

## 1A, 1.2 MHz PWM Boost Converter in Thin SOT23 and DFN Packages

### Features

- 2.5V to 10V Input Voltage Range
- Output Voltage Adjustable to 34V
- Over 1A Switch Current
- 1.2 MHz PWM Operation
- Stable with Ceramic Capacitors
- <1% Line and Load Regulation
- Low Output Voltage Ripple
- <1  $\mu$ A Shutdown Current
- Undervoltage Lockout
- Output Overvoltage Protection (MIC2288YML)
- Overtemperature Shutdown
- Thin 5-Lead SOT23 Package Option
- 2 mm x 2 mm Leadless 8-Lead DFN Package Option
- -40°C to +125°C Junction Temperature Range

### Applications

- Organic EL Power Supply
- TFT-LCD Bias Supply
- 12V Supply for DSL Applications
- Multi-Output DC/DC Converters
- Positive and Negative Output Regulators
- SEPIC Converters

### General Description

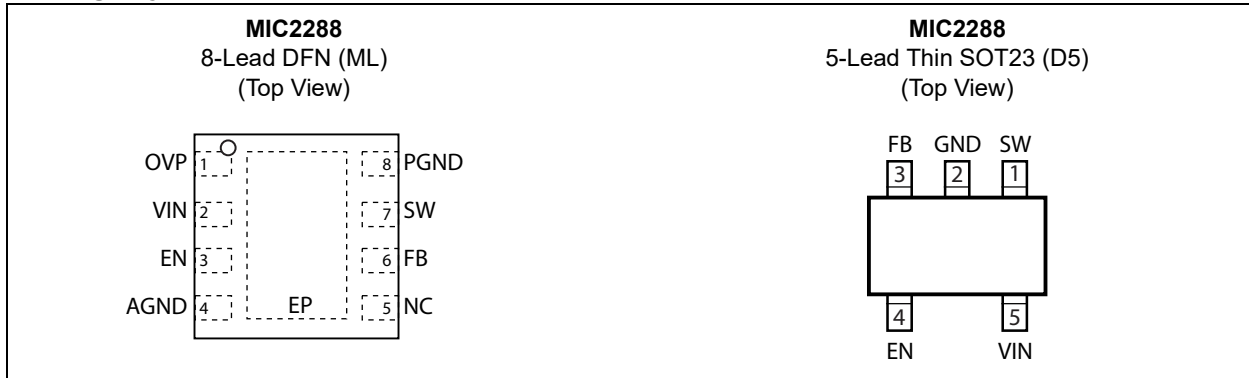
The MIC2288 is a 1.2 MHz PWM, DC/DC boost switching regulator available in low profile Thin SOT23 and 2 mm x 2 mm DFN package options. High-power density is achieved with the MIC2288 device's internal 34V/1A switch, allowing it to power large loads in a tiny footprint.

The MIC2288 implements a constant frequency, 1.2 MHz PWM, Current-mode control scheme with internal compensation that offers excellent transient response and output regulation performance. The high-frequency operation saves board space by allowing small, low profile, external components. The fixed frequency PWM topology also reduces spurious switching noise and ripple to the input power source.

The MIC2288 is available in a low profile 5-lead Thin SOT23 package and a 2 mm x 2 mm 8-lead DFN leadless package. The DFN package option has an output overvoltage protection feature.

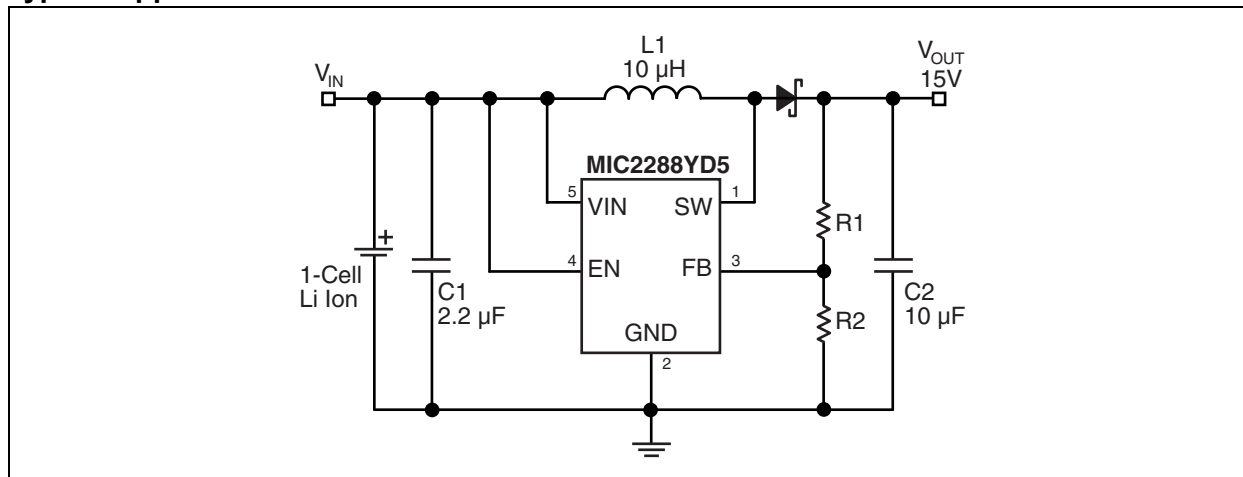
The MIC2288 has a junction temperature range of -40°C to +125°C.

