
PTP & SyncE Network Synchronizers with up to 5 Channels, 10 Inputs, 20 Outputs Product Brief

Features

Highlights

- Up to five independent clock channels
- Any-to-any frequency conversion per channel
- Inputs: up to 10, differential or single-ended
- Outputs: up to 10 differential, up to 20 CMOS
- Output jitter $100 f_{s_{RMS}}$ typical for 156.25 MHz
12 kHz to 20 MHz
- Core power consumption <0.9W
- MiToDSync™ 1-wire time-of-day interface in/out
- MiToDBasic™ 3-wire time-of-day interface out

Frequency and Phase over Packet Networks

- Packet and/or physical-layer frequency, phase and time synchronization
- Physical-layer compliance with ITU-T G.8262, G.8262.1, G.813, G.812, Telcordia GR-1244, GR-253
- Packet-timing compliance with ITU-T G.8261, G.8263, G.8273.2 (class A,B,C,D), G.8273.4
- Enables 5G wireless applications with sub-100 ns time/phase alignment requirements

Input Clocks

- Accepts up to 10 differential or CMOS inputs
- Any input frequency from 0.5 Hz to 1250 MHz
- Per-input activity and frequency monitoring
- Automatic or manual reference switching
- Revertive or nonrevertive switching
- Any input can be a 0.5 Hz to 8 kHz Sync input for Ref-Sync frequency/phase/time locking
- Any input can be a clock with embedded Sync
- Input phase measurement, 1 ps resolution
- Per-input phase adjustment, 1 ps resolution

Up to 8 DPLLs

- Hitless reference switching
- High-resolution holdover averaging
- Per-DPLL phase adjustment, 1 ps resolution
- Programmable bandwidth, tracking range, phase-slope limiting, frequency-change limiting and other advanced features
- Locking to gapped-clock input signals
- Fast lock to 1 Hz inputs, 3 to 60 seconds, depending on test conditions

Output Clocks

- Any frequency 0.5 Hz to 750 MHz
- Each OUTP/N pair can be LVDS, LVPECL, 2xC-MOS, Low- V_{CM} , or programmable differential
- In 2xCMOS mode, the P and N pins can be different frequencies (e.g. 125 MHz and 25 MHz)
- VDD per output pair, CMOS voltages 1.8V to 3.3V
- Per-synth phase adjustment, 1 ps resolution
- Per-output duty cycle adjustment
- Precise output alignment circuitry and per-output phase adjustment
- Per-output enable/disable and glitchless start/stop (stop high or low)

Local Oscillator

- Operates from a single oscillator 9.72 MHz to 400 MHz
- Very-low-jitter applications can connect a TCXO or OCXO as the stability reference and a low-jitter XO as the jitter reference

General Features

- Automatic self-configuration at power-up from internal Flash memory, 7 configurations
- Input-to-output alignment <100 ps
- Numerically controlled oscillator behavior in each DPLL and each synthesizer
- Easy-to-configure design requires no external VCXO or loop filter components
- 5 GPIO pins with many possible behaviors, each REF can be GPI, each OUT can be GPO
- SPI or I²C processor Interface
- 1.8V and 3.3V core VDD voltages
- Easy-to-use evaluation/programming software

Applications

- Central system timing ICs for SyncE, SyncE+1588, routers, switches, OTN, and other carrier-grade systems
- Wireless base stations (3G, W-CDMA, 4G/LTE, LTE-A, 5G)
- Remote Radio Unit (RRU), Remote Access Networks (RAN), small cells, wireless backhaul, wireless repeaters

