′	1:0] =	2 ins	stead							
		14	70-74	repeat Sub-	Loop	0, us	se BG	i[1:0]	² = 2 ,	BA[′	1:0] =	3 ins	stead							
		15	75-79	repeat Sub-	Loop	1, us	se BG	[1:0]	² = 3 ,	BA[′	1:0] =	0 ins	stead							

NOTE :

1. DQS_t, DQS_c are VDDQ.

2. BG1 is don't care for x16 device.

3. C[2:0] are used only for 3DS device.

4. Burst Sequence driven on each DQ signal by Write Command.



[Table 43] IDD5B Measurement-Loop Pattern¹

				-																
CK_t, CK_c	СКЕ	Sub-Loop	Cycle Number	Command	cs_n	ACT_n	RAS_n	CAS_n/A15	WE_n/A14	ОDT	C[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
		0	0	REF	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			1	D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			2	D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			3	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
			4	D#, D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
			4-7	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 1,	BA[1	:0] =	1 inste	ead							
			8-11	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 0,	BA[1	:0] = :	2 inste	ead							
			12-15	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 1,	BA[1	:0] = :	3 inste	ead							
			16-19	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 0,	BA[1	:0] =	1 inste	ead							
g	gh		20-23	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 1,	BA[1	:0] = 2	2 inste	ead							
toggling	Static High	1	24-27	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 0,	BA[1	:0] = :	3 inste	ead							
ţ	Stat		28-31	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 1,	BA[1	:0] = (0 inste	ead							
			32-35	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 2,	BA[1	:0] = (0 inste	ead							
			36-39	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 3,	BA[1	:0] =	1 inste	ead							
			40-43	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 2,	BA[1	:0] = :	2 inste	ead							
			44-47	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 3,	BA[1	:0] = :	3 inste	ead							For x4 and x8 only
			48-51	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 2,	BA[1	:0] =	1 inste	ead							
			52-55	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 3,	BA[1	:0] = :	2 inst	ead							
			56-59	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 2,	BA[1	:0] = :	3 inste	ead							
			60-63	repeat patte	rn 1	.4, us	e BG	[1:0] ²	= 3,	BA[1	:0] = (0 inste	ead							
		2	64 nRFC - 1	repeat Sub-	Loop	1, Tru	uncate	e, if ne	ecess	ary										

NOTE :

1. DQS_t, DQS_c are VDDQ.

2. BG1 is don't care for x16 device.

3. C[2:0] are used only for 3DS device.

4. DQ signals are VDDQ.



[Table 44] IDD7 Measurement-Loop Pattern¹

CK_t, CK_c	CKE	Sub-Loop	Cycle Number	Command	CS_n	ACT_n	RAS_n	CAS_n/A15	WE_n/A14	ОDT	C[2:0] ³	BG[1:0] ²	BA[1:0]	A12/BC_n	A[13,11]	A[10]/AP	A[9:7]	A[6:3]	A[2:0]	Data ⁴
_			0	АСТ	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
		0	1	RDA	0	1	1	0	1	0		0	0	0	0	1	0	0	0	D0=00, D1=FF D2=FF, D3=00 D4=FF, D5=00 D6=00, D7=FF
			2	D	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-
			3	D#	1	1	1	1	1	0	0	3 ²	3	0	0	0	7	F	0	-
				repeat patte	rn 2	.3 unt	il nRF	RD - 1	, if nl	RCD >	> 4. T	runca	te if n	eces	sary					
			nRRD	ACT	0	0	0	0	0	0	0	1	1	0	0	0	0	0	0	-
		1	nRRD + 1	RDA	0	1	1	0	1	0		1	1	0	0	1	0	0	0	D0=FF, D1=00 D2=00, D3=FF D4=00, D5=FF D6=FF, D7=00
				repeat patte	rn 2 .	3 ur	ntil 2*ı	nRRE) - 1,	if nRC	C > 4	4. Tru	ncate	if ne	cessa	ry				
		2	2*nRRD	repeat Sub-	Loop	0, use	e BG[[1:0] ²	= 0,	BA[1:	0] = 2	2 inste	ead							
		3	3*nRRD	repeat Sub-							-									
		4	4*nRRD	repeat patte	rn 2 .	3 ur	ntil nF	AW -	1, if ı	nFAW	/ > 4*I	nRCD	. Tru	ncate	if neo	cessa	ry			
				1																
g	igh	5	nFAW	repeat Sub-	Loop	0, use	BG[[1:0] ²	= 0,	BA[1:	0] = 1	i inste	ead							
toggling	Static High	6	nFAW + nRRD	repeat Sub-	Loop	1, use	BG[[1:0] ²	= 1,	BA[1:	0] = 2	2 inste	ead							
ţ	Sta	7	nFAW + 2*nRRD	repeat Sub-	Loop	0, use	BG[[1:0] ²	= 0,	BA[1:	0] = 3	3 inste	ead							
		8	nFAW + 3*nRRD	repeat Sub-	Loop	1, use	e BG[[1:0] ²	= 1,	BA[1:	0] = () inste	ead							
		9	nFAW + 4*nRRD	repeat Sub-	Loop	4														
		10	2** 5 4)4/						-											
		10	2*nFAW	repeat Sub-							_									
		11	2*nFAW + nRRD	repeat Sub-						-	-									
		12	2*nFAW + 2*nRRD	repeat Sub-						-										
		13	2*nFAW + 3*nRRD	repeat Sub-			e BG[[1:0] ²	= 3,	BA[1:	0] = 3	3 inste	ead							
		14	2*nFAW + 4*nRRD	repeat Sub-	Loop	4														For x4 and x8
		15	3*nFAW	repeat Sub-	000	0 use	BGI	1:01 ²	= 2.	BA[1:	01 = 1	1 inste	ad							only
		16	3*nFAW + nRRD	repeat Sub-	-					_	_									
				repeat Sub-			-			-	-									
		18		repeat Sub-						-	-									
			3*nFAW + 4*nRRD	repeat Sub-			. 59	1.0]	- 3, 1		- (
				1. opcat Cab-	-000	•														
		20	4*nFAW	repeat patte	rn 2 .	3 ur	ntil nR	RC - 1	, if nF	RC > 4	↓*nFA	W. Tr	unca	te if n	ecess	sary				

NOTE : 1. DQS_t, DQS_c are VDDQ. 2. BG1 is don't care for x16 device. 3. C[2:0] are used only for 3DS device. 4. Burst Sequence driven on each DQ signal by Read Command. Outside burst operation, DQ signals are VDDQ.



11.2 4Gb DDR4 SDRAM D-die IDD Specification Table IDD and IPP values are for full operating range of voltage and temperature unless otherwise noted. IDD and IPP values are for full operating range of voltage and temperature unless otherwise noted.

[Table 45] I_{DD} and I_{DDQ} Specification

	256Mx16 (K4	4A4G165WD)		
	DDR4-2133	DDR4-2400		
Symbol	15-15-15	17-17-17	Unit	NOTE
	1.2V	1.2V		
	IDD Max.	IDD Max.		
/ _{DD0}	TBD	TBD	mA	
I _{DD0A}	TBD	TBD	mA	
I _{DD1}	TBD	TBD	mA	
I _{DD1A}	TBD	TBD	mA	
/ _{DD2N}	TBD	TBD	mA	
I _{DD2NA}	TBD	TBD	mA	
I _{DD2NT}	TBD	TBD	mA	
I _{DD2NL}	TBD	TBD	mA	
I _{DD2NG}	TBD	TBD	mA	
I _{DD2ND}	TBD	TBD	mA	
/ _{DD2N_par}	TBD	TBD	mA	
I _{DD2P}	TBD	TBD	mA	
I _{DD2Q}	TBD	TBD	mA	
/ _{DD3N}	TBD	TBD	mA	
/ _{DD3NA}	TBD	TBD	mA	
I _{DD3P}	TBD	TBD	mA	
I _{DD4R}	TBD	TBD	mA	
I _{DD4RA}	TBD	TBD	mA	
I _{DD4RB}	TBD	TBD	mA	
/ _{DD4W}	TBD	TBD	mA	
I _{DD4WA}	TBD	TBD	mA	
/ _{DD4WB}	TBD	TBD	mA	
/ _{DD4WC}	TBD	TBD	mA	
/ _{DD4W_par}	TBD	TBD	mA	
/ _{DD5B}	TBD	TBD	mA	
/ _{DD5F2}	TBD	TBD	mA	
/ _{DD5F4}	TBD	TBD	mA	
/ _{DD6N}	TBD	TBD	mA	
/ _{DD6E}	TBD	TBD	mA	
IDD6R	TBD	TBD	mA	
IDD6A	TBD	TBD	mA	
/DD6A / _{DD7}	TBD	TBD	mA	
	TBD	TBD	mA	
I _{DD8}	עסו	עסו	IIIA	



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IDD and IPP values are for full operating range of voltage and temperature unless otherwise noted. IDD and IPP values are for full operating range of voltage and temperature unless otherwise noted.