### Package Types

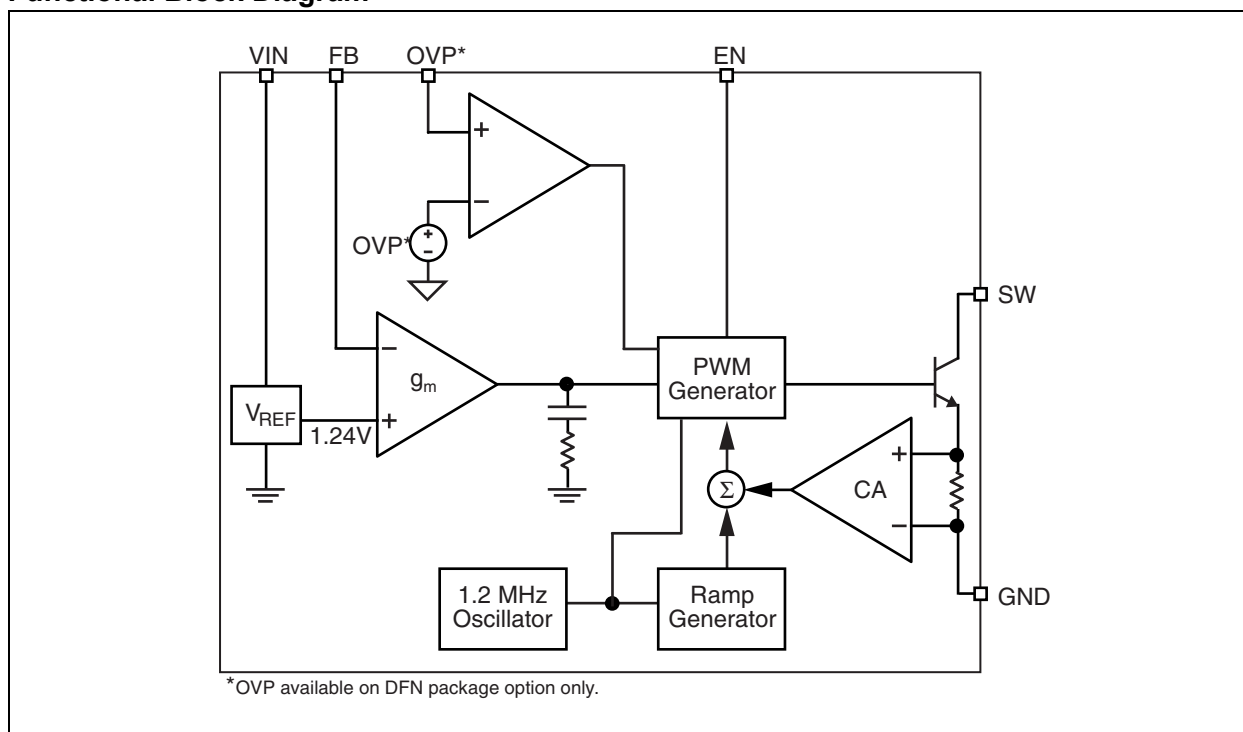


# MIC2288

## Typical Application Circuit



## Functional Block Diagram



## 1.0 ELECTRICAL CHARACTERISTICS

### Absolute Maximum Ratings†

Supply Voltage ( $V_{IN}$ ) .....	+12V
Switch Voltage ( $V_{SW}$ ) .....	-0.3V to +34V
Enable Pin Voltage ( $V_{EN}$ ) .....	-0.3V to $V_{IN}$
FB Voltage ( $V_{FB}$ ) .....	+6.0V
Switch Current ( $I_{SW}$ ) .....	2A
ESD Rating ( <b>Note 1</b> ) .....	+2 kV

### Operating Ratings††

Supply Voltage ( $V_{IN}$ ) .....	+2.5V to +10V
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† **Notice:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational sections of this specification is not intended. Exposure to maximum rating conditions for extended periods may affect device reliability.

†† **Notice:** The device is not ensured to function outside its operating ratings.

**Note 1:** Devices are ESD-sensitive. Handling precautions are recommended. Human body model, 1.5 k $\Omega$  in series with 100 pF.

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## ELECTRICAL CHARACTERISTICS

**Electrical Characteristics:**  $T_A = +25^\circ\text{C}$ ,  $V_{IN} = V_{EN} = 3.6\text{V}$ ,  $V_{OUT} = 10\text{V}$ ,  $I_{OUT} = 20\text{ mA}$ , unless otherwise noted. **Bold** values indicate  $-40^\circ\text{C} \leq T_J \leq \pm 125^\circ\text{C}$ . <sup>(1)</sup>

Parameter	Sym.	Min.	Typ.	Max.	Units	Conditions
Supply Voltage Range	$V_{IN}$	<b>2.5</b>	—	<b>10</b>	V	
Undervoltage Lockout	$V_{UVLO}$	1.8	2.1	2.4	V	
Quiescent Current	$I_{VIN}$	—	2.8	5	mA	$V_{FB} = 2\text{V}$ , not switching
Shutdown Current	$I_{SD}$	—	0.1	1	$\mu\text{A}$	$V_{EN} = 0\text{V}$ ( <b>Note 2</b> )
Feedback Voltage	$V_{FB}$	1.227	1.24	1.252	V	$\pm 1\%$
		<b>1.215</b>	—	<b>1.265</b>		$\pm 2\%$ , overtemperature
Feedback Input Current	$I_{FB}$	—	-450	—	nA	$V_{FB} = 1.24\text{V}$
Line Regulation	—	—	0.1	1	%	$3\text{V} \leq V_{IN} \leq 5\text{V}$
Load Regulation	—	—	0.2	—	%	$5\text{ mA} \leq I_{OUT} \leq 40\text{ mA}$
Maximum Duty Cycle	$D_{MAX}$	<b>85</b>	90	—	%	
Switch Current Limit	$I_{SW}$	—	1.2	—	A	
Switch Saturation Voltage	$V_{SW}$	—	550	—	mV	$I_{SW} = 1\text{A}$
Switch Leakage Current	$I_{SW}$	—	0.01	<b>5</b>	$\mu\text{A}$	$V_{EN} = 0\text{V}$ , $V_{SW} = 10\text{V}$
Enable Threshold	$V_{EN}$	<b>1.5</b>	—	—	V	Turn on
		—	—	<b>0.4</b>		Turn off
Enable Pin Current	$I_{EN}$	—	20	40	$\mu\text{A}$	$V_{EN} = 10\text{V}$
Oscillator Frequency	$f_{SW}$	1.05	1.2	1.35	MHz	
Output Overvoltage Protection	$V_{OVP}$	30	32	34	V	DFN package option only
Overtemperature Threshold Shutdown	$T_J$	—	150	—	$^\circ\text{C}$	
		—	10	—		Hysteresis

**Note 1:** Specification for packaged product only.

**2:**  $I_{SD} = I_{VIN}$ .

## TEMPERATURE SPECIFICATIONS<sup>(1)</sup>

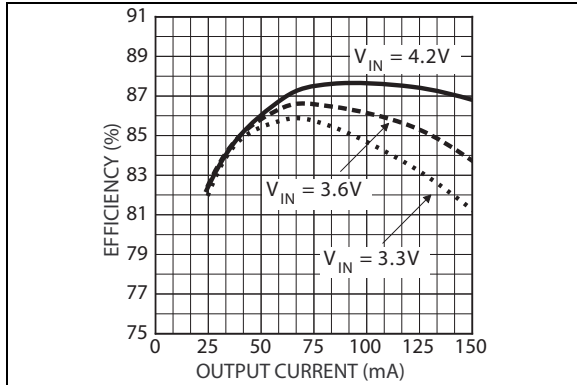
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Temperature Ranges</b>						
Junction Operating Temperature	$T_J$	-40	—	+125	°C	
Storage Temperature Range	$T_S$	-65	—	+150	°C	
<b>Package Thermal Resistances</b>						
Thermal Resistance, 2x2 8-Lead DFN	$\theta_{JA}$	—	93	—	°C/W	
Thermal Resistance, 5-Lead TSOT23	$\theta_{JA}$	—	256	—	°C/W	

**Note 1:** The maximum allowable power dissipation is a function of ambient temperature, the maximum allowable junction temperature and the th1l resistance from junction to air (i.e.,  $T_A$ ,  $T_J$ ,  $\theta_{JA}$ ). Exceeding the maximum allowable power dissipation will cause the device operating junction temperature to exceed the maximum +125°C rating. Sustained junction temperatures above +125°C can impact the device reliability.

