

EMC1701

High-Side Current-Sense and Internal 1°C Temperature Monitor

PRODUCT FEATURES

Datasheet

General Description

The EMC1701 is a combination high-side current sensing device with precision temperature measurement. It measures the voltage developed across an external sense resistor to represent the high-side current of a battery or voltage regulator. The EMC1701 also measures the source voltage and uses these measured values to present a proportional power calculation. The EMC1701 contains additional bi-directional peak detection circuitry to flag instantaneous current spikes with programmable time duration and magnitude threshold. Finally, the EMC1701 includes an internal diode channel for ambient temperature measurement.

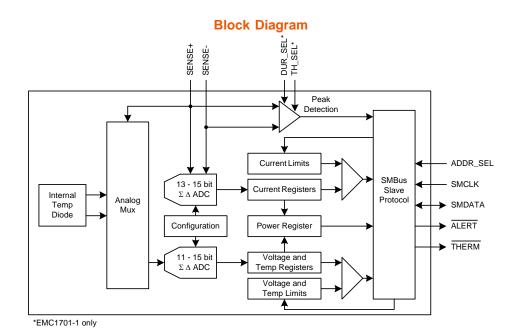
Both current sensing and temperature monitoring include two tiers of protection: one that can be masked and causes the ALERT pin to be asserted, and the other that cannot be masked and causes the THERM pin to be asserted.

Applications

- Notebook and Desktop Computers
- Industrial
- Power Management Systems
- **Embedded Applications**

Features

- High-side current sensor
 - Bi-directional current measurement
 - Measures source voltage and indicates power ratio
 - 1% current measurement accuracy
 - Integrated over 82ms to 2.6sec with 11-bit resolution
 - 3V to 24V bus voltage range
- Independent hardware set instantaneous current peak detector (EMC1701-1 only)
 - Software controls to program time duration and magnitude threshold
- Power supply options
- Bus or separately powered for low voltage operation
- Wide temperature operating range: -40°C to +85°C
- Internal temperature monitor
- ±1°C accuracy (-5°C < T_A < 85°C)
 ALERT and THERM outputs for temperature, voltage, and out-of-current limit reporting
- SMBus 2.0 interface
 - Pin-selectable SMBus Address
 - Block Read and Write
- Available in a 12-pin 4mm x 4mm QFN RoHS Compliant Package (EMC1701-1)
- Available in a 10-pin MSOP RoHS Compliant Package (EMC1701-2)





Ordering Information:

| ORDERING NUMBER | PACKAGE | FEATURES |
|-------------------|---|--|
| EMC1701-1-KP-TR | 12-pin 4mm x 4mm QFN (Lead-free RoHS compliant) | Internal diode, current sensor, hardware set peak detector |
| EMC1701-2-AIZL-TR | 10-pin MSOP (Lead-free RoHS compliant) | Internal diode, current sensor |

REEL SIZE IS 4,000 PIECES

This product meets the halogen maximum concentration values per IEC61249-2-21 For RoHS compliance and environmental information, please visit www.smsc.com/rohs



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Chapter 1 Pin Description

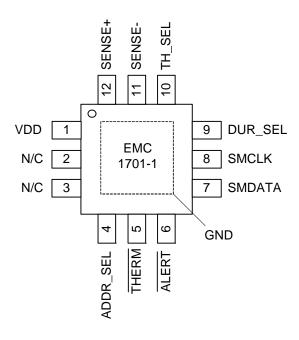


Figure 1.1 EMC1701 Pin Diagram 12-Pin QFN 4mm x 4mm

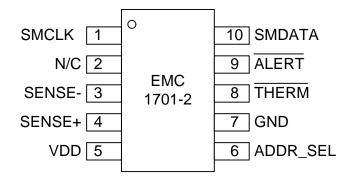


Figure 1.2 EMC1701 Pin Diagram 10-Pin MSOP



Table 1.1 Pin Description for EMC1701

| PIN NUMBER EMC1701-1 | PIN NUMBER EMC1701-2 | PIN NAME | PIN FUNCTION | PIN TYPE |
|----------------------------|----------------------------|----------|--|-------------|
| 1 | 5 | VDD | Positive power supply voltage | Power (24V) |
| 2 | 2 | N/C | Not internally connected | n/a |
| 3 | N/A | N/C | Not internally connected | n/a |
| 4 | 6 | ADDR_SEL | Selects SMBus Address | Al |
| 5 | 8 | THERM | Active low output - requires pull-up resistor | OD (5V) |
| 6 | 9 | ALERT | Active low output - requires pull-up resistor | OD (5V) |
| 7 | 10 | SMDATA | SMBus data input/output - requires external pull-up resistor | DIOD (5V) |
| 8 | 1 | SMCLK | SMBus clock input - requires external pull- up resistor | |
| 9 | N/A | DUR_SEL | Selects peak detector duration | Al |
| 10 | N/A | TH_SEL | Selects peak detector threshold | Al |
| 11 | 3 | SENSE- | Negative current sense measurement point | AI (24V) |
| 12 | 4 | SENSE+ | Positive current sense measurement point | AI (24V) |
| Bottom Pad | 7 | GND | Ground | Power |

The pin types are described in Table 1.2. All pins labeled with (5V) are 5V tolerant. All pins labeled with (24V) are 24V tolerant.

Table 1.2 Pin Types

| PIN TYPE | DESCRIPTION |
|----------|--|
| Power | This pin is used to supply power or ground to the device. |
| AI | Analog Input - this pin is used as an input for analog signals. |
| OD | Open Drain Digital Output - this pin is used as a digital output. It is open drain and requires a pull-up resistor. This pin is 5V tolerant. |
| DI | Digital Input - this pin is used for digital inputs. This pin is 5V tolerant. |
| DIOD | Open Drain Digital Input / Output - this pin is bi-directional. It is open drain and requires a pull-up resistor. This pin is 5V tolerant. |



Chapter 2 Electrical Characteristics

Table 2.1 Absolute Maximum Ratings

| Voltage on 5V tolerant pins | -0.3 to 5.5 | V |
|---|--------------------------------|------|
| Voltage on 2V tolerant pins | -0.3 to 2 | V |
| Voltage on VDD, SENSE- and SENSE+ pins | -0.3 to 26 | V |
| Voltage on any other pin to GND | -0.3 to 4 | V |
| Voltage between Sense pins ((SENSE+ - SENSE-)) | < 6 | V |
| Package Power Dissipation | 0.5W up to $T_A = 85^{\circ}C$ | W |
| Junction to Ambient (θ _{JA}) (QFN12 package) | 58 | °C/W |
| Junction to Ambient (θ _{JA}) (MSOP10 package) | 128 | °C/W |
| Operating Ambient Temperature Range | -40 to 85 | °C |
| Storage Temperature Range | -55 to 150 | °C |
| ESD Rating - SMCLK, SMDATA, ALERT, THERM pins - HBM | 4000 | V |
| ESD Rating - All other pins - HBM | 2000 | V |

- Note 2.1 Stresses at or above those values listed could cause permanent damage to the device. This is a stress rating only, and functional operation of the device at any other condition above those indicated in the operation sections of this specification is not implied. Prolonged stresses above the stated operating levels and below the Absolute Maximum Ratings may degrade device performance and lead to permanent damage.
- **Note 2.2** All voltages are relative to ground.
- Note 2.3 The Package Power Dissipation specification assumes a thermal via design with the thermal landing be soldered to the PCB ground plane with four 12 mil vias (where applicable).
- Note 2.4 Junction to Ambient (θ_{JA}) is dependent on the design of the thermal vias. Without thermal vias and a thermal landing, the θ_{JA} is approximately 60°C/W (EMC1701-1) including localized PCB temperature increase.



2.1 Electrical Specifications

Table 2.2 Electrical Specifications

| ALL TYPICAL VALUES AT $V_{DD} = V_{PULLUP} = 3.3V$, $V_{BUS} = 12V$, AND $T_A = 27^{\circ}C$ UNLESS OTHERWISE NOTED. | | | | | | | | |
|--|---------------------------------|-----|-----|------|------|---|--|--|
| CHARACTERISTIC | SYMBOL | MIN | TYP | MAX | UNIT | CONDITIONS | | |
| DC POWER | | | | | | | | |
| Supply Voltage | V _{DD} | 3 | | 24 | V | | | |
| | | | 610 | 750 | uA | Temp conversions at 0.0625 conversions / second, dynamic averaging disabled current sense active | | |
| VDD Pin Supply Current | I _{DD} | | 650 | 950 | uA | Temp conversions at 4 conversions / second, dynamic averaging disabled current sense active | | |
| | | | 950 | 1100 | uA | Temp conversions at 8 conversions / second, dynamic averaging enabled current sense active | | |
| VDD Pin Supply Current | I _{DD} T_STANDBY | | | 750 | uA | Temp conversions disabled (TMEAS / STOP = '1') current sense active | | |
| VDD Pin Supply Current | I _{DD_ALL_} STANDBY | | | 300 | uA | Temp conversions disabled (TMEAS / STOP = '1') Current sense disabled (IMEAS / STOP = '1') | | |
| | | | 90 | | uA | V _{SENSE} = 0V, V _{DD} = 3V to 24V Current sense active | | |
| SENSE+ Pin Bias Current | I _{SENSE+} | | 15 | | uA | V _{SENSE} = 0V, V _{DD} = 3V to 24V current sense disabled | | |
| | | | 10 | 20 | uA | V _{DD} = 0V | | |
| | | | 10 | | uA | V _{SENSE} = 0V, V _{DD} = 3V to 24V Current sense active | | |
| SENSE- Pin Bias Current | I _{SENSE} - | | 10 | | uA | V _{SENSE} = 0V, VDD = 3V to 24V current sense disabled | | |
| | | | 0 | | uA | $V_{DD} = 0V$ | | |
| Pull-up Voltage | V _{PULLUP} | 3 | | 5.5 | V | <u>Pull-up</u> voltag <u>e for SM</u> Bus, ALERT, and THERM pins | | |
| Leakage Current (±) | I _{LEAK} | | | 5 | uA | ALERT and THERM pins, SMDATA and SMCLK pins powered or unpowered, T _A < 85°C | | |



Table 2.2 Electrical Specifications (continued)

| Table 2.2 Electrical Specifications (continued) | | | | | | | | |
|---|-----------------------------|---------|----------|-----------|-------|--|--|--|
| $V_{DD} = V_{BUS} = 3V \text{ TO } 24V, V_{PULLUP} = 3V \text{ TO } 5.5V, T_{A} = -40^{\circ}\text{C TO } 85^{\circ}\text{C},$ ALL TYPICAL VALUES AT $V_{DD} = V_{PULLUP} = 3.3V, V_{BUS} = 12V, \text{ AND } T_{A} = 27^{\circ}\text{C UNLESS OTHERWISE NOTED.}$ | | | | | | | | |
| CHARACTERISTIC | SYMBOL | MIN | TYP | MAX | UNIT | CONDITIONS | | |
| CURRENT SENSE | | | | | | | | |
| Common Mode Voltage | V _{CM} | 3 | | 24 | V | Voltage on SENSE+ and/or SENSE- pins, referenced to Ground | | |
| Differential Mode Voltage | V _{DIFF} | -6 | | +6 | V | Voltage between SENSE+ and SENSE- pins | | |
| | | 0 | | 10 | mV | 1 LSB = 4.885uV | | |
| Full Scale Range (±) | FSR | 0 | | 20 | mV | 1 LSB = 9.77uV | | |
| (see Section 5.16) | FSK | 0 | | 40 | mV | 1 LSB = 19.54uV | | |
| | | 0 | | 80 | mV | 1 LSB = 39.08uV | | |
| Total Measurement | V. | | 0.5 | 1 | % | Total Error, FSR = 80mV | | |
| Error (±) | V _{SENSE} _ERR | | | 3 | % | Total Error, FSR = 10mV to 40mV | | |
| Offset Error (±) | $ m V_{SENSE}$ _OFF | | | 3 | LSB | Offset Error, FSR = 80mV | | |
| Power Supply Rejection | V _{SENSE} _PSR | | -120 | | dB | $FSR = 10mV \text{ to } 80mV,$ $3V < V_{DD} < 24V$ | | |
| Common Mode Rejection | V _{SENSE} _CMR | | -110 | | dB | FSR = 10mV to 80mV, 3V < V _{BUS} < 24V | | |
| | | S | OURCE VO | DLTAGE | | | | |
| Full Scale Voltage | FSV | 3 | | 23.9883 | V | Voltage on SENSE+ pin | | |
| Total Measurement Error (±) (see Section 4.1.2) | V _{SOURCE} _ERR | | 0.2 | 0.5 | % | | | |
| (666 666611 11112) | | | POWER F | L ATIO | | | | |
| Full Scale Range | | 0 | OWERT | 100 | % | 1 LSB = 1.53m% | | |
| Full Scale Range | | 0 | | 1.6 | % | FSR = 80mV | | |
| Total Measurement Error (±) | P _{RATIO} _ERR | | | 3 | % | FSR = 10mV to 40mV | | |
| , , | _ | CURRENT | CENCE S | | | F3N = 10111V 10 40111V | | |
| | | CURRENT | SENSE PI | EAK DETEC | JIION | | | |
| Peak Detector Threshold Range | V _{TH} | 10 | | 85 | mV | Programmable via TH_SEL pin (EMC1701-1 only) | | |
| Peak Detector Duration Range | T _{DUR} | 1 | | 4096 | ms | Programmable via DUR_SEL pin (EMC1701-1 only) | | |
| V _{SENSE} Peak Detection | t _{FILTER} | | 5 | | us | | | |