[Table 46] IPP Specification

	256Mx16 (K	4A4G165WD)		
	DDR4-2133	DDR4-2400		
Symbol	15-15-15	17-17-17	Unit	NOTE
	1.2V	1.2V		
	IDD Max.	IDD Max.		
/ _{PP0}	TBD	TBD	mA	
/ _{PP1}	TBD	TBD	mA	
I _{PP2N}	TBD	TBD	mA	
I _{PP2P}	TBD	TBD	mA	
/ _{PP3N}	TBD	TBD	mA	
I _{PP3P}	TBD	TBD	mA	
I _{PP4R}	TBD	TBD	mA	
I _{PP4W}	TBD	TBD	mA	
I _{PP5B}	TBD	TBD	mA	
I _{PP5F2}	TBD	TBD	mA	
I _{PP5F4}	TBD	TBD	mA	
I _{PP6N}	TBD	TBD	mA	
I _{PP6E}	TBD	TBD	mA	
I _{PP6R}	TBD	TBD	mA	
I _{PP6A}	TBD	TBD	mA	
I _{PP7}	TBD	TBD	mA	
/ _{PP8}	TBD	TBD	mA	

[Table 47] IDD6 Specification

		Va	lue		
		256Mx16 (K4	A4G165WD)		
Symbol	Temperature Range	DDR4-2133 DDR4-2400		Unit	NOTE
		15-15-15	17-17-17	1	
		1.:	2V]	
I _{DD6N}	0 - 85 °C	TBD	TBD	mA	3,4
I _{DD6E}	0 - 95 °C	TBD	TBD	mA	4,5,6
I _{DD6R}	0 - 45°C	TBD	TBD	mA	4,6,8
I _{DD6A}	0 - 85 ^o C	TBD	TBD	mA	4,6,7

NOTE :

1. Some I_{DD} currents are higher for x16 organization due to larger page-size architecture.

2. Max. values for I_{DD} currents considering worst case conditions of process, temperature and voltage.

3. Applicable for MR2 settings A6=0 and A7=0.

4. Supplier data sheets include a max value for $\mathrm{I}_{\mathrm{DD6}}.$

5. Applicable for MR2 settings A6=0 and A7=1. I_{DD6ET} is only specified for devices which support the Extended Temperature Range feature.

6. Refer to the supplier data sheet for the value specification method (e.g. max, typical) for I_{DD6ET} and I_{DD6TC}

7. Applicable for MR2 settings A6=1 and A7=0. I_{DD6TC} is only specified for devices which support the Auto Self Refresh feature.

8. Applicable for MR2 settings TBD. IDD6R is verified by design and characterization, and may not be subject to production test



12. Input/Output Capacitance

[Table 48] Silicon pad I/O Capacitance

Symbol	Parameter	DDR4-1600	/1866/2133	DDR4	2400	Unit	NOTE
Symbol	Falanetei	min	max	min	max	Unit	NOTE
C _{IO}	Input/output capacitance	0.7	1.4	0.7	1.3	pF	1,2,3
C _{DIO}	Input/output capacitance delta	-0.1	0.1	-0.1	0.1	pF	1,2,3,11
C _{DDQS}	Input/output capacitance delta DQS_t and DQS_c	-	0.05	-	0.05	pF	1,2,3,5
С _{СК}	Input capacitance, CK_t and CK_c	0.2	0.8	0.2	0.7	pF	1,3
C _{DCK}	Input capacitance delta CK_t and CK_c	-	0.05	-	0.05	pF	1,3,4
CI	Input capacitance(CTRL, ADD, CMD pins only)	0.2	0.8	0.2	0.7	pF	1,3,6
C _{DI_CTRL}	Input capacitance delta(All CTRL pins only)	-0.1	0.1	-0.1	0.1	pF	1,3,7,8
C _{DI_ADD_CMD}	Input capacitance delta(All ADD/CMD pins only)	-0.1	0.1	-0.1	0.1	pF	1,2,9,10
C _{ALERT}	Input/output capacitance of ALERT	0.5	1.5	0.5	1.5	pF	1,3
C _{ZQ}	Input/output capacitance of ZQ	0.5	2.3	0.5	2.3	pF	1,3,12
CTEN	Input capacitance of TEN	0.2	2.3	0.2	2.3	pF	1,3,13

NOTE:

1. This parameter is not subject to production test. It is verified by design and characterization. The silicon only capacitance is validated by de-embedding the package L & C parasitic. The capacitance is measured with VDD, VDDQ, VSS, VSSQ applied with all other signal pins floating. Measurement procedure tbd.

2. DQ, DM_n, DQS_T, DQS_C, TDQS_T, TDQS_C. Although the DM, TDQS_T and TDQS_C pins have different functions, the loading matches DQ and DQS

3. This parameter applies to monolithic devices only; stacked/dual-die devices are not covered here

4. Absolute value CK_T-CK_C

5. Absolute value of CIO(DQS_T)-CIO(DQS_C)

6. CI applies to ODT, CS_n, CKE, A0-A15, BA0-BA1, BG0-BG1, RAS_n, CAS_n/A15, WE_n/A14, ACT_n and PAR.

7. CDI CTRL applies to ODT, CS_n and CKE

8. CDI_CTRL = CI(CTRL)-0.5*(CI(CLK_T)+CI(CLK_C))

9. CDI_ADD_ CMD applies to, A0-A15, BA0-BA1, BG0-BG1,RAS_n, CAS_n/A15, WE_n/A14, ACT_n and PAR. 10. CDI_ADD_CMD = CI(ADD_CMD)-0.5*(CI(CLK_T)+CI(CLK_C))

11. $CDIO = CIO(DQ,DM)-0.5^{*}(CIO(DQS_T)+CIO(DQS_C))$

12. Maximum external load capacitance on ZQ pin: tbd pF.

13.TEN pin may be DRAM internally pulled low through a weak pull-down resistor to VSS. In this case CTEN might not be valid and system shall verify TEN signal with Vendor specific information.



[Table 49] DRAM package electrical specifications

Symbol	Peremeter	DDR4-16	00/1866	DDR4-21	33,2400	Unit	NOTE	
Symbol	Parameter	min	max	min	max	Unit	NOTE	
Z _{IO}	Input/output Zpkg	45	85	50	85	Ω	1,2,4,5,10,11	
T _{dlO}	Input/output Pkg Delay	14	42	14	37	ps	1,3,4,5,11	
L _{io}	Input/Output Lpkg	-	3.3	-	3.3	nH	11,12	
C _{io}	Input/Output Cpkg	-	0.78	-	0.78	pF	11,13	
Z _{IO DQS}	DQS_t, DQS_c Zpkg	45	85	45	85	Ω	1,2,5,10,11	
Td _{IO DQS}	DQS_t, DQS_c Pkg Delay	14	42	14	42	ps	1,3,5,10,11	
L _{io DQS}	DQS Lpkg	-	3.3	-	3.3	nH	11,12	
C _{io DQS}	DQS Cpkg	-	0.78	-	0.78	pF	11,13	
DZ _{DIO DQS}	Delta Zpkg DQS_t, DQS_c	-	10	-	10	Ω	1,2,5,7,10	
D _{TdDIO DQS}	Delta Delay DQS_t, DQS_c	-	5	-	5	pF	1,3,5,7,10	
Z _{I CTRL}	Input- CTRL pins Zpkg	50	90	50	90	Ω	1,2,5,9,10,11	
T _{dl_CTRL}	Input- CTRL pins Pkg Delay	14	42	14	42	ps	1,3,5,9,10,11	
Li CTRL	Input CTRL Lpkg	-	3.4	-	3.4	nH	11,12	
Ci CTRL	Input CTRL Cpkg	-	0.7	-	0.7	pF	11,13	
Z _{IADD CMD}	Input- CMD ADD pins Zpkg	50	90	50	90	Ω	1,2,5,8,10,11	
Td _{IADD_CMD}	Input- CMD ADD pins Pkg Delay	14	45	14	45	ps	1,3,5,8,10,11	
Li ADD CMD	Input CMD ADD Lpkg	-	3.6	-	3.6	nH	11,12	
Ci ADD CMD	Input CMD ADD Cpkg	-	0.74	-	0.74	pF	11,13	
Z _{CK}	CLK_t & CLK_c Zpkg	50	90	50	90	Ω	1,2,5,10,11	
Td _{CK}	CLK_t & CLK_c Pkg Delay	14	42	14	42	ps	1,3,5,10,11	
Li CLK	Input CLK Lpkg	-	3.4	-	3.4	nH	11,12	
Ci CLK	Input CLK Cpkg	-	0.7	-	0.7	pF	11,13	
DZ _{DCK}	Delta Zpkg CLK_t & CLK_c	-	10	-	10	Ω	1,2,5,6,10	
D _{TdCK}	Delta Delay CLK_t & CLK_c	-	5	-	5	ps	1,3,5,6,10	
Z _{OZQ}	ZQ Zpkg	40	100	40	100	Ω	1,2,5,10,11	
Td _{O ZQ}	ZQ Delay	20	90	20	90	ps	1,3,5,10,11	
Z _{O ALERT}	ALERT Zpkg	40	100	40	100	Ω	1,2,5,10,11	
Td _{O ALERT}	ALERT Delay	20	55	20	55	ps	1,3,5,10,11	

