Obsolete Device



27C64

64K (8K x 8) CMOS EPROM

FEATURES

- · High speed performance
 - 120 ns access time available
- CMOS Technology for low power consumption
 - 20 mA Active current
 - 100 μA Standby current
- · Factory programming available
- · Auto-insertion-compatible plastic packages
- Auto ID aids automated programming
- Separate chip enable and output enable controls
- High speed "express" programming algorithm
- Organized 8K x 8: JEDEC standard pinouts
 - 28-pin Dual-in-line package
 - 32-pin PLCC Package
 - 28-pin SOIC package
 - Tape and reel
- · Available for the following temperature ranges

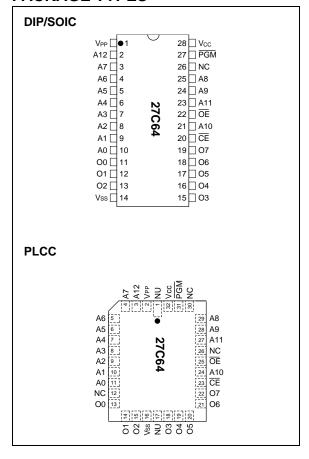
Commercial: 0°C to +70°C
 Industrial: -40°C to +85°C

DESCRIPTION

The Microchip Technology Inc. 27C64 is a CMOS 64K bit (electrically) Programmable Read Only Memory. The device is organized as 8K words by 8 bits (8K bytes). Accessing individual bytes from an address transition or from power-up (chip enable pin going low) is accomplished in less than 120 ns. CMOS design and processing enables this part to be used in systems where reduced power consumption and high reliability are requirements.

A complete family of packages is offered to provide the most flexibility in applications. For surface mount applications, PLCC or SOIC packaging is available. Tape and reel packaging is also available for PLCC or SOIC packages.

PACKAGE TYPES



1.0 ELECTRICAL CHARACTERISTICS

1.1 Maximum Ratings*

Vcc and input voltages w.r.t. Vss-0.6V to + 7.25V

VPP voltage w.r.t. Vss during

programming-0.6V to +14V

Voltage on A9 w.r.t. Vss-0.6V to +13.5V

Output voltage w.r.t. Vss-0.6V to Vcc +1.0V

Storage temperature-65°C to +150°C

Ambient temp. with power applied-65°C to +125°C

*Notice: Stresses above those listed under "Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

TABLE 1-1: PIN FUNCTION TABLE

| Name | Function |
|---------|---|
| A0-A12 | Address Inputs |
| CE | Chip Enable |
| ŌĒ | Output Enable |
| PGM | Program Enable |
| VPP | Programming Voltage |
| O0 - O7 | Data Output |
| Vcc | +5V Power Supply |
| Vss | Ground |
| NC | No Connection; No Internal Connections |
| NU | Not Used; No External Connection Is Allowed |

TABLE 1-2: READ OPERATION DC CHARACTERISTICS

| | Vcc = +5V (±10%) Commercial: Tamb = 0°C to +70°C Industrial: Tamb = -40°C to +85°C | | | | | | | | | |
|-----------------------------------|--|--------------------------------------|------------------|-------------|---------------|----------------|---|--|--|--|
| Parameter | Part* | Status | Symbol | Min | Max | Units | Conditions | | | |
| Input Voltages | all | Logic "1" Logic "0" | VIH VIL | 2.0 -0.5 | Vcc+1 0.8 | V V | | | | |
| Input Leakage | all | ı | ILI | -10 | 10 | μΑ | VIN = 0 to VCC | | | |
| Output Voltages | all | Logic "1" Logic "0" | Voh Vol | 2.4 | 0.45 | V V | IOH = -400 μA IOL = 2.1 mA | | | |
| Output Leakage | all | | ILO | -10 | 10 | μΑ | Vout = 0V to Vcc | | | |
| Input Capacitance | all | _ | CIN | _ | 6 | pF | VIN = 0V; Tamb = 25°C; f = 1 MHz | | | |
| Output Capacitance | all | _ | Соит | _ | 12 | pF | Vout = 0V; Tamb = 25 °C; f = 1 MHz | | | |
| Power Supply Current, Active | C | TTL input TTL input | ICC1 ICC2 | _ | 20 25 | mA mA | $\begin{split} &\text{VCC} = 5.5\text{V}; \ \text{VPP} = \text{VCC}; \\ &\text{f} = 1 \ \text{MHz}; \ \overline{\text{OE}} = \overline{\text{CE}} = \text{VIL}; \\ &\text{IOUT} = 0 \ \text{mA}; \ \text{VIL} = -0.1 \ \text{to} \ 0.8\text{V}; \\ &\text{VIH} = 2.0 \ \text{to} \ \text{VCC}; \ \text{Note} \ 1 \end{split}$ | | | |
| Power Supply Current, Standby | C I all | TTL input TTL input CMOS input | Icc(s) — — | _ _ _ | 2 3 100 | mA mA μA | CE = Vcc ± 0.2V | | | |
| IPP Read Current VPP Read Voltage | all all | Read Mode Read Mode | IPP VPP | Vcc-0.7 | 100 Vcc | μA V | VPP = 5.5V | | | |