Table 2.2 Electrical Specifications (continued)

| $V_{DD} = V_{BUS} = 3V \text{ TO } 24V, \ V_{PULLUP} = 3V \text{ TO } 5.5V, \ T_A = -40^{\circ}\text{C TO } 85^{\circ}\text{C},$ ALL TYPICAL VALUES AT $V_{DD} = V_{PULLUP} = 3.3V, \ V_{BUS} = 12V, \ \text{AND } T_A = 27^{\circ}\text{C UNLESS OTHERWISE NOTED.}$ | | | | | | |
|--|---------------------|------------|----------|-----------|----------|--|
| CHARACTERISTIC | SYMBOL | MIN | TYP | MAX | UNIT | CONDITIONS |
| Threshold Accuracy (±) | V _{TH_ERR} | | 2 | 5 | % | V _{TH} = 80mV |
| | | INTERNAL | TEMPERA | TURE MO | NITOR | |
| Temperature | | | 0.25 | 1 | °C | -5°C < T _A < 85°C |
| Accuracy (±) | | | | 2 | °C | -40°C < T _A < 85°C |
| Temperature Resolution | | | 0.125 | | °C | |
| | | CO | NVERSIO | N TIMES | | |
| First Conversion Ready | t _{CONV_T} | | 180 | 300 | ms | Time after power up before temperature and voltage measurements updated and P _{RATIO} updated |
| SMBus Delay | t _{SMB_D} | | | 25 | ms | Time before SMBus communications should be sent by host |
| | DIGITAL | I/O PINS (| SMCLK, S | MDATA, TH | IERM, AL | LERT) |
| Input High Voltage | V _{IH} | 2.0 | | | V | SMCLK, SMDATA OD pins pulled up to V _{PULLUP} |
| Input Low Voltage | V _{IL} | | | 0.8 | V | |
| Output Low Voltage | V _{OL} | | | 0.4 | V | OD pin pulled to V _{PULLUP} 4 mA current sink |

APPLICATION NOTE: The EMC1701 is trimmed at the 80mV range for best accuracy.

2.2 SMBus Electrical Specifications

Table 2.3 SMBus Electrical Specifications

| V _{DD} = V _{BUS} = 3V to 24V, V _{PULLUP} = 3V to 5.5V, T _A = -40°C to 85°C Typical values are at T _A = 27°C unless otherwise noted. | | | | | | | | | | | |
|--|------------------|-----|-------|---------|-------|------------|--|--|--|--|--|
| CHARACTERISTIC | SYMBOL | MIN | TYP | MAX | UNITS | CONDITIONS | | | | | |
| SMBUS INTERFACE | | | | | | | | | | | |
| Input Capacitance | C _{IN} | | 4 | 10 | pF | | | | | | |
| | | | SMBUS | STIMING | i | | | | | | |
| Clock Frequency | f _{SMB} | 10 | | 400 | kHz | | | | | | |
| Spike Suppression | t _{SP} | | | 50 | ns | | | | | | |



Table 2.3 SMBus Electrical Specifications (continued)

| $V_{DD} = V_{BUS} = 3V$ to 24\ | /, V _{PULLUP} = 3 | 3V to 5.5 | | -40°C to se noted. | | pical values are at T _A = 27°C unless |
|--------------------------------|----------------------------|-----------|-----|-----------------------|-------|--|
| CHARACTERISTIC | SYMBOL | MIN | TYP | MAX | UNITS | CONDITIONS |
| Bus Free Time Start to Stop | t _{BUF} | 1.3 | | | us | |
| Setup Time: Start | t _{SU:STA} | 0.6 | | | us | |
| Setup Time: Stop | t _{SU:STO} | 0.6 | | | us | |
| Data Hold Time | t _{HD:DAT} | 0 | | | us | |
| Data Setup Time | t _{SU:DAT} | 0.6 | | | us | |
| Clock Low Period | t _{LOW} | 1.3 | | | us | |
| Clock High Period | t _{HIGH} | 0.6 | | | us | |
| Clock/Data Fall time | t _{FALL} | | | 300 | ns | Min = 20+0.1C _{LOAD} ns |
| Clock/Data Rise time | t _{RISE} | | | 300 | ns | Min = 20+0.1C _{LOAD} ns |
| Capacitive Load | C _{LOAD} | | | 400 | pF | Total per bus line |



Chapter 3 Communications

3.1 System Management Bus Interface Protocol

The EMC1701 communicates with a host controller, such as an SMSC SIO, through the SMBus. The SMBus is a two-wire serial communication protocol between a computer host and its peripheral devices. A detailed timing diagram is shown in Figure 3.1. Stretching of the SMCLK signal is supported; however, the EMC1701 will not stretch the clock signal.

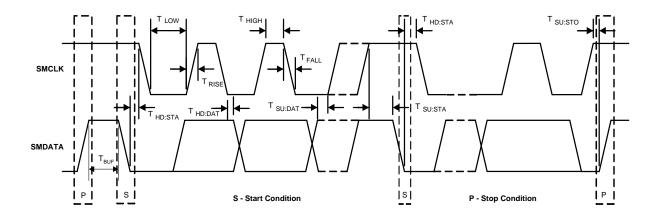


Figure 3.1 SMBus Timing Diagram

3.1.1 SMBus Start Bit

The SMBus Start bit is defined as a transition of the SMBus Data line from a logic '1' state to a logic '0' state while the SMBus Clock line is in a logic '1' state.

3.1.2 SMBus Address and RD / \overline{WR} Bit

The SMBus Address Byte consists of the 7-bit client address followed by a 1-bit RD / \overline{WR} indicator. If this RD / \overline{WR} bit is a logic '0', the SMBus host is writing data to the client device. If this RD / \overline{WR} bit is a logic '1', the SMBus host is reading data from the client device.

The EMC1701 SMBus address is determined by a single resistor connected between ground and the ADDR SEL pin as shown in Table 3.1.

Table 3.1 ADDR_SEL Resistor Setting

| RESISTOR (5%) | SMBUS ADDRESS | RESISTOR (5%) | SMBUS ADDRESS | | |
|---------------|---------------|---------------|---------------|--|--|
| 0 | 1001_100(r/w) | 1600 | 0101_000(r/w) | | |
| 100 | 1001_101(r/w) | 2000 | 0101_001(r/w) | | |
| 180 | 1001_110(r/w) | 2700 | 0101_010(r/w) | | |
| 300 | 1001_111(r/w) | 3600 | 0101_011(r/w) | | |
| 430 | 1001_000(r/w) | 5600 | 0101_100(r/w) | | |



| Table 3.1 ADDR_SEL Resistor Setting (continued |
|--|
|--|

| RESISTOR (5%) | SMBUS ADDRESS | RESISTOR (5%) | SMBUS ADDRESS |
|---------------|---------------|---------------|---------------|
| 560 | 1001_001(r/w) | 9100 | 0101_100(r/w) |
| 750 | 1001_010(r/w) | 20000 | 0101_101(r/w) |
| 1270 | 1001_011(r/w) | Open | 0011_000(r/w) |

All SMBus Data bytes are sent most significant bit first and composed of 8-bits of information.

3.1.3 SMBus ACK and NACK Bits

The SMBus client will acknowledge all data bytes that it receives (as well as the client address if it matches and the ARA address if the ALERT pin is asserted). This is done by the client device pulling the SMBus Data line low after the 8th bit of each byte that is transmitted.

The host will NACK (not acknowledge) the data received from the client by holding the SMBus data line high after the 8th data bit has been sent.

3.1.4 SMBus Stop Bit

The SMBus Stop bit is defined as a transition of the SMBus Data line from a logic '0' state to a logic '1' state while the SMBus clock line is in a logic '1' state. When the EMC1701 detects an SMBus Stop bit, and it has been communicating with the SMBus protocol, it will reset its client interface and prepare to receive further communications.

3.1.5 SMBus Time-out

The EMC1701 includes an SMBus time-out feature. Following a 30ms period of inactivity on the SMBus, the device will time-out and reset the SMBus interface.

The time-out functionality defaults to disabled and can be enabled by writing to the TIMEOUT bit (see Section 5.11).

3.1.6 SMBus and I²C Compliance

The major differences between SMBus and I^2C devices are highlighted here. For complete compliance information, refer to the SMBus 2.0 specification.

- 1. Minimum frequency for SMBus communications is 10kHz.
- 2. The client protocol will reset if the clock is held at a logic '0' for longer than 30ms. This time-out functionality is disabled by default.
- 3. The client protocol will reset if both the clock and data lines are held at a logic '1' for longer than 150us. This function is disabled by default.
- 4. I²C devices do not support the Alert Response Address functionality (which is optional for SMBus).



3.2 SMBus Protocols

The EMC1701 is SMBus 2.0 compatible and supports Send Byte, Read Byte, Receive Byte, Write Byte, Block Read, and Block Write as valid protocols. It will respond to the Alert Response Address protocol but is not in full compliance.

All of the protocols listed below use the convention in Table 3.2.

Table 3.2 Protocol Format

| DATA SENT | DATA SENT TO |
|----------------|----------------|
| TO DEVICE | THE HOST |
| # of bits sent | # of bits sent |

3.2.1 Write Byte

The Write Byte is used to write one byte of data to the registers, as shown in Table 3.3:

Table 3.3 Write Byte Protocol

| START | SLAVE ADDRESS | WR | ACK | REGISTER ADDRESS | ACK | REGISTER DATA | ACK | STOP |
|--------|------------------|----|-----|---------------------|-----|------------------|-----|--------|
| 1 -> 0 | YYYY_YYY | 0 | 0 | XXh | 0 | XXh | 0 | 0 -> 1 |

3.2.2 Read Byte

The Read Byte protocol is used to read one byte of data from the registers, as shown in Table 3.4.

Table 3.4 Read Byte Protocol

| START | SLAVE ADDRESS | WR | ACK | Register Address | ACK | START | Slave Address | RD | ACK | Register Data | NACK | STOP |
|--------|------------------|----|-----|---------------------|-----|--------|------------------|----|-----|------------------|------|--------|
| 1 -> 0 | YYYY_YYY | 0 | 0 | XXh | 0 | 0 -> 1 | YYYY_YYY | 1 | 0 | XXh | 1 | 0 -> 1 |

3.2.3 Send Byte

The Send Byte protocol is used to set the internal address register pointer to the correct address location. No data is transferred during the Send Byte protocol, as shown in Table 3.5.

Table 3.5 Send Byte Protocol

| START | SLAVE ADDRESS | WR | ACK | REGISTER ADDRESS | ACK | STOP |
|--------|------------------|----|-----|---------------------|-----|--------|
| 1 -> 0 | YYYY_YYY | 0 | 0 | XXh | 0 | 0 -> 1 |



3.2.4 Receive Byte

The Receive Byte protocol is used to read data from a register when the internal register address pointer is known to be at the right location (e.g. set via Send Byte). This is used for consecutive reads of the same register, as shown in Table 3.6.

Table 3.6 Receive Byte Protocol

| START | SLAVE ADDRESS | RD | ACK | REGISTER DATA | NACK | STOP |
|--------|------------------|----|-----|---------------|------|--------|
| 1 -> 0 | YYYY_YYY | 1 | 0 | XXh | 1 | 0 -> 1 |

3.2.5 Block Write

The Block Write is used to write multiple data bytes to a group of contiguous registers, as shown in Table 3.7. It is an extension of the Write Byte Protocol.

Table 3.7 Block Write Protocol

| START | SLAVE ADDRESS | WR | ACK | REGISTER ADDRESS | ACK | REGISTER DATA | ACK |
|------------------|------------------|------------------|-----|---------------------|------------------|------------------|--------|
| 1 ->0 | YYYY_YYY | 0 | 0 | XXh | 0 | XXh | 0 |
| REGISTER DATA | ACK | REGISTER DATA | ACK | | REGISTER DATA | ACK | STOP |
| XXh | 0 | XXh | 0 | | XXh | 0 | 0 -> 1 |

3.2.6 Block Read

The Block Read is used to read multiple data bytes from a group of contiguous registers, as shown in Table 3.8. It is an extension of the Read Byte Protocol.