NOTE :

1. This parameter is not subject to production test. It is verified by design and characterization. The package parasitic(L & C) are validated using package only samples. The capacitance is measured with VDD, VDDQ, VSS, VSSQ shorted with all other signal pins floating. The inductance is measured with VDD, VDDQ, VSS and VSSQ shorted and all other signal pins shorted at the die side(not pin). Measurement procedure tbd

2. Package only impedance (Zpkg) is calculated based on the Lpkg and Cpkg total for a given pin where:

 $Zpkg(total per pin) = \sqrt{Lpkg/Cpkg}$

3. Package only delay(Tpkg) is calculated based on Lpkg and Cpkg total for a given pin where:

Tdpkg(total per pin) = $\sqrt{Lpkg*Cpkg}$

Z & Td IO applies to DQ, DM, DQS_C, DQS_T, TDQS_T and TDQS_C
 This parameter applies to monolithic devices only; stacked/dual-die devices are not covered here

6. Absolute value of ZCK_t-ZCK_c for impedance(Z) or absolute value of TdCK_t-TdCK_c for delay(Td)

7. Absolute value of ZIO(DQS_t)-ZIO(DQS_c) for impedance(Z) or absolute value of TdIO(DQS_t)-TdIO(DQS_c) for delay(Td)

8. ZI & Td ADD CMD applies to A0-A13, ACT_n BA0-BA1, BG0-BG1, RAS_n, CAS_n/A15, WE_n/A14. 9. ZI & Td CTRL applies to ODT, CS_n and CKE

10. This table applies to monolithic $X\overline{4}$ and $X\overline{8}$ devices.

11. Package implementations shall meet spec if the Zpkg and Pkg Delay fall within the ranges shown, and the maximum Lpkg and Cpkg do not exceed the maximum values shown.

12. It is assumed that Lpkg can be approximated as Lpkg = $Zo^{*}Td$. 13. It is assumed that Cpkg can be approximated as Cpkg = Td/Zo.



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13. Electrical Characteristics & AC Timing

13.1 Reference Load for AC Timing and Output Slew Rate

Figure 21 represents the effective reference load of 50 ohms used in defining the relevant AC timing parameters of the device as well as output slew rate measurements.

It is not intended as a precise representation of any particular system environment or a depiction of the actual load presented by a production tester. System designers should use IBIS or other simulation tools to correlate the timing reference load to a system environment. Manufacturers correlate to their production test conditions, generally one or more coaxial transmission lines terminated at the tester electronics.

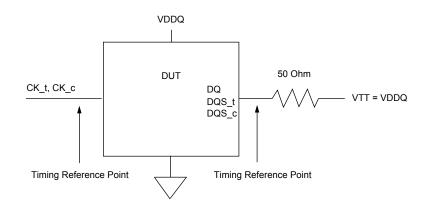


Figure 21. Reference Load for AC Timing and Output Slew Rate

13.2 tREFI

Average periodic Refresh interval (tREFI) of DDR4 SDRAM is defined as shown in the table.

[Table 50] tREFI by device density

Parameter		Symbol	2Gb	4Gb	8Gb	16Gb	Units
Average periodic refresh interval	tREFI	$0^{\circ}C \le TCASE \le 85^{\circ}C$	7.8	7.8	7.8	TBD	μS
, tronago ponodio remoon interval		$85^{\circ}C < TCASE \le 95^{\circ}C$	3.9	3.9	3.9	TBD	μs



13.3 Timing Parameters by Speed Grade

[Table 51] Timing Parameters by Speed Bin for DDR4-1600 to DDR4-2400

Speed		DDR4	-1600	DDR4	1-1866	DDR4-2133		DDR4-2400			
Parameter	Symbol	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Units	NOTE
Clock Timing	Cymbol										
Minimum Clock Cycle Time (DLL off	tCK				İ					1	
mode)	(DLL_OFF)	8	-	8	-	8	-	8	-	ns	22
Average Clock Period	tCK(avg)	1.25	<1.5	1.071	<1.25	0.938	<1.071	0.833	<0.938	ns	35,36
Average high pulse width	tCH(avg)	0.48	0.52	0.48	0.52	0.48	0.52	0.48	0.52	tCK(avg)	
Average low pulse width	tCL(avg)	0.48	0.52	0.48	0.52	0.48	0.52	0.48	0.52	tCK(avg)	
Absolute Clock Period	tCK(abs)	tCK(avg)min + tJIT(per)min_ to t	tCK(avg)m ax + tJIT(per)m ax_tot	tCK(avg)min + tJIT(per)min_ to t	tCK(avg)m ax + tJIT(per)m ax_tot	tCK(avg)min + tJIT(per)min_ to t	tCK(avg)m ax + tJIT(per)m ax_tot	tCK(avg)min + tJIT(per)min _to t	tCK(avg)m ax + tJIT(per)m ax_tot	tCK(avg)	
Absolute clock HIGH pulse width	tCH(abs)	0.45	-	0.45	-	0.45	-	0.45	-	tCK(avg)	23
Absolute clock LOW pulse width	tCL(abs)	0.45	-	0.45	-	0.45	-	0.45	-	tCK(avg)	24
Clock Period Jitter- total	JIT(per)_tot	-63	63	-54	54	-47	47	-42	42	ps	23
Clock Period Jitter- deterministic	JIT(per)_dj	-31	31	-27	27	-23	23	-21	21	ps	26
Clock Period Jitter during DLL locking period	tJIT(per, lck)	-50	50	-43	43	-38	38	-33	33	ps	
Cycle to Cycle Period Jitter	tJIT(cc)_tota I	1:	25	1	07	94	4	8	3	ps	25
Cycle to Cycle Period Jitter determin- istic	tJIT(cc)_dj	6	3	5	54	4	7	4	-2	ps	26
Cycle to Cycle Period Jitter during DLL locking period	tJIT(cc, lck)	1	00	8	36	7	5	6	7	ps	
Duty Cycle Jitter	tJIT(duty)	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	ps	
Cumulative error across 2 cycles	tERR(2per)	-92	92	-79	79	-69	69	-61	61	ps	
Cumulative error across 3 cycles	tERR(3per)	-109	109	-94	94	-82	82	-73	73	ps	
Cumulative error across 4 cycles	tERR(4per)	-121	121	-104	104	-91	91	-81	81	ps	
Cumulative error across 5 cycles	tERR(5per)	-131	131	-112	112	-98	98	-87	87	ps	
Cumulative error across 6 cycles	tERR(6per)	-139	139	-119	119	-104	104	-92	92	ps	
Cumulative error across 7 cycles	tERR(7per)	-145	145	-124	124	-109	109	-97	97	ps	
Cumulative error across 8 cycles	tERR(8per)	-151	151	-129	129	-113	113	-101	101	ps	
Cumulative error across 9 cycles	tERR(9per)	-156	156	-134	134	-117	117	-104	104	ps	
Cumulative error across 10 cycles	tERR(10per)	-160	160	-137	137	-120	120	-107	107	ps	
Cumulative error across 11 cycles	tERR(11per)	-164	164	-141	141	-123	123	-110	110	ps	
Cumulative error across 12 cycles	tERR(12per)	-168	168	-144	144	-126	126	-112	112	ps	
Cumulative error across 13 cycles	tERR(13per)	-172	172	-147	147	-129	129	-114	114	ps	
Cumulative error across 14 cycles	tERR(14per)	-175	175	-150	150	-131	131	-116	116	ps	
Cumulative error across 15 cycles	tERR(15per)	-178	178	-152	152	-133	133	-118	118	ps	
Cumulative error across 16 cycles	tERR(16per)	-180	189	-155	155	-135	135	-120	120	ps	
Cumulative error across 17 cycles	tERR(17per)	-183	183	-157	157	-137	137	-122	122	ps	
Cumulative error across 18 cycles	tERR(18per)	-185	185	-159	159	-139	139	-124	124	ps	
Cumulative error across n = 13, 14 . 49, 50 cycles	tERR(nper)		I	^t ERR(nper)n ^t ERR(nper)r	nin = ((1 + 0.68li nax = ((1 + 0.68l	n(n)) * ^t JIT(per)_ n(n)) * ^t JIT(per)_	total min) total max)		I	ps	
Command and Address setup time to CK_t, CK_c referenced to Vih(ac) / Vil(ac) levels	tlS(base)	115	-	100	-	80	-	62	-	ps	
Command and Address setup time to CK_t, CK_c referenced to Vref levels	tIS(Vref)	215	-	200	-	180	-	162	-	ps	
Command and Address hold time to CK_t, CK_c referenced to Vih(dc) / Vil(dc) levels	tlH(base)	140	-	125	-	105	-	87	-	ps	
Command and Address hold time to CK_t, CK_c referenced to Vref levels	tlH(Vref)	215	-	200	-	180	-	162	-	ps	
Control and Address Input pulse width for each input	tIPW	600	-	525	-	460	-	410	-	ps	
Command and Address Timing											
CAS_n to CAS_n command delay for same bank group	tCCD_L	5	-	5	-	6	-	6	-	nCK	34