^{*} Parts: C=Commercial Temperature Range; I =Industrial Temperature Range.

Note 1: Typical active current increases .5 mA per MHz up to operating frequency for all temperature ranges.

TABLE 1-3: READ OPERATION AC CHARACTERISTICS

AC Testing Waveform: VIH = 2.4V and VIL = 0.45V; VOH = 2.0V VOL = 0.8V

Output Load: 1 TTL Load + 100 pF

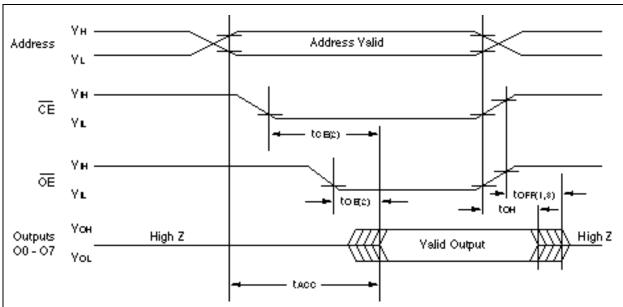
Input Rise and Fall Times: 10 ns

Ambient Temperature: Commercial: Tamb = 0° C to $+70^{\circ}$ C

Industrial: Tamb = -40°C to +85°C

| Parameter | Cum | 27C64-12 | | 27C64-15 | | 27C64-17 | | 27C64-20 | | 27C64-25 | | Units | Conditions | |
|---|------|----------|-----|----------|-----|----------|-----|----------|-----|----------|-----|--------|---------------------------------------|--|
| Farameter | Sym | Min | Max | Ullits | Conditions | |
| Address to Output Delay | tACC | _ | 120 | _ | 150 | 1 | 170 | _ | 200 | _ | 250 | ns | $\overline{CE} = \overline{OE} = VIL$ | |
| CE to Output Delay | tCE | - | 120 | | 150 | ı | 170 | - | 200 | - | 250 | ns | OE = VIL | |
| OE to Output Delay | tOE | | 65 | | 70 | l | 70 | - | 75 | - | 100 | ns | CE = VIL | |
| CE or OE to O/P High Impedance | tOFF | 0 | 50 | 0 | 50 | 0 | 50 | 0 | 55 | 0 | 60 | ns | | |
| Output Hold from Address CE or OE, whichever occurs first | ton | 0 | _ | 0 | _ | 0 | | 0 | _ | 0 | _ | ns | | |

FIGURE 1-1: READ WAVEFORMS



Note 1: tOFF is specified for \overline{OE} or \overline{CE} , whichever occurs first.

2: \overline{OE} may be delayed up to tCE - tOE after the falling edge of \overline{CE} without impact on tCE.

3: This parameter is sampled and is not 100% tested.

TABLE 1-4: PROGRAMMING DC CHARACTERISTICS

| | Ambient Temperature: Tamb = 25° C \pm 5° C VCC = 6.5 V \pm 0.25 V, VPP = VH = 13.0 V \pm 0.25 V | | | | | | | | | | | | |
|-------------------------------|---|---|-------------|--------------|--------|-------------------------------|--|--|--|--|--|--|--|
| Parameter | Status | Status Symbol Min Max. Units Conditions | | | | | | | | | | | |
| Input Voltages | Logic"1" Logic"0" | VIH VIL | 2.0 -0.1 | Vcc+1 0.8 | V | | | | | | | | |
| Input Leakage | _ | ILI | -10 | 10 | μΑ | VIN = 0V to VCC | | | | | | | |
| Output Voltages | Logic"1" Logic"0" | Voh Vol | 2.4 — | — 0.45 | V V | IOH = -400 μA IOL = 2.1 mA | | | | | | | |
| Vcc Current, program & verify | _ | ICC2 | _ | 20 | mA | Note 1 | | | | | | | |
| VPP Current, program | _ | IPP2 | _ | 25 | mA | Note 1 | | | | | | | |
| A9 Product Identification | _ | VH | 11.5 | 12.5 | V | | | | | | | | |

Note 1: VCC must be applied simultaneously or before VPP and removed simultaneously or after VPP.