Table 3.8 Block Read Protocol

| START | SLAVE ADDRESS | WR | ACK | REGISTER ADDRESS | ACK | START | SLAVE ADDRESS | RD | ACK | REGISTER DATA |
|-------|------------------|-----|------------------|---------------------|------------------|-------|------------------|------------------|------|------------------|
| 1->0 | YYYY_YYY | 0 | 0 | XXh | 0 | 1 ->0 | YYYY_YYY | 1 | 0 | XXh |
| ACK | REGISTER DATA | ACK | REGISTER DATA | ACK | REGISTER DATA | ACK | | REGISTER DATA | NACK | STOP |
| 0 | XXh | 0 | XXh | 0 | XXh | 0 | | XXh | 1 | 0 -> 1 |



3.2.7 Alert Response Address

The $\overline{\text{ALERT}}$ output can be used as a processor interrupt or as an SMBus Alert when configured to operate as an interrupt.

When it detects that the ALERT pin is asserted, the host will send the Alert Response Address (ARA) to the general address of 0001_100xb. All devices with active interrupts will respond with their client address, as shown in Table 3.9.

Table 3.9 Alert Response Address Protocol

| START | ALERT RESPONSE ADDRESS | RD | ACK | DEVICE ADDRESS | NACK | STOP |
|--------|------------------------------|----|-----|-------------------|------|--------|
| 1 -> 0 | 0001_100 | 1 | 0 | YYYY_YYY | 1 | 0 -> 1 |

The EMC1701 will respond to the ARA in the following way if the ALERT pin is asserted.

- 1. Send Slave Address and verify that full slave address was sent (i.e. the SMBus communication from the device was not prematurely stopped due to a bus contention event).
- 2. Set the MASK bit to clear the ALERT pin.



Chapter 4 General Description

The EMC1701 is a combination high-side current sensing device with precision voltage and temperature measurement capabilities. It measures the voltage developed across an external sense resistor to represent the high-side current of a battery or voltage regulator. The EMC1701 also measures the source voltage and uses these measured values to present a proportional power calculation. The EMC1701 contains additional bi-directional peak detection circuitry to flag instantaneous current spikes with programmable time duration and magnitude threshold. Finally, the EMC1701 includes an internal diode channel for ambient temperature measurement.

The EMC1701 current-sense measurement converts differential input voltage measured across an external sense resistor to a proportional output voltage. This voltage is digitized using a variable resolution (13-bit to 15-bit) Sigma-Delta ADC and transmitted via the SMBus or I²C protocol. The current range allows for large variations in measured current with high accuracy and low voltage drop across the resistor.

The supply voltage is also measured and stored. When combined with the sense resistor voltage measurement the power provided from the source can be determined. Programmable limits on both voltage and current levels are used to generate an interrupt.

The EMC1701 has two levels of monitoring. The first provides a maskable ALERT signal to the host when the measured temperatures or voltages meet or exceed user programmable limits. This allows the EMC1701 to be used as an independent thermal watchdog to warn the host of temperature hot spots without direct control by the host. The second level of monitoring provides a non maskable interrupt on the THERM pin if the measured values meet or exceed a second programmable limit.

A system diagram is shown in Figure 4.1.

**EMC1701-1 only

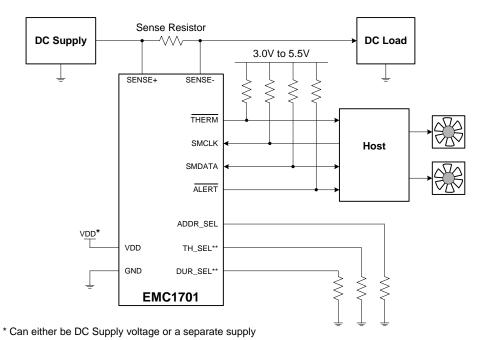


Figure 4.1 EMC1701 System Diagram



4.1 Source Monitoring

The EMC1701 includes circuitry for both source current sensing and source voltage measurement. From these measurements, a ratiometric value corresponding to the power delivered at the SENSE+pin is provided.

4.1.1 Current Measurement

The EMC1701 includes a high-side current sensing circuit. This circuit measures the voltage, V_{SENSE} , induced across a fixed external current sense resistor, R_{SENSE} , and stores a representative voltage as a signed 11-bit number in the Sense Voltage Registers (see Section 5.18).

This circuitry is able to measure the direction of current flow (from SENSE+ to SENSE- or from SENSE- to SENSE+). Current flowing from SENSE+ to SENSE- is defined as positive current. Current flowing from SENSE- to SENSE+ is defined as negative.

The EMC1701 contains user programmable bipolar Full Scale Sense Ranges (FSSR) of ±10mV, ±20mV, ±40mV, or ±80mV (see Section 5.16). The default for this setting is ±80mV.

Each V_{SENSE} measurement is averaged over a user programmable time (see Section 5.16). It is compared against programmable high and low limits (see Section 5.21). If V_{SENSE} exceeds (or drops below) the respective limits, the \overline{ALERT} pin may be asserted (the default operation is to enable current sense interrupts on the \overline{ALERT} pin).

The EMC1701 also contains user programmable current peak detection circuitry (see Section 4.1.4) that will assert the $\overline{\text{THERM}}$ pin if a current spike is detected larger than the programmed threshold and of longer duration than the programmed time. This circuitry is independent of V_{SENSE} .

Full Scale Current (FSC) can be calculated from:

| | where: | | |
|-------------------------------|--|-----|--|
| | FSC is the Full-Scale Current | | |
| $FSC = \frac{FSR}{R_{SENSE}}$ | FSR, the Full Scale Range, is either 10mV, 20mV, 40mV or 80mV (see Section 5.16) | [1] | |
| | R _{SENSE} is the external sense resistor value | | |

Actual source current through R_{SENSE} can then be calculated using:

| | where: | |
|---|--|-----|
| | I _{SOURCE} is the actual source current | |
| $I_{SOURCE} = FSC \times \frac{V_{SENSE}}{2.047}$ | FSC is the Full-Scale Current value (from Equation [1]) | [2] |
| 2, 047 | V _{SENSE} is the value read from the Sense Voltage Registers, ignoring the four lowest bits which are always zero (see Section 5.18) | |

For example: Suppose the system is drawing 1.65A through a $10m\Omega$ resistor and the FSR is set for 20mV. Therefore, by Equation [1], the FSC is 2A.

For a positive voltage the Sense Voltage Registers are read, ignoring the lower four bits since they are always zero, as 69_8h (0110_1001_1000b or 1688d) which is 82.5% of the full scale source current. This results in a calculated source current of 1.649A using Equation [2].



For a negative voltage the Sense Voltage Registers are read as 96_8h, also ignoring the lower four bits since they are always zero. To calculate source current the binary value is first converted from two's complement by inverting the bits and adding one:

 $96_8h = 1001_0110_1000b$. Inverting equals 0110_1001_0111b (69_7h) and adding one gives 0110_1001_1000b (69_8h).

This results in the same calculated value as in the positive voltage case.

4.1.2 Voltage Measurement

Source voltage is measured on the supply side of the R_{SENSE} resistor (SENSE+) and stored as an unsigned 11-bit number in the Source Voltage Registers as V_{SOURCE} (see Section 5.19).

Each V_{SOURCE} measurement is averaged over a user programmable time (see Section 5.6 and Section 5.15). The measurement is delayed by the programmed conversion rate. V_{SOURCE} is compared against programmable high, low, and critical limits (see Section 5.12, Section 5.13, and Section 5.14). If the value meets or exceeds the high limits or drops below the low limits, the \overline{ALERT} pin \underline{may} be asserted (default is to enable this function). If the value meets or exceeds the critical limit, the \overline{THERM} pin will be asserted (see Section 5.23).

Full Scale Voltage (FSV) is given by the maximum value of the Source Voltage Registers:

| | where: | |
|----------------|--|-----|
| FSV = 23.9883V | FSV is the Full-Scale Voltage (a constant) | [3] |

Actual source voltage at the SENSE+ pin can be calculated using:

| | where: | |
|--|---|-----|
| | Source Voltage is the voltage at the SENSE+ pin | |
| Source Voltage = $FSV \times \frac{V_{SOURCE}}{4,094}$ | FSV is the Full-Scale Voltage (from Equation [3]) | [4] |
| | V _{SOURCE} is the digital value read from the Source Voltage Registers. Note that the lowest five bits are always zero (see Section 5.19) | |

For example: Suppose that the actual source voltage is 10.65V. The Source Voltage Registers are read as $V_{SOURCE} = 71$ _Ah (0111_0001_1010b or 1818d) which is 44.4% of the full scale source voltage. This results in a calculated source voltage of 10.65V using Equation [4].

Note that the actual source voltage may also be determined by scaling each bit set by the indicated bit weighting as described in Section 5.19.

4.1.3 Power Calculation

The EMC1701 may be used to determine the average power provided at the source side of R_{SENSE} (SENSE+) using the value, P_{RATIO} , contained in the Power Ratio Registers (see Section 5.20). The value represents the % of maximum calculable power.

 P_{RATIO} is mathematically generated by multiplying the absolute values of V_{SENSE} and V_{SOURCE} (see Section 4.1.1 and Section 4.1.2) and stored as a shifted 16-bit unsigned number. P_{RATIO} is updated whenever either V_{SENSE} or V_{SOURCE} is updated.



Full Scale Power can be calculated from:

| | where: | |
|------------------------|---|-----|
| | FSP is the Full-Scale Power | |
| $FSP = FSC \times FSV$ | FSC is the Full-Scale Current (from Equation [1]) | [5] |
| | FSV is the Full-Scale Voltage (from Equation [3]) | |

Actual power drawn from the source can be calculated using:

| | where: | |
|--|--|-----|
| PRATIO | P _{SOURCE} is the actual power provided by the source measured at SENSE+ | |
| $P_{SOURCE} = FSP \times \frac{P_{RATIO}}{65,535}$ | FSP is the Full-Scale Power (from Equation [5]) | [6] |
| | P _{RATIO} is the value read from the Power Ratio Registers (see Section 5.20) | |

For example: Suppose that the actual source voltage is 10.65V and the source current through a $10m\Omega$ resistor is 1.65A. The FSC value is 2A per Equation [1]; thus, the expected power is 17.573W which is 36.6% of the FSP value.

Reading the Power Ratio Registers will report P_{RATIO} as 24,003d (0101_1101_1100_0011b or 5D_C3h), which is 36.6% of the full scale source power. This results in a calculated source power of 17.6W.

4.1.4 Current Peak Detection

The EMC1701-1 includes a hardware set instantaneous current peak detector (this circuitry is also available in the EMC1701-2 but must be configured via SMBus). The peak detector threshold and duration values may also be set via the SMBus.

The peak detector supports detection of current spikes that occur faster than the minimum current sensing conversion time. This allows quick reaction to events requiring system-level response. The circuitry compares the measured current against a user-defined threshold value and user-defined time duration. If the measured current exceeds the threshold, an internal timer is started. If the timer reaches the programmed duration, the THERM pin is asserted (see Figure 4.2 for an example of peak current detection) and the PEAK status bit set.

The THERM pin will remain asserted until the Peak is no longer detected at which point it will be released. The PEAK status bit will likewise be cleared.

The Peak Detection circuitry may also assert the ALERT pin. In this case, the ALERT pin must be configured to operate in Comparator mode. If the ALERT pin is configured to operate in Interrupt mode, the Peak Detection circuitry will not cause the ALERT pin to be asserted.

The Peak Detection circuitry includes filtering (t_{FILTER}). When the instantaneous current exceeds the threshold, it must drop below the threshold for a period of time greater than t_{FILTER} before the timer is reset. The Peak Detection circuitry works for current flowing in either direction through the sense resistor (R_{SENSE}).

APPLICATION NOTE: The Peak Detector circuitry works independently of the current measurement integration.



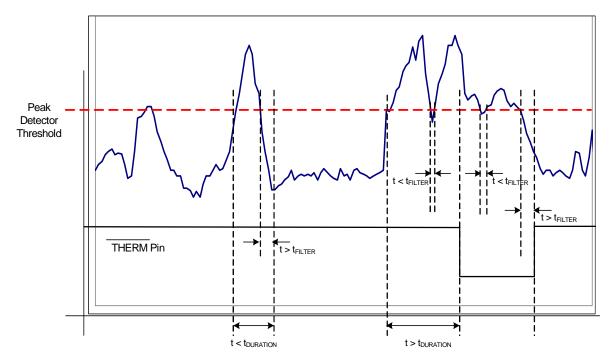


Figure 4.2 Peak Detection Example

The peak detector threshold is determined upon device power up by the value of the resistor connected between the TH_SEL pin and ground (for EMC1701-1 only) or via the SMBus (see Section 5.17). The resistor selects one of 16 different V_{SENSE} measurement limits (from 10mV to 85mV) as shown in Table 4.1.