datasheet

Speed	Speed		-1600	DDR4	-1866	DDR4-	-2133	DDR4	-2400		
Parameter	Symbol	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Units	NOTE
CAS_n to CAS_n command delay for different bank group	tCCD_S	4	-	4	-	4	-	4	-	nCK	34
ACTIVATE to ACTIVATE Command delay to different bank group for 2KB page size	tRRD_S(2K)	Max(4nCK,6n s)	-	Max(4nCK,5. 3ns)	-	Max(4nCK,5. 3ns)	-	Max(4nCK,5 .3ns)	-	nCK	34
ACTIVATE to ACTIVATE Command delay to different bank group for 2KB page size	tRRD_S(1K)	Max(4nCK,5n s)	-	Max(4nCK,4. 2ns)	-	Max(4nCK,3. 7ns)	-	Max(4nCK,3 .3ns)	-	nCK	34
ACTIVATE to ACTIVATE Command delay to different bank group for 1/ 2KB page size	tRRD_S(1/ 2K)	Max(4nCK,5n s)	-	Max(4nCK,4. 2ns)	-	Max(4nCK,3. 7ns)	-	Max(4nCK,3 .3ns)	-	nCK	34
ACTIVATE to ACTIVATE Command delay to same bank group for 2KB page size	tRRD_L(2K)	Max(4nCK,7. 5ns)	-	Max(4nCK,6. 4ns)	-	Max(4nCK,6. 4ns)	-	Max(4nCK,6 .4ns)	-	nCK	34
ACTIVATE to ACTIVATE Command delay to same bank group for 1KB page size	tRRD_L(1K)	Max(4nCK,6n s)	-	Max(4nCK,5. 3ns)	-	Max(4nCK,5. 3ns)	-	Max(4nCK,4 .9ns)	-	nCK	34
ACTIVATE to ACTIVATE Command delay to same bank group for 1/2KB page size	tRRD_L(1/ 2K)	Max(4nCK,6n s)	-	Max(4nCK,5. 3ns)	-	Max(4nCK,5. 3ns)	-	Max(4nCK,4 .9ns)	-	nCK	34
Four activate window for 2KB page size	tFAW_2K	Max(28nCK,3 5ns)	-	Max(28nCK,3 0ns)	-	Max(28nCK,3 0ns)	-	Max(28nCK, 30ns)	-	ns	34
Four activate window for 1KB page size	tFAW_1K	Max(20nCK,2 5ns)	-	Max(20nCK,2 3ns)	-	Max(20nCK,2 1ns)	-	Max(20nCK, 21ns)	-	ns	34
Four activate window for 1/2KB page size	tFAW_1/2K	Max(16nCK,2 0ns)	-	Max(16nCK,1 7ns)	-	Max(16nCK,1 5ns)	-	Max(16nCK, 13ns)	-	ns	34
Delay from start of internal write trans- action to internal read command for different bank group	tWTR_S	max(2nCK,2. 5ns)	-	max(2nCK,2. 5ns)	-	max(2nCK,2. 5ns)	-	max (2nCK, 2.5ns)	-		1,2,e, 34
Delay from start of internal write trans- action to internal read command for same bank group	tWTR_L	max(4nCK,7. 5ns)	-	max(4nCK,7. 5ns)	-	max(4nCK,7. 5ns)	-	max (4nCK,7.5ns)	-		1,34
Internal READ Command to PRE- CHARGE Command delay	tRTP	max(4nCK,7. 5ns)	-	max(4nCK,7. 5ns)	-	max(4nCK,7. 5ns)	-	max (4nCK,7.5ns)	-		
WRITE recovery time	tWR	15	-	15	-	15	-	15	-	ns	1
Write recovery time when CRC and DM are enabled	tWR_CRC _DM	tWR+max (4nCK,3.75ns)	-	tWR+max (5nCK,3.75ns)	-	tWR+max (5nCK,3.75ns)	-	tWR+max (5nCK,3.75n s)	-	ns	1, 28
delay from start of internal write trans- action to internal read command for different bank group with both CRC and DM enabled	tWTR_S_C RC_DM	tWTR_S+ma x (4nCK,3.75ns)	-	tWTR_S+ma x (5nCK,3.75ns)	-	tWTR_S+ma x (5nCK,3.75ns)	-	tWTR_S+m ax (5nCK,3.75n s)	-	ns	2, 29, 34
delay from start of internal write trans- action to internal read command for same bank group with both CRC and DM enabled	tWTR_L_C RC_DM	tWTR_L+max (4nCK,3.75ns)	-	tWTR_L+max (5nCK,3.75ns)	-	tWTR_L+max (5nCK,3.75ns)	-	tWTR_L+m ax (5nCK,3.75n s)	-	ns	3,30, 34
DLL locking time	tDLLK	597	-	597	-	768	-	768	-	nCK	
Mode Register Set command cycle time	tMRD	8	-	8	-	8	-	8	-	nCK	
Mode Register Set command update delay	tMOD	max(24nCK,1 5ns)	-	max(24nCK,1 5ns)	-	max(24nCK,1 5ns)	-	max(24nCK, 15ns)	-		
Multi-Purpose Register Recovery Time	tMPRR	1	-	1	-	1	-	1	-	nCK	33
Multi Purpose Register Write Recovery Time	tWR_MPR	tMOD (min) + AL + PL	-	tMOD (min) + AL + PL	-	tMOD (min) + AL + PL	-	tMOD (min) + AL + PL	-	-	
Auto precharge write recovery + pre- charge time	tDAL(min)			Program	imed WR + rour	ndup (tRP / tCK(a	avg))			nCK	
CS_n to Command Address Latency	1										
CS_n to Command Address Latency	tCAL	3	-	4	-	4	-	5	-	nCK	
DRAM Data Timing		·						·	·		
DQS_t,DQS_c to DQ skew, per group, per access	tDQSQ	-	TBD	-	TBD	-	TBD	-	TBD	tCK(avg) /2	13,18
DQS_t,DQS_c to DQ Skew determin- istic, per group, per access	tDQSQ	-	TBD	-	TBD	-	TBD	-	TBD	tCK(avg) /2	14,16,1 8
DQ output hold time from DQS_t,DQS_c	tQH	TBD	-	TBD	-	TBD	-	TBD	-	tCK(avg) /2	13,17,1 8
DQ output hold time deterministic from DQS_t, DQS_c	tQH	TBD	-	TBD	-	TBD	-	TBD	-	UI	14,16.1 8
DQS_t,DQS_c to DQ Skew total, per group, per access; DBI enabled	tDQSQ	-	TBD	-	TBD	-	TBD	-	TBD	UI	13,19
DQ output hold time total from DQS_t, DQS_c; DBI enabled	tQH	TBD	-	TBD	-	TBD	-	TBD	-	UI	13,19



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Preliminary Rev. 0.5 DDR4 SDRAM