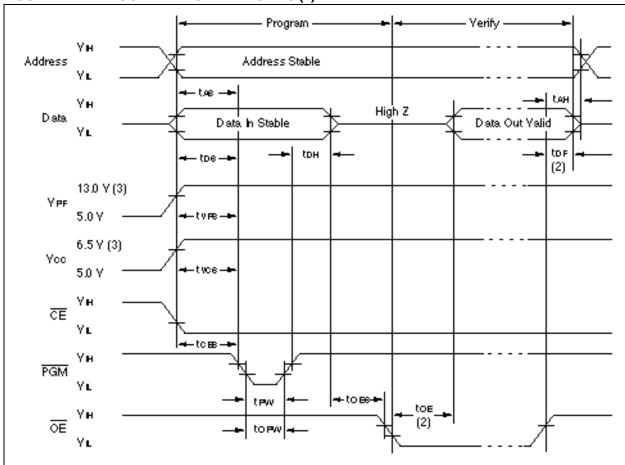
TABLE 1-5: PROGRAMMING AC CHARACTERISTICS

| for Program, Program Verify and Program Inhibit Modes AC Testing Waveform: VIH=2.4V and VIL=0.45V; VOH=2.0V; VOL=0.8V Ambient Temperature: Tamb=25°C ±5°C VCC= 6.5V ± 0.25V, VPP = VH = 13.0V ± 0.25V | | | | | | | | | | |
|--|--------|-----|-----|-------|----------------|--|--|--|--|--|
| Parameter | Symbol | Min | Max | Units | Remarks | | | | | |
| Address Set-Up Time | tAS | 2 | _ | μs | | | | | | |
| Data Set-Up Time | tDS | 2 | _ | μs | | | | | | |
| Data Hold Time | tDH | 2 | _ | μs | | | | | | |
| Address Hold Time | tAH | 0 | _ | μs | | | | | | |
| Float Delay (2) | tDF | 0 | 130 | ns | | | | | | |
| Vcc Set-Up Time | tvcs | 2 | _ | μs | | | | | | |
| Program Pulse Width (1) | tPW | 95 | 105 | μs | 100 μs typical | | | | | |
| CE Set-Up Time | tCES | 2 | _ | μs | | | | | | |
| OE Set-Up Time | toes | 2 | _ | μs | | | | | | |
| VPP Set-Up Time | tvps | 2 | _ | μs | | | | | | |
| Data Valid from OE | toe | _ | 100 | ns | | | | | | |

Note 1: For express algorithm, initial programming width tolerance is 100 μs ±5%.

^{2:} This parameter is only sampled and not 100% tested. Output float is defined as the point where data is no longer driven (see timing diagram).

FIGURE 1-2: PROGRAMMING WAVEFORMS (1)



Notes: (1) The input timing reference is 0.8 Y for YL and 2.0 Y for YH.

- (2) to F and to E are characteristics of the device but must be accommodated by the programmer.
- (3) Ycc = 6.5 Y ±0.25 Y, YPP = YH = 13.0 Y ±0.25 Y for Express algorithm.

TABLE 1-6: MODES

| Operation Mode | CE | ŌĒ | PGM | VPP | A9 | 00 - 07 |
|-----------------|-----|-----|-----|-----|----|---------------|
| Read | VIL | VIL | VIH | Vcc | Х | Dout |
| Program | VIL | VIH | VIL | VH | X | DIN |
| Program Verify | VIL | VIL | VIH | VH | Х | Dout |
| Program Inhibit | ViH | X | X | VH | X | High Z |
| Standby | ViH | X | X | Vcc | X | High Z |
| Output Disable | VIL | VIH | VIH | Vcc | X | High Z |
| Identity | VIL | VIL | VIH | Vcc | VH | Identity Code |

X = Don't Care

1.2 Read Mode

(See Timing Diagrams and AC Characteristics)

Read Mode is accessed when

- a) the $\overline{\text{CE}}$ pin is low to power up (enable) the chip
- b) the $\overline{\text{OE}}$ pin is low to gate the data to the output pins

For Read operations, if the addresses are stable, the address access time (tACC) is equal to the delay from $\overline{\text{CE}}$ to output (tCE). Data is transferred to the output after a delay from the falling edge of $\overline{\text{OE}}$ (tOE).