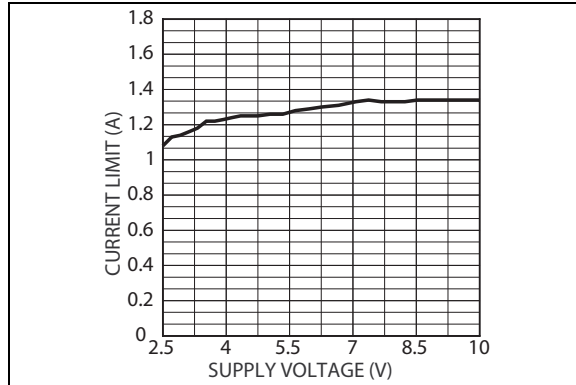
# MIC2288

## 2.0 TYPICAL PERFORMANCE CURVES

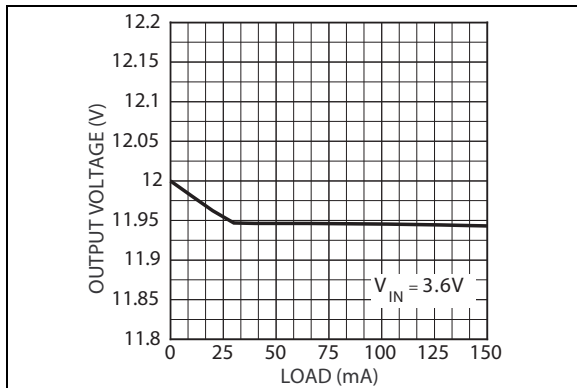
**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.



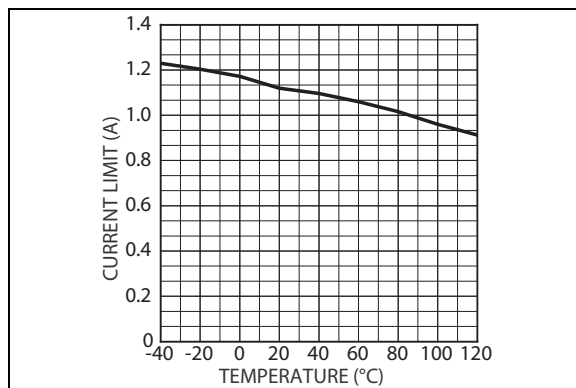
**FIGURE 2-1:** Efficiency at  $V_{OUT} = 12V$ .



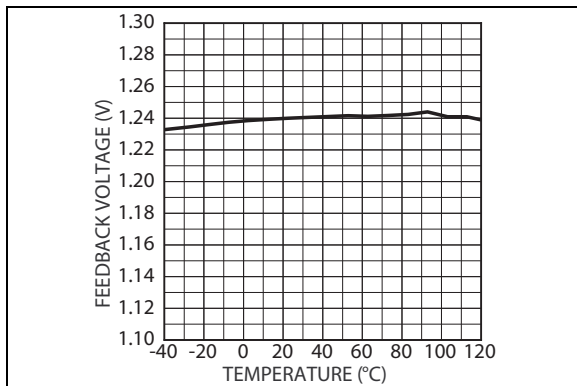
**FIGURE 2-4:** Current Limit vs. Supply Voltage.



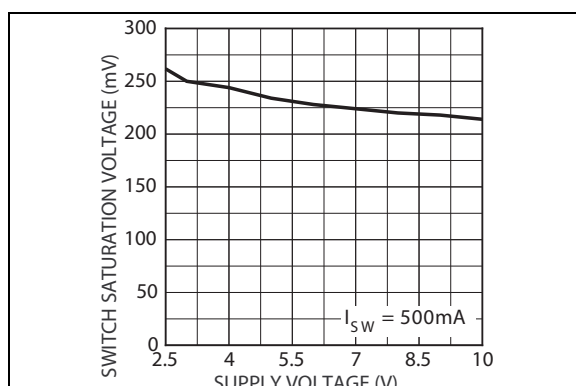
**FIGURE 2-2:** Load Regulation.



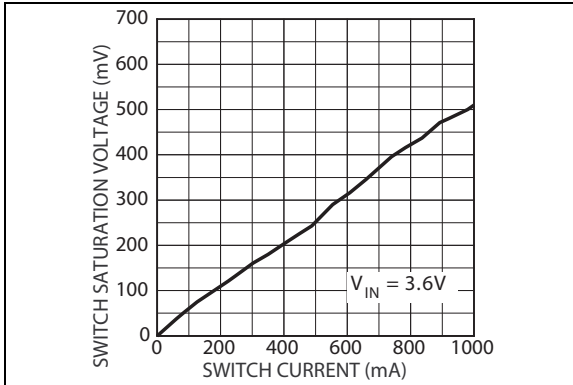
**FIGURE 2-5:** Current Limit vs. Temperature.



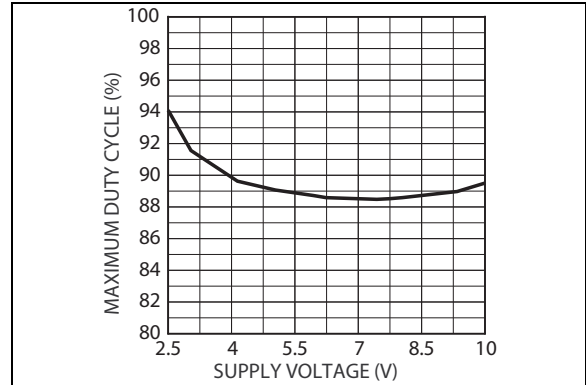
**FIGURE 2-3:** Feedback Voltage vs. Temperature.



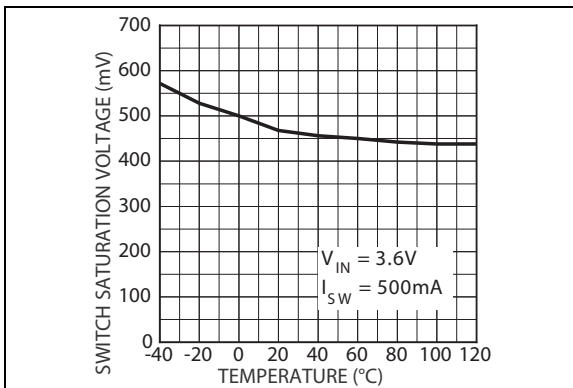
**FIGURE 2-6:** Switch Saturation vs. Supply Voltage.