Table 4.1 TH_SEL Resistor Setting (EMC1701-1 only)

| RESISTOR (5%) | PEAK DETECTION THRESHOLD | RESISTOR (5%) | PEAK DETECTION THRESHOLD |
|---------------|-----------------------------|---------------|-----------------------------|
| 0 | 10mV | 1600 | 50mV |
| 100 | 15mV | 2000 | 55mV |
| 180 | 20mV | 2700 | 60mV |
| 300 | 25mV | 3600 | 65mV |
| 430 | 30mV | 5600 | 70mV |
| 560 | 35mV | 9100 | 75mV |
| 750 | 40mV | 20000 | 80mV |
| 1270 | 45mV | Open | 85mV |

The peak detector duration is determined upon device power up by the value of the resistor between the DUR_SEL pin and ground (for EMC1701-1 only) or via the SMBus (see Section 5.17). The resistor selects one of 16 different time durations from 1 ms to 4.096s as shown in Table 4.2.



Table 4.2 DUR_SEL Resistor Setting (EMC1701-1 only)

| RESISTOR (5%) | PEAK DETECTION MINIMUM DURATION (T _{DURATION}) | RESISTOR (5%) | PEAK DETECTION MINIMUM DURATION (T _{DURATION}) |
|---------------|--|---------------|--|
| 0 | 1ms | 1600 | 384ms |
| 100 | 5ms | 2000 | 512ms |
| 180 | 26 ms | 2700 | 768ms |
| 300 | 51 ms | 3600 | 1024ms |
| 430 | 77 ms | 5600 | 1536ms |
| 560 | 102ms | 9100 | 2048ms |
| 750 | 128ms | 20000 | 3072ms |
| 1270 | 256ms | Open | 4096ms |

4.2 VDD Biasing Options

The wide device operating voltage range allows the EMC1701 to be powered from either the source voltage or an external supply. The EMC1701 contains circuitry to detect the voltage supply level on the VDD pin and enable an internal regulator as necessary.

4.3 Modes of Operation

The EMC1701 has multiple modes of operation as described here:

- Fully Active In this mode of operation, the device is measuring the temperature channel, source voltage, and sense voltage. All data is updated at the end of the respective conversion and the limits are checked. Writing to the One-Shot register will have no effect.
- Current Sense only In this mode of operation, the device is measuring source voltage and sense voltage only. The temperature data is not updated. V_{SOURCE} and V_{SENSE} data are updated at the end of the respective conversion and the limits are checked. Writing to the One-Shot register will update the temperature measurements. This one-shot measurement may cause the ALERT or THERM pins to be asserted if the measured temperature violates the respective limits.
- Temperature only In this mode of operation, the device is measuring the temperature channels only. V_{SOURCE} and V_{SENSE} data are not updated. The temperature data is updated at the end of the conversion and the limits are checked. Writing to the One-Shot register will update V_{SOURCE} and V_{SENSE}. This one-shot measurement may cause the ALERT or THERM pins to be asserted if the measured voltage or current sense readings meet or exceed the respective limits.
- Standby (Stop) In this mode of operation, the majority of circuitry is powered down to reduce supply current. The temperature, source voltage, and sense voltage measurements are not updated and the limits are not checked. In this mode of operation, the SMBus is fully active and the part will return requested data. Writing to the One-Shot register (see Section 5.8) will enable the device to update all measurement channels (temperature, V_{SOURCE}, and V_{SENSE}). This one-shot measurement may cause the ALERT or THERM pins to be asserted if any of the measured values violate their respective limits. Once all the channels are updated, the device will return to the Standby mode.



4.4 ALERT Output

The ALERT pin is an open drain output and requires a pull-up resistor to V_{PULLUP} and has two modes of operation: Interrupt mode and Comparator mode. The mode of the ALERT output is selected via the ALERT / COMP bit in the Configuration Register (see Section 5.5).

The <u>ALERT</u> pin modes apply to the High Limit only for all channels. The Low Limits will always cause the <u>ALERT</u> pin to behave as if it were in Interrupt mode.

The ALERT pin is used as an interrupt signal or as an SMBus Alert signal that allows an SMBus slave to communicate an error condition to the master. One or more SMBus Alert outputs can be hard-wired together.

4.4.1 ALERT Pin Interrupt Mode

When configured to operate in Interrupt mode, the \overline{ALERT} pin asserts low when an out-of-limit measurement (\geq high limit or < low limit) is detected on any temperature measurement and the consecutive alert queue has been filled.

Additionally, the ALERT pin may be asserted if the measured current or the source voltage are out of limit (\geq high limit or < low limit).

The ALERT pin will remain asserted as long as an out-of-limit condition remains. Once the out-of-limit condition has been removed, the ALERT pin will remain asserted until the appropriate status bits are cleared. The pin can be masked by setting the MASK_ALL bit. Once the ALERT pin has been masked, it will be de-asserted and remain de-asserted until the MASK_ALL bit is cleared by the user. Any interrupt conditions that occur while the ALERT pin is masked will update the Status Register normally.

When the $\overline{\text{ALERT}}$ pin is configured to operate in Interrupt mode, the Peak Detector circuitry will not generate interrupts when a current peak is detected.

4.4.2 ALERT Pin Comparator Mode

When the ALERT pin is configured to operate in Comparator mode, it will be asserted if the measured temperature meets or exceeds the high limit. The ALERT pin will remain asserted until the temperature drops below the high limit minus the Tcrit Hysteresis value (see Section 5.9).

Additionally, the ALERT pin may be asserted if the measured current or the source voltage meet or exceed their respective high limit. The ALERT pin will remain asserted until the measured values drop below the corresponding high limit minus the Vcrit Hysteresis value (see Section 5.23).

When the ALERT pin is asserted in Comparator mode, the corresponding high limit status bits will be set. Reading these bits will not clear them until the ALERT pin is deasserted. Once the ALERT pin is deasserted, the status bits will be automatically cleared.

The MASK_ALL (see Section 5.5) bit will not block the ALERT pin in this mode; however, individual mask bits (see Section 5.10) will control the respective events that will assert the ALERT pin.

When the ALERT pin is configured to operate in Comparator mode and the Peak Detector circuitry is linked to the ALERT pin, an interrupt will be generated when a current peak is detected (see Section 5.15).

4.5 THERM Output

The THERM output is asserted independently of the ALERT output and cannot be masked. Whenever the measured temperature meets or exceeds the user programmed Tcrit Limit value for the programmed number of consecutive measurements, the THERM output is asserted. Once it has been asserted, it will remain asserted until the measured temperatures drops below the Tcrit Limit minus the Tcrit Hysteresis (also programmable).

Additionally, the THERM pin will be asserted if the current sense Peak Detection circuitry has detected a current spike (see Section 4.1.4). The THERM pin will remain asserted so long as the Peak Detection circuitry continues to detect excessive instantaneous current (greater than the programmed threshold).



As well, the THERM pin will be asserted if the measured current or source voltage meet or exceed the user programmed Vcrit Limit values. In this case, the THERM pin will remain asserted until all measured voltages drop below the Vcrit Limit minus the Vcrit Hysteresis (see Section 5.23).

4.6 Temperature Measurement

The EMC1701 measures the internal or ambient temperature.

The device contains programmable High, Low, and Tcrit limits for the internal temperature channel. If the temperature drops below the Low limit or meets or exceeds the High limit, the ALERT pin can be asserted (based on user settings). If the measured temperature meets or exceeds the Tcrit limit, the THERM pin is asserted unconditionally, providing two tiers of temperature detection.



Chapter 5 Register Description

The registers shown in Table 5.1 are accessible through the SMBus. An entry of '-' indicates that the bit is not used and will always read '0'.

Table 5.1 Register Set in Hexadecimal Order

| REGISTER ADDRESS | R/W | REGISTER NAME | FUNCTION | DEFAULT VALUE | PAGE |
|---------------------|-----|----------------------------------|--|------------------|---------|
| 00h | R | Internal Diode Data High Byte | Stores the integer data for the Internal Diode (mirrored at address 38h) | 00h | Page 31 |
| 02h | R | Status | Stores the status bits for the Internal Diode (mirrored at address 34h) | 00h | Page 31 |
| 03h | R/W | Configuration | Controls the general operation of the device (mirrored at address 09h) | 00h | Page 32 |
| 04h | R/W | Conversion Rate | Controls the conversion rate for updating measurement data (mirrored at address 0Ah) | 06h (4/sec) | Page 33 |
| 05h | R/W | Internal Diode High Limit | Stores the 8-bit high limit for the Internal Diode (mirrored at address 0Bh) | 55h (85°C) | Page 33 |
| 06h | R/W | Internal Diode Low Limit | Stores the 8-bit low limit for the Internal Diode (mirrored at address 0Ch) | 80h (-128°C) | Page 33 |
| 09h | R/W | Configuration | Controls the general operation of the device (mirrored at address 03h) | 00h | Page 32 |
| 0Ah | R/W | Conversion Rate | Controls the conversion rate for updating measurement data (mirrored at address 04h) | 06h (4/sec) | Page 33 |
| 0Bh | R/W | Internal Diode High Limit | Stores the 8-bit high limit for the Internal Diode (mirrored at address 05h) | 55h (85°C) | Page 33 |
| 0Ch | R/W | Internal Diode Low Limit | Stores the 8-bit low limit for the Internal Diode (mirrored at address 06h) | 80h (-128°C) | Page 33 |
| 0Fh | W | One-Shot | A write to this register initiates a one-shot update. | 00h | Page 34 |
| 1Fh | R/W | Channel Mask Register | Controls the masking of individual channels | 00h | Page 34 |
| 20h | R/W | Internal Diode Tcrit Limit | Stores the 8-bit critical temperature limit for the Internal Diode | 64h (100°C) | Page 34 |
| 21h | R/W | Tcrit Hysteresis | Stores the 8-bit hysteresis value that applies to all THERM limits | 0Ah (10°C) | Page 34 |



Table 5.1 Register Set in Hexadecimal Order (continued)

| REGISTER ADDRESS | R/W | REGISTER NAME | FUNCTION | DEFAULT VALUE | PAGE |
|---------------------|-----|--|--|------------------|----------|
| 22h | R/W | Consecutive Alert | Controls the number of out-of-limit conditions that must occur before an interrupt is asserted | 70h | Page 35 |
| 29h | R | Internal Diode Data Low Byte | Stores the fractional data for the Internal Diode (mirrored at register 39h) | 00h | Page 31 |
| 34h | R-C | Status | Stores the status bits for the measured temperature channels, Current Sense circuitry, and Peak Detector circuitry | 00h | Page 31 |
| 35h | R-C | High Limit Status | Status bits for the High Limits | 00h | Page 36 |
| 36h | R-C | Low Limit Status | Status bits for the Low Limits | 00h | Page 36 |
| 37h | R-C | Crit Limit Status | Status bits for the Tcrit and Vcrit Limits | 00h | Page 37 |
| 38h | R | Internal Diode High Byte | Stores the integer data for the Internal Diode | 00h | Page 31 |
| 39h | R | Internal Diode Low Byte | Stores the fractional data for the Internal Diode | 00h | Page 31 |
| | | Current Sens | e Control and Measurement | | |
| 50h | R/W | Voltage Sampling Configuration | Controls voltage sampling | 80h | Page 37 |
| 51h | R/W | Current Sense Sampling Configuration | Controls the current sensing sampling and update times | 03h | Page 38 |
| 52h | R/W | Peak Detection Config | Controls the peak detection configuration | 00h | Page 40 |
| 54h | R | Sense Voltage High Byte | Stores the voltage measured across R _{SENSE} | 00h | Page 42 |
| 55h | R | Sense Voltage Low Byte | | 00h | Page 42 |
| 58h | R | Source Voltage High Byte | Stores voltage measured on the source side of R _{SENSE} | 00h | Page 43 |
| 59h | R | Source Voltage Low Byte | | 00h | Page 43 |
| 5Bh | R | Power Ratio High Byte | Stores the power ratio value | 00h | Page 43 |
| 5Ch | R | Power Ratio Low Byte | | 00h | Page 43 |
| | | Current Sens | e and Source Voltage Limits | | |
| 60h | R/W | Sense Voltage High Limit | Stores the high limit for V _{SENSE} | 7Fh | Page 44 |
| | l | 1 | | 1 | <u> </u> |