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1.0 BLOCK DIAGRAM

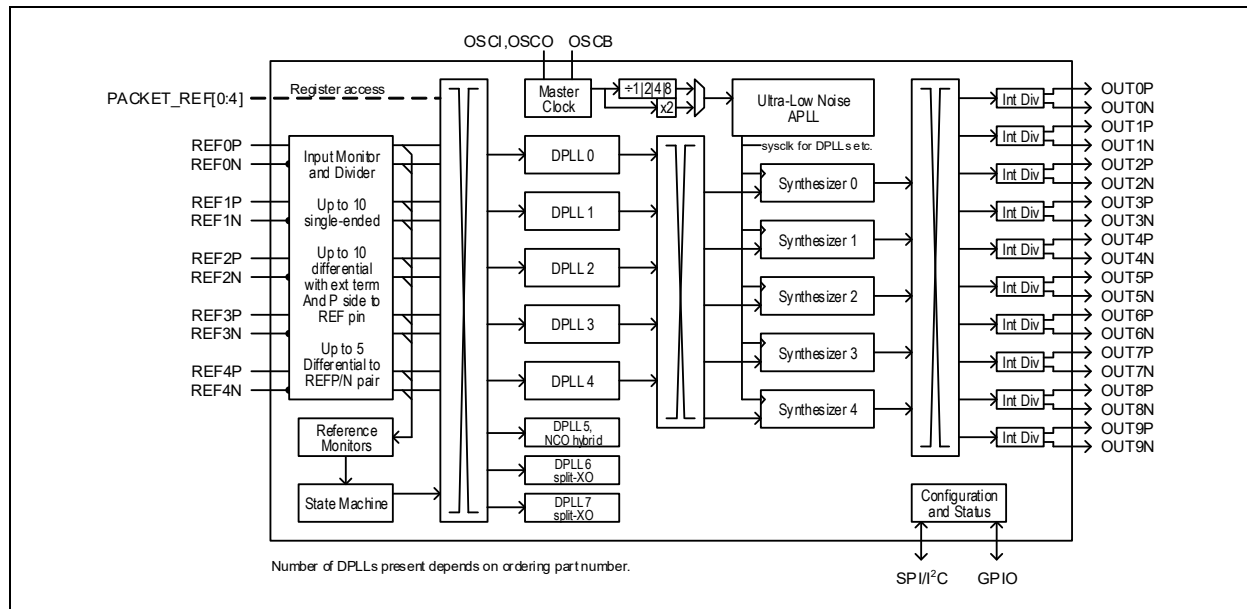


FIGURE 1-1: Functional Block Diagram.

2.0 APPLICATION EXAMPLE

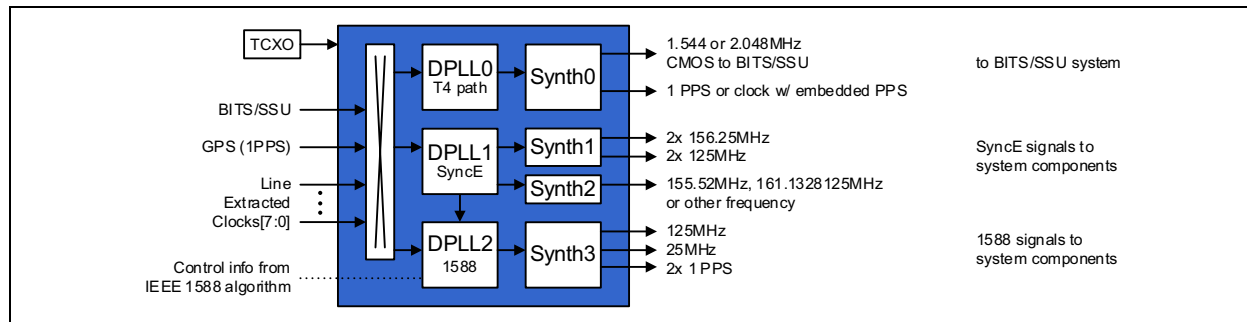


FIGURE 2-1: Synchronous Ethernet and IEEE 1588 Central Timing Application.