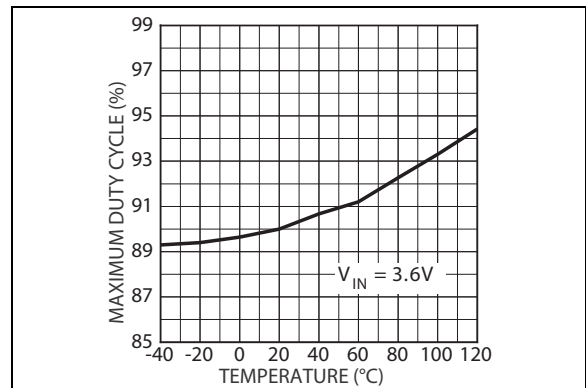
**FIGURE 2-7:** Switch Saturation vs. Switch Current.



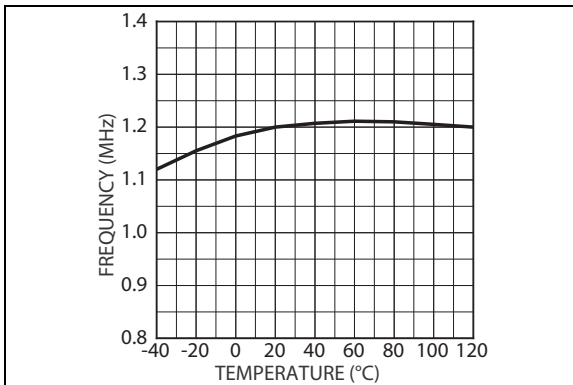
**FIGURE 2-10:** Maximum Duty Cycle vs. Supply Voltage.



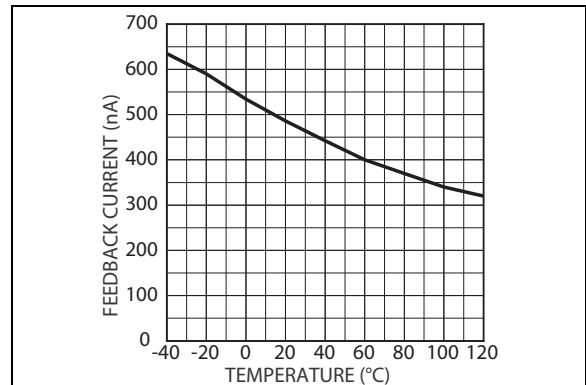
**FIGURE 2-8:** Switch Saturation vs. Temperature.



**FIGURE 2-11:** Maximum Duty Cycle vs. Temperature.

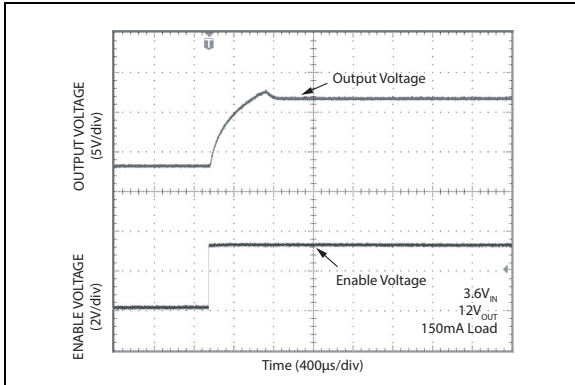


**FIGURE 2-9:** Frequency vs. Temperature.

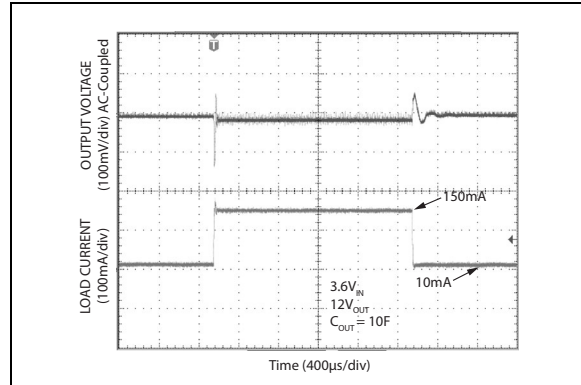


**FIGURE 2-12:** FB Pin Current vs. Temperature.

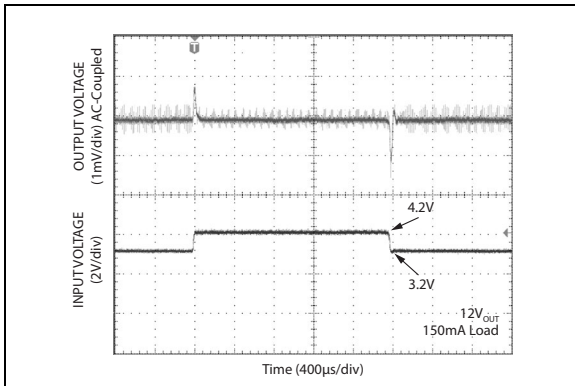
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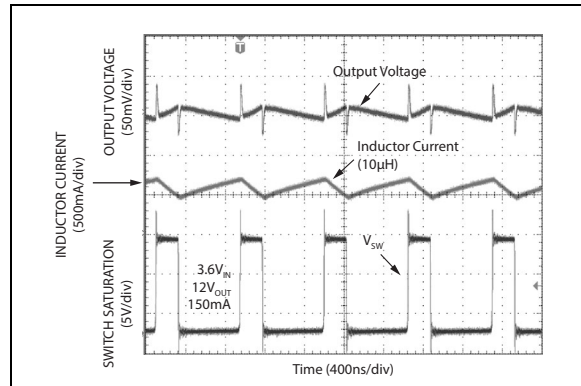
**FIGURE 2-13:** Enable Characteristics.



**FIGURE 2-15:** Load Transient Response.



**FIGURE 2-14:** Line Transient Response.



**FIGURE 2-16:** Output Voltage Ripple and Switching Waveforms.



### 3.0 PIN DESCRIPTIONS

The descriptions of the pins are listed in [Table 3-1](#).

**TABLE 3-1: PIN FUNCTION TABLE**

Pin Number 5-Lead TSOT23	Pin Number 8-Lead DFN	Pin Name	Description
1	7	SW	Switch Node (Input): Internal power bipolar collector.
2	—	GND	Ground (Return): Ground.
3	6	FB	Feedback (Input): 1.24V output voltage sense node.
4	3	EN	Enable (Input): Logic high enables regulator. Logic low shuts down regulator. Do not leave floating.
5	2	VIN	Supply (Input): 2.5V to 10V input voltage.
—	1	OVP	Output Overvoltage Protection (Input): Tie this pin to $V_{OUT}$ to clamp the output voltage to 34V maximum in Fault conditions. Tie this pin to ground if OVP function is not required.
—	5	NC	No Connect: No internal connection to die.
—	4	AGND	Analog ground.
—	8	PGND	Power ground.
—	EP	GND	Exposed backside pad.