Table 5.1 Register Set in Hexadecimal Order (continued)

| REGISTER ADDRESS | R/W | REGISTER NAME | FUNCTION | DEFAULT VALUE | PAGE |
|---------------------|-----|------------------------------------|--|------------------|---------|
| 61h | R/W | Sense Voltage Low Limit | Stores the low or negative limit for the V _{SENSE} voltage | 80h | Page 44 |
| 64h | R/W | Source Voltage High Limit | Stores the high limit for the voltage on the source side of R _{SENSE} | FFh | Page 44 |
| 65h | R/W | Source Voltage Low Limit | Stores the low limit for the voltage on the source side of R _{SENSE} | 00h | Page 44 |
| 66h | R/W | Sense Voltage Vcrit Limit | Stores the critical limit for V _{SENSE} | 7Fh | Page 44 |
| 68h | R/W | Source Voltage Vcrit Limit | Stores the critical limit for the voltage on the source side of R _{SENSE} | FFh | Page 44 |
| 69h | R/W | Sense Vcrit Hysteresis | Stores the hysteresis for the V _{SENSE} Vcrit limit | 0Ah | Page 44 |
| 6Ah | R/W | Source Voltage Vcrit Hysteresis | Stores the hysteresis for the source voltage Vcrit limits | 0Ah | Page 44 |
| FCh | R | Product Features | Stores information about which pin controlled product features are set | 00h | Page 45 |
| FDh | R | Product ID | Stores a fixed value that identifies each product | 38h | Page 45 |
| FEh | R | SMSC ID | Stores a fixed value that represents SMSC | 5Dh | Page 46 |
| FFh | R | Revision | Stores a fixed value that represents the revision number | 82h | Page 46 |

5.1 Data Read Interlock

When any measurement channel high byte register is read (temperature or V_{SOURCE} or V_{SENSE}), the corresponding low byte is copied into an internal 'shadow' register. The user is free to read the low byte at any time and be guaranteed that it will correspond to the previously read high byte. Regardless if the low byte is read or not, reading from the same high byte register again will automatically refresh this stored low byte data.

5.2 Block Mode Support

All of the status and temperature data may be retrieved with a block read of 6 bytes starting at register address 34h.

All of the voltage measurement, current sense data, and power information may be retrieved with a block read of 6 bytes starting at register address 54h.



5.3 Temperature Data Registers

Table 5.2 Temperature Data Registers

| ADDR | R/W | REGISTER | В7 | В6 | В5 | В4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|----------------|------|------|-------|----|----|----|----|----|---------|
| 00h | R | Internal Diode | Sign | 64 | 32 | 16 | 8 | 4 | 2 | 1 | 00h |
| 38h | | High Byte | | | | | | | | | |
| 29h | R | Internal Diode | 0.5 | 0.25 | 0.125 | - | - | - | - | - | 00h |
| 39h | | Low Byte | | | | | | | | | |

As shown in Table 5.2, temperature data is stored as an 11-bit value with the high byte representing the integer value and the low byte representing the fractional value left justified to occupy the MSBits.

Table 5.3 Temperature Data Format

| TEMPERATURE (°C) | BINARY | HEX (AS READ BY REGISTERS) |
|------------------|----------------|----------------------------|
| -63.875 | 1100_0000_001b | C0_20h |
| -63 | 1100_0001_000b | C1_00h |
| -1 | 1111_1111_000b | FF_00h |
| -0.125 | 1111_1111_111b | FF_E0h |
| 0 | 0000_0000_000b | 00_00h |
| 0.125 | 0000_0000_001b | 00_20h |
| 1 | 0000_0001_000b | 01_00h |
| 63 | 0011_1111_000b | 3F_00h |
| 64 | 0100_0000_000b | 40_00h |
| 65 | 0100_0001_000b | 41_00h |
| 127 | 0111_1111_000b | 7F_00h |
| 127.875 | 0111_1111_111b | 7F_E0h |

5.4 Status Register

Table 5.4 Status Register

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|----------|------|------|----|------|-----|----|------|----|---------|
| 02h | R | Status | BUSY | PEAK | - | HIGH | LOW | - | CRIT | - | 00h |
| 34h | | | | | | | | | | | |

The Status Register reports general error conditions. To identify specific channels, refer to Section 5.12, Section 5.13, and Section 5.14. The individual Status Register bits are cleared when the appropriate High Limit, Low Limit, or Crit Limit status register has been read or cleared.



- Bit 7 BUSY This bit indicates that one of the ADCs is currently converting. This bit does not cause either the ALERT or THERM pins to be asserted.
- Bit 6 PEAK This bit is set when the Peak Detector circuitry has detected a current peak that is greater than the programmed threshold for longer than the programmed duration. This bit is not sticky and will be cleared when the condition has been removed. When set, the THERM pin or ALERT pin (Comparator mode only) may be asserted (see Section 5.15).
- Bit 4 HIGH This bit is set when any of the temperature channels meets or exceeds its programmed high limit. This bit will also be set if the V_{SENSE} or V_{SOURCE} channels meet or exceed their respective high limits. See the High Limit Status Register for specific channel information (Section 5.12). When set, the ALERT pin is asserted.
- Bit 3 LOW This bit is set when any of the temperature channels drops below its programmed low limit. This bit will also be set if the $V_{\mbox{\footnotesize SENSE}}$ or $V_{\mbox{\footnotesize SOURCE}}$ channels drop below their respective low limits. See the Low Limit Status Register for specific channel information (Section 5.13). When set, the ALERT pin is asserted.
- Bit 1 CRIT This bit is set when any of the temperature channels meets or exceeds its programmed Tcrit limit. This bit will also be set if the V_{SENSE} or V_{SOURCE} channels meet or exceed their respective Vcrit limits (see the Section 5.14, "Crit Limit Status Register" for specific channel information). When set, the THERM pin is asserted. This bit is not sticky and will be cleared when the error condition has been removed.

5.5 Configuration Register

ADDR R/W REGISTER **B7 B1 B0 DEFAULT B6 B5 B4 B3 B2** R/W Configuration MASK **TMEAS** ALERT/ **IMEAS** 00h ALL /STOP COMP /STOP

Table 5.5 Configuration Register

The Configuration Register controls the basic operation of the device. This register is fully accessible at either address.

Bit 7 - MASK_ALL - Masks the ALERT pin from asserting.

- '0' (default) The ALERT pin is not masked. If any of the appropriate status bits are set, the ALERT pin will be asserted.
- '1' The ALERT pin is masked if configured in Interrupt mode (see Section 4.4.1, "ALERT Pin Interrupt Mode"). The Status Registers will be updated normally.

Bit 6 - TMEAS / STOP - Controls Temperature measurement modes.

- '0' (default) The device is active, measuring the temperature channel.
- '1' The device is not measuring temperature channels. It will update the temperature channel when a One-Shot command is given.

Bit 5 - ALERT/COMP - Controls the operation of the ALERT pin.

- '0' (default) The ALERT pin acts in Interrupt mode as described in Section 4.4.1.
- '1' The ALERT pin acts in Comparator mode as described in Section 4.4.2. In this mode the MASK_ALL bit is ignored.

Bit 2 - IMEAS / STOP - Controls V_{SENSE} and V_{SOURCE} measurement modes.

• '0' (default) - The device is measuring source voltage and sense voltage.

03h

09h



 '1' -The device is not measuring the source voltage and sense voltage. It will update V_{SENSE} and V_{SOURCE} registers when a One-Shot command is given.

5.6 Conversion Rate Register

Table 5.6 Conversion Rate Register

| ADDR | R/W | REGISTER | В7 | В6 | В5 | В4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|--------------------|----|----|----|----|----|-----|-------------|----|----------------|
| 04h | R/W | Conversion Rate | - | - | - | - | | T_0 | T_CONV[2:0] | | 06h (4/sec) |
| 0Ah | | Rale | | | | | | | | | (4/560) |

The Conversion Rate Register controls how often the $V_{\sf SOURCE}$ and temperature measurement channels are updated and compared against the limits. This register is fully accessible at either address.

Bits 2-0 - T_CONV[2:0] - Determines the conversion rate as shown in Table 5.7. This conversion rate applies to temperature measurement and source voltage measurement.

Table 5.7 Conversion Rate

| | T_CONV[2:0] | | |
|---|-------------|---|---------------------|
| 2 | 1 | 0 | CONVERSION RATE |
| 0 | 0 | 0 | 1 per 16 sec |
| 0 | 0 | 1 | 1 per 8 sec |
| 0 | 1 | 0 | 1 per 4 sec |
| 0 | 1 | 1 | 1 per 2 sec |
| 1 | 0 | 0 | 1 per sec |
| 1 | 0 | 1 | 2 per sec |
| 1 | 1 | 0 | 4 per sec (default) |
| 1 | 1 | 1 | 8 per sec |

5.7 Temperature Limit Registers

Table 5.8 Temperature Limit Registers

| ADDR | R/W | REGISTER | В7 | В6 | В5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|------------------------------|------|----|----|----|----|----|----|----|-----------------|
| 05h | R/W | Internal Diode High Limit | Sign | 64 | 32 | 16 | 8 | 4 | 2 | 1 | 55h (85°C) |
| 0Bh | | High Limit | | | | | | | | | (65 C) |
| 06h | R/W | Internal Diode Low Limit | Sign | 64 | 32 | 16 | 8 | 4 | 2 | 1 | 80h (-128°C) |
| 0Ch | | LOW LITTIL | | | | | | | | | (-120 C) |



The device contains both high and low limits for the temperature channels. If the <u>measured</u> temperature meets or exceeds the high limit, the corresponding status bit is set, and the <u>ALERT</u> pin is asserted. Likewise, if the measured temperature is less than or equal to the low limit, the corresponding status bit is set and the <u>ALERT</u> pin is asserted.

The limit registers with multiple addresses are fully accessible at either address.

When the device is Standby or Current Sense only mode, updating the limit registers will have no effect until the next conversion cycle occurs. This conversion cycle can be initiated via a write to the One-Shot Register or by clearing the TMEAS_STOP bit in the Configuration Register (see Section 5.5).

5.8 One-Shot Register

Table 5.9 One-Shot Register

| ADDR. | R/W | REGISTER | В7 | В6 | В5 | В4 | В3 | B2 | B1 | В0 | DEFAULT |
|-------|-----|----------|---------|----|----|----|----|------------------------|----|---------|---------|
| 0Fh | W | One-Shot | Writing | | | | | e convers s reads 0 | | e. Data | 00h |

Writing to the One-Shot register will automatically update those channels that are not currently measured. If the device is Fully Active, writing to this register will have no effect. If the IMEAS_STOP bit is set, writing to this register will update the V_{SENSE} and V_{SOURCE} voltage measurements. If the TMEAS_STOP bit is set, writing to this register will update all of the temperature channel measurements.

5.9 Tcrit Limit Registers

Table 5.10 Tcrit Limit Registers

| ADDR. | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|-------|-----|-------------------------------|------|----|----|----|----|----|----|----|----------------|
| 20h | R/W | Internal Diode Tcrit Limit | Sign | 64 | 32 | 16 | 8 | 4 | 2 | 1 | 64h (100°C) |
| 21h | R/W | Tcrit Hysteresis | - | 64 | 32 | 16 | 8 | 4 | 2 | 1 | 0Ah (10°C) |

The Tcrit Limit Registers are used to determine whether a <u>critical thermal</u> event has occurred. If the measured temperature meets or exceeds the Tcrit Limit, the THERM pin is asserted.

Unlike the ALERT pin, the THERM pin cannot be masked. Additionally, the THERM pin will be released once the temperature drops below the corresponding threshold minus the Tcrit Hysteresis.

5.10 Channel Mask Register

Table 5.11 Channel Mask Register

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|-----------------|-----------------|---------------|---------------|----|----|----|----|-------------|---------|
| 1Fh | R/W | Channel Mask | VSENSE_ MASK | VSRC_ MASK | PEAK_ MASK | - | - | - | - | INT MASK | 00h |



The Channel Mask Register controls individual channel masking. When a channel is masked, the ALERT pin will not be asserted when the masked channel reads an out-of-limit error. The channel mask does not mask the THERM pin.

Bit 7 - VSENSE_MASK - Masks the $\overline{\text{ALERT}}$ pin from asserting when the V_{SENSE} value meets or exceeds the high limit or drops below the low limit. This bit will have no effect on the $\overline{\text{THERM}}$ pin functionality.

- '0' (default) The V_{SENSE} voltage channel will cause the ALERT pin to be asserted (if enabled).
- '1' The V_{SENSE} voltage channel will not cause the ALERT pin to be asserted (if enabled).