3.0 DETAILED FEATURES

3.1 General

- Up to five independent clock channels
- Operates from a single crystal resonator or clock oscillator
 - ≥ 48 MHz for lowest jitter
 - 9.72 MHz to 400 MHz total frequency range
- Configurable via SPI or I²C interface
- Internal nonvolatile memory
 - Factory-configurable power-on configuration
 - Multiple time writeable/re-writeable
- Default settings can be overridden using SPI/I²C

3.2 Input Block Features

- Ten input reference pins; each can accept a CMOS signal or the POS side of a differential pair; or two can be paired to accept both sides of a differential pair
- Any input can be a SYNC signal (0.5 Hz to 8 kHz) for Ref-Sync frequency/phase/time locking
- Any input can be a clock with embedded Sync signal (0.5 Hz to 1 kHz, duty cycle distortion for Sync)
- Any input can be a MiToDSync signal carrying one to three channels of frequency/phase/ToD information
- Input clocks can be any frequency from 0.5 Hz up to 1250 MHz (300 MHz max for CMOS inputs)
- Supported telecom frequencies include PDH, SDH, Synchronous Ethernet, OTN, wireless
- Inputs constantly monitored by programmable frequency and single-cycle monitors
- Single-cycle monitor can quickly disqualify a reference when measured period is incorrect
- Frequency measurement and monitoring (coarse, fine, and frequency-step monitors)
- Optional input clock invalidation on GPIO or GPI assertion to react to LOS signals from PHYs
- Input phase measurement, 1 ps resolution
- Per-input phase adjustment, 1 ps resolution
- Each REF pin can be a GPI (general-purpose input)

3.3 DPLL Features

- Up to eight DPLLs: up to five for clock I/O channels, one for NCO-hybrid mode (SyncE assist), and two for locking to OCXOs for split-XO configuration
- Very high-resolution DPLL architecture
- State machine automatically transitions among freerun, tracking, and holdover states
- Revertive or nonrevertive reference selection algorithm
- Programmable bandwidth from 0.1 mHz to 470 Hz
- Less than 0.1 dB gain peaking
- Fast frequency/phase/time lock capability for 1PPS or clock+1PPS input references
- Programmable phase-slope limiting (PSL)
- Programmable frequency rate-of-change limiting (FCL)
- Programmable tracking range (i.e. hold-in range)
- Truly hitless reference switching
- Per-DPLL phase adjustment, 1 ps resolution
- High-resolution frequency and phase measurement (4e-15 and 1 ps)
- Fast detection of input clock failure and transition to holdover mode
- High-resolution holdover frequency averaging
 - Initial offset better than 10 ppb when using < 10 Hz filter
 - Initial offset better than 1 ppb when using < 0.1 Hz filter
 - Initial offset better than 0.1 ppb when using < 0.01 Hz filter
 - Initial offset better than 0.01 ppb when using < 0.001 Hz filter (translates to 864 ns over 24 hours)
- Supports holdover compensation for oscillator aging and temperature changes by learning oscillator characteristics during locked operation
- Time-of-Day registers: 48-bit seconds, 32-bit nanoseconds, writeable on input PPS edge

3.4 Synthesizer Features

- Five next-generation low-jitter, low-power, any-frequency synthesizers
- A total of five output frequency families
- Any-to-any frequency conversion with 0 ppm error
- Easy-to-configure, completely encapsulated design requires no external VCXO or loop filter components
- Jitter suitable for OC-192, STM-64, and 1G, 10G, 40G, 100G, and 400G Ethernet jitter requirements