Speed		DDR4	-1600	DDR4	-1866	DDR4-	2133	DDR4	-2400		NOTE	
Parameter	Symbol	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Units	NOTE	
DQ to DQ offset , per group, per access referenced to DQS_t, DQS_c	tDQSQ	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	UI	15,16	
Data Strobe Timing	r			i		1		İ	i	r	1	
DQS_t, DQS_c differential READ Pre- amble (2 clock preamble)	tRPRE	0.9	TBD	0.9	TBD	0.9	TBD	0.9	TBD	tCK		
DQS_t, DQS_c differential READ Postamble	tRPST	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	tCK		
DQS_t,DQS_c differential output high time	tQSH	0.4	-	0.4	-	0.4	-	0.4	-	tCK	21	
DQS_t,DQS_c differential output low time	tQSL	0.4	-	0.4	-	0.4	-	0.4	-	tCK	20	
DQS_t, DQS_c differential WRITE Preamble	tWPRE	0.9	-	0.9	-	0.9	-	0.9	-	tCK		
DQS_t, DQS_c differential WRITE Postamble	tWPST	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD	tCK		
DQS_t and DQS_c low-impedance time (Referenced from RL-1)	tLZ(DQS)	-450	225	-390	195	-360	180	-300	150	ps		
DQS_t and DQS_c high-impedance time (Referenced from RL+BL/2)	tHZ(DQS)	-	225	-	195	-	180	-	150	ps		
DQS_t, DQS_c differential input low pulse width	tDQSL	0.46	0.54	0.46	0.54	0.46	0.54	0.46	0.54	tCK		
DQS_t, DQS_c differential input high pulse width	tDQSH	0.46	0.54	0.46	0.54	0.46	0.54	0.46	0.54	tCK		
DQS_t, DQS_c rising edge to CK_t, CK_c rising edge (1 clock preamble)	tDQSS	-0.27	0.27	-0.27	0.27	-0.27	0.27	-0.27	0.27	tCK		
DQS_t, DQS_c falling edge setup time to CK_t, CK_c rising edge	tDSS	0.18	-	0.18	-	0.18	-	0.18	-	tCK		
DQS_t, DQS_c falling edge hold time from CK_t, CK_c rising edge	tDSH	0.18	-	0.18	-	0.18	-	0.18	-	tCK		
MPSM Timing												
Command path disable delay upon MPSM entry	tMPED	tMOD(min) + tCPDED(min)	-	tMOD(min) + tCPDED(min)	-	tMOD(min) + tCPDED(min)	-	tMOD(min) + tCP- DED(min)	-			
Valid clock requirement after MPSM entry	tCKMPE	tMOD(min) + tCPDED(min)	-	tMOD(min) + tCPDED(min)	-	tMOD(min) + tCPDED(min)	-	tMOD(min) + tCP- DED(min)	-			
Valid clock requirement before MPSM exit	tCKMPX	tCKSRX(min)		tCKSRX(min)		tCKSRX(min)		tCK- SRX(min)	-			
Exit MPSM to commands not requiring a locked DLL	tXMP	TBD		TBD		TBD		TBD	-			
Exit MPSM to commands requiring a locked DLL	tXMPDLL	tXMP(min) + tXSDLL(min)		tXMP(min) + tXSDLL(min)		tXMP(min) + tXSDLL(min)		tXMP(min)+ tXS- DLL(min)	-			
CS setup time to CKE	tMPX_S	TBD	-	TBD	-	TBD	-	TBD	-			
CS hold time to CKE	tMPX_H	TBD	-	TBD	-	TBD	-	TBD	-			
Calibration Timing	1			1		1		1	1	1	1	
Power-up and RESET calibration time	tZQinit	1024	-	1024	-	1024	-	1024	-	nCK		
Normal operation Full calibration time Normal operation Short calibration	tZQoper tZQCS	512 128	-	512 128	-	512 128	-	512 128	-	nCK nCK		
time Reset/Self Refresh Timing												
Exit Reset from CKE HIGH to a valid command	tXPR	max (5nCK,tRFC(min)+ 10ns)	-	max (5nCK,tRFC(min)+ 10ns)	-	max (5nCK,tRFC(min)+ 10ns)	-	max (5nCK,tRFC (min)+10ns)	-			
Exit Self Refresh to commands not re- quiring a locked DLL	tXS	tRFC(min)+1 0ns	-	tRFC(min)+1 Ons	-	tRFC(min)+1 0ns	-	tRFC(min)+ 10ns	-			
SRX to commands not requiring a locked DLL in Self Refresh ABORT	tXS_ABORT (min)	tRFC4(min)+ 10ns	-	tRFC4(min)+ 10ns	-	tRFC4(min)+ 10ns	-	tRFC4(min) +10ns	-			
Exit Self Refresh to ZQCL,ZQCS and MRS (CL,CWL,WR,RTP and Gear Down)	tXS_FAST (min)	tRFC4(min)+ 10ns	-	tRFC4(min)+ 10ns	-	tRFC4(min)+ 10ns	-	tRFC4(min) +10ns	-			
Exit Self Refresh to commands requir- ing a locked DLL	tXSDLL	tDLLK(min)	-	tDLLK(min)	-	tDLLK(min)	-	tDLLK(min)	-			
Minimum CKE low width for Self re- fresh entry to exit timing	tCKESR	tCKE(min)+1 nCK	-	tCKE(min)+1 nCK	-	tCKE(min)+1 nCK	-	tCKE(min)+ 1nCK	-			
Minimum CKE low width for Self re- fresh entry to exit timing with CA Pari- ty enabled	tCKESR_ PAR	tCKE(min)+ 1nCK+PL	-	tCKE(min)+ 1nCK+PL	-	tCKE(min)+ 1nCK+PL	-	tCKE(min)+ 1nCK+PL	-			