1.3 Standby Mode

The standby mode is defined when the \overline{CE} pin is high (VIH) and a program mode is not defined.

When these conditions are met, the supply current will drop from 20 mA to 100 μ A.

1.4 Output Enable

This feature eliminates bus contention in microprocessor-based systems in which multiple devices may drive the bus. The outputs go into a high impedance state when the following condition is true:

• The OE and PGM pins are both high.

1.5 <u>Erase Mode (U.V. Windowed Versions)</u>

Windowed products offer the capability to erase the memory array. The memory matrix is erased to the all 1's state when exposed to ultraviolet light. To ensure complete erasure, a dose of 15 watt-second/cm² is required. This means that the device window must be placed within one inch and directly underneath an ultraviolet lamp with a wavelength of 2537 Angstroms, intensity of $12,000\mu\text{W/cm}^2$ for approximately 20 minutes.

1.6 **Programming Mode**

The Express Algorithm has been developed to improve the programming throughput times in a production environment. Up to ten 100-microsecond pulses are applied until the byte is verified. No overprogramming is required. A flowchart of the express algorithm is shown in Figure 1-3.

Programming takes place when:

- a) Vcc is brought to the proper voltage,
- b) VPP is brought to the proper VH level,
- c) the CE pin is low,
- d) the \overline{OE} pin is high, and
- e) the \overline{PGM} pin is low.

Since the erased state is "1" in the array, programming of "0" is required. The address to be programmed is set via pins A0-A12 and the data to be programmed is presented to pins O0-O7. When data and address are stable, \overline{OE} is high, \overline{CE} is low and a low-going pulse on the \overline{PGM} line programs that location.

1.7 Verify

After the array has been programmed it must be verified to ensure all the bits have been correctly programmed. This mode is entered when all the following conditions are met:

- a) Vcc is at the proper level,
- b) VPP is at the proper VH level,
- c) the \overline{CE} line is low,
- d) the PGM line is high, and
- e) the OE line is low.

1.8 Inhibit

When programming multiple devices in parallel with different data, only \overline{CE} or \overline{PGM} need be under separate control to each device. By pulsing the \overline{CE} or \overline{PGM} line low on a particular device in conjunction with the \overline{PGM} or \overline{CE} line low, that device will be programmed; all other devices with \overline{CE} or \overline{PGM} held high will not be programmed with the data, although address and data will be available on their input pins (i.e., when a high level is present on \overline{CE} or \overline{PGM}); and the device is inhibited from programming.

1.9 Identity Mode

In this mode, specific data is output which identifies the manufacturer as Microchip Technology Inc. and device type. This mode is entered when Pin A9 is taken to VH (11.5V to 12.5V). The $\overline{\text{CE}}$ and $\overline{\text{OE}}$ lines must be at VIL. A0 is used to access any of the two non-erasable bytes whose data appears on O0 through O7.

| Pin → | Input | Output | | | | | | | | |
|------------------------------|------------|--------|--------|--------|--------|--------|-----|--------|-----|-------------|
| Identity | Α0 | 0 7 | O 6 | O 5 | O 4 | O 3 | 0 2 | 0 | 0 0 | H e x |
| Manufacturer Device Type* | VIL VIH | 0 0 | 0 0 | 1 0 | 0 0 | 1 0 | 0 | 0 1 | 1 | 29 02 |

^{*} Code subject to change

PROGRAMMING EXPRESS ALGORITHM FIGURE 1-3: Conditions: Tamb = $25^{\circ}C \pm 5^{\circ}C$ Start $Ycc = 6.5 \pm 0.25 Y$ YPP = 13.0 ±0.25Y ADDR = First Location Ycc = 6.5YYPP= 13.0Y ŧ X = 0Program one 100 µs pulse Increment X Yerify Pass Byte Fail Nο Yes / Device X = 10? Failed Last Yes Address? No Increment Address Ycc = YPP = 4.5Y, 5.5YΆIÌ No bytes

Device

Passed

Device

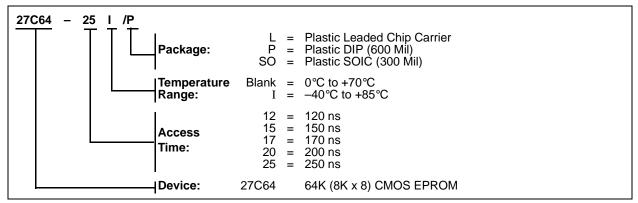
Failed

= original

data?