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## 4.0 FUNCTIONAL DESCRIPTION

The MIC2288 is a constant frequency, PWM Current-mode boost regulator. See the [Functional Block Diagram](#). The MIC2288 is composed of an oscillator, slope compensation ramp generator, current amplifier,  $g_m$  error amplifier, PWM generator and a 1A bipolar output transistor. The oscillator generates a 1.2 MHz clock. The clock's two functions are to trigger the PWM generator that turns on the output transistor and to reset the slope compensation ramp generator. The current amplifier is used to measure the switch current by amplifying the voltage signal from the internal sense resistor. The output of the current amplifier is summed with the output of the slope compensation ramp generator. This summed current loop signal is fed to one of the inputs of the PWM generator.

The  $g_m$  error amplifier measures the feedback voltage through the external feedback resistors, and amplifies the error between the detected signal and the 1.24V reference voltage. The output of the  $g_m$  error amplifier provides the voltage loop signal that is fed to the other input of the PWM generator. When the current loop signal exceeds the voltage loop signal, the PWM generator turns off the bipolar output transistor. The next clock period initiates the next switching cycle, maintaining the constant frequency Current-mode PWM control.

## 5.0 APPLICATION INFORMATION

### 5.1 DC/DC PWM Boost Conversion

The MIC2288 is a constant frequency boost converter. It operates by taking a DC input voltage and regulating a higher DC output voltage. Figure 5-1 shows a typical circuit. Boost regulation is achieved by turning on an internal switch, which draws current through the inductor (L1). When the switch turns off, the inductor's magnetic field collapses, causing the current to be discharged into the output capacitor through an external Schottky diode (D1). Voltage regulation is achieved by modulating the pulse width or Pulse-Width Modulation (PWM).

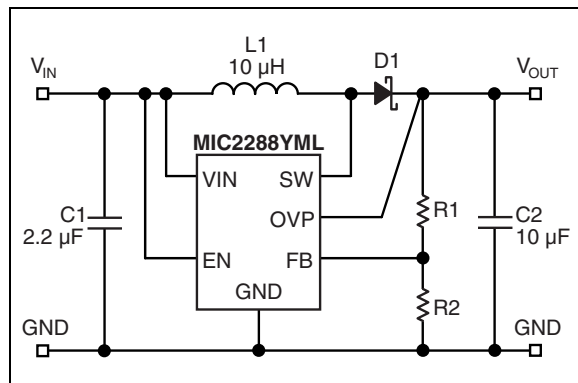


FIGURE 5-1: Typical Application Circuit.

### 5.2 Duty Cycle Considerations

Duty cycle refers to the switch on-to-off time ratio and can be calculated as follows for a boost regulator:

#### EQUATION 5-1:

$$D = 1 - \frac{V_{IN}}{V_{OUT}}$$

The duty cycle required for voltage conversion should be less than the maximum duty cycle of 85%. Also, in light load conditions where the input voltage is close to the output voltage, the minimum duty cycle can cause pulse skipping. This is due to the energy stored in the inductor causing the output to overshoot slightly over the regulated output voltage. During the next cycle, the error amplifier detects the output as being high and skips the following pulse. This effect can be reduced by increasing the minimum load or by increasing the inductor value. Increasing the inductor value reduces peak current, which in turn, reduces energy transfer in each cycle.

### 5.3 Overvoltage Protection

For the DFN package option, there is an overvoltage protection function. If the feedback resistors are disconnected from the circuit, or the feedback pin is shorted to ground, the feedback pin will fall to ground potential. This will cause the MIC2288 to switch at full duty cycle in an attempt to maintain the feedback voltage. As a result, the output voltage will climb out of control. This may cause the switch node voltage to exceed its maximum voltage rating, possibly damaging the IC and the external components. To ensure the highest level of protection, the MIC2288 OVP pin will shut the switch off when an overvoltage condition is detected, saving the regulator and other sensitive circuitry downstream.

### 5.4 Component Selection

#### 5.4.1 INDUCTOR

Inductor selection is a balance between efficiency, stability, cost, size and rated current. For most applications, 10 µH is the recommended inductor value. It is usually a good balance between these considerations.

Larger inductance values reduce the peak-to-peak ripple current, affecting efficiency. This has the effect of reducing both the DC losses and the transition losses. There is also a secondary effect of an inductor's DC Resistance (DCR). The DCR of an inductor will be higher for more inductance in the same package size. This is due to the longer windings required for an increase in inductance. Because the majority of input current (minus the MIC2288 operating current) is passed through the inductor, higher DCR inductors will reduce efficiency.

To maintain stability, increasing the inductor value will have to be associated with an increase in output capacitance. This is due to the unavoidable "right half plane zero" effect for the continuous current boost converter topology. The frequency at which the right half plane zero occurs can be calculated as follows:

#### EQUATION 5-2:

$$f_{RHPZ} = \frac{V_{IN}^2}{V_{OUT} \times L \times I_{OUT} \times 2\pi}$$

The right half plane zero has the undesirable effect of increasing gain, while decreasing phase. This requires that the loop gain is rolled off before this has significant effect on the total loop response. This can be accomplished by either reducing inductance (increasing RHPZ frequency) or increasing the output capacitor value (decreasing loop gain).

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## 5.4.2 OUTPUT CAPACITOR

Output capacitor selection is also a trade-off between performance, size and cost. Increasing output capacitance will lead to an improved transient response, but also an increase in size and cost. X5R or X7R dielectric ceramic capacitors are recommended for designs with the MIC2288. Y5V values may be used, but to compensate their drift over temperature, more capacitance is required. The following table shows the recommended ceramic (X5R) output capacitor value vs. output voltage.

**TABLE 5-1: OUTPUT CAPACITOR SELECTION**

Output Voltage	Recommended Output Capacitance
<6V	22 $\mu$ F
<16V	10 $\mu$ F
<34V	4.7 $\mu$ F

## 5.4.3 DIODE SELECTION

The MIC2288 requires an external diode for operation. A Schottky diode is recommended for most applications due to their lower forward voltage drop and reverse recovery time. Ensure the diode selected can deliver the peak inductor current and the maximum reverse voltage is rated greater than the output voltage.