datasheet

Preliminary Rev. 0.5 DDR4 SDRAM

PromoterSymbolSymbolMAXNMAMAXNMAMAXNMAN	Speed		DDR4	-1600	DDR4	-1866	DDR4-	-2133	DDR4	-2400		
Referse Fig. (No. 2) COS STE No. 10 - Internation of the set of	Parameter	Symbol	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Units	NOTE
Betters in right of the probate in the pro	Valid Clock Requirement after Self Refresh Entry (SRE) or Power-Down Entry (PDE)	tCKSRE		-		-		-		-		
Beden E. (BX) of Youe - Down IDS (R) Warring (N) 1 <th1< th=""></th1<>	Valid Clock Requirement after Self Refresh Entry (SRE) or Power-Down when CA Parity is enabled		(5nCK,10ns)	-	(5nCK,10ns)	-	(5nCK,10ns)	-	(5nCK,10ns)	-		
BLAP Deter Shift LL on target of command proves DVP (mox (mD_C,Gm) ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·< ·<	Valid Clock Requirement before Self Refresh Exit (SRX) or Power-Down Exit (PDX) or Reset Exit	tCKSRX		-		-		-		-		
value commands bp mss (a, b) · mss (a, b) <thmss< th=""> mss <thmss< th=""> <thms< td=""><td>Power Down Timing</td><td>1</td><td></td><td></td><td></td><td></td><td></td><td></td><td>1</td><td></td><td>1</td><td></td></thms<></thmss<></thmss<>	Power Down Timing	1							1		1	
Normal pairs Normal pairs	Exit Power Down with DLL on to any valid command;Exit Precharge Power Down with DLL frozen to commands not requiring a locked DLL	tXP		-		-		-		-		
Peake Down Entry to EuX Timing IPD ICKE (min) 9'IREFI ICKE (min) 1'ICKE (min)	CKE minimum pulse width	tCKE		-		-		-		-		31,32
Thing of ACT command to Power ontry IACT PORE I ·< I I	Command pass disable delay	tCPDED	4	-	4	-	4	-	4	-	nCK	
Dom IncTPDEN 1 . 1 . 2 . R.C 7 Timing of REF or PELA command IPRPDEN 1 . 1 . 2 R.C 7 Timing of REF or PELA command ID Power IPRPDEN RL +1+1 L +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 RL +1+1 <td>Power Down Entry to Exit Timing</td> <td>tPD</td> <td>tCKE(min)</td> <td>9*tREFI</td> <td>tCKE(min)</td> <td>9*tREFI</td> <td>tCKE(min)</td> <td>9*tREFI</td> <td>tCKE(min)</td> <td>9*tREFI</td> <td></td> <td>6</td>	Power Down Entry to Exit Timing	tPD	tCKE(min)	9*tREFI	tCKE(min)	9*tREFI	tCKE(min)	9*tREFI	tCKE(min)	9*tREFI		6
Prove Down entry PHPCUEN I - I - I - I - I - I - I - I - I - I - I - I - I - I - I - I - I - I - I	Timing of ACT command to Power Down entry	tACTPDEN	1	-	1	-	2	-	2	-	nCK	7
ar Down entry DED/EN PEC+4*1 - FL*4*1	Timing of PRE or PREA command to Power Down entry	tPRPDEN	1	-	1	-	2	-	2	-	nCK	7
Down try (BLOT, BLAMRS, BLOT) WIRPDEN MURTUNIN (KNOW) - MURA (KNOW) <	Timing of RD/RDA command to Pow- er Down entry	tRDPDEN	RL+4+1	-	RL+4+1	-	RL+4+1	-	RL+4+1	-	nCK	
Down entry (BQROTF, BLARRS, BC4OTF) WR.4PDER WL.4+WR+1 - WL.4+WR+1 WL.2+(WR+1 - WL.2+(WR+1	Timing of WR command to Power Down entry (BL8OTF, BL8MRS, BC4OTF)	tWRPDEN		-		-		-		-	nCK	4
$ \begin{array}{ c c c c c } \begin{tabular}{ c c c c c } begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	Timing of WRA command to Power Down entry (BL8OTF, BL8MRS, BC4OTF)	tWRAPDEN	WL+4+WR+1	-	WL+4+WR+1	-	WL+4+WR+1	-		-	nCK	5
Downer (BCAMRS) DEN VUL*2*WK*1 - VUL*2*WK*1 - 1 1 - 1 0 1 0 1 0 1 0 1 1 1 1 1 1	Timing of WR command to Power Down entry (BC4MRS)			-		-		-		-	nCK	4
Down entryIREFPDEN1-1-1-2-2-nnn <th< td=""><td>Timing of WRA command to Power Down entry (BC4MRS)</td><td></td><td>WL+2+WR+1</td><td>-</td><td>WL+2+WR+1</td><td>-</td><td>WL+2+WR+1</td><td>-</td><td></td><td>-</td><td>nCK</td><td>5</td></th<>	Timing of WRA command to Power Down entry (BC4MRS)		WL+2+WR+1	-	WL+2+WR+1	-	WL+2+WR+1	-		-	nCK	5
Down entrytMSPDENtMOD(min)-tMOD(min)-tMOD(min)-tMOD(min)-tMOD(min)-tMOD(min)-tMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-ttMOD(min)-MOD(min)MOD(min)-MOD(min)MOD(min)MOD(min)MOD(min)MOD(min	Timing of REF command to Power Down entry	tREFPDEN	1	-	1	-	2	-	2	-	nCK	7
Mode Register Set command cycle time in PDA modetMRD_PDAmax(16nCK,1 Ons)max(16nCK,1 On<)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nCK,1 Ons)max(16nC	Timing of MRS command to Power Down entry	tMRSPDEN	tMOD(min)	-	tMOD(min)	-	tMOD(min)	-	tMOD(min)	-		
time in PDA mode time DA ons ons ons tions tions c c c Mode Register Set command update delay in PDA mode MOD_PDA tMOD_V tMOD tmode	PDA Timing	1									Į.	
delay in PDA mode INCOPDA INCO INC	Mode Register Set command cycle time in PDA mode	tMRD_PDA										
Asynchronous RTT turn-on delay (Power-Down with DLL frozen) tAONAS 1.0 9.0 1.0 9.0 1.0 9.0 ns Asynchronous RTT turn-off delay (Power-Down with DLL frozen) tAORAS 1.0 9.0 1.0 9.0 1.0 9.0 ns Asynchronous RTT turn-off delay (Power-Down with DLL frozen) tAORAS 1.0 9.0 1.0 9.0 1.0 9.0 ns RTT dynamic change skew tADC 0.3 0.7 0.3 0.7 0.3 0.7 0.3 0.7 tCK(avg) Write Leveling Timing write leveling mode is programmed tWLMRD 40 - 40 - 40 - nCK 12 DQS_VDQS_n delay after write level- ing mode is programmed tWLDQSEN 25 - 25 - 25 - nCK 12 Write leveling setup time from rising DQS_n crossing to rising DQS_trop 0.13 - 0.13 - tCK(avg) - tCK(avg) - tCK(avg) - tCK(avg) - tCK(avg	Mode Register Set command update delay in PDA mode	tMOD_PDA	tMO	DD	tMO	OD	tMC	D	tM	OD		
(Power-Down with DLL frozen) DOUNDS 1.0 9.0 1.0 <th1< td=""><td>ODT Timing</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></th1<>	ODT Timing											
(Power-Down with DLL frozen) IAOPAS I.0 9.0 I.0 1.0 1.0 1.0 1.0 1.0 1.0 <th1< td=""><td>Asynchronous RTT turn-on delay (Power-Down with DLL frozen)</td><td>tAONAS</td><td>1.0</td><td>9.0</td><td>1.0</td><td>9.0</td><td>1.0</td><td>9.0</td><td>1.0</td><td>9.0</td><td>ns</td><td></td></th1<>	Asynchronous RTT turn-on delay (Power-Down with DLL frozen)	tAONAS	1.0	9.0	1.0	9.0	1.0	9.0	1.0	9.0	ns	
Write Leveling Timing First DQS_t/DQS_n rising edge after write leveling mode is programmed tWLMRD 40 - 40 - 40 - nCK 12 DQS_t/DQS_n delay after write leveling mode is programmed tWLDQSEN 25 - 25 - 25 - nCK 12 DQS_t/DQS_n delay after write leveling mode is programmed tWLDQSEN 25 - 25 - 25 - nCK 12 Write leveling setup time from rising CK_t, CK_c crossing to rising DQS_t/ tWLS 0.13 - 0.13 - 0.13 - tCK(avg) 12 Write leveling hold time from rising DQS_t/ tWLS 0.13 - 0.13 - 0.13 - tCK(avg) 12 Write leveling hold time from rising CK_t, CK_c crossing tWLH 0.13 - 0.13 - 0.13 - tCK(avg) 12 Write leveling output delay tWLO 0 9.5 0 9.5 0 9.5 0 9.5 ns 12 Write leveling output delay tWLO 0 9.5 0	Asynchronous RTT turn-off delay (Power-Down with DLL frozen)	tAOFAS	1.0	9.0	1.0	9.0	1.0	9.0	1.0	9.0	ns	
First DQS_t/DQS_n rising edge after write leveling mode is programmedtWLMRD40-40-40-40-nCK12DQS_t/DQS_n delay after write level- ing mode is programmedtWLDQSEN25-25-25-25-nCK12Write leveling setup time from rising CK_t, CK_c crossing to rising DQS_t/ DQS_n crossingtWLS0.13-0.13-0.13-0.13-tCK(avg)Write leveling hold time from rising DQS_t/DQS_n crossingtWLH0.13-0.13-0.13-0.13-tCK(avg)Write leveling output delaytWLO09.509.509.509.5nsWrite leveling output delaytWLO09.509.509.509.5nsCA Parity TimingtWLODDDDDDDDDDDDDCommands not guaranteed to be exe-tPAR_UNKNDIDIDIDIDIDIDIDIDIDIDIDIDIDI	RTT dynamic change skew	tADC	0.3	0.7	0.3	0.7	0.3	0.7	0.3	0.7	tCK(avg)	
write leveling mode is programmedtWLMRD40-40-40-40-12DQS_t/DQS_n delay after write level- ing mode is programmedtWLDQSEN25-25-25-25-nCK12Write leveling setup time from rising DQS_n crossingtWLS0.13-0.13-0.13-0.13-nCK12Write leveling hold time from rising DQS_n crossingtWLS0.13-0.13-0.13-0.13-tCK(avg)Write leveling number from rising DQS_t/DQS_n crossing to rising CK_t, CK_c crossing to rising CK_t, CK_c crossing to rising CK_t, CK_c crossing to rising CK_t, CK_c crossing to rising CK_t, CK_c crossingtWLH0.13-0.13-0.13-tCK(avg)Write leveling output delaytWLO09.509.509.509.509.5nsWrite leveling output delaytWLOE0.13-tCK(avg)nsWrite leveling output errortWLOE0.13-0.13-nsCommands not guaranteed to be exe-tPAR_UNKNDIDIDIDIDIDIDIDIDIDIDIDICommands not guaranteed to be exe-tPAR_UNKNDIDIDIDIDIDIDIDIDIDIDIDICommand	Write Leveling Timing											
ing mode is programmedtWLDQSEN25-25-25-10K12Write leveling setup time from rising DQS_n crossingtWLS0.13-0.13-0.13-0.13-tCK(avg)Write leveling hold time from rising DQS_t/DQS_n crossingtWLH0.13-0.13-0.13-tCK(avg)Write leveling output delaytWLO09.509.509.509.50Write leveling output delaytWLOE0.13-0.13-tCK(avg)Write leveling output delaytWLO09.509.509.509.5Write leveling output delaytWLOE0.13-tCK(avg)Commands not guaranteed to be exe.tPAR_UNKNDIDIDIDIDIDIDIDIDI	First DQS_t/DQS_n rising edge after write leveling mode is programmed	tWLMRD	40	-	40	-	40	-	40	-	nCK	12
CK_t, CK_c crossing to rising DQS_t/ DQS_n crossing tWLS 0.13 - 0.13 - 0.13 - tCK(avg) Write leveling hold time from rising DQS_t/DQS_n crossing to rising CK_t, CK_c crossing tWLH 0.13 - 0.13 - 0.13 - tCK(avg) Write leveling output delay tWLO 0 9.5 0 1 0 0 <t< td=""><td>DQS_t/DQS_n delay after write level- ing mode is programmed</td><td>tWLDQSEN</td><td>25</td><td>-</td><td>25</td><td>-</td><td>25</td><td>-</td><td>25</td><td>-</td><td>nCK</td><td>12</td></t<>	DQS_t/DQS_n delay after write level- ing mode is programmed	tWLDQSEN	25	-	25	-	25	-	25	-	nCK	12
DQS_t/DQS_n crossing to rising tWLH 0.13 - 0.13 - 0.13 - tCK(avg) Write leveling output delay tWLO 0 9.5 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Write leveling setup time from rising CK_t, CK_c crossing to rising DQS_t/ DQS_n crossing	tWLS	0.13	-	0.13	-	0.13	-	0.13	-	tCK(avg)	
Control Control	Write leveling hold time from rising DQS_t/DQS_n crossing to rising CK_t, CK_ crossing	tWLH	0.13	-	0.13	-	0.13	-	0.13	-	tCK(avg)	
CA Parity Timing Commands not guaranteed to be exe- tPAR_UNKN DI DI DI DI DI DI DI DI DI DI DI DI DI	Write leveling output delay	tWLO	0	9.5	0	9.5	0	9.5	0	9.5	ns	
Commands not guaranteed to be exe- tPAR_UNKN DI DI DI DI DI DI DI	Write leveling output error	tWLOE									ns	
	CA Parity Timing											
	Commands not guaranteed to be exe- cuted during this time		-	PL	-	PL	-	PL	-	PL		