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3.5 Output Clock Features

- Up to 20 single-ended outputs, up to 10 differential outputs, from any synthesizer
- Each output can be one differential output or two CMOS outputs
- Output clocks can be any frequency from 0.5 Hz to 750 MHz (250 MHz max for CMOS)
- Output jitter $100 f_{s_{RMS}}$ typical for 156.25 MHz and many other frequencies (12 kHz to 20 MHz)
- In CMOS mode, the OUTxN frequency can be an integer divisor of the OUTxP frequency (Example 1: OUT3P 125 MHz, OUT3N 25 MHz. Example 2: OUT2P 25 MHz, OUT2N 1 Hz)
- Outputs directly interface (DC-coupled) with LVDS, LVPECL, HCSL, and CMOS components
- Supported telecom frequencies include PDH, SDH, Synchronous Ethernet, OTN
- Can produce clock frequencies for microprocessors, ASICs, FPGAs, and other components
- Can produce PCIe Gen 1 to 5 clocks
- Each output pair can have clock plus embedded Sync signal (0.5 Hz to clock div 4)
- Each output pair can be MiToDSync signals carrying one to three channels of frequency/phase/ToD information
- Sophisticated output-to-output phase alignment
- Per-synthesizer phase adjustment, 1 ps resolution
- Per-output phase adjustment to accommodate trace delays or compensate for system routing paths
- Per-output duty cycle/pulse width configuration
- Per-output enable/disable
- Per-output glitchless start/stop (stop high or low)
- Each OUT pin can be a GPO (general-purpose output)
- Each OUT pin can be a MiToDBasic data signal which can be combined with a MHz clock output and a 4 kHz sync output to form a 3-wire MiToDBasic interface carrying one channel of frequency/phase/ToD information

3.6 Local Oscillator

- Operates from a single oscillator (jitter reference for the device). Acceptable frequencies: 9.72 MHz to 400 MHz. Best jitter: ≥ 48 MHz.
- Very-low-jitter applications can connect a TCXO or OCXO (any frequency, any output jitter) as the stability reference and a low-cost low-jitter XO as the jitter reference
- This ability to have separate jitter and stability references greatly reduces the cost of the TCXO or OCXO (no jitter requirement, no high-frequency-requirement) and allows reuse of already-qualified TCXO and OCXO components
- Supports redundant TCXOs or OCXOs connected to two REF pins

3.7 General Features

- Automatic self-configuration at power-up from internal Flash memory
- Input-to-output alignment < 200 ps with external feedback
- Fast Ref-Sync locking for frequency and 1PPS phase alignment with lower-cost oscillator
- Generates output SYNC signals: 1PPS (IEEE 1588), 2 kHz or 8 kHz (SONET/SDH), or other frequency
- JESD204B clocking: clock and SYSREF signal generation with skew adjustment
- Numerically controlled oscillator (NCO) behavior allows system software to steer DPLL frequency or synthesizer frequency with resolution better than 0.005 ppt
- Spread-spectrum modulation available in each synthesizer (PCIe compliant)
- Five general-purpose I/O pins each with many possible status and control options
- SPI or I²C serial microprocessor interface

3.8 Evaluation Software

- Simple, intuitive Windows-based graphical user interface
- Supports all device features and register fields
- Makes lab evaluation of the device quick and easy
- Generates configuration scripts
- Works with or without an evaluation board

4.0 SOFTWARE FEATURES

The following figure shows the Time Synchronization Algorithm system environment. The subsections below list the features of the Time Synchronization Algorithm.