Bit 6 - VSRC_MASK - Masks the $\overline{\text{ALERT}}$ pin from asserting when the V_{SOURCE} value meets or exceeds the high limit or drops below the low limit. This bit will have no effect on the $\overline{\text{THERM}}$ pin functionality.

- '0' (default) The V_{SOURCE} voltage channel will cause the ALERT pin to be asserted (if enabled).
- '1' The V_{SOURCE} voltage channel will not cause the ALERT pin to be asserted (if enabled).

BIt 5 - PEAK_MASK - Masks the ALERT pin from <u>asserting</u> when the Peak Detector circuitry detects a current spike. This bit will have no effect on the THERM pin functionality.

- '0' (default) The Peak Detector circuitry will cause the ALERT pin to be asserted (if enabled).
- '1' The Peak Detector circuitry will not cause the ALERT pin to be asserted (if enabled).

Bit 0 - INTMASK - Masks the ALERT pin from asserting when the Internal Diode temperature is out-of-limit.

- '0' (default) The Internal Diode channel will cause the ALERT pin to be asserted if it is out-of-limit.
- '1' The Internal Diode channel will not cause the ALERT pin to be asserted if it is out-of-limit.

5.11 Consecutive Alert Register

Table 5.12 Consecutive Alert Register

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|----------------------|-------------|----|--------|-----|----|--------|-----|----|---------|
| 22h | R/W | Consecutive Alert | TIME OUT | СТ | THRM[2 | :0] | С | ALRT[2 | :0] | - | 70h |

The Consecutive Alert Register determines how many times an out-of-limit error must be detected in consecutive measurements before the interrupt status registers are asserted. This applies to temperature limits only. The voltage measurement and current sense measurements are controlled via the Voltage Channel Configuration register and Current Sense Configuration register respectively (see Section 5.15 and Section 5.16).

When the ALERT pin is configured as a comparator, the consecutive alert counter will ignore low limit errors and only increment if the measured temperature meets or exceeds the High Limit.

Bit 7 - TIMEOUT - Determines whether the SMBus Timeout function is enabled.

- '0' (default) The SMBus Timeout feature is disabled. The SMCLK line can be held low indefinitely without the device resetting its SMBus protocol.
- '1' The SMBus Timeout feature is enabled. If the SMCLK line is held low for more than 30ms, the device will reset the SMBus protocol.

Bits 6-4 - CTHRM[2:0] - Determines the number of consecutive measurements that must exceed the corresponding Tcrit Limit before the THERM pin is asserted.



Bits 3-1 - CALRT[2:0] - Determines the number of consecutive measurements that must have an out-of-limit condition before the ALERT pin is asserted. The bits are decoded as shown in Table 5.13. The default setting is 1 consecutive out-of-limit conversion.

Table 5.13 Consecutive ALERT / THERM Settings

| 2 | 1 | 0 | NUMBER OF CONSECUTIVE OUT-OF-LIMIT MEASUREMENTS |
|---|---|---|--|
| 0 | 0 | 0 | 1 (default for CALRT[2:0]) |
| 0 | 0 | 1 | 2 |
| 0 | 1 | 1 | 3 |
| 1 | 1 | 1 | 4 (default for CTHRM[2:0]) |

5.12 High Limit Status Register

Table 5.14 High Limit Status Register

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|----------------------|-----------------|---------------|----|----|----|----|----|-----------|---------|
| 35h | R-C | High Limit Status | VSENSE_ HIGH | VSRC_ HIGH | - | - | - | - | - | l HIGH | 00h |

The High Limit Status Register contains the status bits that are set when a temperature or voltage channel high limit is met or exceeded. If any of these bits are set, the HIGH status bit in the Status Register is set. Reading from the High Limit Status Register will clear all bits if the error condition has been removed. Reading from the register will also clear the HIGH status bit in the Status Register if the error condition has been removed.

If not masked, the ALERT pin will be set if the programmed number of consecutive alert counts have been met and any of these status bits are set. Once set, the status bits will remain set until read unless the ALERT pin is configured as a comparator output (see Section 4.4.2).

Bit 7 - VSENSE_HIGH - This bit is set when the V_{SENSE} value meets or exceeds its programmed high limit.

Bit 6 - VSRC_HIGH - This bit is set when the $V_{\mbox{SOURCE}}$ value meets or exceeds its programmed high limit

Bit 0 - IHIGH - This bit is set when the Internal Diode channel meets or exceeds its programmed high limit.

5.13 Low Limit Status Register

Table 5.15 Low Limit Status Register

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|---------------------|----------------|--------------|----|----|----|----|----|------|---------|
| 36h | R-C | Low Limit Status | VSENSE_ LOW | VSRC_ LOW | ı | ı | 1 | ı | - | ILOW | 00h |

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The Low Limit Status Register contains the status bits that are set when a temperature or voltage channel drops below the low limit. If any of these bits are set, the LOW status bit in the Status Register is set. Reading from the Low Limit Status Register will clear all bits. Reading from the register will also clear the LOW status bit in the Status Register if the error status has been removed.

If not masked, the $\overline{\text{ALERT}}$ pin will be set if the programmed number of consecutive alert counts have been met and any of these status bits are set.

Once set, the status bits will remain set until read.

- Bit 7 VSENSE_LOW This bit is set when the V_{SENSE} value drops below its programmed low limit.
- Bit 6 VSRC_LOW This bit is set when the V_{SOURCE} value drops below its programmed low limit.
- Bit 0 ILOW This bit is set when the Internal Diode channel drops below its programmed low limit.

5.14 Crit Limit Status Register

Table 5.16 Crit Limit Status Register

| ADDR | R/W | REGISTER | B7 | В6 | В5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|----------------------|------------------|----------------|----|----|----|----|----|--------|---------|
| 37h | R-C | Crit Limit Status | VSENSE_ VCRIT | VSRC_ VCRIT | - | - | - | - | - | ITCRIT | 00h |

The Crit Limit Status register contains the status bits that are set when a temperature or voltage channel Tcrit or Vcrit Limit is met or exceeded (see Section 5.9 and Section 5.23). If any of these bits are set, the CRIT status bit in the Status register is set. Reading from the Crit Limit Status register will not clear the status bits. Once the temperature drops below the Tcrit Limit minus the Tcrit Hysteresis, the corresponding status bits will be automatically cleared. Once the voltage drops below the Vcrit Limit minus the Vcrit Hysteresis, the corresponding status bits will be automatically cleared. The CRIT bit in the Status register will be cleared when all individual bits are cleared.

Bit 7 - VSENSE_VCRIT - This bit is set when the V_{SENSE} value meets or exceeds its programmed Vcrit limit. When set, this bit will assert the \overline{THERM} pin.

Bit 6 - VSRC_VCRIT- This bit is set when the V_{SOURCE} value meets or exceeds its programmed Vcrit limit. When set, this bit will assert the \overline{THERM} pin.

Bit 0 - ITCRIT - This bit is set when the Internal Diode channel meets or exceeds its programmed Tcrit limit. When set, this bit will assert the THERM pin.

5.15 Voltage Sampling Configuration Register

Table 5.17 Voltage Sampling Configuration Register

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|-------------------------------|------------------------|----|----|----|-------|---------|------|---------|---------|
| 50h | R/W | Voltage Sampling Config | PK_ ALERT_ THERM | 1 | 1 | - | V_QUE | UE[1:0] | V_AV | 'G[1:0] | 80h |

The Voltage Sampling Configuration register controls functionality for the source voltage measurement and Peak Detector circuitry.

Bit 7 - PK_ALERT_THERM - Determines whether the ALERT pin or THERM pin is asserted if the Peak Detector detects a current spike. If configured to assert the ALERT pin, the PEAK_MASK can block the pin assertion normally. If configured to assert the THERM pin, it will not be masked.



- '0' The Peak Detector circuitry will assert the ALERT pin when a current spike is detected. The ALERT pin must be configured to operate in Comparator mode or it will not be asserted.
- '1' (default) The Peak Detector circuitry will assert the THERM pin when a current spike is detected.

Bits $3 - 2 - V_{QUEUE[1:0]}$ - Determine the number of consecutive measurements that V_{SOURCE} must exceed the limits before flagging an interrupt.

Table 5.18 Voltage Queue Settings

| V_QUE | UE[1:0] | |
|-------|---------|---|
| 1 | 0 | NUMBER OF CONSECUTIVE OUT-OF-LIMIT MEASUREMENTS |
| 0 | 0 | 1 (default) |
| 0 | 1 | 2 |
| 1 | 0 | 3 |
| 1 | 1 | 4 |

Bits 1-0 - V_AVG[1:0] - Controls the digital averaging that is applied to the source voltage measurement, as shown in Table 5.19.

Table 5.19 Voltage Averaging Settings

| V | | |
|---|---|--------------------|
| 1 | 0 | AVERAGING |
| 0 | 0 | Disabled (default) |
| 0 | 1 | 2x |
| 1 | 0 | 4x |
| 1 | 1 | 8x |

5.16 Current Sense Sampling Configuration Register

Table 5.20 Current Sense Sampling Configuration Register

| ADDR | R/W | REGISTER | В7 | В6 | В5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|----------------------------------|---------------|----|----|------------------|-------|----------------|----|------------|---------|
| 51h | R/W | Current Sense Sampling Config | CS_Ql [1:0 | | | SAMP_ i [1:0] | CS_S/ | AMP_ [[1:0] | | RNG :0] | 03h |

The Current Sense Sampling Configuration register stores the controls for determining the Current Sense sampling / update time.

Bits 7 - 6 - CS_QUEUE[1:0] - Determine the number of consecutive measurements that the measured V_{SENSE} must exceed the limits before flagging an interrupt.



Table 5.21 Sense Queue Settings

| CS_QUE | EUE[1:0] | |
|--------|----------|---|
| 1 | 0 | NUMBER OF CONSECUTIVE OUT-OF-LIMIT MEASUREMENTS |
| 0 | 0 | 1 (default) |
| 0 | 1 | 2 |
| 1 | 0 | 3 |
| 1 | 1 | 4 |

Bits 5 - 4 - CS_SAMP_AVG[1:0] - Determines the number of averages that the Current Sensing Circuitry will take as shown in Table 5.22.

Table 5.22 Current Sense Averaging Settings

| CS_S | | |
|------|---|--------------|
| 1 | 0 | AVERAGING |
| 0 | 0 | 1x (default) |
| 0 | 1 | 2x |
| 1 | 0 | 4x |
| 1 | 1 | 8x |

Bits 3 - 2 - CS_SAMP_TIME[1:0] - Determines the sampling time of the Current Sensing Circuitry as shown in Table 5.23. The V_{SENSE} voltage will be updated at this rate representing the average current over the Sampling Time multiplied by the Averaging factor as shown in Table 5.24.

Table 5.23 Current Sensing Sampling Time Settings

| CS_SAMP | _TIME[1:0] | |
|---------|------------|------------------------------|
| 1 | 0 | CURRENT SENSOR SAMPLING TIME |
| 0 | 0 | 82ms (default) |
| 0 | 1 | 82ms |
| 1 | 0 | 164ms |
| 1 | 1 | 328ms |



Table 5.24 Total Sampling Times

| | AVERAGING SELECTION | | | | | | | | |
|---------------|---------------------|-------|--------|--------|--|--|--|--|--|
| SAMPLING TIME | 1X | 2X | 4X | 8X | | | | | |
| 82ms | 82ms | 164ms | 328ms | 655ms | | | | | |
| 164ms | 164ms | 328ms | 655ms | 1310ms | | | | | |
| 328ms | 328ms | 655ms | 1310ms | 2620ms | | | | | |

Bits 1 - 0 - CS_RNG[1:0] - Determines the Current Sense maximum expected voltage (full scale range) as shown in Table 5.25.

Table 5.25 Current Sensing Range (Full Scale Range) Settings

| CS_RI | NG[1:0] | |
|-------|---------|----------------------|
| 1 | 0 | CURRENT SENSOR RANGE |
| 0 | 0 | 10mV |
| 0 | 1 | 20mV |
| 1 | 0 | 40mV |
| 1 | 1 | 80mV (default) |

5.17 Peak Detection Configuration Register

Table 5.26 Peak Detection Configuration Register

| ADDR | R/W | REGISTER | В7 | В6 | B5 | В4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|-----------------------------|----|---------|----------|----|----|--------|--------|-----|---------|
| 52h | R/W | Peak Detection Config | Ī | PEAK_DE | T_TH[3:0 |] | PE | AK_DET | _DUR[3 | :0] | 00h |

The Peak Detection Configuration register controls the threshold and durations used by the Peak Detection circuitry. At all times, the Peak Detection threshold and duration are set by the values written into this register. The resistors on the TH_SEL and DUR_SEL pins are used to determine the initial values of this register (EMC1701-1 only) and will not be retained if the value is over written by the user.