## 5.4.4 INPUT CAPACITOR

A minimum 1  $\mu$ F ceramic capacitor is recommended for designing with the MIC2288. Increasing input capacitance will improve performance and greater noise immunity on the source. The input capacitor should be as close as possible to the inductor and the MIC2288, with short traces for good noise performance.

## 5.4.5 FEEDBACK RESISTORS

The MIC2288 utilizes a feedback pin to compare the output to an internal reference. The output voltage is adjusted by selecting the appropriate feedback resistor network values. The R2 resistor value must be less than or equal to 5 k $\Omega$  ( $R2 \leq 5 \text{ k}\Omega$ ). The desired output voltage can be calculated as follows:

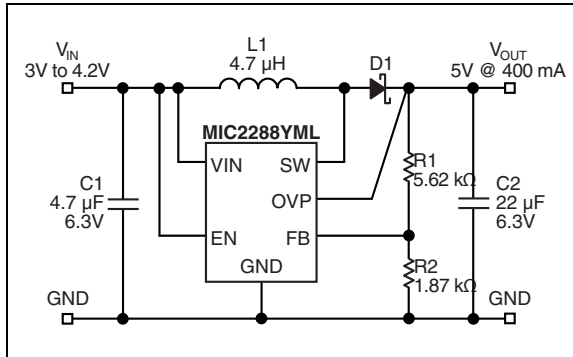
### EQUATION 5-3:

$$V_{OUT} = V_{REF} \times \left( \frac{R1}{R2} + 1 \right)$$

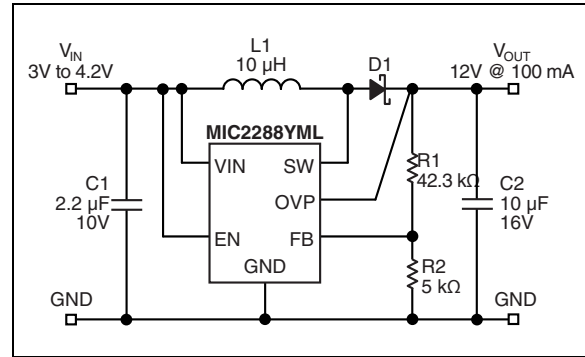
Where:

$$V_{REF} = 1.24V$$

## 6.0 APPLICATION CIRCUITS



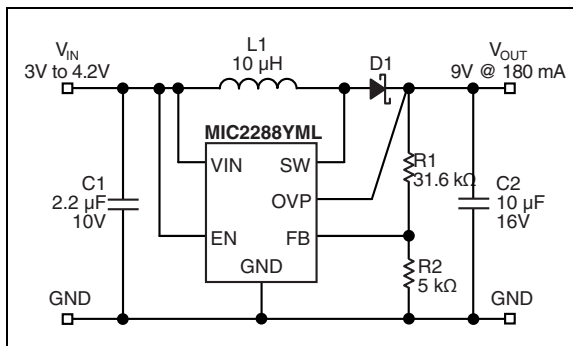
**FIGURE 6-1:** 3.0V to 4.2V  $V_{IN}$  to 5  $V_{OUT}$  @ 400 mA.



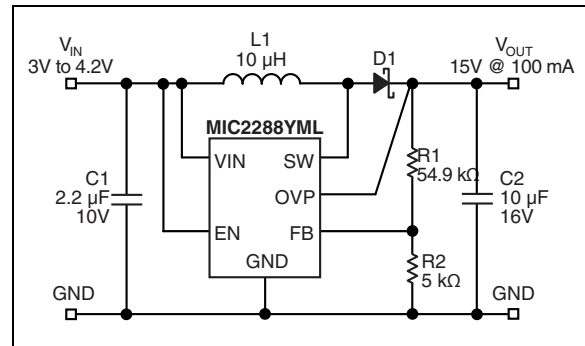
**FIGURE 6-3:** 3.0V to 4.2V  $V_{IN}$  to 12  $V_{OUT}$  @ 100 mA.

Ref	Description	Part Number	Vendor
C1	4.7 $\mu$ F, 6.3V, 0805, X5R, Cer Cap	08056D475MAT	AVX
C2	22 $\mu$ F, 6.3V, 0805, X5R, Cer Cap	12066D226KAT	AVX
D1	1A, 40V, Schottky Diode	MBRM140T3	On <sup>®</sup> Semi.
L1	4.7 $\mu$ H, 650 mA, Inductor	LQH32CN4R7M33L	Murata

Ref	Description	Part Number	Vendor
C1	4.7 $\mu$ F, 6.3V, 0805, X5R, Cer Cap	08056D475MAT	AVX
C2	10 $\mu$ F, 16V, 1206, X5R, Cer Cap	1206YD106MAT	AVX
D1	1A, 40V, Schottky Diode	MBRM140T3	On <sup>®</sup> Semi.
L1	10 $\mu$ H, 650 mA, Inductor	LQH43CN100K03	Murata



**FIGURE 6-2:** 3.0V to 4.2V  $V_{IN}$  to 9  $V_{OUT}$  @ 180 mA.

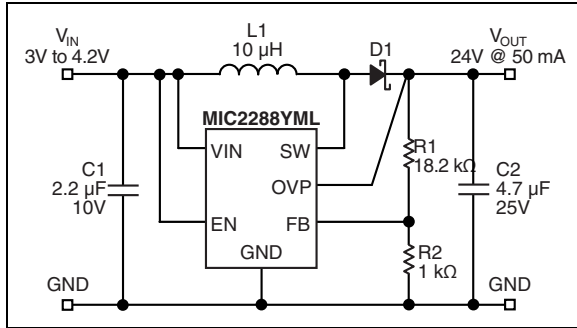


**FIGURE 6-4:** 3.0V to 4.2V  $V_{IN}$  to 15  $V_{OUT}$  @ 100 mA.

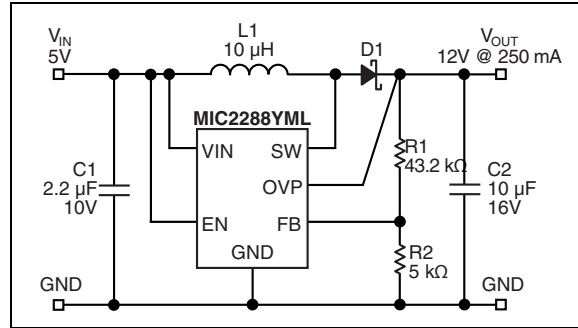
Ref	Description	Part Number	Vendor
C1	2.2 $\mu$ F, 10V, 0805, X5R, Cer Cap	08052D225KAT	AVX
C2	10 $\mu$ F, 16V, 1206, X5R, Cer Cap	1206YD106MAT	AVX
D1	1A, 40V, Schottky Diode	MBRM140T3	On <sup>®</sup> Semi.
L1	10 $\mu$ H, 650 mA, Inductor	LQH43CN100K03	Murata