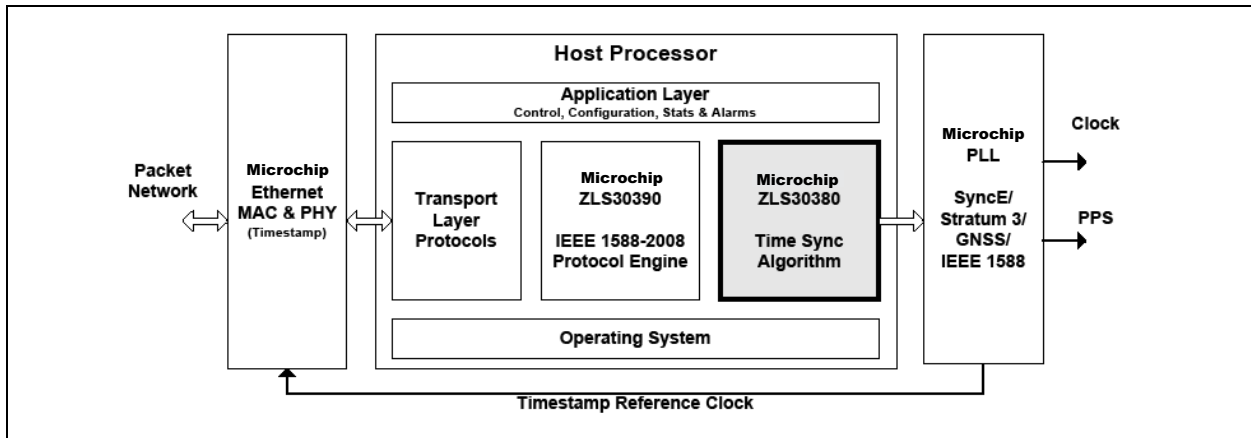


FIGURE 4-1: Time Synchronization Algorithm System Environment.

4.1 Time Synchronization Algorithm

The Time Synchronization Algorithm is responsible to accurately synchronize the local clock to a selected Server. The Time Synchronization Algorithm is synchronizing the Client to the Server to meet a variety of specifications or applications related to frequency accuracy (FFO), frequency (MTIE, TDEV), phase (1 Hz or 1PPS) and time (UTC & GNSS/GPS).

The Time Synchronization Algorithm can run on a variety of host processor architectures, whether embedded into an SoC or on a dedicated small scale CPU (such as Microchip's SmartFusion2 SoC FPGA). The Time Synchronization Algorithm interconnects with a wide array of software-programmable clock generators (such as Microchip's Network Synchronizer PLLs), protocol engines (such as Microchip's ZLS30390 IEEE 1588-2008 Protocol Engine), and underlying Ethernet MACs and PHYs that perform hardware timestamping.

4.2 End Application Target Performance

The Time Synchronization Algorithm is suitable for many end application targets, including:

- Frequency offset accuracy performance for GSM, WCDMA-FDD, LTE-FDD femtocell, small cell (residential, urban, rural, enterprise), picocell, and macrocell applications, with target performance less than ± 15 ppb.
- Frequency performance for ITU-T G.823 and G.824 synchronization interface, as well as G.8261 PNT EEC, PNT PEC, and CES interface specifications.
- Phase Synchronization performance for WCDMA-TDD, Mobile WiMAX, TD-SCDMA, CDMA2000, LTE-TDD, LTE-A, LTE-A Pro, and 5G NR femtocell, small cell (residential, urban, rural, enterprise), picocell, and macrocell applications with target performance less than ± 1 μ s phase alignment.
- Time Synchronization for TAI, UTC-traceability, and GNSS/GPS replacement.

4.3 Packet Networks

The Time Synchronization Algorithm is suitable for high performance over a variety of packet networks including:

- ITU-T G.8261 Appendix VI
- ITU-T G.8261.1 network limit compliant
- ITU-T G.8271.1 network limit compliant without SyncE
- ITU-T G.8271.2 network limit compliant
- Native Ethernet (switched) & IP (routed) networks
- xDSL
- Microwave
- Fully aware, partially aware, and unaware timing supported networks

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- Networks including intermediate Boundary Clocks and Transparent Clocks
- Networks with and without SyncE or frequency physical layer support

4.4 Clock Specifications

The Time Synchronization Algorithm meets the performance requirements from ITU-T packet clock specifications, or draft packet clock specifications, including:

- ITU-T G.8261 Appendix VI
- ITU-T G.8263 PEC-S
- ITU-T G.8273.2 T-BC full on-path without SyncE
- ITU-T G.8273.2 T-BC full on-path with SyncE
- ITU-T G.8273.2 T-TSC full on-path without SyncE
- ITU-T G.8273.2 T-TSC full on-path with SyncE
- ITU-T G.8273.4 T-BC-A (draft)
- ITU-T G.8273.4 T-BC-P (draft)
- ITU-T G.8273.4 T-TSC-A (draft)
- ITU-T G.8273.4 T-TSC-P (draft)