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Speed		DDR4-1600		DDR4	-1866	DDR4	-2133	DDR4	-2400		
Parameter	Symbol	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	Units	NOTE
Delay from errant command to ALERT_n assertion	tPAR_ALER T_ON	-	PL+6ns	-	PL+6ns	-	PL+6ns	-	PL+6ns		
Pulse width of ALERT_n signal when asserted	tPAR_ALER T_PW	48	96	56	112	64	128	72	144	nCK	
Time from when Alert is asserted till controller must start providing DES commands in Persistent CA parity mode	tPAR_ALER T_RSP	-	43	-	50	-	57	-	64	nCK	
Parity Latency	PL		4		4	4	ļ	:	5	nCK	
CRC Error Reporting											
CRC error to ALERT_n latency	tCRC_ALER T	3	13	3	13	3	13	3	13	ns	
CRC ALERT_n pulse width	CRC_ALER T_PW	6	10	6	10	6	10	6	10	nCK	
tREFI											•
	2Gb	160	-	160	-	160	-	160	-	ns	34
tRFC1 (min)	4Gb	260	-	260	-	260	-	260	-	ns	34
	8Gb	350	-	350	-	350	-	350	-	ns	34
	16Gb	TBD	-	TBD	-	TBD	-	TBD	-	ns	34
	2Gb	110	-	110	-	110	-	110	-	ns	34
tRFC2 (min)	4Gb	160	-	160	-	160	-	160	-	ns	34
	8Gb	260	-	260	-	260	-	260	-	ns	34
	16Gb	TBD	-	TBD	-	TBD	-	TBD	-	ns	34
	2Gb	90	-	90	-	90	-	90	-	ns	34
	4Gb	110	-	110	-	110	-	110	-	ns	34
tRFC4 (min)	8Gb	160	-	160	-	160	-	160	-	ns	34
	16Gb	TBD	-	TBD	-	TBD	-	TBD	-	ns	34



NOTE :

- 1. Start of internal write transaction is defined as follows :

- For BL8 (Fixed by MRS and on-the-fly): Rising clock edge 4 clock cycles after WL.
 For BC4 (on-the-fly): Rising clock edge 4 clock cycles after WL.
 For BC4 (fixed by MRS): Rising clock edge 2 clock cycles after WL.
 A separate timing parameter will cover the delay from write to read when CRC and DM are simultaneously enabled
- Commands requiring a locked DLL are: READ (and RAP) and synchronous ODT commands.
 tWR is defined in ns, for calculation of tWRPDEN it is necessary to round up tWR/tCK to the next integer.
- 5. WR in clock cycles as programmed in MR0.
- tREFI depends on TOPER.
- CKE is allowed to be registered low while operations such as row activation, precharge, autoprecharge or refresh are in progress, but power-down
- IDD spec will not be applied until finishing those operations. 8. For these parameters, the DDR4 SDRAM device supports tnPARAM[nCK]=RU{tPARAM[ns]/tCK(avg)[ns]}, which is in clock cycles assuming all input clock jitter specifications are satisfied
- 9. When CRC and DM are both enabled, tWR_CRC_DM is used in place of tWR.
- 10. When CRC and DM are both enabled tWTR_S_CRC_DM is used in place of tWTR_S.
- 11. When CRC and DM are both enabled tWTR_L_CRC_DM is used in place of tWTR_L
- 12. The max values are system dependent.

13. DQ to DQS total timing per group where the total includes the sum of deterministic and random timing terms for a specified BER. BER spec and measurement method are tbd.

- 14. The deterministic component of the total timing. Measurement method tbd.
- 15. DQ to DQ static offset relative to strobe per group. Measurement method tbd.
- 16. This parameter will be characterized and guaranteed by design.
- 17 When the device is operated with the input clock jitter, this parameter needs to be derated by the actual tjit(per)_total of the input clock. (output deratings are relative to the SDRAM input clock). Example tbd.
- 18. DRAM DBI mode is off.
- 19. DRAM DBI mode is enabled. Applicable to x8 and x16 DRAM only.
- 20. tQSL describes the instantaneous differential output low pulse width on DQS_t DQS_c, as measured from on falling edge to the next consecutive rising edge
- 21. tQSH describes the instantaneous differential output high pulse width on DQS_t DQS_c, as measured from on falling edge to the next consecutive rising edge
- 22. There is no maximum cycle time limit besides the need to satisfy the refresh interval tREFI
- 23. tCH(abs) is the absolute instantaneous clock high pulse width, as measured from one rising edge to the following falling edge
- 24. tCL(abs) is the absolute instantaneous clock low pulse width, as measured from one falling edge to the following rising edge
- 25. Total jitter includes the sum of deterministic and random jitter terms for a specified BER. BER target and measurement method are tbd.
- 26. The deterministic jitter component out of the total jitter. This parameter is characterized and gauranteed by design.
- 27. This parameter has to be even number of clocks
- 28. When CRC and DM are both enabled, tWR_CRC_DM is used in place of tWR.
- 29. When CRC and DM are both enabled tWTR_S_CRC_DM is used in place of tWTR_S.
- 30. When CRC and DM are both enabled tWTR_L_CRC_DM is used in place of tWTR_L.
- 31. After CKE is registered LOW, CKE signal level shall be maintained below VILDC for tCKE specification (Low pulse width).
- 32. After CKE is registered HIGH, CKE signal level shall be maintained above VIHDC for tCKE specification (HIGH pulse width).
- 33. Defined between end of MPR read burst and MRS which reloads MPR or disables MPR function.
- 34. Parameters apply from tCK(avg)min to tCK(avg)max at all standard JEDEC clock period values as stated in the Speed Bin Tables.
- 35. This parameter must keep consistency with Speed-Bin Tables shown in section 10.
- 36. DDR4-1600 AC timing apply if DRAM operates at lower than 1600 MT/s data rate.

UI=tCK(avg).min/2



13.4 The DQ input receiver compliance mask for voltage and timing (see figure)

The DQ input receiver compliance mask for voltage and timing is shown in the figure below. The receiver mask (Rx Mask) defines area the input signal must not encroach in order for the DRAM input receiver to be expected to be able to successfully capture a valid input signal; it is not the valid data-eye.

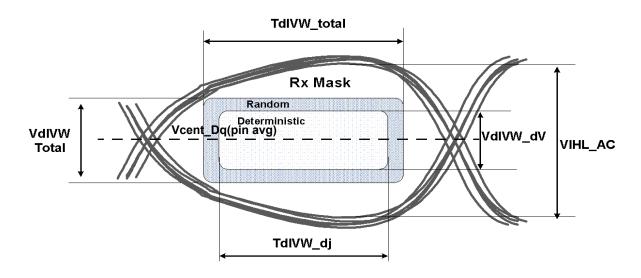


Figure 22. DQ Receiver(Rx) compliance mask

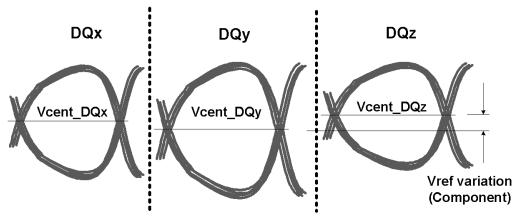


Figure 23. Across pin Vref DQ voltage variation

Vcent_DQ(pin avg) is defined as the midpoint between the largest Vref_DQ voltage level and the smallest Vref_DQ voltage level across all DQ pins for a given DRAM component. Each DQ pin Vref level is defined by the center, i.e. widest opening, of the cumulative data input eye as depicted in Figure 22. This clarifies that any DRAM component level variation must be accounted for within the DRAM Rx mask. The component level Vref will be set by the system to account for Ron and ODT settings.