These values may be updated at any time via the SMBus.

Bits 7-4 - PEAK_DET_TH[3:0] - Determines the Peak Detector Threshold level as shown in Table 5.27.



Table 5.27 PEAK_DET_TH[3:0] Bit Decode

| | PEAK_DE | | | |
|---|---------|---|---|--------------------------|
| 3 | 2 | 1 | 0 | PEAK DETECTION THRESHOLD |
| 0 | 0 | 0 | 0 | 10mV |
| 0 | 0 | 0 | 1 | 15mV |
| 0 | 0 | 1 | 0 | 20mV |
| 0 | 0 | 1 | 1 | 25mV |
| 0 | 1 | 0 | 0 | 30mV |
| 0 | 1 | 0 | 1 | 35mV |
| 0 | 1 | 1 | 0 | 40mV |
| 0 | 1 | 1 | 1 | 45mV |
| 1 | 0 | 0 | 0 | 50mV |
| 1 | 0 | 0 | 1 | 55mV |
| 1 | 0 | 1 | 0 | 60mV |
| 1 | 0 | 1 | 1 | 65mV |
| 1 | 1 | 0 | 0 | 70mV |
| 1 | 1 | 0 | 1 | 75mV |
| 1 | 1 | 1 | 0 | 80mV |
| 1 | 1 | 1 | 1 | 85mV |

Bits 4-0 - PEAK_DET_DUR[3:0] - Determines the Peak Detector minimum time threshold as shown in Table 5.28.

Table 5.28 PEAK_DET_DUR[3:0] Bit Decode

| | PEAK_DET | _DUR[3:0] | | DEAK DETECTION MINUM |
|---|----------|-----------|---|---------------------------------|
| 3 | 2 | 1 | 0 | PEAK DETECTION MINIMUM DURATION |
| 0 | 0 | 0 | 0 | 1ms |
| 0 | 0 | 0 | 1 | 5.12ms |
| 0 | 0 | 1 | 0 | 25.6 ms |
| 0 | 0 | 1 | 1 | 51.2 ms |
| 0 | 1 | 0 | 0 | 76.8 ms |
| 0 | 1 | 0 | 1 | 102.4ms |
| 0 | 1 | 1 | 0 | 128.0ms |
| 0 | 1 | 1 | 1 | 256.0ms |



Table 5.28 PEAK_DET_DUR[3:0] Bit Decode (continued)

| | PEAK_DET | _DUR[3:0] | | DEAK DETECTION MINIMUM |
|---|----------|-----------|---|------------------------------------|
| 3 | 2 | 1 | 0 | PEAK DETECTION MINIMUM DURATION |
| 1 | 0 | 0 | 0 | 384.0ms |
| 1 | 0 | 0 | 1 | 512.0ms |
| 1 | 0 | 1 | 0 | 768.0ms |
| 1 | 0 | 1 | 1 | 1024.0ms |
| 1 | 1 | 0 | 0 | 1536.0ms |
| 1 | 1 | 0 | 1 | 2048.0ms |
| 1 | 1 | 1 | 0 | 3072.0ms |
| 1 | 1 | 1 | 1 | 4096.0ms |

5.18 Sense Voltage Registers

Table 5.29 Sense Voltage Registers

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|----------------------------|------|------|-----|-----|-----|----|----|----|---------|
| 54h | R | Sense Voltage High Byte | Sign | 1024 | 512 | 256 | 128 | 64 | 32 | 16 | 00h |
| 55h | R | Sense Voltage Low Byte | 8 | 4 | 2 | 1 | | | | | 00h |

The Sense Voltage registers store the measured V_{SENSE} voltage across the sense resistor (R_{SENSE}) placed between the SENSE+ and SENSE- pins (see Section 4.1.1, "Current Measurement"). Note that the bit weighting values are for representation of the voltage relative to full scale. There is no internal scaling of data and all normal binary bit weightings still apply.

The Sense Voltage register data format is standard 2's complement format with the positive full scale value (7F_Fh) and negative full scale value (80_0h) equal to the programmed maximum sense voltage (see Section 5.16, "Current Sense Sampling Configuration Register").

The Sign bit indicates the direction of current flow. If the Sign bit is '0', current is flowing through R_{SENSE} from the SENSE+ pin to the SENSE- pin. If the Sign bit is '1', the current is flowing through R_{SENSE} from the SENSE- pin to the SENSE+ pin. See Section 4.1.1, "Current Measurement" for examples.

Table 5.30 V_{SENSE} Data Format

| V _{SENSE} | BINARY | HEX (AS READ BY REGISTERS) |
|--------------------|----------------|----------------------------|
| Minus Full Scale | 1000_0000_0000 | 80_0h |
| -2 LSB | 1111_1111_1110 | FF_Eh |
| -1 LSB | 1111_1111_1111 | FF_Fh |
| Zero | 0000_0000_0000 | 00_0h |

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Table 5.30 V_{SENSE} Data Format (continued)

| V _{SENSE} | BINARY | HEX (AS READ BY REGISTERS) |
|--------------------|----------------|----------------------------|
| +1 LSB | 0000_0000_0001 | 00_1h |
| +2 LSB | 0000_0000_0010 | 00_2h |
| Plus Full Scale | 0111_1111_1111 | 7F_Fh |

5.19 Source Voltage Registers

Table 5.31 Source Voltage Registers

| ADDR | R/W | REGISTER | В7 | В6 | В5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|----------------------------------|--------|--------|--------|-----|------|-------|--------|--------|---------|
| 58h | R | V _{SOURCE} High Byte | 12 | 6 | 3 | 1.5 | 0.75 | 0.375 | 0.1875 | 0.0938 | 00h |
| 59h | R | V _{SOURCE} low Byte | 0.0469 | 0.0234 | 0.0117 | - | - | - | - | - | 00h |

The Source Voltage registers store the voltage measured at the SENSE+ pin (see Section 4.1.2, "Voltage Measurement") as a digital value, V_{SOURCE}, consisting of a high byte and low byte with five of its LSBs always zero.

The measured voltage is determined by summing the bit weights of each bit set. For example, if V_{BUS} was 7.4V, the Source Voltage registers would read 0100_1110 for the high byte and 1100_0000b for the low byte corresponding to 6V + 0.75V + 0.375V + 0.1875V + 0.0469V + 0.0234V = 7.383V.

The bit weightings are assigned for human interpretation. They should be disregarded when translating the information via a computing system as shown in Section 4.1.2, "Voltage Measurement".

The Source Voltage registers cannot support negative values, and all values less than 0V will be recorded as 0V.

5.20 Power Ratio Registers

Table 5.32 Power Ratio Registers

| ADDR | R/W | REGISTER | В7 | В6 | В5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|--------------------------|-------|-------|------|------|------|------|-----|-----|---------|
| 5Bh | R | Power Ratio High Byte | 32768 | 16384 | 8192 | 4096 | 2048 | 1024 | 512 | 256 | 00h |
| 5Ch | R | Power Ratio Low Byte | 128 | 64 | 32 | 16 | 8 | 4 | 2 | 1 | 00h |

The Power Ratio registers store a power factor value that is used to determine the final average power delivered to the system (see Section 4.1.3, "Power Calculation"). The power factor value is the result of the multiplication of the V_{SENSE} reading and the V_{SOURCE} reading values shifted to a 16-bit number. It represents the ratio of delivered power with respect to maximum power.



5.21 V_{SENSE} Limit Registers

Table 5.33 V_{SENSE} Limit Registers

| ADDR | R/W | REGISTER | B7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|-----------------------------|------|------|-----|-----|-----|----|----|----|---------|
| 60h | R/W | Sense Voltage High Limit | Sign | 1024 | 512 | 256 | 128 | 64 | 32 | 16 | 7Fh |
| 61h | R/W | Sense Voltage Low Limit | Sign | 1024 | 512 | 256 | 128 | 64 | 32 | 16 | 80h |

The V_{SENSE} Limit registers store a high and low limit for V_{SENSE} . V_{SENSE} is compared against both limits after each update.

The data format for the limit is a raw binary form that is relative to the maximum V_{SENSE} that has been programmed.

If the measured sense voltage meets or exceeds the high limit or drops below the low limit, the ALERT pin is asserted and the VSENSE_HIGH or VSENSE_LOW status bits are set in the High Limit Status or Low Limit Status registers (see Section 5.12 and Section 5.13).

APPLICATION NOTE: V_{SENSE} is always checked to be greater than the high limit or less than the low limit including when V_{SENSE} is negative.

5.22 Source Voltage Limit Registers

Table 5.34 Source Voltage Limit Registers

| ADDR | R/W | REGISTER | В7 | В6 | В5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|---------------------------------|----|----|----|-----|------|-------|--------|--------|---------|
| 64h | R/W | Source Voltage High Limit | 12 | 6 | 3 | 1.5 | 0.75 | 0.375 | 0.1875 | 0.0938 | FFh |
| 65h | R/W | Source Voltage Low Limit | 12 | 6 | 3 | 1.5 | 0.75 | 0.375 | 0.1875 | 0.0938 | 00h |

The Source Voltage Limit registers store the high and low limits for V_{SOURCE} . V_{SOURCE} is compared against all limits after each update.

If V_{SOURCE} meets or exceeds the corresponding high limit or drops below the low limit, the ALERT pin is asserted and the VSRC_HIGH or VSRC_LOW status bits are set in the High Limit Status or Low Limit Status registers (see Section 5.12 and Section 5.13).

5.23 Critical Voltage Limit Registers

Table 5.35 Critical Voltage Limit Registers

| ADDR | R/W | REGISTER | В7 | В6 | В5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|------------------------------|------|------|-----|-----|-----|----|----|----|---------|
| 66h | R/W | Sense Voltage Vcrit Limit | Sign | 1024 | 512 | 256 | 128 | 64 | 32 | 16 | 7Fh |

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Table 5.35 Critical Voltage Limit Registers (continued)

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|------------------------------------|----|----|----|-----|------|-------|--------|--------|---------|
| 68h | R/W | Source Voltage Vcrit Limit | 12 | 6 | 3 | 1.5 | 0.75 | 0.375 | 0.1875 | 0.0938 | FFh |
| 69h | R/W | Sense Voltage Vcrit Hysteresis | - | - | - | 256 | 128 | 64 | 32 | 16 | 0Ah |
| 6Ah | R/W | Source Voltage Vcrit Hysteresis | - | - | - | 1.5 | 0.75 | 0.375 | 0.1875 | 0.0938 | 0Ah |

The Critical Voltage Limit registers store the critical voltage limits (Vcrit limits) for V_{SENSE} and V_{SOURCE} .

If the respective value meets or exceeds its critical limit, the THERM pin will be asserted low and the respective VCRIT status bit will be set (see Section 5.14, "Crit Limit Status Register"). It will remain asserted until the respective value drops below its limit minus the respective Vcrit Hysteresis value.

5.24 Product Features Register (EMC1701-1 only)

Table 5.36 Product Features

| ADDR | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|---------------------|----|-------|---------|----|----|-------|----------|----|---------|
| FCh | R | Product Features | | TH_SI | EL[3:0] | | | DUR_S | SEL[3:0] | | 00h |

The Product Features register indicates functionality that is selected by the user based on pin states upon device power up. This register applies to the EMC1701-1 only. It will always read 00h for the EMC1701-2.

Bits 7-4 - TH_SEL[3:0] - Indicates the selected Peak Detector Threshold setting as determined by the TH_SEL pin. This value will be the default setting for the PEAK_DET_TH[3:0] bits and uses the same decode as given in Table 5.27.

Bits 3-0 - DUR_SEL[3:0] - Indicates the selected Peak Detector minimum duration setting as determined by the DUR_SEL pin. This value will be the default setting for the PEAK_DET_DUR[3:0] bits and uses the same decode as given in Table 5.28.

5.25 Product ID Register

Table 5.37 Product ID Register

| ADDR | R/W | REGISTER | В7 | В6 | B5 | В4 | В3 | B2 | B1 | В0 | DEFAULT |
|------|-----|------------|----|----|----|----|----|----|----|----|---------|
| FDh | R | Product ID | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 38h |

The Product ID Register holds a unique value that identifies the device.



5.26 SMSC ID Register

Table 5.38 Manufacturer ID Register

| ADDR. | R/W | REGISTER | В7 | В6 | В5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|-------|-----|----------|----|----|----|----|----|----|----|----|---------|
| FEh | R | SMSC ID | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | 5Dh |

The Manufacturer ID register contains an 8-bit word that identifies SMSC as the manufacturer of the EMC1701.

5.27 Revision Register

Table 5.39 Revision Register

| ADDR. | R/W | REGISTER | В7 | В6 | B5 | B4 | В3 | B2 | B1 | В0 | DEFAULT |
|-------|-----|----------|----|----|----|----|----|----|----|----|---------|
| FFh | R | Revision | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 82h |

The Revision register contains an 8-bit word that identifies the die revision.