Ref	Description	Part Number	Vendor
C1	2.2 $\mu$ F, 10V, 0805, X5R, Cer Cap	08052D225KAT	AVX
C2	10 $\mu$ F, 16V, 1206, X5R, Cer Cap	1206YD106MAT	AVX
D1	1A, 40V, Schottky Diode	MBRM140T3	On <sup>®</sup> Semi.
L1	10 $\mu$ H, 650 mA, Inductor	LQH43CN100K03	Murata

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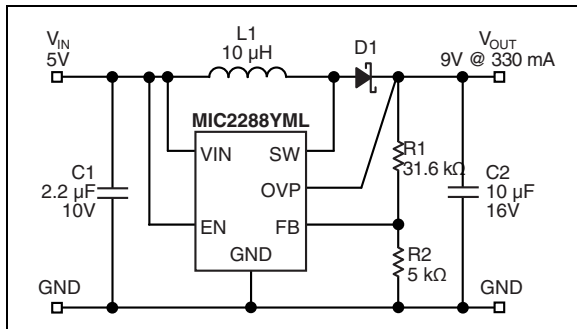
**FIGURE 6-5:** 3.0V to 4.2V  $V_{IN}$  to 24V  $V_{OUT}$  @ 50 mA.



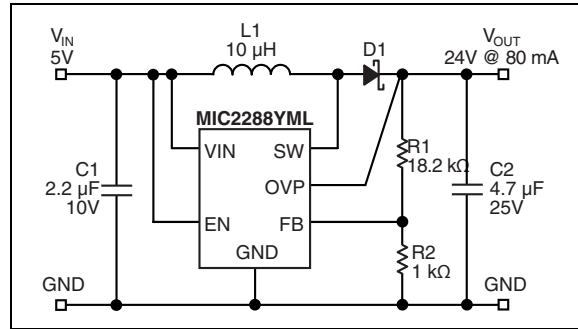
**FIGURE 6-7:** 5  $V_{IN}$  to 12V  $V_{OUT}$  @ 250 mA.

Ref	Description	Part Number	Vendor
C1	2.2 $\mu$ F, 10V, 0805, X5R, Cer Cap	08052D225KAT	AVX
C2	4.7 $\mu$ F, 25V, 1206, X5R, Cer Cap	12063D475KAT	AVX
D1	1A, 40V, Schottky Diode	MBRM140T3	On <sup>®</sup> Semi.
L1	10 $\mu$ H, 650 mA, Inductor	LQH43CN100K03	Murata

Ref	Description	Part Number	Vendor
C1	2.2 $\mu$ F, 10V, 0805, X5R, Cer Cap	08052D225KAT	AVX
C2	10 $\mu$ F, 16V, 1206, X5R, Cer Cap	1206YD106MAT	AVX
D1	1A, 40V, Schottky Diode	MBRM140T3	On <sup>®</sup> Semi.
L1	10 $\mu$ H, 650 mA, Inductor	LQH43CN100K03	Murata



**FIGURE 6-6:** 5  $V_{IN}$  to 9V  $V_{OUT}$  @ 330 mA.



**FIGURE 6-8:** 5  $V_{IN}$  to 24V  $V_{OUT}$  @ 80 mA.

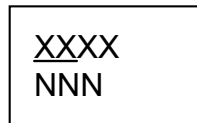
Ref	Description	Part Number	Vendor
C1	2.2 $\mu$ F, 10V, 0805, X5R, Cer Cap	08052D225KAT	AVX
C2	10 $\mu$ F, 16V, 1206, X5R, Cer Cap	1206YD106MAT	AVX
D1	1A, 40V, Schottky Diode	MBRM140T3	On <sup>®</sup> Semi.
L1	10 $\mu$ H, 650 mA, Inductor	LQH43CN100K03	Murata

Ref	Description	Part Number	Vendor
C1	2.2 $\mu$ F, 10V, 0805, X5R, Cer Cap	08052D225KAT	AVX
C2	4.7 $\mu$ F, 25V, 1206, X5R, Cer Cap	12063D475KAT	AVX
D1	1A, 40V, Schottky Diode	MBRM140T3	On <sup>®</sup> Semi.
L1	10 $\mu$ H, 650 mA, Inductor	LQH43CN100K03	Murata

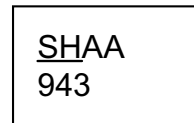
## 7.0 PACKAGING INFORMATION

### 7.1 Package Marking Information

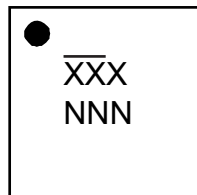
5-Lead TSOT23\*



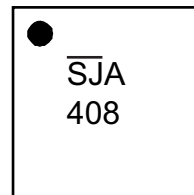
Example



8-Lead TDFN\*



Example



<b>Legend:</b>	XX...X	Product code or customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC® designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package.
	•, ▲, ▼	Pin one index is identified by a dot, delta up, or delta down (triangle mark).
<b>Note:</b>	In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information. Package may or may not include the corporate logo.	
	Underbar (¯) and/or Overbar (¯) symbol may not be to scale.	

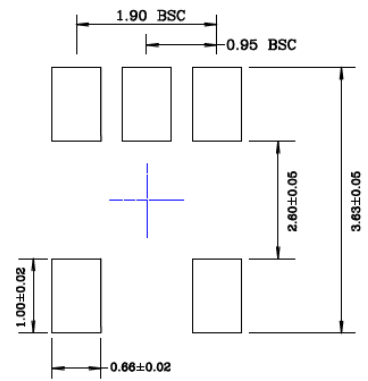
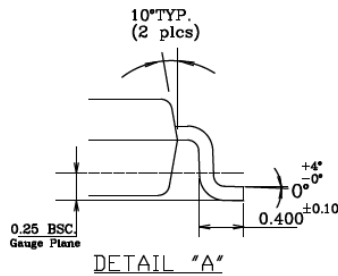
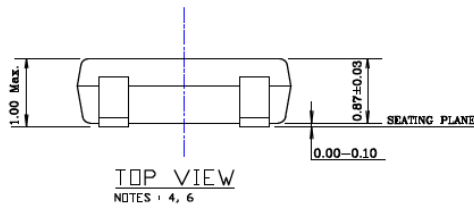
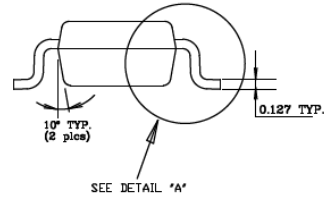
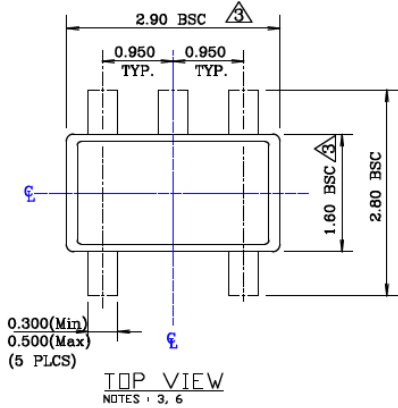
# MIC2288