4.5 Profiles

The Time Synchronization Algorithm is suitable for use in a wide variety of markets and applications, including the following IEEE 1588-2008 Profiles:

- IEEE 1588 Annex J.3 Delay Request-Response Default Profile (2008)
- IEEE 1588 Annex J.4 Peer-to-peer Default Profile (2008)
- ITU-T G.8265.1 Telecom Profile for Frequency Synchronization (Edition 1)
- ITU-T G.8275.1 Telecom Profile for Phase with Full Timing Support Networks (Edition 1)
- ITU-T G.8275.1 Telecom Profile for Phase with Full Timing Support Networks (Edition 2)
- ITU-T G.8275.2 Telecom Profile for Phase with Partial Timing Support Networks (Edition 1)
- CableLabs CM-SP-RDTI Remote DTI Profile (Edition I0x)
- AES 67 Standard for Audio Applications of Networks – High-Performance Streaming Audio-over-IP interoperability: PTP Profile for Media Applications
- SMPTE 2059-2 Profile for Use of IEEE-1588 Precision Time Protocol in Professional Broadcast Applications
- AES R16 Project Report – PTP parameters for AES67 and SMPTE ST 2059-2 interoperability
- IEEE C37.238 Standard Profile for Use of IEEE 1588 Precision Time Protocol in Power System Applications (Edition 2011)
- IEEE C37.238 Standard Profile for Use of IEEE 1588 Precision Time Protocol in Power System Applications (Edition 2017)
- IEC 61850-9-3 Precision time protocol profile for power utility automation (Edition 1.0)
- IEC 62439-3 PTP profiles for high-availability automation networks (Edition 3.0)
- IEEE802.1as AVB-TSN gPTP
- IEEE 1588-2018 Annex J.5 High Accuracy Profile (based on White Rabbit)
- IETF TICTOC Enterprise Profile

4.6 Monitoring & Redundancy

The Time Synchronization Algorithm includes monitoring and redundancy for high availability synchronization, including:

- Synchronization to the best available server
- Client monitoring of secondary server references
 - Monitoring includes full time synchronization reporting of secondary server
 - Supports a programmable number of secondary server connections
- Hitless reference switching between multiple servers
- Holdover when server packet connectivity is lost
- TIE-clear option to build out, or clear, phase offsets between server references

4.7 General

The Time Synchronization Algorithm includes many advanced features to aide in the high-accuracy & high-stability applications, including:

- Full PLL state machine (Freerun, Holdover, Frequency Lock Acquiring, Frequency Lock Acquired, Phase Lock Acquired), with programmable thresholds for state transitions
- Programmable, non-linear packet selection with PDV suppression
- Programmable bandwidth configurability from sub-mHz to 100s of mHz.
- Programmable packet rates from 1 packet/second to over 128 packets/second
- Programmable phase slope limiting, down to 1 ns/s
- Programmable frequency change limiting, down to 1 ppb/s
- Warm-start to initialize or seed the Time Synchronization Algorithm from a stored or last-known-good frequency offset to improve convergence
- Programmable thresholds for management of phase errors: when to adjust with frequency offsets and when to adjust with phase jumps
- User ability to manually add frequency offsets due to temperature or aging (especially during holdover state)

4.8 Reporting

The Time Synchronization Algorithm includes user reporting to aide in performance debugging, including:

- Set of user notifications about packet network events, such as packet loss, small transient phase jumps, large transient phase jumps, outliers, network path re-routes
- Set of metrics related to the synchronization, such as frequency stability and phase stability
- Independent reporting of the forward path and reverse path lock status
- Oscillator stability analysis for excessive aging or temperature variation
- Server tracking impairments such as pull-in range exceeded