Chapter 6 Package Description

6.1 EMC1701-1 Package Drawing (12-Pin QFN 4mm x 4mm)

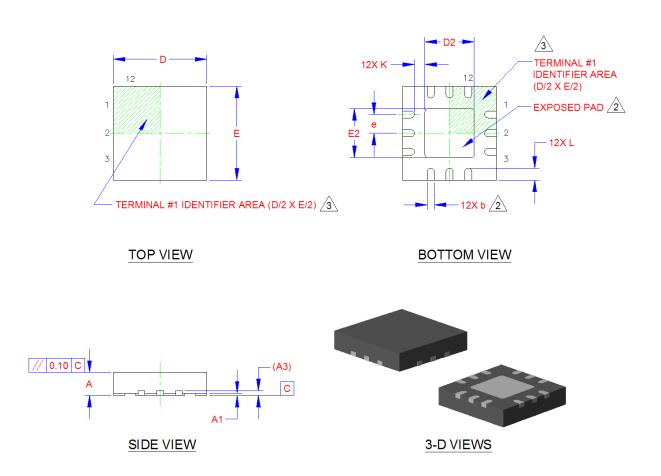


Figure 6.1 12-Pin QFN 4mm x 4mm Package Drawings

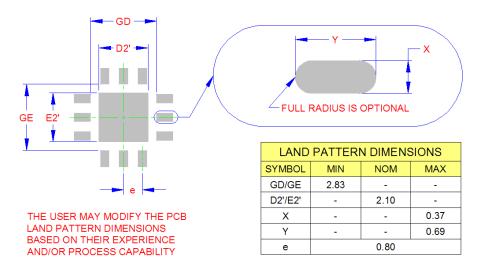


| COMMON DIMENSIONS | | | | | | | | | |
|-------------------|------|----------------|------|------|--------------------------|--|--|--|--|
| SYMBOL | MIN | NOM | MAX | NOTE | REMARK | | | | |
| Α | 0.80 | 0.85 | 0.90 | - | OVERALL PACKAGE HEIGHT | | | | |
| A1 | 0 | 0.02 | 0.05 | - | STANDOFF | | | | |
| А3 | | 0.20 REF | | - | LEAD-FRAME THICKNESS | | | | |
| D/E | 3.90 | 4.00 | 4.10 | - | X/Y BODY SIZE | | | | |
| D2/E2 | 2.00 | 2.10 | 2.20 | 2 | X/Y EXPOSED PAD SIZE | | | | |
| L | 0.45 | 0.45 0.50 0.55 | | | TERMINAL LENGTH | | | | |
| b | 0.25 | 0.30 | 0.35 | 2 | TERMINAL WIDTH | | | | |
| K | 0.20 | 0.20 | | | TERMINAL TO PAD DISTANCE | | | | |
| е | | 0.80 BSC | | - | TERMINAL PITCH | | | | |

NOTES:

- 1. ALL DIMENSIONS ARE IN MILLIMETERS.
- 2. POSITION TOLERANCE OF EACH TERMINAL AND EXPOSED PAD IS \pm 0.05mm AT MAXIMUM MATERIAL CONDITION. DIMENSIONS "b" APPLIES TO PLATED TERMINALS AND IT IS MEASURED BETWEEN 0.15 AND 0.30 mm FROM THE TERMINAL TIP.
- 3. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL BUT MUST BE LOCATED WITHIN THE AREA INDICATED.

Figure 6.2 12-Pin QFN 4mm x 4mm Package Dimensions and Notes



RECOMMENDED PCB LAND PATTERN

Figure 6.3 12-Pin QFN 4mm x 4mm PCB Footprint



6.2 EMC1701-2 Package Drawing (10-pin MSOP)

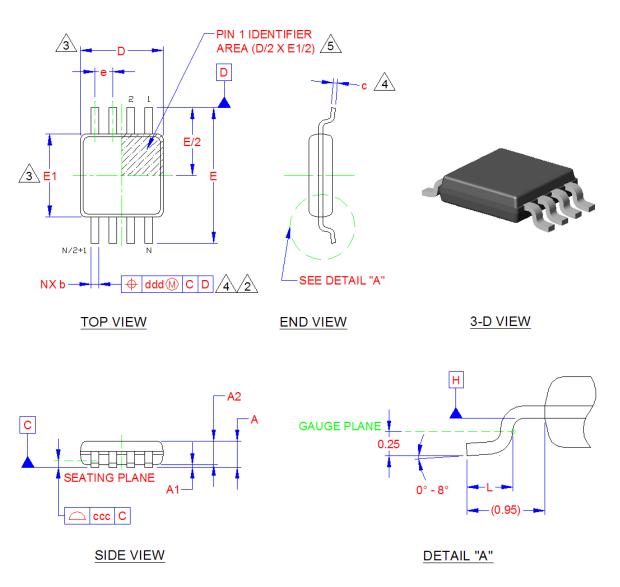


Figure 6.1 10-Pin MSOP Package Drawings (see Note 6.1)

Note 6.1 Although Figure 6.1 the shows a picture of an 8-pin device, dimensions are given for the 10-pin device in Figure 6.2.



| Symbol | MIN | NOM | MAX | Description / Remark | | |
|--------------|---------------------|----------|------|---|--|--|
| Α | 0.80 | - | 1.10 | Overall Package Height | | |
| A1 | 0.05 | - | 0.15 | Standoff | | |
| A2 | 0.75 | 0.85 | 0.95 | Package Body Thickness | | |
| D | 2.80 | 3.00 | 3.20 | X Body Size | | |
| E | 4.65 | 4.90 | 5.15 | Lead Span | | |
| E1 | 2.80 | 3.00 | 3.20 | Y Body Size | | |
| L | 0.40 | - | 0.80 | Lead Foot Length | | |
| b (N = 8) | 0.22 | - | 0.38 | Lood Width | | |
| b (N = 10) | 0.17 | - | 0.27 | Lead Width | | |
| С | 0.08 | - | 0.23 | Lead thickness | | |
| e (N = 8) | | 0.65 BSC | , | Load Ditab | | |
| e (N = 10) | e (N = 10) 0.50 BSC | | ; | Lead Pitch | | |
| ccc | 0 | - | 0.10 | Lead Coplanarity (Bending in Z direction) | | |
| ddd (N = 8) | 0 | - | 0.13 | Load Desition (Pending in V. V. plane) | | |
| ddd (N = 10) | 0 | - | 0.08 | Lead Position (Bending in X-Y plane) | | |

Notes:

- 1. All dimensions are in millimeters. "N" is the total number of leads.
- Dimension "b" does not include dambar protrusion. Dambar cannot be located on the lower radius of the foot.
- Dimension "D" does not include mold protrusions or flash. Maximum mold protrusions or flash is 0.15mm per end, and per side. Dimensions "D" & "E1" are determined at the datum plane "H".
- Dimensions "b" and "c" apply to the flat section of the lead, between 0.08 to 0.15mm from the lead tip.
- 5. Details of pin 1 identifier are optional, but must be located within the index area indicated.

Figure 6.2 10-Pin MSOP Package Dimensions and Notes



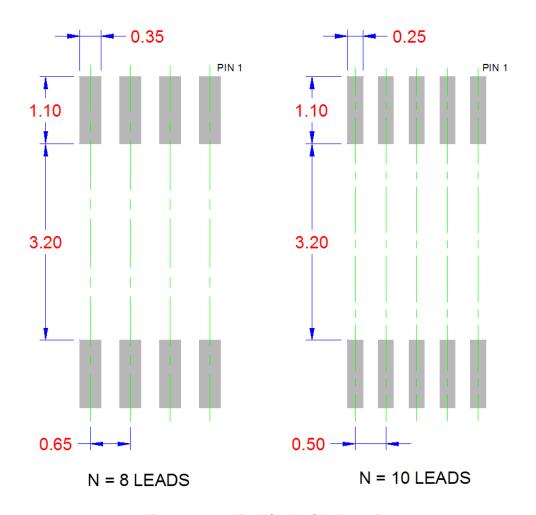
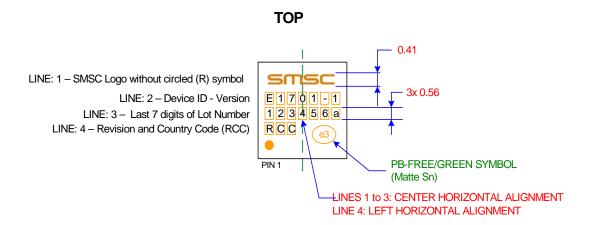


Figure 6.3 10-Pin MSOP PCB Footprint



6.3 EMC1701 Package Markings



BOTTOM MARKING NOT ALLOWED

Figure 6.1 EMC1701-1 Package Markings

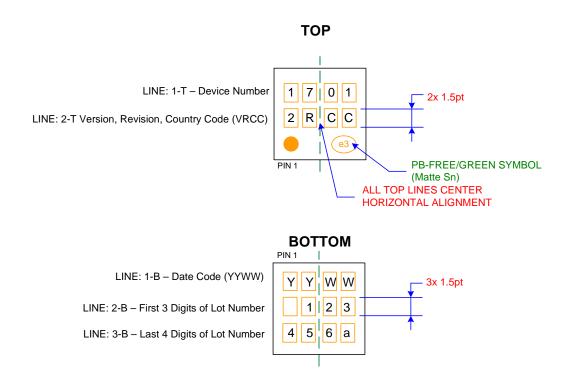


Figure 6.2 EMC1701-2 Package Markings



Chapter 7 Datasheet Revision History

Table 7.1 Customer Revision History

| REVISION LEVEL & DATE | SECTION/FIGURE/ENTRY | CORRECTION |
|-----------------------|---|--|
| Rev. 1.2 (09-27-10) | Table 2.1, "Absolute Maximum Ratings" | Added spec for voltage between SENSE pins. |
| | Table 2.2, "Electrical Specifications" | Updated all electrical specs for current sense measurement, supply current, and peak detector. |
| | Electrical Specifications APPLICATION NOTE: | Added note: The EMC1701 is trimmed at the 80mV range for best accuracy. |
| Rev. 1.1 (06-16-10) | System Diagram | Updated. |
| | Section 5.12, "High Limit Status Register" and Section 5.13, "Low Limit Status Register" | ALERT# pin won't be set if masked. |
| | Table 5.25, "Current Sensing Range (Full Scale Range) Settings" | Changed title from Current Sensing Range to Current Sensing Range (Full Scale Range) Settings. |
| | Table 2.1, "Absolute Maximum Ratings" | Upper limit of Operating Ambient Temperature Range changed from 125°C to 85°C. |
| | Table 2.2, "Electrical Specifications" | T _A upper limit changed from 125°C to 85°C. Bus voltage symbol changed from V _{SOURCE} to V _{BUS} . I _{DD} at 4 conversions/second with dynamic averaging enabled changed from 0.95 typ and 1.375 max to 0.9 typ and 1.3 max. I _{DD} at 4 conversions/second with dynamic averaging disabled changed from 0.80 typ to 0.8 typ. I _{DD} at 1 conversion/second with dynamic averaging disabled changed from 650 typ and 1 max to 0.7 typ and 1.0 max. V _{SENSE} Full Scale Sense Range values changed from 0 min and +/- max values to - min values and + max values; conditions changed. Total Unadjusted V _{SENSE} Measurement Error (V _{SENSE} Tue) renamed V _{SENSE} Measurement Error (V _{SENSE} Tue) renamed V _{SENSE} Measurement Error (V _{SENSE} ERR); typ value at 20-80mV FSR changed from 0.8 to +/-0.5 and max changed from +/-1.5 to +/-1; typ value at 10mV FSR changed from 0.2 to +/-0.8 and max changed from +/-2 to +/-1.5. V _{SENSE} Measurement Gain Error has new symbol V _{SENSE} GN; added typ +/-0.2 and changed max from 0.5 to +/-0.5. V _{TH_ERR} changed from +/-20 to +/-2. V _{SOURCE} ERR changed conditions; typ changed from 0.05 to +/-0.2 and max changed from 1 to +/-0.5. Added Power Ratio Measurement specs. Data hold time changed from 0.6 min and 6 max to 0 min and no max. |
| | Section 5.27, "Revision Register" | Functional revision C changed default from 81h to 82h. |





Table 7.1 Customer Revision History (continued)

| REVISION LEVEL & DATE | SECTION/FIGURE/ENTRY | CORRECTION | | |
|-----------------------|----------------------|------------------|--|--|
| | Document | Added EMC1701-2. | | |
| Rev. 1.0 (11-09-09) | Formal release | | | |