27C64 Product Identification System

To order or to obtain information, e.g., on pricing or delivery, please use the listed part numbers, and refer to the factory or the listed sales offices.



Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the
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CERTIFIED BY DNV

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AMERICAS

Corporate Office

2355 West Chandler Blvd. Chandler, AZ 85224-6199 Tel: 480-792-7200 Fax: 480-792-7277

Technical Support: 480-792-7627 Web Address: www.microchip.com

Atlanta

3780 Mansell Road, Suite 130 Alpharetta, GA 30022 Tel: 770-640-0034 Fax: 770-640-0307

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Detroi

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Kokomo

2767 S. Albright Road Kokomo, IN 46902 Tel: 765-864-8360 Fax: 765-864-8387

Los Angeles

25950 Acero St., Suite 200 Mission Viejo, CA 92691 Tel: 949-462-9523 Fax: 949-462-9608

San Jose

1300 Terra Bella Avenue Mountain View, CA 94043 Tel: 650-215-1444 Fax: 650-961-0286

Toronto

6285 Northam Drive, Suite 108 Mississauga, Ontario L4V 1X5, Canada Tel: 905-673-0699 Fax: 905-673-6509

ASIA/PACIFIC

Australia

Microchip Technology Australia Pty Ltd Unit 32 41 Rawson Street Epping 2121, NSW Sydney, Australia Tel: 61-2-9868-6733 Fax: 61-2-9868-6755

China - Beijing

Unit 706B Wan Tai Bei Hai Bldg. No. 6 Chaoyangmen Bei Str. Beijing, 100027, China Tel: 86-10-85282100 Fax: 86-10-85282104

China - Chengdu

Rm. 2401-2402, 24th Floor, Ming Xing Financial Tower No. 88 TIDU Street Chengdu 610016, China Tel: 86-28-86766200 Fax: 86-28-86766599

China - Fuzhou

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China - Shenzhen

Rm. 1812, 18/F, Building A, United Plaza No. 5022 Binhe Road, Futian District Shenzhen 518033, China Tel: 86-755-82901380

Fax: 86-755-8295-1393 China - Shunde

Room 401, Hongjian Building, No. 2 Fengxiangnan Road, Ronggui Town, Shunde District, Foshan City, Guangdong 528303, China Tel: 86-757-28395507 Fax: 86-757-28395571

China - Qingdao

Rm. B505A, Fullhope Plaza, No. 12 Hong Kong Central Rd. Qingdao 266071, China

Tel: 86-532-5027355 Fax: 86-532-5027205

India

Divyasree Chambers 1 Floor, Wing A (A3/A4) No. 11, O'Shaugnessey Road Bangalore, 560 025, India Tel: 91-80-22290061 Fax: 91-80-22290062

Japan

Yusen Shin Yokohama Building 10F 3-17-2, Shin Yokohama, Kohoku-ku, Yokohama, Kanagawa, 222-0033, Japan Tel: 81-45-471- 6166 Fax: 81-45-471-6122

Korea

168-1, Youngbo Bldg. 3 Floor Samsung-Dong, Kangnam-Ku Seoul, Korea 135-882 Tel: 82-2-554-7200 Fax: 82-2-558-5932 or 82-2-558-5934

Singapore

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Taiwan

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Taiwan

Taiwan Branch 11F-3, No. 207 Tung Hua North Road Taipei, 105, Taiwan

Tel: 886-2-2717-7175 Fax: 886-2-2545-0139

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Taiwan Branch 13F-3, No. 295, Sec. 2, Kung Fu Road Hsinchu City 300, Taiwan Tel: 886-3-572-9526 Fax: 886-3-572-6459

EUROPE

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Durisolstrasse 2 A-4600 Wels Austria

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Italy

Via Salvatore Quasimodo, 12 20025 Legnano (MI) Milan, Italy Tel: 39-0331-742611 Fax: 39-0331-466781

Netherlands

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United Kingdom

505 Eskdale Road Winnersh Triangle Wokingham Berkshire, England RG41 5TU Tel: 44-118-921-5869

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