## 5-Lead Thin SOT23 Package Outline and Recommended Land Pattern

**TITLE**

5 LEAD TSOT PACKAGE OUTLINE & RECOMMENDED LAND PATTERN

<b>DRAWING #</b>	TSOT-5LD-PL-1	<b>UNIT</b>	MM
------------------	---------------	-------------	----



- NOTE:**
1. Dimensions and tolerances are as per ANSI Y14.5M, 1994.
  2. Die is facing up for mold. Die is facing down for trim/form, ie. reverse trim/form.
  3. Dimensions are exclusive of mold flash and gate burr.
  4. The footlength measuring is based on the gauge plane method.
  5. All specification comply to Jedec Spec M0193 Issue C.
  6. All dimensions are in millimeters.

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>.

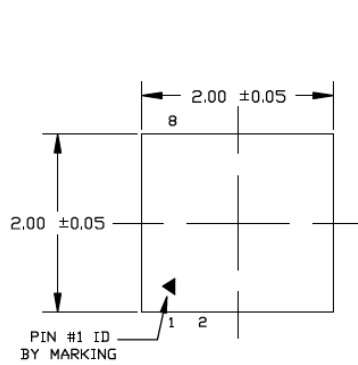


## 8-Lead 2 mm x 2 mm Thin DFN Package Outline and Recommended Land Pattern

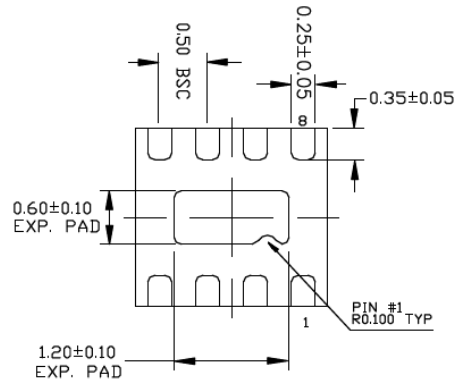
**TITLE**

8 LEAD TDFN 2x2mm PACKAGE OUTLINE & RECOMMENDED LAND PATTERN

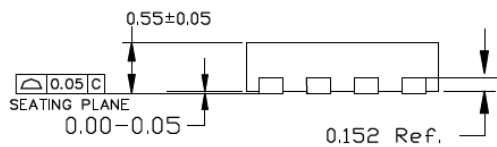
DRAWING #	TDFN22-8LD-PL-1	UNIT	MM
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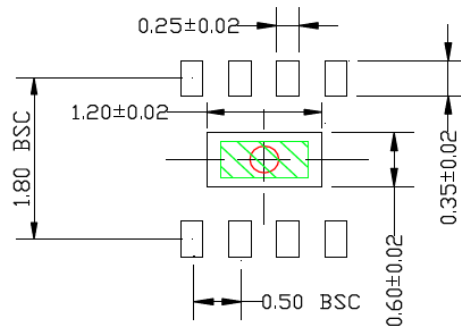
**TOP VIEW**  
NOTE: 1, 2, 3



**BOTTOM VIEW**  
NOTE: 1, 2, 3



**END VIEW**  
NOTE: 1, 2, 3



**RECOMMENDED LAND PATTERN**  
NOTE: 4, 5

- NOTE:
1. MAX PACKAGE WARPAGE IS 0.05 MM
  2. MAX ALLOWABLE BURR IS 0.076MM IN ALL DIRECTIONS
  3. PIN #1 IS ON TOP WILL BE LASER MARKED
  4. RED CIRCLE IN LAND PATTERN REPRESENTS THERMAL VIA. SIZE SHOULD BE 0.30-0.3 MM IN DIAMETER AND SHOULD BE CONNECTED TO GND FOR MAX THERMAL PERFORMANCE
  5. GREEN RECTANGLES (SHADED AREA) REPRESENTS SOLDER STENCIL OPENING ON EXPOSED PAD AREA. SIZE SHOULD BE 0.40x0.90 MM.

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>.

# MIC2288

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NOTES:

## APPENDIX A: REVISION HISTORY

### Revision C (June 2020)

The following is the list of modifications:

- Updated part numbers C2 and L1 ([Figure 6-1](#)).
- Updated part number L1 ([Figure 6-3](#)).
- Updated part number C2 ([Figure 6-5](#)).
- Updated part numbers C2 and L1 ([Figure 6-8](#)).

### Revision B (September 2018)

- Updated values for C2 in the table beneath [Figure 6-3](#).

### Revision A (May 2018)

- Converted Micrel document MIC2288 to Microchip data sheet template DS20006034A.
- Minor grammatical text changes throughout.
- Updated Low Output Voltage Ripple in [Features](#).
- Added clarification to EN description in [Table 3-1](#).
- Updated drawing for EN in [Figure 5-1](#).
- Updated drawings and figure captions for each entry in [Section 6.0 “Application Circuits”](#).

# MIC2288

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NOTES:

## PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, contact your local Microchip representative or sales office.

Device	<u>X</u>	<u>XX</u>	<u>-XX</u>
Part No.	Junction Temp. Range	Package	Media Type
<b>Device:</b>	MIC2288:	1A, 1.2 MHz PWM Boost Converter	
<b>Junction Temperature Range:</b>	Y =	-40°C to +125°C, RoHS-Compliant	
<b>Package:</b>	D5 =	5-Lead Thin SOT23	
	ML =	8-Lead 2 mm x 2 mm TDFN	
<b>Media Type:</b>	TX =	3,000/Reel (Reverse T/R, TSOT only)	
	TR =	3,000/Reel (TSOT only)	
	TR =	5,000/Reel (TDFN only)	

<b>Examples:</b>	
a) MIC2288YD5-TX:	MIC2288, -40°C to +125°C Temperature Range, 5-Lead TSOT23, 3,000/Reel (Reverse T/R)
b) MIC2288YD5-TR:	MIC2288, -40°C to +125°C Temperature Range, 5-Lead TSOT23, 3,000/Reel
c) MIC2288YML-TR:	MIC2288, -40°C to +125°C Temperature Range, 8-Lead TDFN, 5,000/Reel

**Note 1:** Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.

# MIC2288

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NOTES:

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**Note the following details of the code protection feature on Microchip devices:**

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
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- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as “unbreakable.”

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