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5.0 PIN DIAGRAM

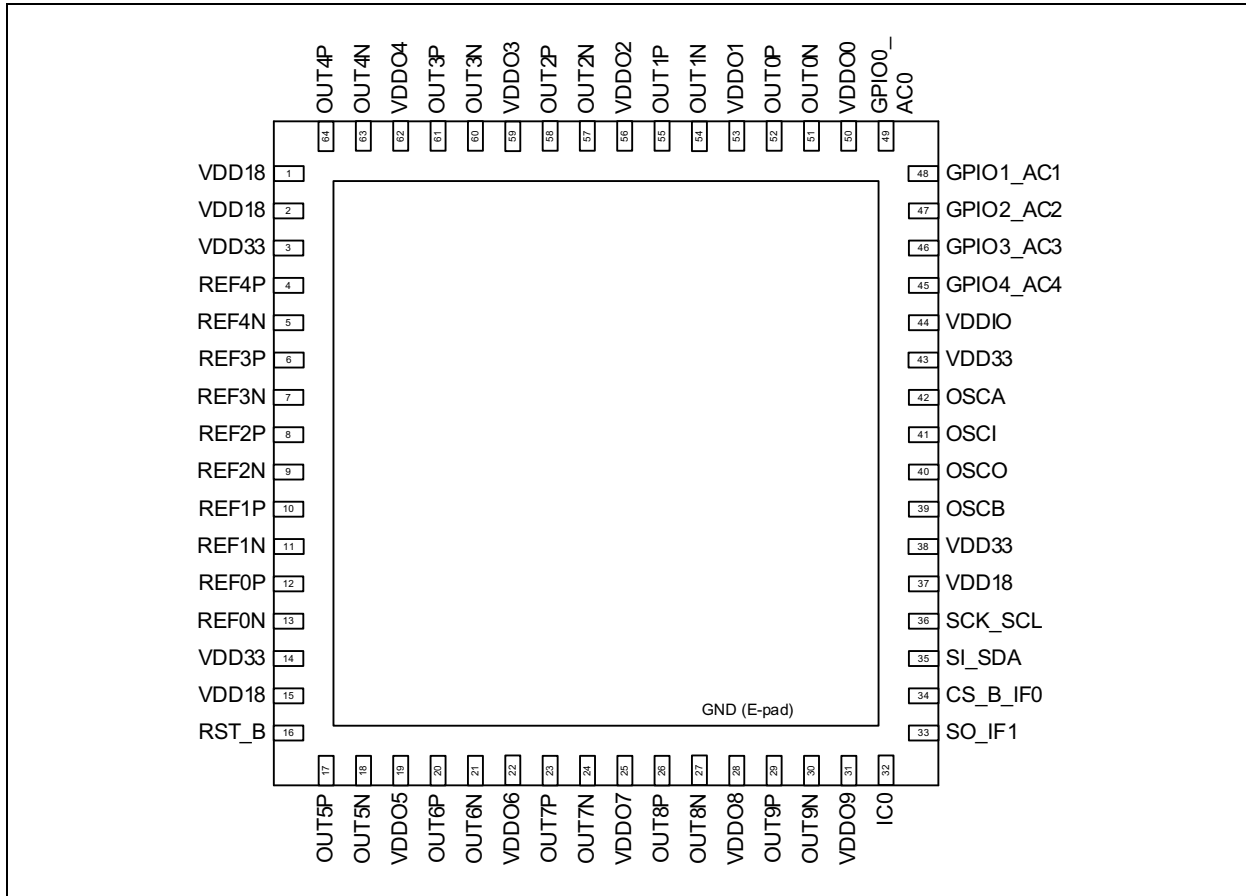


FIGURE 1: 64-Lead 9 mm x 9 mm VQFN (0.5 mm pitch) for ZL30731, ZL30732, ZL30733, ZL30734, ZL30735.

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