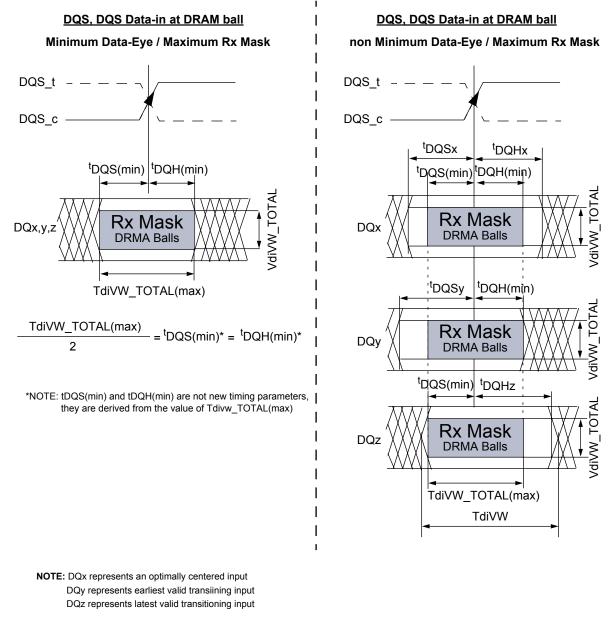
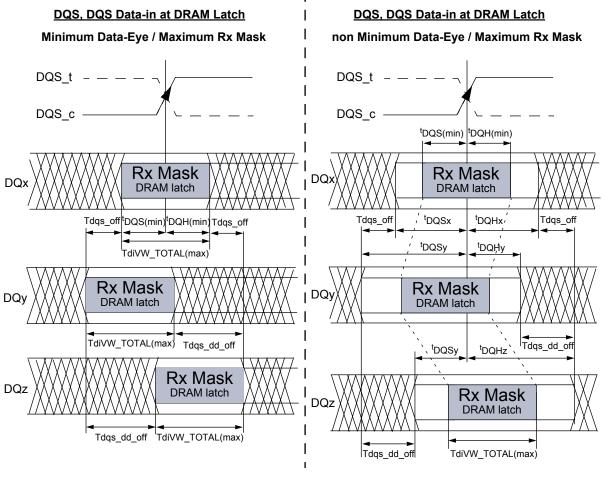


Figure 24. DQ to DQS Timings at DRAM Balls

All of the timing terms in Figure 24 are measured at the VdIVW_total voltage levels centered around Vcent_DQ(pin avg) and are referenced to the DQS_t/DQS_c center aligned to the DQ per pin.



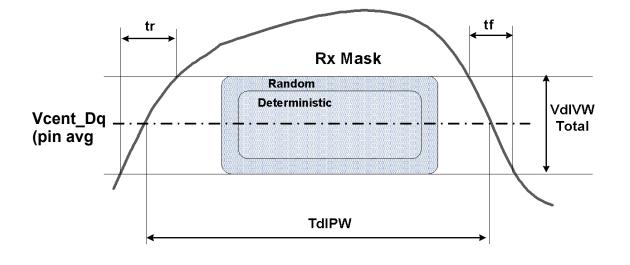


NOTE: DQx represents an optimally centered input DQy represents earliest valid transiining input DQz represents latest valid transitioning input

Figure 25. DQ to DQS Timings at DRAM latch

All of the timing terms in Figure 25 are measured at the VdIVW_total voltage levels centered around Vcent_DQ(pin avg) and are referenced to the DQS_t/ DQS_c center aligned. Typical view assumes DQx, DQy, and DQz edges are aligned at DRAM balls.





NOTE : 1. SRIN_dIVW=VdIVW_Total/(tr or tf), signal must be monotonic within tr and tf range.

Figure 26. DQ TdIPW and SRIN_dIVW definition (for each input pulse)



[Table 52] DRAM DQs In Receive Mode; * UI=tck(avg)min/2

Symbol	Parameter	DDR4 - 160	0/1866/2133	DDR4	- 2400	Unit	NOTE
Symbol	Parameter	min	max	min	max	Unit	NOTE
VdIVW_total	Rx Mask voltage - p-p total	-	136 (note12)	-	TBD	mV	1,2,4,6
VdIVW_dV	Rx Mask voltage - deterministic	-	136	-	TBD	mV	1,5,13
TdIVW_total	Rx timing window total	-	0.2 (note12)	-	TBD	UI*	1,2,4,6
TdIVW_dj	Rx deterministic timing	-	0.2	-	TBD	UI*	1,5,13
VIHL_AC	DQ AC input swing pk-pk	186	-	TBD	-	mV	7
TdIPW	DQ input pulse width	0.58		TBD	-	UI*	8
Tdqs_off	DQ to DQS Setup offset	-	TBD	-	TBD	UI*	9
Tdqh_off	DQ to DQS Hold offset	-	TBD	-	TBD	UI*	9
Tdqs_dd_off	DQ to DQ Setup offset	-	TBD	-	TBD	UI*	10
Tdqh_dd_off	DQ to DQ Hold offset	-	TBD	-	TBD	UI*	10
SRIN_dIVW	Input Slew Rate over VdIVW_total	TBD	9	TBD	TBD	V/ns	11

NOTE :

 Data Rx mask voltage and timing total input valid window where VdIVW is centered around Vcent_DQ(pin avg). The data Rx mask is applied per bit and should include voltage and temperature drift terms. The design specification is BER <1e-16 and how this varies for lower BER is tbd. The BER will be characterized and extrapolated if necessary using a dual dirac method from a higher BER(tbd).

2. Rx mask voltage AC swing peak-peak requirement over TdIVW_total with at least half of TdIVW_total(max) above Vcent_DQ(pin avg) and at least half of TdIVW_total(max) below Vcent_DQ(pin avg).

3. Rx differential DQ to DQS jitter total timing window at the VdIVW voltage levels centered around Vcent_DQ(pin avg).

4. Defined over the DQ internal Vref range 1.

5. Deterministic component of the total Rx mask voltage or timing. Parameter will be characterized and guaranteed by design. Measurement method tbd

6. Overshoot and Undershoot Specifications tbd.

7. DQ input pulse signal swing into the receiver must meet or exceed VIHL AC at any point over the total UI. No timing requirement above level. VIHL AC is the peak to peak voltage centered around Vcent_DQ(pin avg)

8. DQ minimum input pulse width defined at the Vcent_DQ(pin avg).

9. DQ to DQS setup or hold offset defined within byte from DRAM ball to DRAM internal latch; ^tDQS and ^tDQH are the minimum DQ setup and hold per DQ pin; each is equal to one-half of TdIVW_total(max).

10. DQ to DQ setup or hold delta offset within byte. Defined as the static difference in Tdqs_off(max) and Tdqs_off(min) or Tdqh(max) – Tdqh(min) for a given component, from DRAM ball to DRAM internal latch.

11. Input slew rate over VdIVW Mask centered at Vcent_DQ(pin avg). Slowest DQ slew rate to fastest DQ slew rate per transition edge must be within tbd V/ns of each other. 12. The total timing and voltage terms(tdIVW_total & VdIVWtotal) are valid for any BER lower {lower fail rate} than the spec.

13. VdIVW_total - VdIVW_dV and TdIVW_total - TdIVW_dj define the difference between random and deterministic fail mask. When VdIVW_total - VdIVW_dV = 0 and TdIVW_total - TdIVW_dj = 0, random error is assumed to be zero.



13.5 DDR4 Function Matrix

DDR4 SDRAM has several features supported by ORG and also by Speed. The following Table is the summary of the features.

[Table 53] Function Matrix (By ORG. V:Supported, Blank:Not supported)

Functions	x4	x8	x16	NOTE
Write Leveling	V	V	V	
Temperature controlled Refresh	V	V	V	
Low Power Auto Self Refresh	V	V	V	
Fine Granularity Refresh	V	V	V	
Multi Purpose Register	V	V	V	
Data Mask		V	V	
Data Bus Inversion		V	V	
TDQS		V		
ZQ calibration	V	V	V	
DQ Vref Training	V	V	V	
Per DRAM Addressability	V	V	V	
Mode Register Readout	V	V	V	
CAL	V	V	V	
WRITE CRC	V	V	V	
CA Parity	V	V	V	
Control Gear Down Mode	V	V	V	
Programmable Preamble	V	V	V	
Maximum Power Down Mode	V	V		
Boundary Scan Mode			V	
Additive Latency	V	V		
3DS	V	V		

[Table 54] Function Matrix (By Speed. V:Supported, Blank:Not supported)

Functions	1600/1866/2133 Mbps	2400 Mbps	NOTE
Write Leveling	V	V	
Temperature controlled Refresh	V	V	
Low Power Auto Self Refresh	V	V	
Fine Granularity Refresh	V	V	
Multi Purpose Register	V	V	
Data Mask	V	V	
Data Bus Inversion	V	V	
TDQS	V	V	
ZQ calibration	V	V	
DQ Vref Training	V	V	
Per DRAM Addressability	V	V	
Mode Register Readout	V	V	
CAL	V	V	
WRITE CRC	V	V	
CA Parity	V	V	
Control Gear Down Mode			
Programmable Preamble (= 2tCK)		V	
Maximum Power Down Mode	V	V	
Boundary Scan Mode	V	V	
3DS	V	V	

